

The Valuation of Storage

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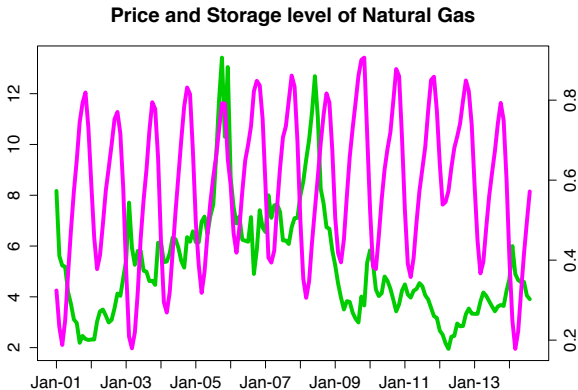
Joint work with Kumar Muthuraman and Stathis Tompaidis

December 2, 2014

Examples of Storage

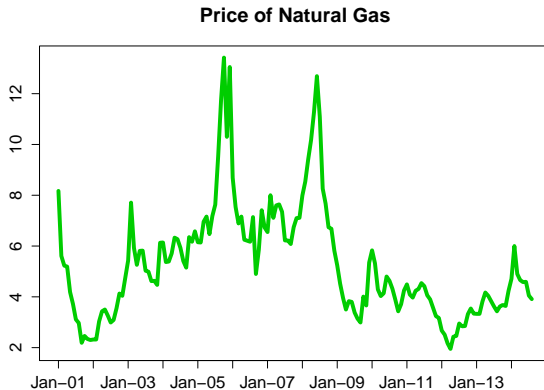
- Silos - Agricultural Commodities
- Tanks - Oil
- Caverns - Natural Gas
- Lake Reservoirs and Dams - Water \Rightarrow Electricity.

Motivation



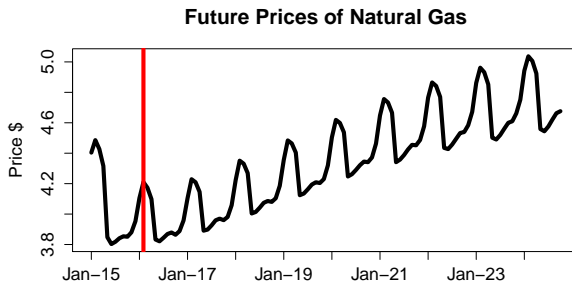
Data comes from U.S. Energy Information Administration.

Historical Prices



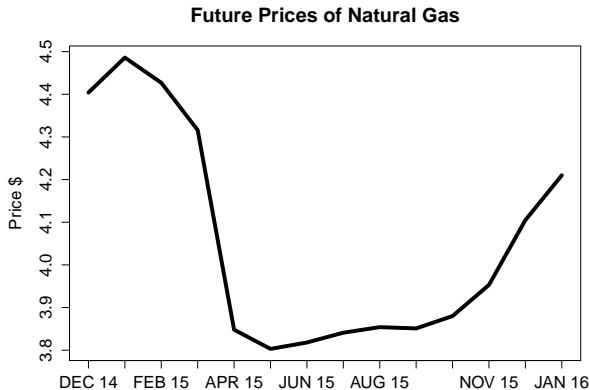
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Future Prices



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Future Prices



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Price Dynamics

- Schwartz (1997)
- Schwartz and Smith (2000)
- Seppi (2000)
- Jaillet (2004)

Price Dynamics

Paper	Price Dynamics
Hodges (2004)	Schwartz (1997) one factor model + $\sin()$
Boogert (2008)	Schwartz (1997) one factor model
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Secomandi (2010)	Jaillet (2004)

Price Dynamics

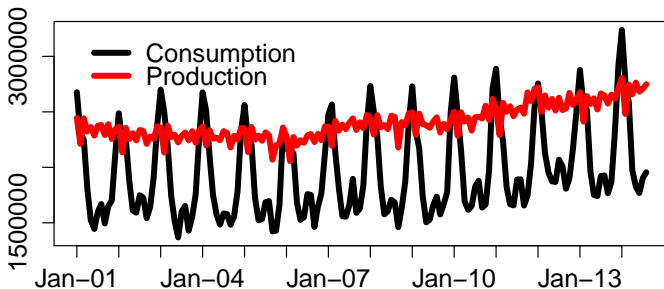
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Secomandi (2010)	Jaillet (2004)
Ours	Schwartz (1997) one factor model

Constraints of Storage

- Transaction costs.
- Depreciation rates.
- Delivery rate.
- Capacity.

Why Constraints?

Production and Consumption of Natural Gas



Data comes from U.S. Energy Information Administration.

Storage Valuation

Paper	Trans	Depre	Delivery	Cap	Type	Opt
Hodges (2004)	None	CP	U	B	C	O
Boogert (2008)	CP	None	B	B	D	S
Chen (2008)	CP	None	B	B	C	S
Thompson (2009)	CF	None	B	B	C	O
Secomandi (2010)	CP	None	B	B	D	O

CP: Constant Proportional CF: Constant Fixed

B: Bounded U: Unbounded

C: Continuous D: Discrete

O: Optimal S: Suboptimal

Storage Valuation

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Ours	B & C	None	U	B	C	O

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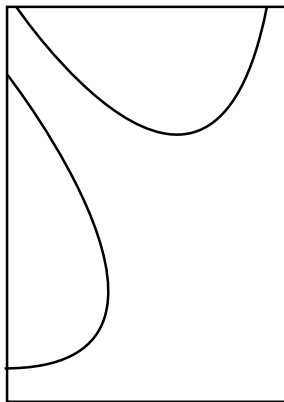
Method

- Continuous Time Singular Control \Rightarrow HJB equation.
- HJB equation (free boundary problem) is very hard to solve.
- Moving boundary method is used in 1 dimension.
 - Start with an initial guess and iteratively improve it until convergence.
 - A sequence of fixed boundary problems \rightarrow free boundary problem

1D Moving boundary Method

- Muthuraman and Kumar (2006)
- Chockalingam and Muthuraman (2007,2010)
- Muthuraman and Zha (2008)
- Feng and Muthuraman (2010)

1 Dimension VS 2 Dimensions



Overview of Results

- Fixed boundary problem is solved efficiently.
- Moving boundary method is generalized to 2 dimensions.
- Optimal value and strategy are obtained.

Model

- One factor model

$$dS_t = \kappa(\mu - \ln S_t)S_t dt + \sigma S_t dW_t$$

- By Ito's formula, $X_t = \ln(S_t)$ is an Ornstein-Uhlenbeck process,

$$dX_t = \kappa(\alpha - X_t)dt + \sigma dW_t.$$

where $\alpha = \mu - \sigma^2/(2\kappa)$.

Model

- Storage level at time t is Q_t . L_t, U_t represent cumulative injections and withdrawals at time t .

$$dQ_t = dL_t - dU_t$$

- Admissible if $Q_t \in (Q_{min}, Q_{max}) \quad \forall t \geq 0$.
- Costs of injection and withdrawal, $\lambda(X_t, Q_t)$ and $\mu(X_t, Q_t)$, are continuous and bounded.

Model

- Objective: to maximize discounted infinite-horizon cash flows.

$$V(x, q) = \max_{(L, U) \in \mathcal{U}} \mathbb{E}_{x, q} \left(\int_0^\infty e^{-\beta t} (e^{X_t} - \mu(Q_t^1)) dU_t - \int_0^\infty e^{-\beta t} (e^{X_t} + \lambda(Q_t^2)) dL_t \right) \quad (1)$$

where $X_0 = x$ and $Q_0 = q$.

The Hamilton-Jacobi-Bellman Equation

- Dynamic programming arguments and Ito's formula yield the Hamilton-Jacobi-Bellman (HJB) equation.

$$\max \left(\mathcal{L}V, \frac{\partial V}{\partial q} - (e^x + \lambda(q)), -\frac{\partial V}{\partial q} + (e^x - \mu(q)) \right) = 0$$

with $\mathcal{L}V = \frac{1}{2}\sigma^2 \frac{\partial^2 V}{\partial x^2} + \alpha(\kappa - x) \frac{\partial V}{\partial x} - \beta V$.

- A verification theorem assures us that a function that solves the HJB equation is the value function for the original control problem and a policy that achieves this value function is the optimal policy.

The Hamilton-Jacobi-Bellman Equation

- Assume V is known and the change of policy at one point (x_0, q_0) won't affect it.
Now at (x_0, q_0) , ϵ is bought at price e^{x_0} . The average buying profit is

$$\frac{[V(x_0, q_0 + \epsilon) - V(x_0, q_0)] - \epsilon(e^x + \lambda(q))}{\epsilon} \xrightarrow{\epsilon \rightarrow 0} \frac{\partial V}{\partial q} - (e^x + \lambda(q))$$

- $\mathcal{L}V(x, q)$: holding profit at (x, q) .
- $\frac{\partial V}{\partial q}(x, q) - (e^x + \lambda(q))$: selling profit at (x, q) .
- $-\frac{\partial V}{\partial q}(x, q) + (e^x - \mu(q))$: buying profit at (x, q) .
- HJB equation.

$$\max \left(\mathcal{L}V, \frac{\partial V}{\partial q} - (e^x + \lambda(q)), -\frac{\partial V}{\partial q} + (e^x - \mu(q)) \right) = 0$$

Holding, Selling and Buying Regions

- The state space $(x, q) \in \mathbb{R}_+^2$ is divided into three kinds of regions.
- Holding region: holding profit = 0, selling & buying profit < 0
- Selling region: selling profit = 0, holding & buying profit < 0
- Buying region: buying profit = 0, holding & selling profit < 0

Solving the Fixed Boundary Problem

- In the holding region

$$\frac{1}{2}\sigma^2\frac{\partial^2 V}{\partial x^2} + \alpha(\kappa - x)\frac{\partial V}{\partial x} - \beta V = 0$$

- Defining $y = \kappa(x - \alpha)^2/\sigma^2$, we have

$$y\frac{\partial^2 V}{\partial y^2} + (0.5 - y)\frac{\partial V}{\partial y} - \frac{\beta}{2\kappa}V = 0$$

which is the Kummer Equation. The solution is the sum of hypergeometric1F1 and the hypergeometricU functions.

$$\begin{aligned} V(x, q) = & A(q)\text{HyperGeoU}\left(\frac{\beta}{2\kappa}, \frac{1}{2}, \frac{\kappa}{\sigma^2}(x - \alpha)^2\right) \\ & + B(q)\text{HyperGeo1F1}\left(\frac{\beta}{2\kappa}, \frac{1}{2}, \frac{\kappa}{\sigma^2}(x - \alpha)^2\right) \end{aligned}$$

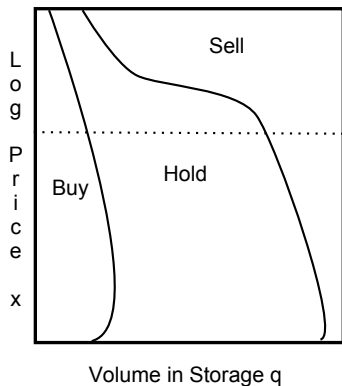
Boundary conditions can determine $A(q)$ and $B(q)$.

The Structure of Optimal Boundary

Theorem

When the price is high enough, regardless of storage, selling is the optimal strategy.

The Structure of Optimal Boundary



Theorem

Under optimal policy, there won't exist x and $q_1 \neq q_2$ such that buying happens at (x, q_1) while selling happens at (x, q_2) .

The Moving Boundary Method

- Challenges
 - Initial guess.
 - 2 dimensions.
 - Direction.
 - Distance.

The Moving Boundary Method

- Challenges

- Initial guess.
- 2 dimensions.
 - Direction.
 - Distance.

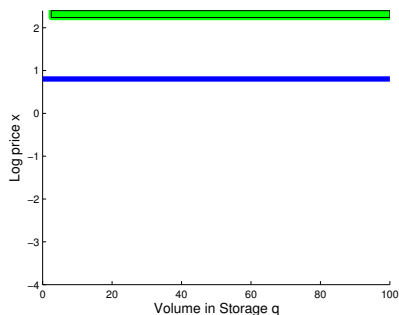


Figure : Initial Guess

The Moving Boundary Method

- Challenges

- Initial guess.
- 2 dimensions.
 - Direction.
 - Distance.

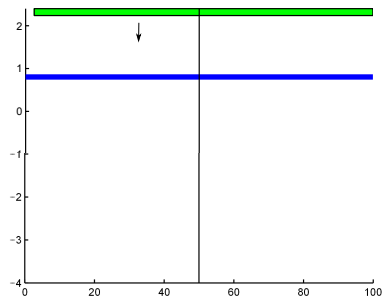


Figure : Initial Guess

Algorithm

- 1 Begin with selling at very high price for all $q > 0$.
- 2 Move selling and buying boundaries along price x alternatively until convergence.

Distance

Because there is *No Coming Back*, overshooting must be avoided.
Sell

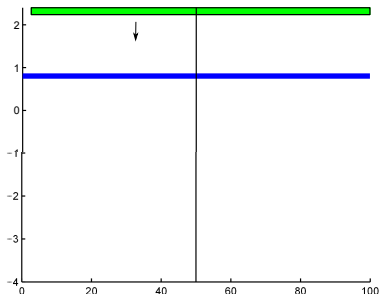


Figure : Current Policy

Distance

Because there is *No Coming Back*, overshooting must be avoided.
Sell

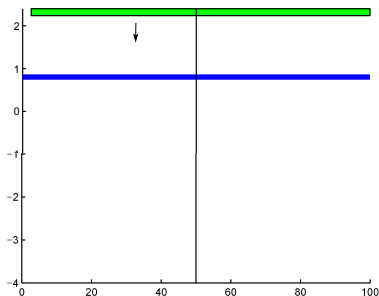


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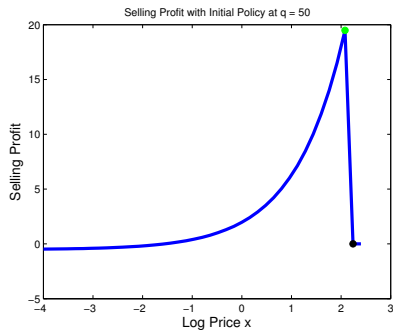


Figure : Selling Profit

Distance

Because there is *No Coming Back*, overshooting must be avoided.
Sell

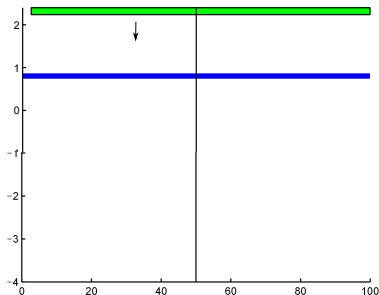


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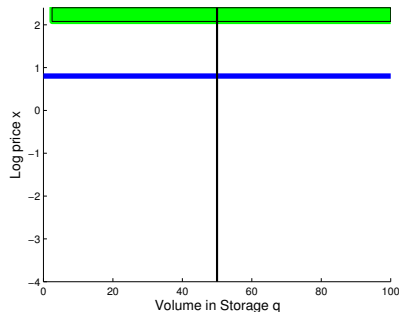


Figure : After Movement

Buy

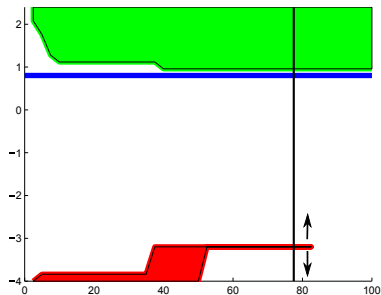


Figure : Current Policy

Buy

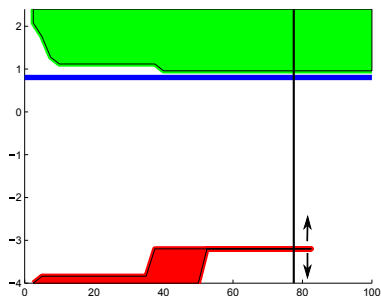


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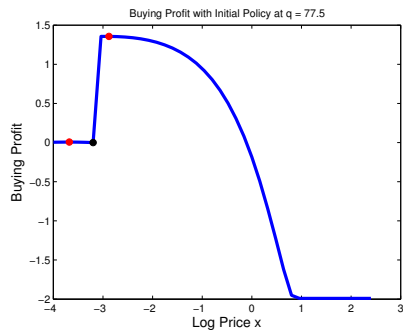


Figure : Buying Profit

Buy

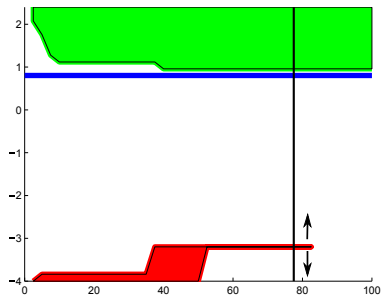


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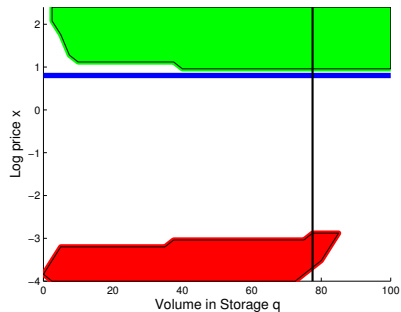


Figure : After Movement

Proof of Convergence

Theorem

Each movement improves value function.

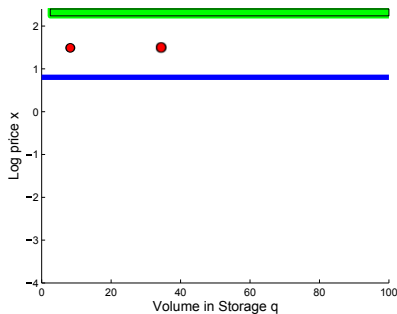


Figure : Initial Guess

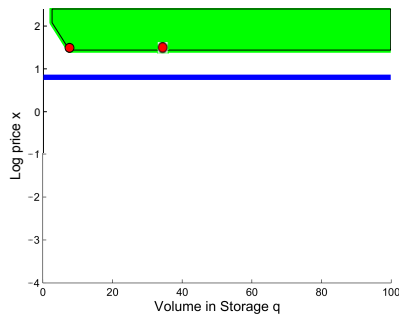


Figure : Initial Guess

Proof of Convergence

Theorem

The boundaries can be kept moving.

Extensions

- Seasonality and Finite time.
- Depreciation.
- Random injection and withdrawal.