```
#include <mathstronauts arduino library.h>
int trig =8;
int echo =9;
void setup() {
  // put your setup code here, to run once:
 pinMode(trig, OUTPUT);
 pinMode(echo, INPUT);
 Serial.begin(9600);
}
void loop() {
  //1. Read distance from ultrasonic
  float distance = ultrasonicDistance(trig, echo);
  //2. Print distance
  Serial.println(distance);
 delay(100);
}
```