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Initial Setup

Change your laptop's IP Address to match the drive, so they can communicate and the laptop can be used to configure the drive.

The Olympus Lexium MDrive LMDCE573 is shipped with a factory default IP Address as follows.

IP Address: 192.168.33.1Subnet Mask: 255.255.0.0

- 1. Connect 48 VDC power to the Lexium MDrive.
- 2. Connect Ethernet cable from your laptop to the Lexium MDrive.
- **3.** Change your laptop's LAN IP address to 192.168.33.220, and the subnet mask to 255.255.255.0 by doing the following:
 - a. Open Network and Sharing Center.
 - **b.** In the System Tray, right-click the network icon.



Figure PH018-12 - System Tray, Network Icon

Network Connections opens.

c. Click "Open Network and Sharing Center".



Figure PH018-13 - Network Connections

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Network and Sharing Center opens.

d. Click "Local Area Connection".

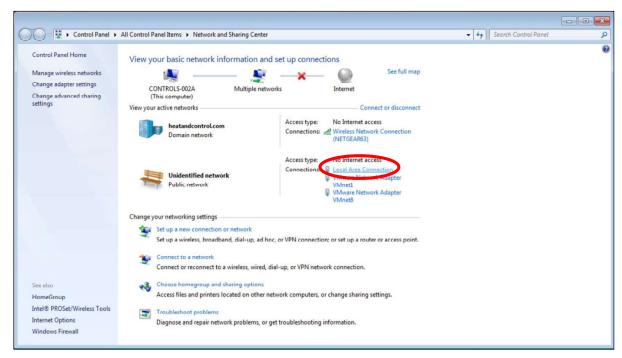


Figure PH018-14 - Network and Sharing Center

Local Area Connection Status opens.

e. Click "Properties".

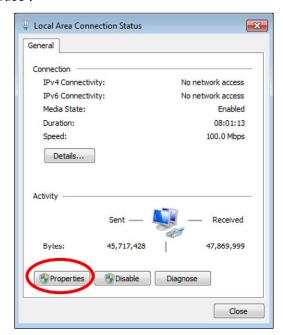


Figure PH018-15 - Local Area Connection Status

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The Local Area Connection Properties window opens.

Select "Internet Protocol Version 4 (TCP/IPv4)" and click "Properties".

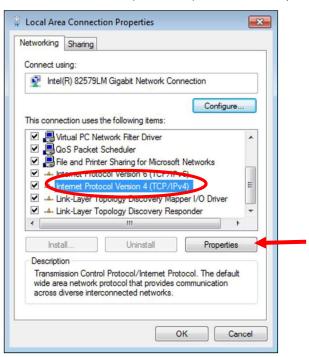


Figure PH018-16 - Local Area Connection Properties

The Internet Protocol Version 4 (TCP/IPv4) Properties window opens.

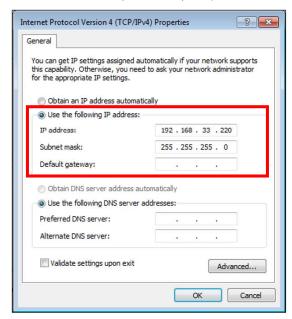


Figure PH018-17 - Change IP Address and Subnet Mask

g. Change the IP address to 192.168.33.220 and the subnet mask to 255.255.255.0. The window should look exactly like Figure PH018-17.

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- h. Click OK, twice, and then close the Local Area Network Status and the Network and Sharing Center.
- 4. On the desktop, double-click the Lexium MDrive Software Suite icon.



Figure PH018-18 - Lexium MDrive Software Suite Desktop Icon

5. When the program opens, click "Launch Lexium MDrive Ethernet Interface.

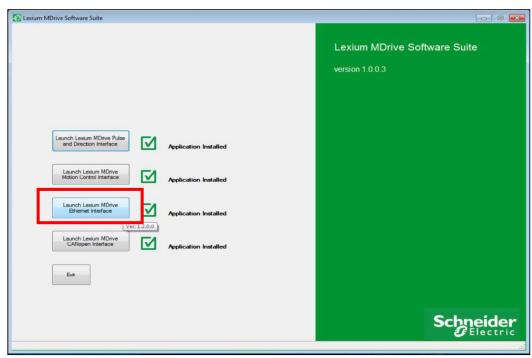


Figure PH0 18-19 - Lexium MDrive Software

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6. The Lexium MDrive Ethernet TCP/IP Configuration Utility opens.

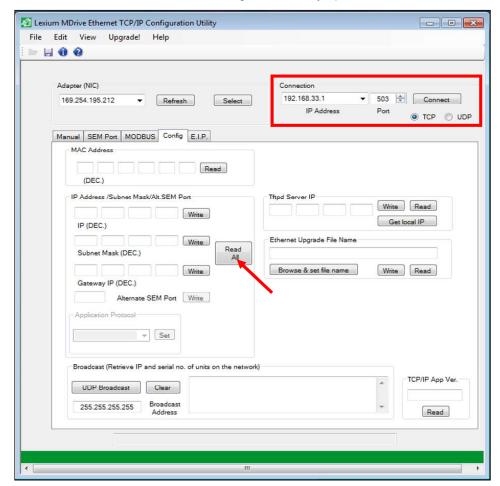


Figure PH018-20 - TCP/IP Configuration Utility

- 7. Make sure the Connection box shows 192.168.33.1 as the IP Address.
- 8. Click "Connect".
- 9. Select the Config tab.
- 10. Click "Read All".

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The window populates (see Figure PH018-21).

Note: Connection information is at the bottom of the screen.

- 11. Verify or change the IP address and/or subnet mask. They should be 192.168.33.1 for the IP address and 255.255.255.0 for the subnet mask.
- 12. Make sure the Application Protocol is EtherNet/IP.

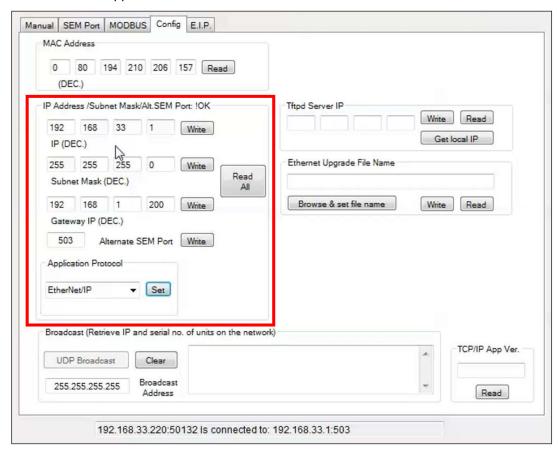


Figure PH018-21 - Config. Window

Make sure your screen looks exactly like Figure PH018-21.

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- 13. Select the E.I.P. tab.
- 14. Configure the input devices to look exactly like Figure PH018-22.

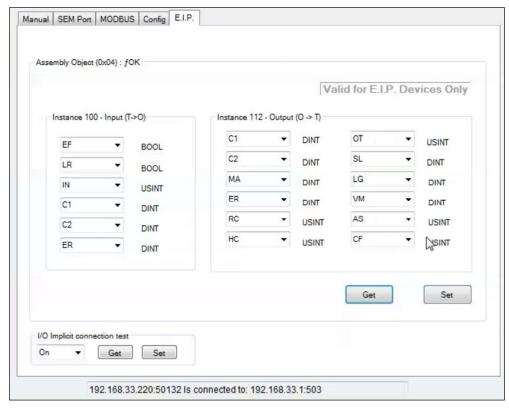


Figure PH018-22 - E.I.P Tab

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15. Select the SEM Port tab.

To read the Lexium MDrive status parameter type "PR" + "Parameter Name".

(i.e. PR A => parameter read acceleration setpoint.)

To set Acceleration = 1,000,000 type the following in the command line.

- o A = 1,000,000 <Enter>
- 16. Manually set the following parameters as listed below:

```
A = 1000000
                  <Enter>
                                 (Acceleration)
o D = 2000000
                  <Enter>
                                 (Deceleration)
o LD = 5000
                  <Enter>
                                 (Rotor Lead Limit)
  LG = 5000
                  <Enter>
                                 (Rotor Lag Limit)
o VM = 2000000 <Enter>
                                 (Maximum Velocity)
                                 (Hybrid Mode => Variable Current)
o AS = 2
                  <Enter>
o HC = 5
                                 (Hold Current)
                  <Enter>
   RC = 25
                  <Enter>
                                 (Run Current)
0
      S
                  <Enter>
                                 (To Save parameter setting to Non-Volatile
                                 Memory)
```

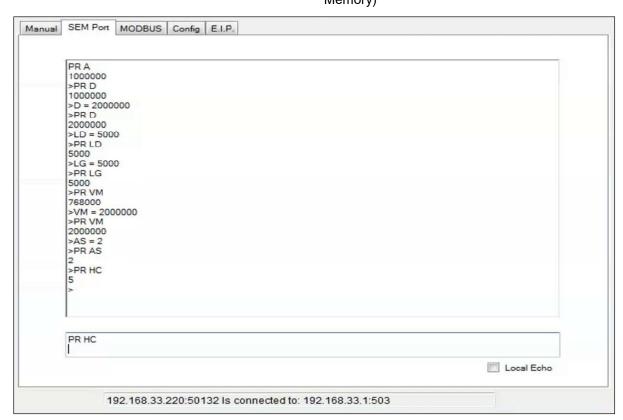


Figure PH018-23 - SEM Port Tab

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17. Test the Lexium MDrive.

To jog the Lexium MDrive for testing, type in "MR" + "Motor Counts".

(i.e. MR 500000 => Move Relative position 500000 motor counts)

To jog clockwise 500,000 counts type in the following.

MR = 500000 <Enter>

To jog counter-clockwise 500,000 counts type in the following.

MR = -500000 <Enter>

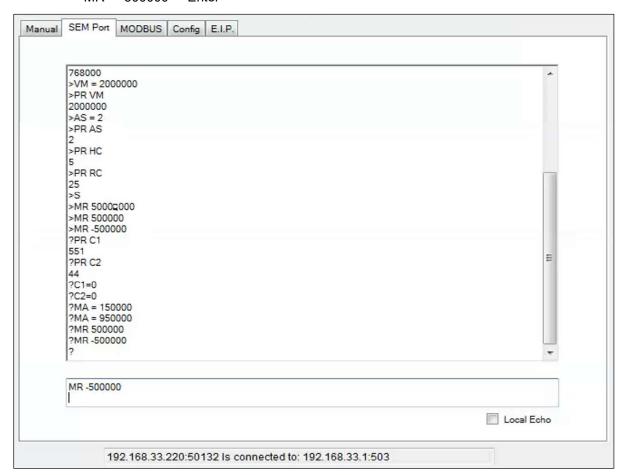


Figure PH018-24 – Testing

18. The Lexium MDrive is now ready for Ethernet control.

Troubleshooting

The following are the meanings of the indicator lights on the Motor and the Gateway.

Motor Indicator Lights

Status indicators

The Lexium MDrive has two LEDs for status indication.

- LED 1: Status of the power supply
- LED 2: Status indication. Indication functions programmed using the Lexium MDrive Pulse/direction Configuration Utility advanced mode. See Lexium MDrive Software Suite manual.

LED 1

Color	Status		
Off	No Power		
Green	Power supply in range		
Red	Power supply out of range		

LED 2

See the Pulse/direction Configuration Utility section of the Lexium MDrive Software Suite manual for available attention states.

Color	Status		
Off	Not configured		
Green	No attention state exists		
Red	Preset attention state exists		

Figure PH018-25 - Meaning of Motor Indicator LEDs

Location of LEDs on the Motor.

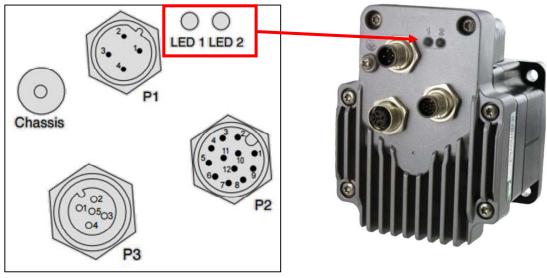


Figure PH018-26 - Motor LEDs

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Gateway Indicator Lights

EtherNet/IP		
NS (Network Sta	tus - LED 1)	7
Off	Mary and the	No power, no Ethernet connection
Red	Solid	Unrecoverable fault
Red	Flashing	Recoverable fault or IO connection timed out
Green	Solid	Normal runtime operation (I/O connection allocated)
	Flashing	Device is idle or not allocated to a client (PLC)
Red+Green	Alternating	Power-up self test in progress
MS (Module Stat	tus - LED 2)	
Off		No power
Ded	Solid	Unrecoverable fault
Red	Flashing	Minor, recoverable fault
Conon	Solid	I/O connection established
Green	Flashing	Standby, no I/O connection established
Red+Green	Alternating	Power-up self test in progress

Location of LEDs on the Gateway.

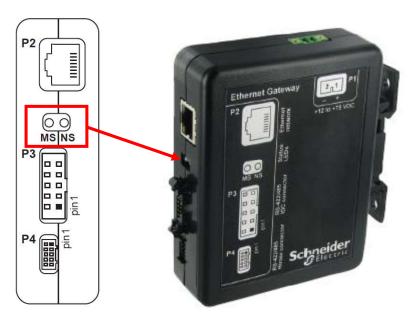


Figure PH018-27 - Gateway LEDs

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Revision Record

Revision Level	Date	Ву	Description
Rev 00	09/13/16	Devin Riley & Arlene Mason	Initial Release

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