01.05 rootfinding: without derivatives

what if f(x) has no (or unknown) f'(x)?

1 secant method, variants

secant method

replace the derivative with a difference quotient. ie, replace tangent line with secant line through previous two guesses. ie, approximation for derivative at x_i is difference quotient

$$\frac{f(x_i)-f(x_{i-1})}{x_i-x_{i-1}}.$$

secant method

 $x_0, x_1 = \text{initial guesses}$

$$x_{i+1} = x_i - f(x_i) \cdot \underbrace{\frac{x_i - x_{i-1}}{f(x_i) - f(x_{i-1})}}_{\sim rac{1}{f'(x_i)}}, \quad i = 1, 2, 3, \ldots$$

✓ algorithm

```
icount = 0

fx_old = f(x_old)
if abs(fx_old) < epsilon # epsilon ~ eta
  return x_old

fx_older = f(x_older)
if abs(fx_older) < epsilon # epsilon ~ eta
  return x_older

dq = (fx_old - fx_older)/(x_old - x_older)
x_new = x_old - fx_old/dq
fx = f(x_new)
icount = icount + 1</pre>
```

```
# while (abs(fx) > epsilon) and (icount <= imax): # epsilon ~ eta
while (abs(x_new - x_old) > epsilon) and (icount <= imax):
    x_older = x_old
    fx_older = fx_old
    x_old = x_new
    fx_old = fx
    dq = (fx_old - fx_older)/(x_old - x_older)
    x_new = x_old - fx_old/dq
    fx = f(x_new)
    icount = icount + 1</pre>
```

convergence

assume that method converges to r and f'(r)
eq 0, then the approximate error relationship

$$e_{i+1}pprox \left|rac{f''(r)}{2f'(r)}
ight|e_ie_{i-1}$$

holds and implies

$$e_{i+1}pprox \left|rac{f''(r)}{2f'(r)}
ight|^{lpha-1}e_i^lpha,$$

where $\alpha=\frac{1+\sqrt{5}}{2}\approx 1.62$. secant method convergence to simple roots is called **superlinear**, meaning that it lies between linearly and quadratically convergent methods.

example 16

example 01, revisted. apply secant method with $x_0=0, x_1=1$ to find root of $f(x)=x^3+x-1$.

$$x_{i+1} = x_i = rac{(x_i^3 + x_i - 1)(x_i - x_{i-1})}{x_i^3 + x_i - (x_{i-1}^3 + x_{i-1})}$$

$$\Downarrow \quad x_0=0, x_1=1$$

$$x_2 = 1 - rac{(1)(1-0)}{(1+1-0)} = rac{1}{2}$$

$$x_3 = rac{1}{2} - rac{-rac{3}{8}(rac{1}{2} - 1)}{rac{3}{8} - 1} = rac{7}{11}.$$

code, example 16

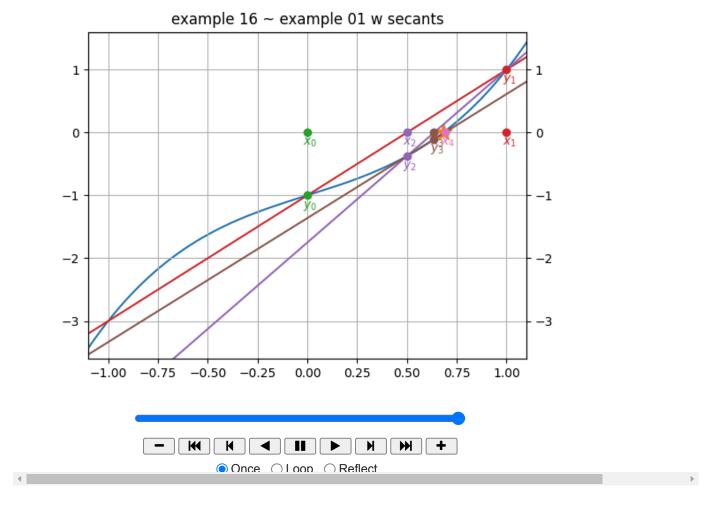
```
1 # example 16, secant method for example 01 # mod example 14
2
3 if __name__ == "__main__":
4
```

expected convergence: [0.8068743]

example 16 ~ example 01 w secants. x0 = [0, 1].

ļ	i	x[i]	e[i]	"/e[i-1]^α
ļ				
-	000	0.000000000000000	0.68232780382802	
	001	1.000000000000000	0.31767219617198	0.58963609730649
	002	0.50000000000000	0.18232780382802	1.16591656728344
	003	0.63636363636364	0.04596416746438	0.72174623555971
	004	0.69005235602094	0.00772455219292	1.12751982884733
	005	0.68202041964819	0.00030738417983	0.80384864065885
	006	0.68232578140989	0.00000202241813	0.97481374069426
	007	0.68232780435903	0.0000000053101	0.86774886684321
	008	0.68232780382802	0.000000000000000	1.01567939794005
	009	0.68232780382802	0.000000000000000	207243987.96379616856575

1 ani



generalizations of secant method

✓ regula falsi

aka "method of false position". regula falsi is similar to bisection but midpoint replaced by secant-like approximation. ie, given bracketing interval [a, b],

$$c = a - rac{f(a)(a-b)}{f(a)-f(b)} = rac{b \ f(a)-a \ f(b)}{f(a)-f(b)},$$

where $c \in [a,b]$ and next subinterval chosen to bracket root.

✓ algorithm, regula falsi

given [a,b] st
$$f(a) \cdot f(b) < 0$$

for $i = 1,2,3,...$

```
c = [b·f(a) - a·f(b)] / [f(a) - f(b)]
if f(c) == 0 stop
if f(a)·f(c) < 0
   b = c
else
   a = c
end
next</pre>
```

code, regula falsi

```
1 # algorithm, basic
2
3 def secant_rf(f,ab,tol=le-8):
4

1 # algorithm, basic # modified bisect_expanded from lecture 01_01
2
3 def secant_rf_expanded(f,ab,tol=le-8,all=False,workspace=False):
4
```

✓ example 17

apply regula falsi on interal [-1,1] to find root r=0 of $f(x)=x^3-2\,x^2+rac{3}{2}\,x$.

$$x_0 = -1, x_1 = 1$$

$$x_2 = rac{x_1 \cdot f(x_0) - x_0 \cdot f(x_1)}{f(x_0) - f(x_1)} = rac{1(-rac{9}{2}) - (-1)(rac{1}{2})}{-rac{9}{2} - rac{1}{2}} = rac{4}{5}.$$

 $f(-1)\cdot f(\frac{4}{5})<0 \implies [x_0,x_2]=[-1,\frac{4}{5}]\sim$ better than $\frac{1}{2}$ of bisection; however, sometimes its not your birthday.

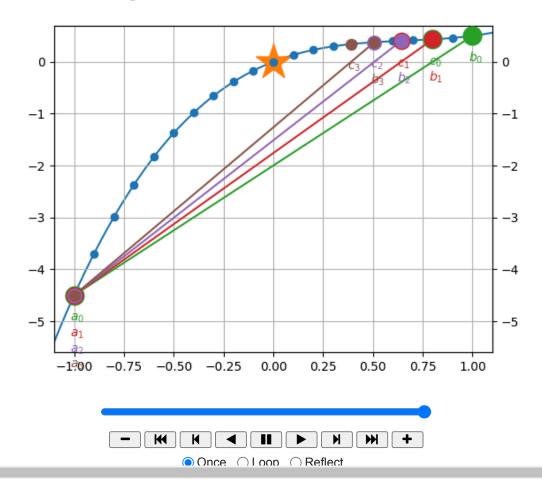
code, example 17, regula falsi

```
1 # requires prior execution of secant_rf_expanded() # mod lecture 01_01 first code
2
3 if __name__ == "__main__":
4
```

\rightarrow regular falsi: $x^3 + 2x^2 - 1.5x$, $x \in [-1.0,1.0]$

		f(a) 		. , , ,		f(c)	
000 001 002	-1.00000000 -1.00000000 -1.00000000	-4.50000000 -4.50000000 -4.50000000 -4.50000000	1.00000000 0.80000000 0.64233577	0.50000000 0.43200000 0.40333785	0.80000000 0.64233577 0.50724082	0.43200000 0.40333785 0.37678437	001 001 001

regular falsi: $x^3 + 2x^2 - 1.5x$, $x \in [-1.0, 1.0]$



✓ code, example 17, secant

```
1  # example 17, secant method # mod example 16
2
3  if __name__ == "__main__": ...
164
```

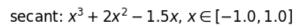
⇒ expected convergence: [1.19458315]

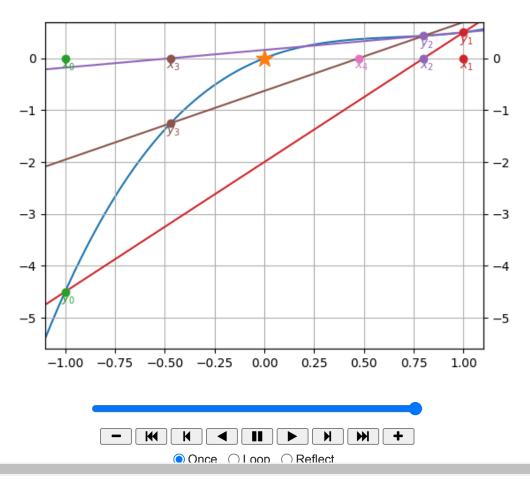
secant:
$$x^3 + 2x^2 - 1.5x$$
, $x \in [-1.0,1.0]$

Ţ	i	x[i]	e[i]	"/e[i-1]^α
(900	-1.000000000000000	1.000000000000000	
(901	1.00000000000000	1.000000000000000	1.000000000000000
į (902	0.80000000000000	0.8000000000000	i 0.80000000000000 i
į (903	-0.47058823529412	0.47058823529412	0.67521916496024
į (904	0.47424724729948	0.47424724729948	1.60576763820552
j (905	0.25965464146786	0.25965464146786	0.86822303833010 j
j			j	j j
į (908	0.03994345289533	0.03994345289533	1.49983922882677
į (909	-0.00643218295752	0.00643218295752	1.17833000297553
į (910	0.00035223951983	0.00035223951983	1.23876434915084
į (911	0.00000300563144	0.00000300563144	1.16216844505921

1 ani

 $\overline{2}$





✓ mullers method

draw parabola y=p(x) through three previous points (vs line through two previous points) and its intersection with x-axis closest to x_i is next iteration x_{i+1} .

- for multiple intersections, select the one closest to previous iteration;
- if parabola misses x-axis then it gets complex and costs extra tuition. \odot

oscar velize <u>@youtube</u>

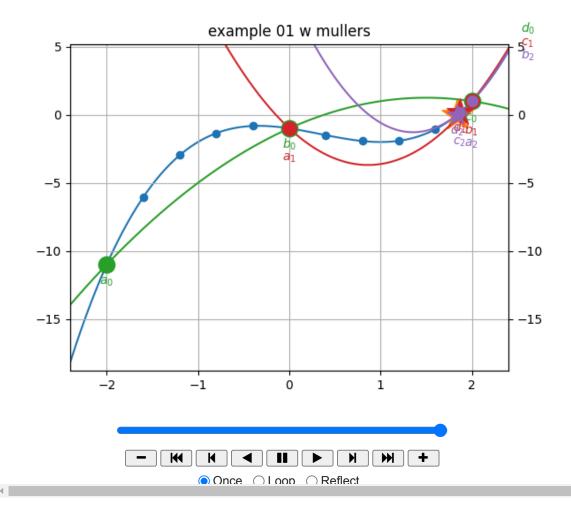
code, mullers method

```
1 # https://en.wikipedia.org/wiki/Muller%27s_method # mod
2
3 import cmath as cm
4 import numpy as np
5
```

```
6 # newtons divided difference
7 def dd(f,xx):
8 if len(xx) == 2:
     a,b = xx
1 # instead of complex number hack, use future methods
3 import numpy as np
5 def mullers_lol(f,xs,max_iter=100,tol=1e-8,method=0):
1 # example 01 with mullers # mod secant example
3 if __name__ == "__main__":
5
  import scipy as sp
   step 0, parabola: -1.0 + 3.0 \cdot x - 1.0 \cdot x^2
                  roots: [2.6180339887498976,0.38196601125010493]
    step 1, parabola: -1.0 - 6.23606798·x + 3.61803399·x<sup>2</sup>
                  roots: [1.871307386268059, -0.14770058851807896]
    step 2, parabola: 8.79829268 - 14.87782909·x + 5.48934138·x<sup>2</sup>
                  roots: [1.8385321777112726,0.8717800572671759]
    step 3, parabola: 8.00723819 - 14.15294492·x + 5.32787355·x<sup>2</sup>
                  roots: [1.8392902102200412,0.8171063380988388]
    step 4, parabola: 5.32800227 - 11.26393044·x + 4.54912977·x<sup>2</sup>
                  roots: [1.8392867552294225,0.6367759193327744]
```

example 01 w mullers: $x^3 - x^2 - x - 1$

ļ	i	a	b	С	gap	e[i]	"/e[i-1]
	000	 -2.00000000	0.00000000	2.00000000	2.00000000	0.16071324	
İ	001	0.0000000	2.00000000	2.61803399	0.61803399	0.77874723	4.84556973
ĺ	002	2.00000000	2.61803399	1.87130739	-0.74672660	0.03202063	0.04111813
ĺ	003	2.61803399	1.87130739	1.83853218	-0.03277521	0.00075458	0.02356535
١	004	1.87130739	1.83853218	1.83929021	0.00075803	0.00000346	0.00457873
ĺ	005	1.83853218	1.83929021	1.83928676	-0.00000345	0.00000000	0.00000442



inverse quadratic interpolation (IQI)

similar to mullers but with parabola x=p(y), which is handy for limiting the x-axis intesection to a single point. consider second-degree polynomial x=P(y) through points (a,A),(b,B),(c,C).

$$P(y) = a \frac{(y-B)(y-C)}{(A-B)(A-C)} + b \frac{(y-A)(y-C)}{(B-A)(B-C)} + c \frac{(y-A)(y-B)}{(C-A)(C-B)}$$

$$\Downarrow P(A) = a, P(B) = b, P(C) = c, y = 0$$

$$P(0) = c - \frac{r(r-q)(c-b) + (1-r)s(c-a)}{(q-1)(r-1)(s-1)}, \quad q = \frac{f(a)}{f(b)}, r = \frac{f(c)}{f(b)}, s = \frac{f(c)}{f(a)}$$

$$\Downarrow a = x_i, b = x_{i+1}, c = x_{i+2}, A = f(x_i), B = f(x_{i+1}), C = f(x_{i+2})$$

$$x_{i+3} = x_{i+2} - rac{r(r-q)(x_{i+2}-x_{i+1}) + (1-r)s(x_{i+2}-x_i)}{(q-1)(r-1)(s-1)}, \quad q = rac{f(x_i)}{f(x_{i+1})}, r = rac{f(x_{i+2})}{f(x_{i+1})}, s = rac{f(x_{i+2})}{f(x_i)}.$$

here x_{i+3} replaces x_i but an alternative implementation replaces the largest source of backward error.

lemonfully @youtube @wiki

- lemonfully points out that while this method is asymptotically faster than secants, it only is if initial points chosen well.
- oscar veliz (in the lead up to brents method) also points out this unreliability.
- ✓ oh, why not

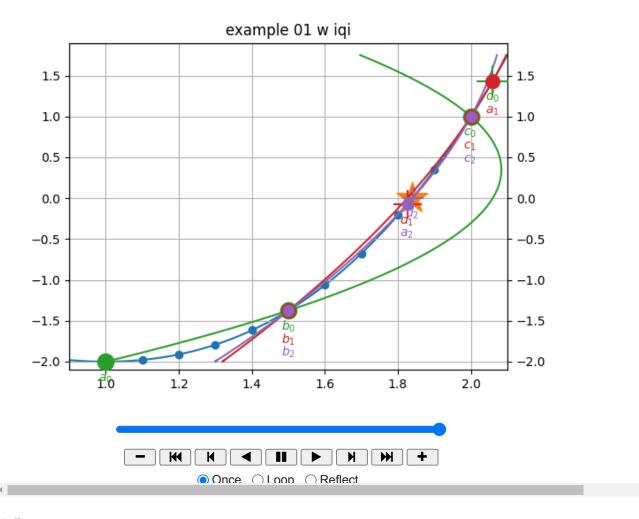
```
1 # a few reasons come to mind
3 import numpy as np
4 import statistics as st
6 def iqi(f,xs,max_iter=100,tol=1e-8,doyourworst=False,workspace=False):
1 if __name__ == "__main__":
root: [1.83928676]
    example 01 w iqi: x^3 - x^2 - x - 1
                                                                                       "/e[i-1]
                                     b l
                                                   c l
                                                          bwe (\Delta y)
                       a l
                                                                   0.83928676
      000 | 1.00000000
                           1.50000000
                                         2.00000000 | 0.50000000
      001
             2.05964912
                           1.50000000
                                         2.00000000
                                                        0.43554618
                                                                      0.22036237
                                                                                    0.26255909
      002 | 1.82546813
                           1.50000000
                                         2.00000000
                                                      | 1.07473271 | 0.01381863
                                                                                    0.06270865
      003 | 1.82546813 | 1.84037070 | 2.00000000 | 0.08066758 | 0.00108394 |
                                                                                    0.07844079
      004 | 1.82546813 | 1.84037070 | 1.83928426 | 0.00594852 | 0.00000250 |
                                                                                    0.00230327
```

005 | 1.83928676 | 1.84037070 | 1.83928426 | 0.00001366 | 0.00000000 |

006 | 1.83928676 | 1.83928676 | 1.83928426 | 0.00000000 | 0.00000000 | 0.00000497

0.00001790

```
1 ani
2
```



```
1 # briefly
3 if __name__ == "__main__":
5
    f = lambda x: pow(x,3) + x - 1
7
    if True:
      x = iqi(f,[0.,0.5,1.])
8
9
      print(f"iqi, std: {x}\n")
10
      x = iqi(f,[0.,0.5,1.],doyourworst=True)
11
12
      print(f"iqi, bwe: {x}\n")
→ iqi, std: 0.6823278038280194
     iqi, bwe: 0.6823278038280194
```

2 brents method

this hybrid method uses concepts of secant method, its generalizations and bisection. it expands dekkers method which uses secant backed up by bisection.

for continuous function f over bounded interval [a,b] where $f(a)\cdot f(b)<0$, brents method keeps track of current x_i that is best in sense of backward error and bracket $[a_i,b_i]$ of root, roughly speaking brents uses IQI to replace one of x_i,a_i,b_i if (1) the backward error improves and (2) the bracketing interval is cut at least in half, if that fails, the secant method is attempted, if that fails, bisection occurs which guarantees that uncertainty is lat least halved.


```
1 # https://blogs.mathworks.com/cleve/2015/10/12/zeroin-part-1-dekkers-algorithm/
2
3 import numpy as np
4 import scipy as sp
5
6 def dekker(f,a,b,display=0):
7
8  fa = f(a)
9  fb = f(b)
10  if fa*fb > 0:
11  raise Exception("interval does not bracket root.")
12
13  print(f"{1:5.0f} initial {a:19.15f} {fa:23.15e}")
14  print(f"{2:5.0f} initial {b:19.15f} {fb:23.15e}")
15  k = 2
16  c = a; fc = fa
```

Show hidden output

code, brent

code, brent @scipy

```
1 import scipy as sp
2
3 f = lambda x: pow(x,3) - pow(x,2) - x - 1
4 ab = (0.,2.)
5
6 root,soln = sp.optimize.brentq(f,ab[0],ab[1],full_output=True)
7 print(f"root: {root}\n")
8 print(soln)
9 #print(soln.method) # sigh = n/a
10
```

→ root: 1.8392867552141612

 ${\tt converged:}\ {\tt True}$

flag: converged

function_calls: 10
 iterations: 9

root: 1.8392867552141612

- oscar veliz <u>@youtube</u> (multiple methods including brents method)
- brents method
- richard brent
- theodorus dekker with a bonus
- library function documentation <u>@scipy @matlab</u>
- matlab <u>@online</u>