

Ejercicio 16 ★

Escribir la secuencia de instrucciones resultantes de compilar los siguientes términos con el compilador de Cálculo Lambda a la máquina SECD visto en la teórica, y escribir la traza de ejecución para cada una de dichas secuencias.

- I. $(\lambda x.x)$ True
- II. $(\lambda x.\lambda x.x)$ False True
- III. $(\lambda x.\lambda y.(\lambda x.\text{if } x \text{ then } y \text{ else } x) x)$ False True
- IV. $(\lambda x.(\lambda f.(\lambda y.f \text{ True}) \text{ False}) (\lambda y.\text{if } y \text{ then } x \text{ else } y))$ False

$$i) (\llbracket \cdot \rrbracket \{ (\lambda x.x) \text{True} \}) = (\llbracket \cdot \rrbracket \{ \lambda x.x \}; \llbracket \cdot \rrbracket \{ \text{True} \}; \Delta P = \text{MKCLO}(\llbracket \cdot \rrbracket \{ x \}; \text{ret}); \text{LDB}(\text{tt}); \Delta P = \text{MKCLO}(\text{LD}(\text{O}); \text{ret}); \text{LDB}(\text{TT}); \Delta P$$

esta separamos en código y da el entorno dummy

$$\text{MKCLO}(\text{LD}(\text{O}); \text{ret}); \text{LDB}(\text{TT}); \Delta P \mid \llbracket \cdot \rrbracket \mid \llbracket \cdot \rrbracket \mid \llbracket \cdot \rrbracket \rightarrow$$

$$\text{LDB}(\text{TT}); \Delta P \mid \langle \text{LD}(\text{O}); \text{ret}, \llbracket \cdot \rrbracket \rangle : \llbracket \cdot \rrbracket \mid \llbracket \cdot \rrbracket \mid \llbracket \cdot \rrbracket \rightarrow$$

$$\Delta P \mid \text{TT} : \langle \text{LD}(\text{O}); \text{ret}, \llbracket \cdot \rrbracket \rangle : \llbracket \cdot \rrbracket \mid \llbracket \cdot \rrbracket \mid \llbracket \cdot \rrbracket \rightarrow$$

$$\text{LD}(\text{O}); \text{ret} \mid \llbracket \cdot \rrbracket \mid \text{TT} : \llbracket \cdot \rrbracket \mid \langle \llbracket \cdot \rrbracket, \llbracket \cdot \rrbracket, \llbracket \cdot \rrbracket \rangle : \llbracket \cdot \rrbracket \rightarrow$$

$$\text{ret} \mid \text{TT} : \llbracket \cdot \rrbracket \mid \text{TT} : \llbracket \cdot \rrbracket \mid \langle \llbracket \cdot \rrbracket, \llbracket \cdot \rrbracket, \llbracket \cdot \rrbracket \rangle : \llbracket \cdot \rrbracket \rightarrow$$

$$\llbracket \cdot \rrbracket \mid \text{TT} : \llbracket \cdot \rrbracket \mid \llbracket \cdot \rrbracket \mid \langle \llbracket \cdot \rrbracket, \llbracket \cdot \rrbracket, \llbracket \cdot \rrbracket \rangle : \llbracket \cdot \rrbracket$$

$$ii) (\llbracket \cdot \rrbracket \{ (\lambda x.\lambda y.(\lambda x.\text{if } x \text{ then } y \text{ else } x) x) \text{False True} \})$$

$$= (\llbracket \cdot \rrbracket \{ (\lambda x.\lambda y.(\lambda x.\text{if } x \text{ then } y \text{ else } x) x) \text{False} \}; \llbracket \cdot \rrbracket \{ \text{True} \}; \Delta P$$

$$= (\llbracket \cdot \rrbracket \{ \lambda x.\lambda y.(\lambda x.\text{if } x \text{ then } y \text{ else } x) x \}; \llbracket \cdot \rrbracket \{ \text{False} \}; \Delta P; \llbracket \cdot \rrbracket \{ \text{True} \}; \Delta P;$$

$$= \text{MKCLO}(\llbracket \cdot \rrbracket \{ \lambda y.(\lambda x.\text{if } x \text{ then } y \text{ else } x) x \}; \text{ret}); \text{LDB}(\text{FF}); \Delta P; \text{LDB}(\text{tt}); \Delta P;$$

$$= \text{MKCLO}(\text{MKCLO}(\llbracket \cdot \rrbracket \{ (\lambda x.\text{if } x \text{ then } y \text{ else } x) x \}; \text{ret}); \text{ret}); \text{LDB}(\text{FF}); \Delta P; \text{LDB}(\text{TT}); \Delta P;$$

$$= \text{MKLO}(\text{MKCLO}(\llbracket \cdot \rrbracket \{ \lambda x.\text{if } x \text{ then } y \text{ else } x \}; \llbracket \cdot \rrbracket \{ x \}; \Delta P; \text{ret}); \text{ret}); \text{LDB}(\text{FF}); \Delta P; \text{LDB}(\text{TT}); \Delta P;$$

$$= \text{MKCLO}(\text{MKCLO}(\text{MKCLO}(\llbracket \cdot \rrbracket \{ \text{if } x \text{ then } y \text{ else } x \}; \text{ret}) \text{LD}(\tau); \Delta P; \text{ret}); \text{ret}); \text{LDB}(\text{FF}); \Delta P; \text{LDB}(\text{TT}); \Delta P;$$

$$= \text{MKCLO}(\text{MKCLO}(\text{MKCLO}(\text{LD}(\text{O})); \text{Test}(\text{LD}(\tau), \text{LD}(\text{O}))) \text{LD}(\tau); \Delta P; \text{ret}); \text{ret}); \text{LDB}(\text{FF}); \Delta P; \text{LDB}(\text{TT}); \Delta P;$$

5 veces haciendo la ejecución ΔP , da false.