Report Generated by Test Manager

Title: Test

Author:

Date: 07-Jun-2024 08:09:38

Test Environment

Platform: PCWIN64 MATLAB: (R2024a)

Summary

Name	Outcome	Duration (Seconds)
Results: 2024-Jun-07 08:08:51	2 🗷	45.547
OperatingModeAndErrorLogic_TestFile	②	0.83
RequirementsVerification	Ø	0.831
■ <u>TestCorrectOutputForEachState</u>	Ø	0.83
BaselineAndEquivalence TestFile	Ø	16.564
Functional Scenario Equivalence	Ø	16.565
■ IntroductionScenario	⊘	16.564

Results: 2024-Jun-07 08:08:51

Result Type: Result Set Parent: None

Start Time: 07-Jun-2024 08:08:52 End Time: 07-Jun-2024 08:09:38 Outcome: Total: 2, Passed: 2

Back to Report Summary

OperatingModeAndErrorLogic_TestFile

Test Result Information

Result Type: Test File Result

Parent: Results: 2024-Jun-07 08:08:51

Start Time: 07-Jun-2024 08:08:52 End Time: 07-Jun-2024 08:08:53 Outcome: Total: 1, Passed: 1

Test Suite Information

Name: OperatingModeAndErrorLogic_TestFile

Back to Report Summary

RequirementsVerification

Test Result Information

Result Type: Test Suite Result

Parent: OperatingModeAndErrorLogic_TestFile

Start Time: 07-Jun-2024 08:08:52 End Time: 07-Jun-2024 08:08:53 Outcome: Total: 1, Passed: 1

Test Suite Information

Name: RequirementsVerification

Back to Report Summary

Test Correct Output For Each State

Test Result Information

Result Type: Test Case Result

Parent: <u>RequirementsVerification</u>

Start Time: 07-Jun-2024 08:08:52 End Time: 07-Jun-2024 08:08:53

Outcome: Passed

Test Case Information

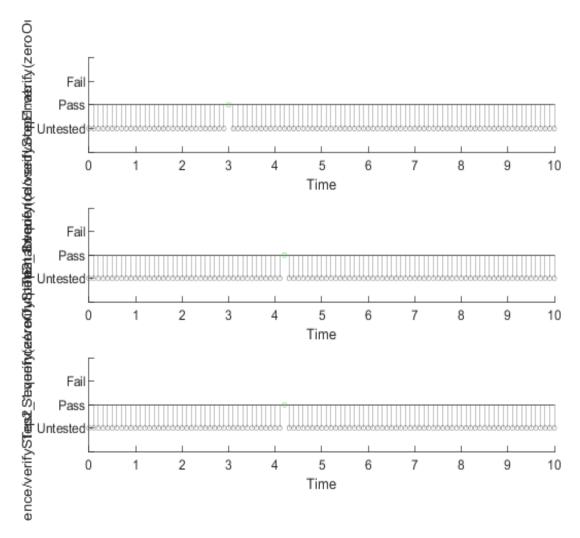
Name: TestCorrectOutputForEachState

Type: Baseline Test

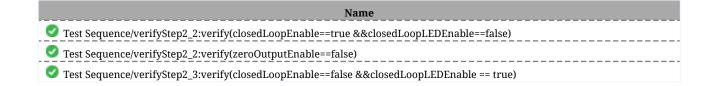
Verify Result

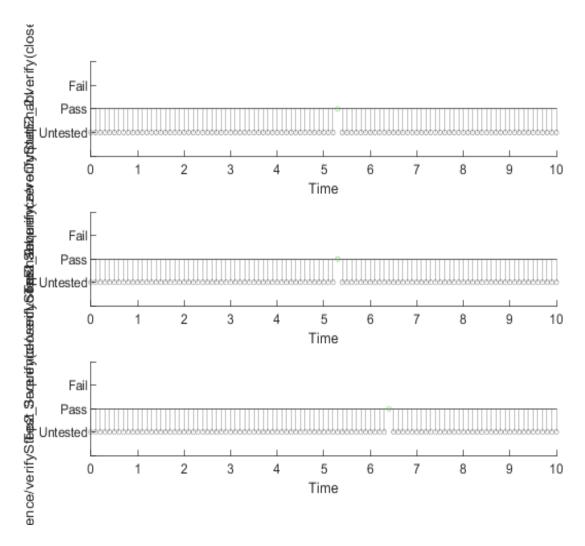
Name	Link to Plo
Test Sequence/verifyStep1:verify(zeroOutputEnable ==true)	<u>Link</u>
Test Sequence/verifyStep2_1:verify((closedLoopEnable && closedLoopLEDEnable) == false)	Link
Test Sequence/verifyStep2_1:verify(zeroOutputEnable==false)	Link
Test Sequence/verifyStep2_2:verify(closedLoopEnable==true &&closedLoopLEDEnable==false)	<u>Link</u>
Test Sequence/verifyStep2_2:verify(zeroOutputEnable==false)	<u>Link</u>
Test Sequence/verifyStep2_3:verify(closedLoopEnable==false &&closedLoopLEDEnable == true)	Link
Test Sequence/verifyStep2_3:verify(zeroOutputEnable==false)	Link
Test Sequence/verifyStep2_4:verify(closedLoopEnable&&closedLoopLEDEnable == true)	Link
Test Sequence/verifyStep2_4:verify(zeroOutputEnable==false)	Link
Test Sequence/verifyStep3:verify(zeroOutputEnable==true)	Link

Name
Test Sequence/verifyStep1:verify(zeroOutputEnable ==true)
Test Sequence/verifyStep2_1:verify((closedLoopEnable && closedLoopLEDEnable) == false)
Test Sequence/verifyStep2_1:verify(zeroOutputEnable==false)

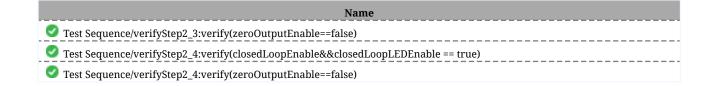


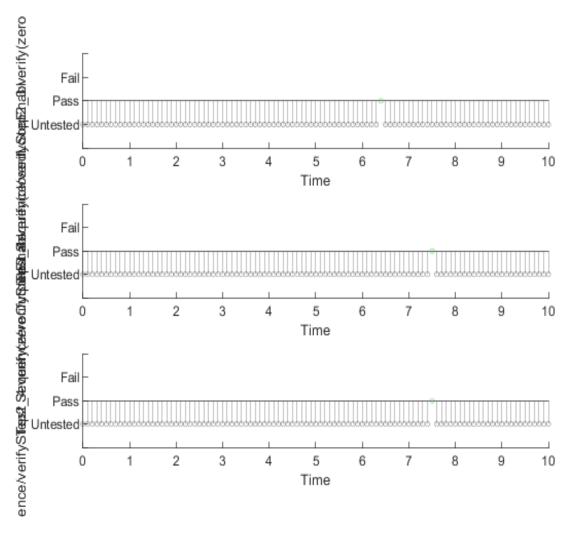
Back to Report SummaryBack to Signal Summary





Back to Report SummaryBack to Signal Summary





Back to Report SummaryBack to Signal Summary

Simulation

System Under Test Information

Model: OperatingModeAndErrorLogic

Harness: OperatingModeAndErrorLogic_RequirementsVer

ification

Harness Owner: OperatingModeAndErrorLogic

Release: Current

Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: Configuration1

Start Time: 0 Stop Time: 10

Checksum: 3071334955 2781418243 3584531251 3722619504

Test Logs:

No baseline criteria evaluation performed as no baseline data is available for this test.

Back to Report Summary

BaselineAndEquivalence_TestFile

Test Result Information

Result Type: Test File Result

Parent: Results: 2024-Jun-07 08:08:51

Start Time: 07-Jun-2024 08:09:20 End Time: 07-Jun-2024 08:09:36 Outcome: Total: 1, Passed: 1

Test Suite Information

Name: BaselineAndEquivalence_TestFile

Back to Report Summary

Functional Scenario Equivalence

Test Result Information

Result Type: Test Suite Result

Parent: BaselineAndEquivalence_TestFile

Start Time: 07-Jun-2024 08:09:20

End Time: 07-Jun-2024 08:09:36 Outcome: Total: 1, Passed: 1

Description:

This test suite will go through various functional scenario, and compared them to the saved results from 2024a. This series of tests is only used to verify possible regressions cross releases, model configuration changes and impact on results from refactoring. No requirements are validated.

Test Suite Information

Name: Functional Scenario Equivalence

Back to Report Summary

IntroductionScenario

Test Result Information

Result Type: Test Case Result

Parent: <u>Functional Scenario Equivalence</u>

Start Time: 07-Jun-2024 08:09:20 End Time: 07-Jun-2024 08:09:36

Outcome: Passed

Description:

This a regression test using the "introduction scenario" which is the deafult scenario when opening the project and model.

Test Case Information

Name: IntroductionScenario

Type: Baseline Test

Baseline Name: Baseline_IntroductionScenario.mat

Baseline File: C:\VersionControl\Git\MBD_for_SEPIC\Data\Scena

rioAndBaseline\Baseline_IntroductionScenario.m

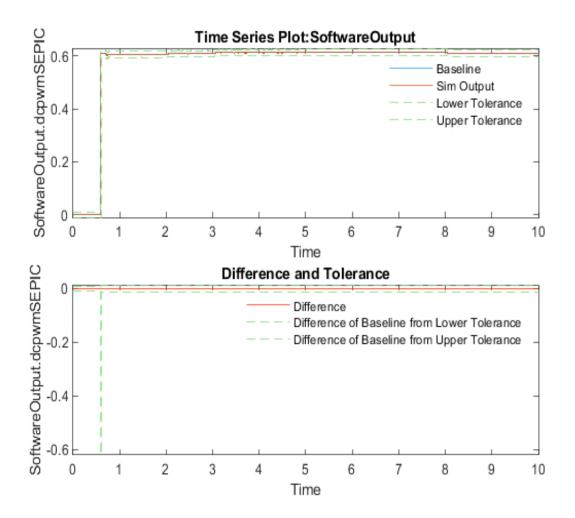
at

Baseline Comparison

	Abs T				Ma		Uni	Sampl		IIni	Sample Ti			Link to Plo
Name	ol	Rel Tol	Lead Tol	Lag Tol		Data Type 1	ts 1	e Tim	Data Type 2	ts 2	me 2	Interp	Sync	t t
Software					ff			e 1				!		
Output.dcpw	0.01	0.02	0.0001	0.0001	0	single	1	0.001	। । single	1 1	0.001	zoh	ı union	<u>Link</u>
mSEPIC	 	 	 	 	 	 	 	 	 	 		 	 	
Software	 			 								i !	 	
Output.dcpw	0.01	0.02	0.0001	0.0001	0	single	1		single	1	0.001	i L zoh	i union	Link
mLEDvector(į		
Sensors.v														
oltSEPIC	0.05	0.02	0.0001	0.0001	0	single		0.0005	single		0.0005	zoh	union !	<u>Link</u>
Sensors.c	10	0.00	0.0001	0.0001		_:		0.0005			0.0005	+ !		T :1-
urrSEPIC	10 	0.02 	0.0001	0.0001 	U 	single	 - 	0.0005	single		0.0005	zon 	union	<u>Link</u>
Sensors.c	I I I	 	 	 				 		 		 	 	
urrLEDstrips(5 !	0.02	0.0001	0.0001	0	single			single		0.0005	i zoh	union	<u>Link</u>
2) Sensors.v	 -			+					 			<u>-</u>	 	
oltPSU	0.05	0.02	0.0001	0.0001	0	single		0.0005	single		0.0005	zoh	union	<u>Link</u>
Software	 !			 				 	 	+		+ !	 	
Output.dcpw	0.01	0.02	0.0001	 0 0001	0	single	1	 	single	! ! ! 1 !	0.001	l l zoh	union	Link
mLEDvector(0.01 	0.02 	0.0001 	0.0001 			* -	 	l I		0.001	ZOII 	l 	LIIIK
2)	¦			! 			 -	 	 	 		ļ	 	
Software	i I			!								į !		
Output.dcpw mLEDvector(0.01	0.02	0.0001	0.0001	0	single	1		single	1	0.001	zoh	union	<u>Link</u>
3)	!			! !										
Software								 	 			+ !		
Output.dcpw	0.01	0.02	0.0001	 0 0001	. 0	single	1	 	single	! ! 1 !	0.001	l l zoh	union	Link
mLEDvector(0.01 	0.02 	0.0001 	0.0001 			1	 	l I	1 	0.001	ZOII 	l I	<u>EHIK</u>
4)	 	 	 -	 	 	 	! -	 -	 	 		! +	 	
Software Output.dcpw	 	 	 	 				 	 			 	 	
mLEDvector(0.01	0.02	0.0001	0.0001	0	single	1		single	1	0.001	zoh	union	<u>Link</u>
5)	i !			i !								į		
Software	. 0.01	. 0.02	0.0001	 0.0001	0	cingle	1		cingle		0.001	 zob	l I	Liple
Output.dcpw	0.01	0.02	0.0001	10.0001 	U	single	1		single	1	0.001	i zon !	union	<u>Link</u>

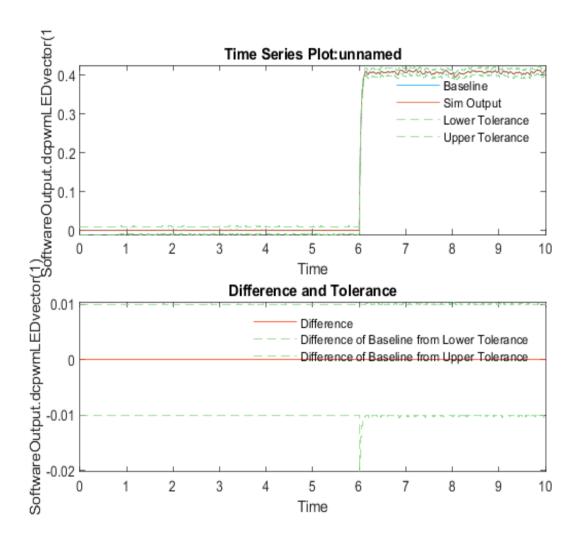
mLEDvector(į				
Sensors.c			 	 				 				 		
urrLEDstrips(5	0.02	0.0001	0.0001	0	single			single	į	0.0005	zoh	union	<u>Link</u>
Sensors.c			 									 		
urrLEDstrips(5	0.02	0.0001	0.0001	0	single			single	i	0.0005	zoh	union	<u>Link</u>
Sensors.c				+ ! !				 					 +	
urrLEDstrips(5	0.02	0.0001	0.0001	0	single			single	i	0.0005	zoh	union	<u>Link</u>
Sensors.c		 	 	+ 				 		 - -		 	++	
urrLEDstrips(5	0.02	0.0001	0.0001	0	single			single	i	0.0005	zoh	union	<u>Link</u>
Sensors.c			 	+			 			i			 	
urrLEDstrips(5	0.02	0.0001	0.0001	0	single			single		0.0005	zoh	union	<u>Link</u>
6)				!!!						- 1			: :	

Name	Abs Tol	Rel Tol	Lead Tol	Lag Tol	Max D iff	Data Type 1	Units 1	Sample Ti me 1	Data Type 2	Units 2	Sample Ti me 2	Interp	Sync
Software		i I											
Output.dcpw	0.01	0.02	0.0001	0.0001	0	single	1	0.001	single	1	0.001	ı zoh ı	union
mSEPIC			i I			l	į			į		į į	



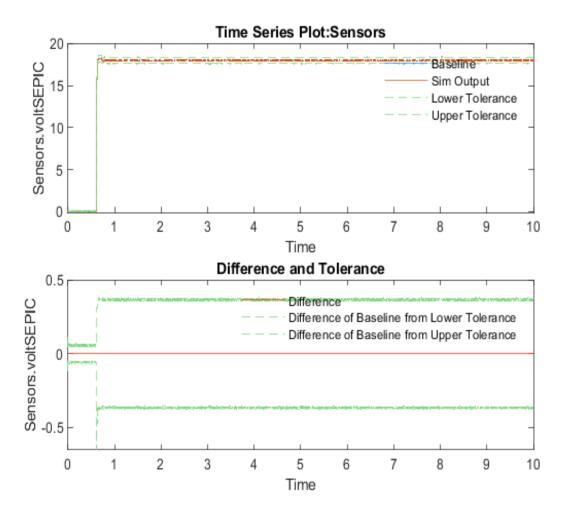
Back to Report SummaryBack to Criteria Results

Name	Ahs Tol	Rel Tol	Lead Tol	Lag Tol	Max D	Data Type	Units	Sample T	Data Type	Units	Sample Tim	Interp	Sync
Turne	1100 101		Lead 101	Lug 101	iff	1	1	ime 1	2	2	e 2	THE P	oyne.
Software		į	i !										
Output.dcpw	0.01	 0.02	0.0001	 0.0001		single	1		single	1	0.001	zoh	union
mLEDvector(0.01	1 0.02	0.0001 	0.0001 		Single	1 1			1	1 0.001	2011	ı
1)		 	 	 								 	



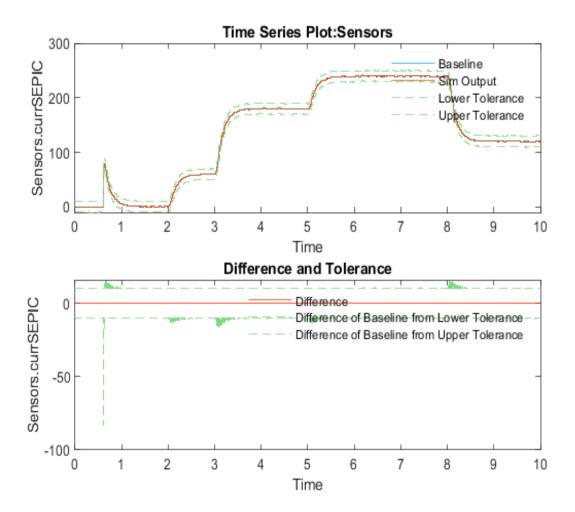
Back to Report SummaryBack to Criteria Results

Name	Abs Tol	Rel Tol	Lead Tol	Lag Tol	Max D iff	Data Type 1	Units 1	Sample Tim e 1	Data Type 2	Units 2	Sample Tim e 2	Interp Sync
Sensors.v	0.05	0.02	0.0001	0.0001	0	single		0.0005	single		0.0005	zoh union



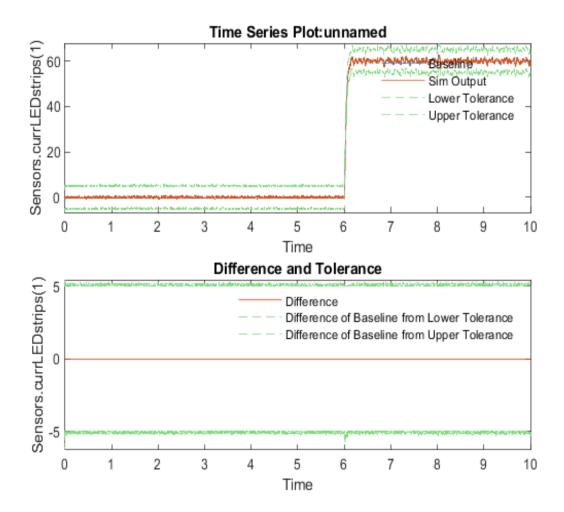
Back to Report SummaryBack to Criteria Results

Name	Abs T ol		Lead Tol	Lag Tol	Max D iff	Data Type 1	Units 1	Sample Tim e 1	Data Type 2	Units 2		Interp	Sync
Sensors.c urrSEPIC	10	0.02	0.0001	0.0001	0	single		0.0005	single		0.0005	zoh 1	union



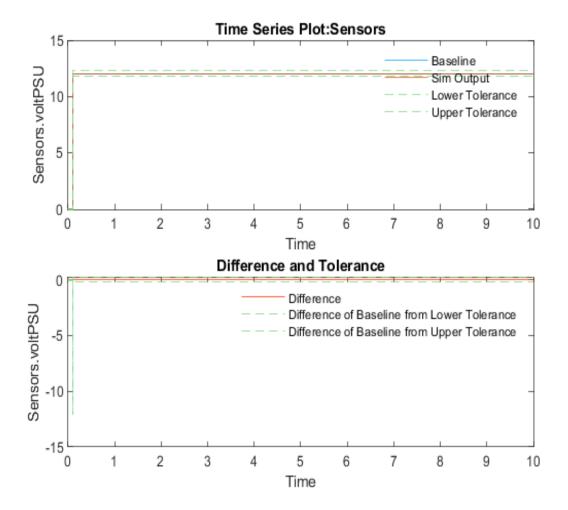
Back to Report SummaryBack to Criteria Results

Name	Abs T ol		Lead Tol	Lag Tol	Max Di ff	Data Type 1	Units 1	Sample T ime 1	Data Type 2	Units 2	Sample Time 2	Interp	Sync
Sensors.c		l I	l I		i I	l I	l I	i i	l I		l I	i i	
urrLEDstrips(5	0.02	0.0001	0.0001	0	single	 	 	single		0.0005	zoh i	ınion
1)						 					 		



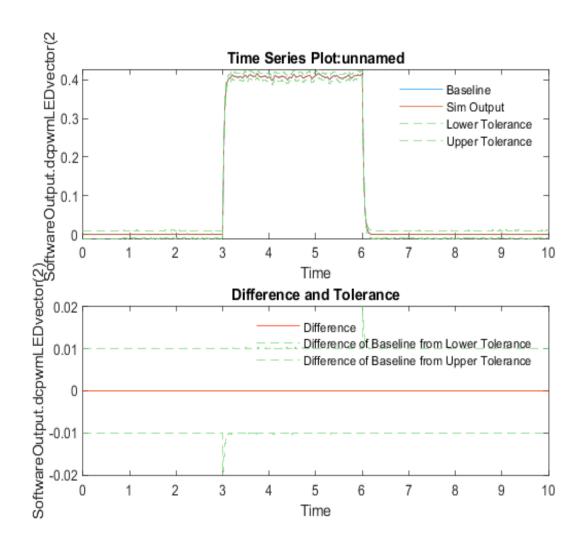
Back to Report SummaryBack to Criteria Results

Name	Abs Tol	Rel Tol	Lead Tol	Lag Tol	Max D iff	Data Type 1	Units 1	Sample Tim e 1	Data Type 2	Units 2		Interp	Sync
Sensors.v	0.05	0.02	0.0001	0.0001	0	single	i ! !	0.0005	single		0.0005	zoh i	union



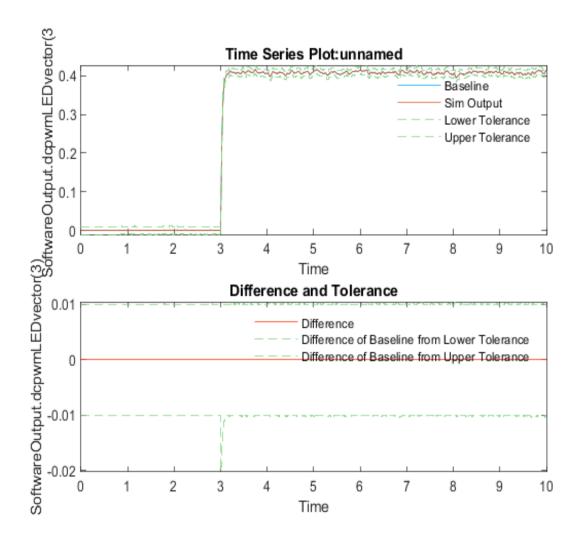
Back to Report SummaryBack to Criteria Results

Name	Abs Tol	Rel Tol	Lead Tol	Lag Tol	Max D	Data Type	Units	Sample T	Data Type	Units	Sample Tim	Interp	Sync
	120				iff	1	1	ime 1	2	2	e 2		0,110
Software													
Output.dcpw	0.01	 0.02	0.0001	 0 0001	0	single	1		single	1	0.001	: zoh	union
mLEDvector(0.01	0.02 	0.0001 	0.0001 		Siligic	1			1	0.001	l Zon	l
2)		 	 	 								I	



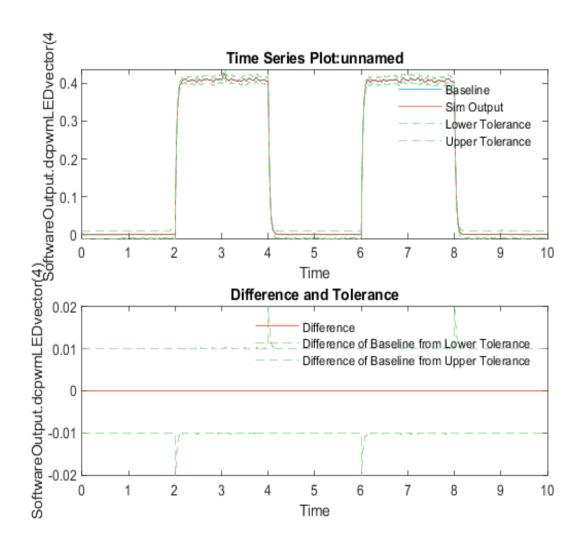
Back to Report SummaryBack to Criteria Results

Name	Abs Tol	Rel Tol	Lead Tol	Lag Tol	Max D iff	Data Type 1	Units 1	Sample T ime 1	Data Type 2	Units 2	Sample Tim e 2	Interp	Sync
Software			 								 		
Output.dcpw	0.01	0.02	0.0001	0.0001	0	single	1		single	1	0.001	zoh	union
mLEDvector(! 		
3)											! 		



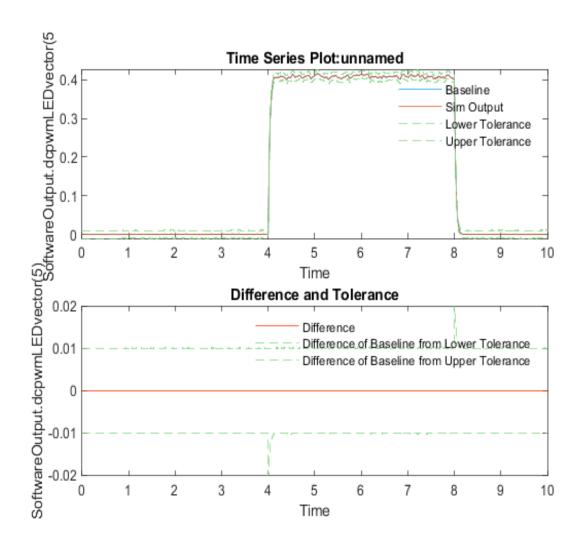
Back to Report SummaryBack to Criteria Results

Name	Abs Tol	Rel Tol	Lead Tol	Lag Tol	Max D iff	Data Type 1	Units 1	Sample T ime 1	Data Type 2	Units 2	Sample Tim e 2	Interp	Sync
Software			i i								i i		
Output.dcpw mLEDvector(0.01	0.02	i 0.0001	0.0001	0	single	1		single	1	0.001	zoh	union
i i				l							i I		
4)		!	!								l I		



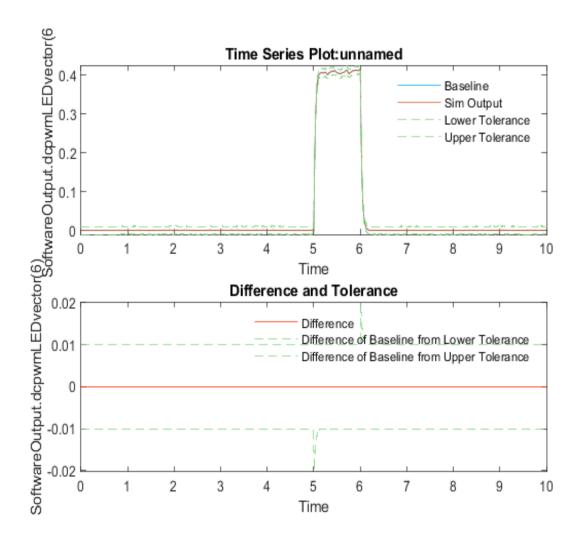
Back to Report SummaryBack to Criteria Results

Name	Abs Tol	Rel Tol	Lead Tol	Lag Tol	Max D iff	Data Type 1	Units 1	Sample T ime 1	Data Type 2	Units 2	Sample Tim e 2	Interp	Sync
Software											 	i i	i i
Output.dcpw	0.01	0.02	0.0001	0.0001	0	single	1		single	1	0.001	zoh	union
mLEDvector(! 		
5)		į			İ						! 		



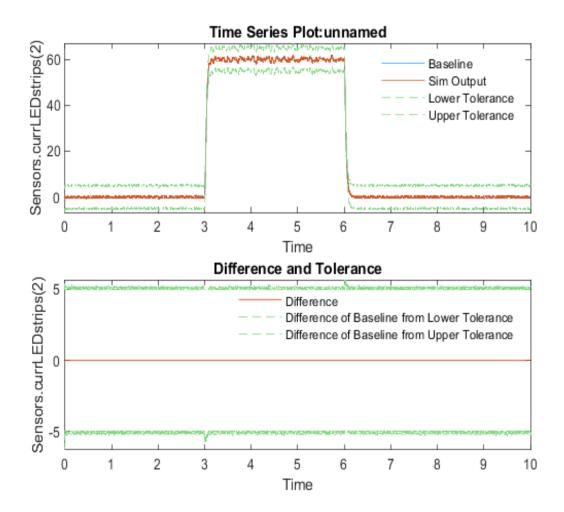
Back to Report SummaryBack to Criteria Results

Name	Abe Tol	Dol Tol	Lead Tol	I ag Tol	Max D	Data Type	Units	Sample T	Data Type	Units	Sample Tim	Interp	Syme
Name	ADS 101	Kei 101	Leau 101	Lag 101	iff	1	1	ime 1	2	2	e 2	milei p	Sync
Software											i I		
Output.dcpw	0.01	 	0.0001	 	0	single	1		single	1		: ! zoh !	union
mLEDvector(0.01 	0.02 	0.0001 	0.0001 	0	Siligie	1		single	1	0.001 	ZOII	l I
6)] 	



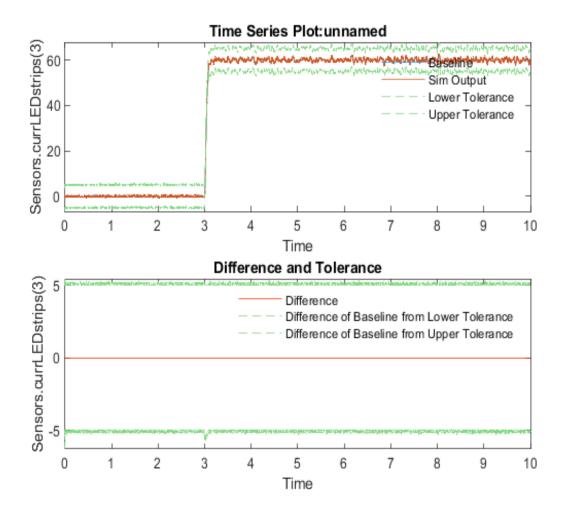
Back to Report SummaryBack to Criteria Results

Name	Abs T ol		Lead Tol	Lag Tol	Max Di ff	Data Type 1	Units 1	Sample T ime 1	Data Type 2	Units 2	Sample Time 2	Interp	Sync
Sensors.c		l I	l I		i I	l I	l I	i i			l I		
urrLEDstrips(5	0.02	0.0001	0.0001	0	single	 	 	single		0.0005	zoh i	union
2)		İ					İ				 		



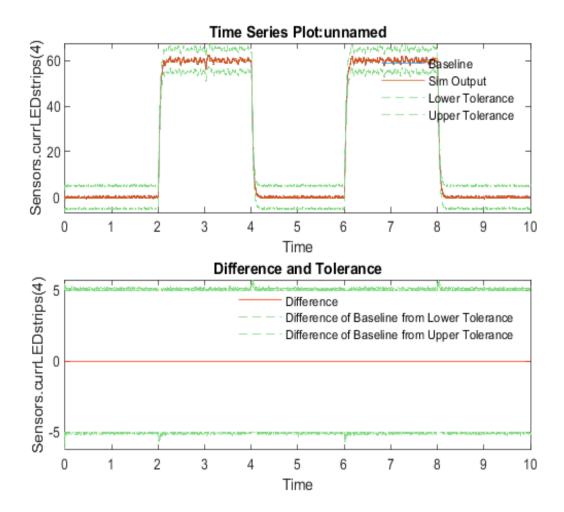
Back to Report SummaryBack to Criteria Results

Name	Abs T ol		Lead Tol	Lag Tol	Max Di ff	Data Type 1	Units 1	Sample T ime 1	Data Type 2	Units 2	Sample Time 2	Interp	Sync
Sensors.c		l I	l I		i I	l I	l I	i i			1		
urrLEDstrips(5	0.02	0.0001	0.0001	0	single	 	 	single		0.0005	ı zoh ı	union
3)						 							



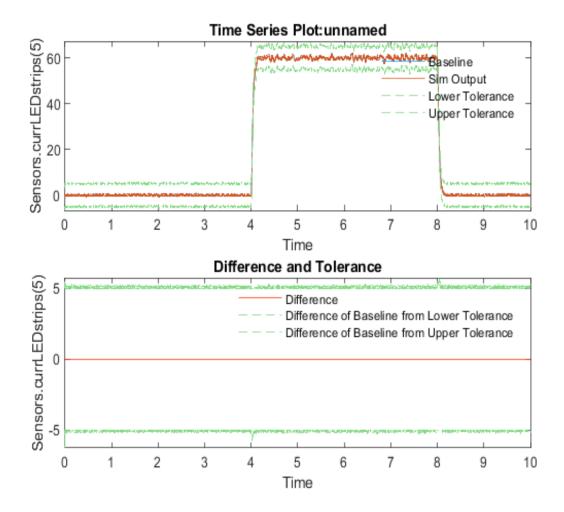
Back to Report SummaryBack to Criteria Results

Name	Abs T ol		Lead Tol	Lag Tol	Max Di ff	Data Type 1	Units 1	Sample T ime 1	Data Type 2	Units 2	Sample Time 2	Interp	Sync
Sensors.c		l I	l I		i I	l I	l I	i i			l I		
urrLEDstrips(5	0.02	0.0001	0.0001	0	single	 	 	single		0.0005	zoh i	union
4)		İ					İ				 		



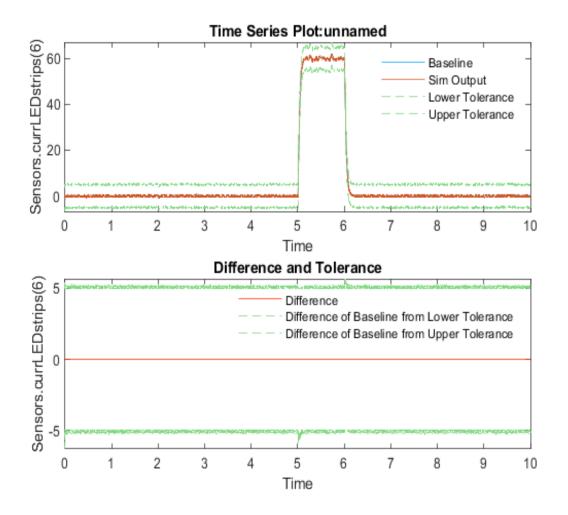
Back to Report SummaryBack to Criteria Results

Name	Abs T ol		Lead Tol	Lag Tol	Max Di ff	Data Type 1	Units 1	Sample T ime 1	Data Type 2	Units 2	Sample Time 2	Interp	Sync
Sensors.c					i I		l I	i I			l	l	
urrLEDstrips(5	0.02	0.0001	0.0001	0	single	 	! !	single		0.0005	zoh	union
5)					! !		 	 			1	 	



Back to Report SummaryBack to Criteria Results

Name	Abs T ol		Lead Tol	Lag Tol	Max Di ff	Data Type 1	Units 1	Sample T ime 1	Data Type 2	Units 2	Sample Time 2	Interp	Sync
Sensors.c		l	l I				l	i i			l I	l	
urrLEDstrips(5	0.02	0.0001	0.0001	0	single		 	single		0.0005	zoh	union
6)													



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Baseline_IntroductionScenario.mat

Baseline Information

Baseline Name: Baseline_IntroductionScenario.mat

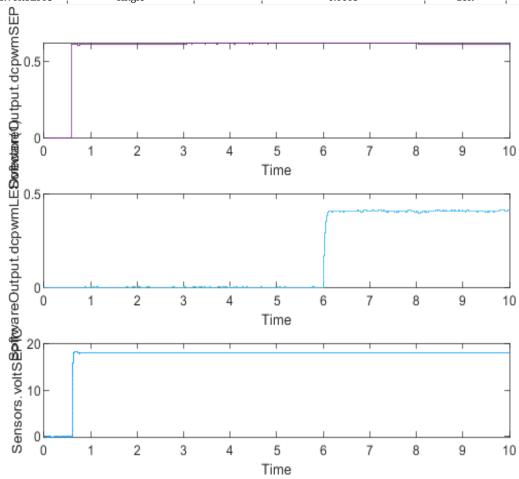
Baseline File: C:\VersionControl\Git\MBD_for_SEPIC\Data\Scena

 $rio And Baseline \backslash Baseline_Introduction Scenario.m$

at

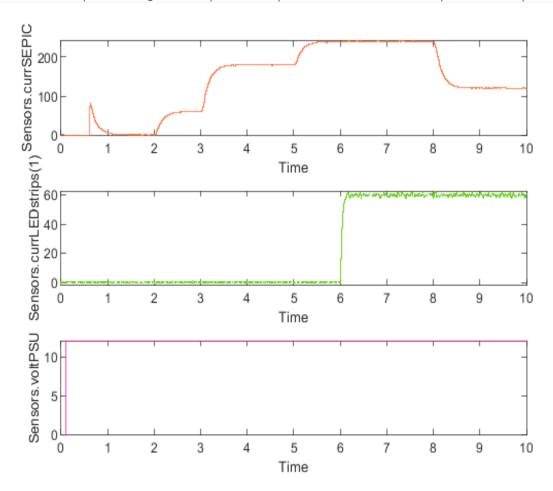
Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plo t
SoftwareOutput.dcp wmSEPIC	single	1	0.001	zoh	union	<u>Link</u>
SoftwareOutput.dcp wmLEDvector(1)	single	1		zoh	union	Link
Sensors.voltSEPIC	single	i i ·+	0.0005	zoh	union	Link
Sensors.currSEPIC	single	i i ·+	0.0005	zoh	union	Link
Sensors.currLEDstri ps(1)	single			zoh	union	Link
Sensors.voltPSU	single	i i	0.0005	zoh	union	Link
SoftwareOutput.dcp wmLEDvector(2)	single	1		zoh	union	<u>Link</u>
SoftwareOutput.dcp wmLEDvector(3)	single	1		zoh	union	<u>Link</u>
SoftwareOutput.dcp wmLEDvector(4)	single	1		zoh	union	Link
SoftwareOutput.dcp wmLEDvector(5)	single	1		zoh	union	<u>Link</u>
SoftwareOutput.dcp wmLEDvector(6)	single	1		zoh	union	Link
Sensors.currLEDstri	single			zoh	union	<u>Link</u>
Sensors.currLEDstri	single			zoh	union	Link
Sensors.currLEDstri ps(4)	single			zoh	union	<u>Link</u>
Sensors.currLEDstri	single			zoh	union	Link
Sensors.currLEDstri	single			zoh	union	Link

Name	Data Type	Units	Sample Time	Interp	Sync
SoftwareOutput.dcp wmSEPIC	single	1	0.001	zoh	union
SoftwareOutput.dcp wmLEDvector(1)	single	1		zoh	union
Sensors.voltSEPIC	single		0.0005	zoh	union



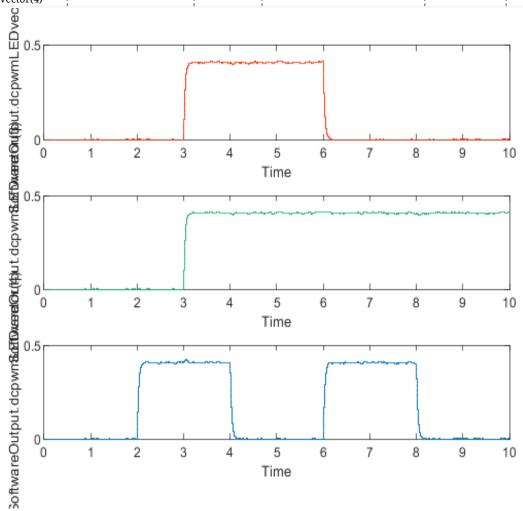
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Name	Data Type	Units	Sample Time	Interp	Sync
Sensors.currSEPIC	single	 	0.0005	zoh	union
Sensors.currLEDstri ps(1)	single	i I I		zoh	union
Sensors.voltPSU	single	 	0.0005	zoh	union



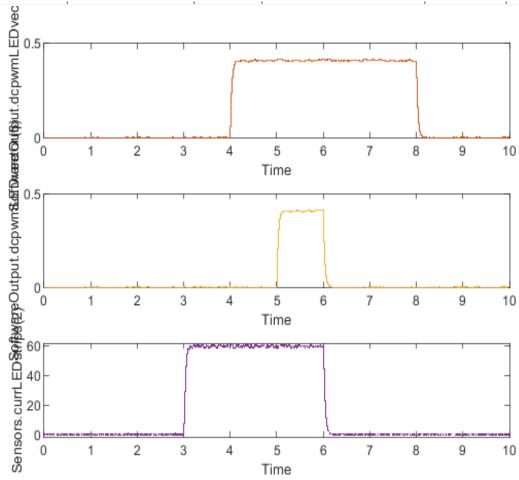
Back to Report SummaryBack to Signal Summary

Name	Data Type	Units	Sample Time	Interp	Sync
SoftwareOutput.dcp	aingla	1		zoh	i union
wmLEDvector(2)	single	1	 	ZOII 	U111011
SoftwareOutput.dcp	. ,	4		,	i i .
wmLEDvector(3)	single	1	 	zoh	union
SoftwareOutput.dcp	. ,	4		,	
wmLEDvector(4)	single	1 1		zoh	ı union



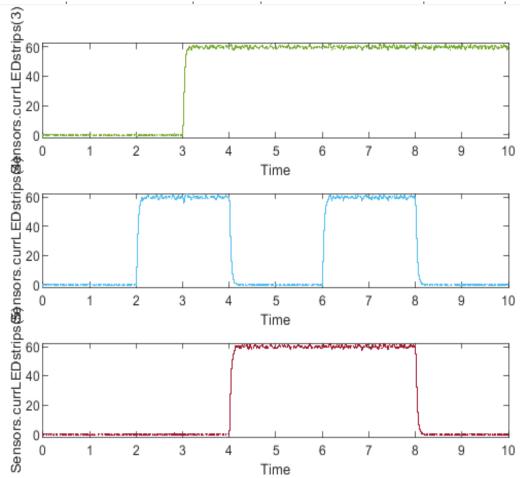
Back to Report SummaryBack to Signal Summary

Name	Data Type	Units	Sample Time	Interp	Sync
SoftwareOutput.dcp	single	1		zoh	union
wmLEDvector(5)	single	1 I		ZOII 	L
SoftwareOutput.dcp		4		,	
wmLEDvector(6)	single) 1 		zoh	union
Sensors.currLEDstri	. ,			,	
ps(2)	single			zoh	union



Back to Report SummaryBack to Signal Summary

Name	Data Type	Units	Sample Time	Interp	Sync
Sensors.currLEDstri ps(3)	single	i I I		zoh	union
Sensors.currLEDstri ps(4)	single	 		zoh	union
Sensors.currLEDstri	single			zoh	union



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Simulation

System Under Test Information

Model: DCDC_SEPIC_TopLevelModel

Release: Current Simulation Mode: normal

Override SIL or PIL Mode: 0

Configuration Set: ConfigSet_ode23t_TopLevel

External Input Name: TopLevel_IntroductionScenario.mat

External Input File: C:\VersionControl\Git\MBD_for_SEPIC\Data\Scena

 $rio And Baseline \verb|\TopLevel_IntroductionScenario.|$

mat

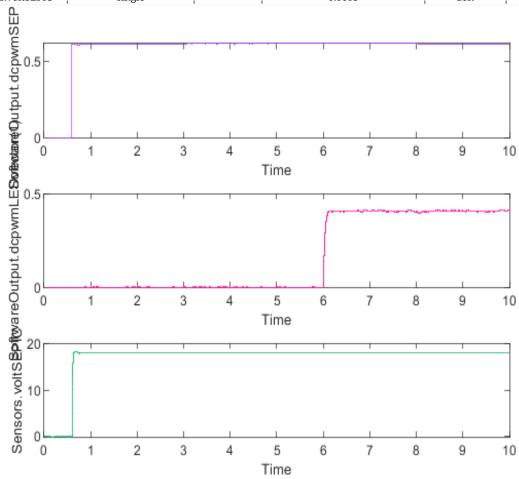
Start Time: 0 Stop Time: 10

Checksum: 2693543987 4179266261 3017007837 1814957089

Simulation Output

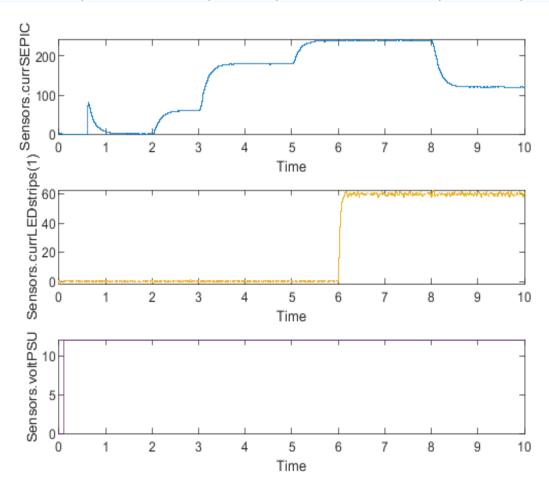
Name	Data Type	Units	Sample Time	Interp	Sync	Link to Plo t
SoftwareOutput.dcp wmSEPIC	single	1	0.001	zoh	union	<u>Link</u>
SoftwareOutput.dcp wmLEDvector(1)	single	1	0.001	zoh	union	<u>Link</u>
Sensors.voltSEPIC	single	i +	0.0005	zoh	union	<u>Link</u>
Sensors.currSEPIC	single	i +	0.0005	zoh	union	<u>Link</u>
Sensors.currLEDstri ps(1)	single		0.0005	zoh	union	<u>Link</u>
Sensors.voltPSU	single	i +	0.0005	zoh	union	<u>Link</u>
SoftwareOutput.dcp wmLEDvector(2)	single	1	0.001	zoh	union	<u>Link</u>
SoftwareOutput.dcp wmLEDvector(3)	single	1	0.001	zoh	union	<u>Link</u>
SoftwareOutput.dcp wmLEDvector(4)	single	1	0.001	zoh	union	<u>Link</u>
SoftwareOutput.dcp wmLEDvector(5)	single	1	0.001	zoh	union	<u>Link</u>
SoftwareOutput.dcp wmLEDvector(6)	single	1	0.001	zoh	union	<u>Link</u>
Sensors.currLEDstri	single		0.0005	zoh	union	<u>Link</u>
Sensors.currLEDstri	single		0.0005	zoh	union	<u>Link</u>
Sensors.currLEDstri ps(4)	single		0.0005	zoh	union	<u>Link</u>
Sensors.currLEDstri ps(5)	single		0.0005	zoh	union	<u>Link</u>
Sensors.currLEDstri	single		0.0005	zoh	union	Link

Name	Data Type	Units	Sample Time	Interp	Sync
SoftwareOutput.dcp wmSEPIC	single	1	0.001	zoh	union
SoftwareOutput.dcp wmLEDvector(1)	single	1	0.001	zoh	union
Sensors.voltSEPIC	single		0.0005	zoh	union



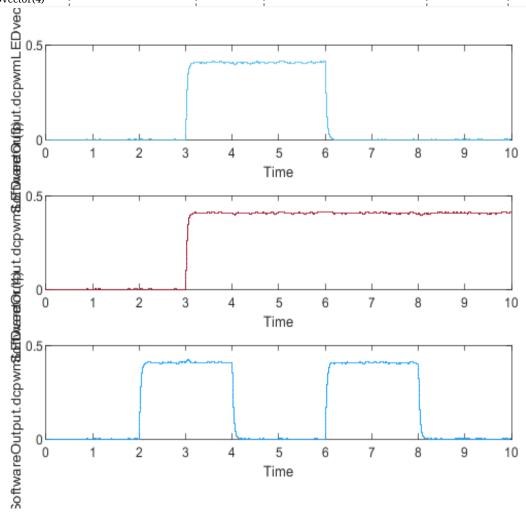
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Name	Data Type	Units	Sample Time	Interp	Sync
Sensors.currSEPIC	single	 	0.0005	zoh	union
Sensors.currLEDstri ps(1)	single		0.0005	zoh	union
Sensors.voltPSU	single		0.0005	zoh	union



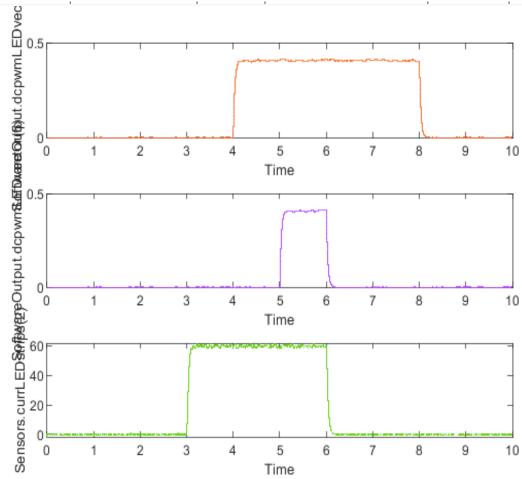
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Name	Data Type	Units	Sample Time	Interp	Sync
SoftwareOutput.dcp	single	1	0.001	zoh	union
wmLEDvector(2)	siligie		0.001	2011	umon
SoftwareOutput.dcp		4	0.004	,	
wmLEDvector(3)	single	1	0.001	zoh	union
SoftwareOutput.dcp	. ,		0.004	,	
wmLEDvector(4)	single	1	0.001	zoh	union



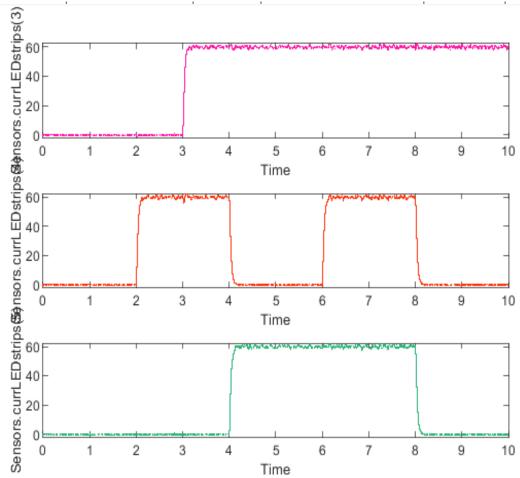
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Name	Data Type	Units	Sample Time	Interp	Sync
SoftwareOutput.dcp	single	1	0.001	zoh	union
wmLEDvector(5)	Single	·i	0.001 		
SoftwareOutput.dcp	single	1	0.001	zoh	union
wmLEDvector(6)	single	1	0.001	2011	union
Sensors.currLEDstri	. ,		0.0005	,	
ps(2)	single		0.0005	zoh	union



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Name	Data Type	Units	Sample Time	Interp	Sync
Sensors.currLEDstri ps(3)	single		0.0005	zoh	union
Sensors.currLEDstri ps(4)	single		0.0005	zoh	union
Sensors.currLEDstri	single		0.0005	zoh	union



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