

# Characterization of Logarithmic Fekete Critical Configurations of at Most Six Points in All Dimensions

ISSAC - Guanajuato, México - August 1, 2025

Diego Armentano, Leandro Bentancur, Federico Carrasco,  
Marcelo Fiori, **Matías Valdés**, and Mauricio Velasco



UNIVERSIDAD  
DE LA REPÚBLICA  
URUGUAY



# Outline

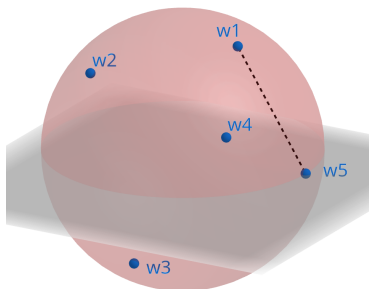
- 1 Introduction
- 2 Formulation of Critical Configurations
- 3 Five points
- 4 Six points
- 5 Conclusions and Future Work

# Fekete Problem

Position  $n$  points on the sphere  $S^d \subset \mathbb{R}^{d+1}$ , so as to maximize the product of the distances between pairs of points:

$$\prod_{1 \leq i < j \leq n} \|w_i - w_j\|,$$

$$w_i \in S^d \subset \mathbb{R}^{d+1}.$$

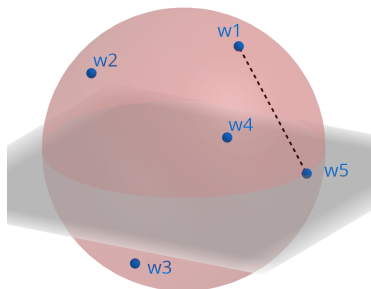


# Fekete Problem

Position  $n$  points on the sphere  $S^d \subset \mathbb{R}^{d+1}$ , so as to maximize the product of the distances between pairs of points:

$$\prod_{1 \leq i < j \leq n} \|w_i - w_j\|,$$

$$w_i \in S^d \subset \mathbb{R}^{d+1}.$$



Equivalently: place the points to minimize the logarithmic energy

$$E_{\log}(w) := - \sum_{1 \leq i < j \leq n} \log(\|w_i - w_j\|^2), \quad w_i \in S^d \subset \mathbb{R}^{d+1}.$$

# Why caring about this problem?

Fekete problem: minimize the logarithmic energy on  $S^d$ :

$$E_{\log}(w) := - \sum_{1 \leq i < j \leq n} \log(\|w_i - w_j\|^2), \quad w_i \in S^d \subset \mathbb{R}^{d+1}.$$

# Why caring about this problem?

Fekete problem: minimize the logarithmic energy on  $S^d$ :

$$E_{\log}(w) := - \sum_{1 \leq i < j \leq n} \log(\|w_i - w_j\|^2), \quad w_i \in S^d \subset \mathbb{R}^{d+1}.$$

Bezout III - Shub and Smale (1993) [1]

Fekete solutions (projected to the plane) are useful for initializing homotopy algorithms. Even solutions up to a logarithmic factor.

# Why caring about this problem?

Fekete problem: minimize the logarithmic energy on  $S^d$ :

$$E_{\log}(w) := - \sum_{1 \leq i < j \leq n} \log(\|w_i - w_j\|^2), \quad w_i \in S^d \subset \mathbb{R}^{d+1}.$$

Bezout III - Shub and Smale (1993) [1]

Fekete solutions (projected to the plane) are useful for initializing homotopy algorithms. Even solutions up to a logarithmic factor.

Smale's 7th problem for the next Century (1998) [4]

Give an “efficient” algorithm that, for each number of points  $n$ , finds  $\hat{w} \in (S^2)^n$  with optimal value up to a logarithmic factor:

$$E_{\log}(\hat{w}) - E_{\log}^* \leq c \log(n), \quad \text{for a universal constant } c.$$

# What is known about Fekete problem

- Optimal configurations known for few values of  $n$  and  $d$ .
- In  $S^2$ , optimals are known only for:  $n = 2, 3, 4, 5, 6$  and 12.
- Optimal value known asymptotically, up to linear term [9]:

$$\text{in } S^2: E_{\log}^* = \left( \frac{1}{2} - \log 2 \right) \frac{n^2}{2} - \frac{n \log n}{4} + Cn + o(n), \quad C = ?$$

- Any critical configuration satisfies:  $\sum_{i=1}^n w_i = \vec{0}$ .
- Has saddle-points [8, 10], and degenerate minima [11].
- Numerically: number of spurious local minima in  $S^2$  increases “dramatically” with  $n$  [2]; although none is known in  $S^2$ .
- Only one spurious local minima is known [8, 10]:  $n = 6$  in  $S^3$ .



# Contributions and Approach

## Contributions

- Formulate critical confs. as solutions of a polynomial system.
- Formulation is useful for any sphere  $S^d$ .
- For  $n \leq 6$  points, and all sphere dimensions  $d$ , we:
  - recover previously known results in a Unified Framework.
  - find and classify all Critical Configurations, including unknown Saddle.

# Contributions and Approach

## Contributions

- Formulate critical confs. as solutions of a polynomial system.
- Formulation is useful for any sphere  $S^d$ .
- For  $n \leq 6$  points, and all sphere dimensions  $d$ , we:
  - recover previously known results in a Unified Framework.
  - find and classify all Critical Configurations, including unknown Saddle.

## Approach

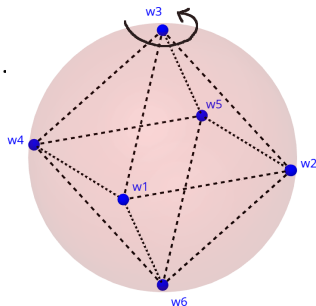
- Determine the number of exact solutions  $m$  of the formulation.
- Find as many solutions as possible, until we reach  $m$ .

# Removing Orthogonal Symmetry

$$E_{\log}(w) := - \sum_{1 \leq i < j \leq n} \log(\|w_i - w_j\|^2).$$

Energy is invariant under rotations of the sphere.

This gives  $\infty$  solutions (but we need to count solutions).

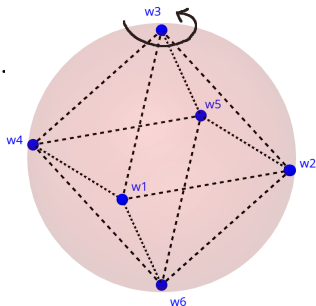


# Removing Orthogonal Symmetry

$$E_{\log}(w) := - \sum_{1 \leq i < j \leq n} \log(\|w_i - w_j\|^2).$$

Energy is invariant under rotations of the sphere.

This gives  $\infty$  solutions (but we need to count solutions).



## Change of variables

Instead of the  $w_i$ , use dot products (“angles”) as variables:

$$x_{ij} := w_i^T w_j = \cos(\theta_{ij}).$$

Rotations of a solution give the exact same solution (in the  $x_{ij}$ ).

# Equations in terms of dot products

Lagrange optimality conditions, expressed in the  $x_{ij} := w_i^T w_j$ :

$$(n-1)x_{ki} - \sum_{j=1, j \neq i}^n \frac{x_{ki} - x_{kj}}{1 - x_{ij}} = 0, \quad \forall i \neq k.$$

# Equations in terms of dot products

Lagrange optimality conditions, expressed in the  $x_{ij} := w_i^T w_j$ :

$$(n-1)x_{ki} - \sum_{j=1, j \neq i}^n \frac{x_{ki} - x_{kj}}{1 - x_{ij}} = 0, \quad \forall i \neq k.$$

Introduce auxiliary variables  $z_{ij}$ , and corresponding equations:

$$\boxed{z_{ij}(1 - x_{ij}) = 1.} \quad (1)$$

# Equations in terms of dot products

Lagrange optimality conditions, expressed in the  $x_{ij} := w_i^T w_j$ :

$$(n-1)x_{ki} - \sum_{j=1, j \neq i}^n \frac{x_{ki} - x_{kj}}{1 - x_{ij}} = 0, \quad \forall i \neq k.$$

Introduce auxiliary variables  $z_{ij}$ , and corresponding equations:

$$\boxed{z_{ij}(1 - x_{ij}) = 1.} \quad (1)$$

$$\boxed{(n-1)x_{ki} - \sum_{j=1, j \neq i}^n (x_{ki} - x_{kj})z_{ij} = 0, \quad \forall i \neq k.} \quad (2)$$

Gives a polynomial expression, and ensures  $x_{ij} \neq 1$  ( $w_i \neq w_j$ ).

# Equations in terms of dot products

Equations:

$$z_{ij}(1 - x_{ij}) = 1.$$

$$(n - 1)x_{ki} - \sum_{j=1, j \neq i}^n (x_{ki} - x_{kj})z_{ij} = 0, \forall i \neq k.$$



# Equations in terms of dot products

Equations:

$$z_{ij}(1 - x_{ij}) = 1.$$

$$(n - 1)x_{ki} - \sum_{j=1, j \neq i}^n (x_{ki} - x_{kj})z_{ij} = 0, \forall i \neq k.$$

Variables:  $x_{ij}$ ,  $z_{ij}$ ,  $i < j$ .

# Equations in terms of dot products

Equations:

$$z_{ij}(1 - x_{ij}) = 1.$$

$$(n - 1)x_{ki} - \sum_{j=1, j \neq i}^n (x_{ki} - x_{kj})z_{ij} = 0, \forall i \neq k.$$

Variables:  $x_{ij}$ ,  $z_{ij}$ ,  $i < j$ .

## Number of variables and equations

	$n$	3	4	5	6	7	8
variables	$2\binom{n}{2}$	6	12	20	30	42	56
equations	$n(3n - 1)/2$	12	22	35	51	70	92

# Number of solutions for $n = 5$ points (any sphere)

## Gröbner theory

- Let  $I$  be the ideal generated by the polynomials of the system.
- Given a Gröbner basis of  $I$ , its Leading Monomials determine:
  - ① if the system has a finite number of solutions:  $\dim(I) = 0$ , and
  - ② in that case, the exact number of solutions:  $\deg(I)$ .
- This counts solutions in  $\mathbb{C}$  and counting multiplicities.

# Number of solutions for $n = 5$ points (any sphere)

## Gröbner theory

- Let  $I$  be the ideal generated by the polynomials of the system.
- Given a Gröbner basis of  $I$ , its Leading Monomials determine:
  - ① if the system has a finite number of solutions:  $\dim(I) = 0$ , and
  - ② in that case, the exact number of solutions:  $\deg(I)$ .
- This counts solutions in  $\mathbb{C}$  and counting multiplicities.

## For $n = 5$

$\dim(I) = 0$  and  $\deg(I) = 38$  solutions.

# Number of solutions for $n = 5$ points (any sphere)

## Gröbner theory

- Let  $I$  be the ideal generated by the polynomials of the system.
- Given a Gröbner basis of  $I$ , its Leading Monomials determine:
  - ① if the system has a finite number of solutions:  $\dim(I) = 0$ , and
  - ② in that case, the exact number of solutions:  $\deg(I)$ .
- This counts solutions in  $\mathbb{C}$  and counting multiplicities.

## For $n = 5$

$\dim(I) = 0$  and  $\deg(I) = 38$  solutions.

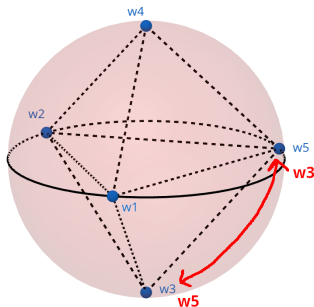
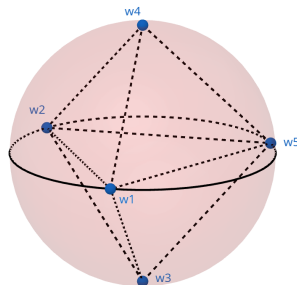
## Next step

Search for solutions, until we match the 38 existent.

# Finding solutions for $n = 5$ points (any sphere)

Easy to check that a particular critical conf. for  $n = 5$  in  $S^2$  is 1:3:1.

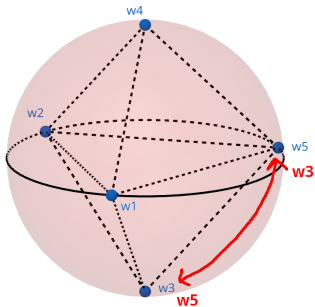
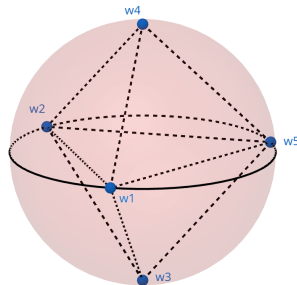
Some permutations give different solutions in  $x_{ij}$ , but of same “kind”.



# Finding solutions for $n = 5$ points (any sphere)

Easy to check that a particular critical conf. for  $n = 5$  in  $S^2$  is 1:3:1.

Some permutations give different solutions in  $x_{ij}$ , but of same “kind”.

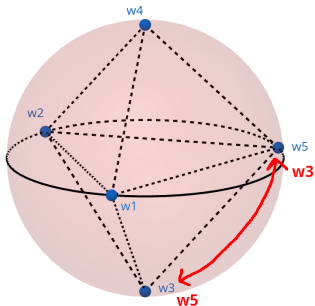
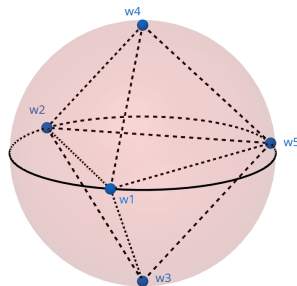


Given a “kind” of solution: how many permutations of the points  $w_i$  give different solutions in the variables  $x_{ij}$ ?

# Finding solutions for $n = 5$ points (any sphere)

Easy to check that a particular critical conf. for  $n = 5$  in  $S^2$  is 1:3:1.

Some permutations give different solutions in  $x_{ij}$ , but of same “kind”.



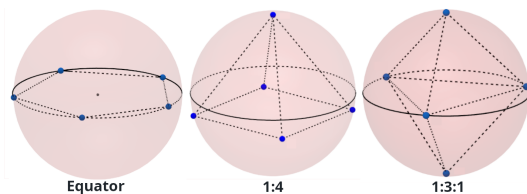
Given a “kind” of solution: how many permutations of the points  $w_i$  give different solutions in the variables  $x_{ij}$ ?

We find this number by trying all possible  $n!$  permutations.



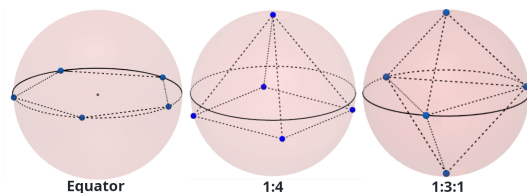
# Finding solutions for $n = 5$ points (any sphere)

We can easily imagine other kind of solutions.



# Finding solutions for $n = 5$ points (any sphere)

We can easily imagine other kind of solutions.

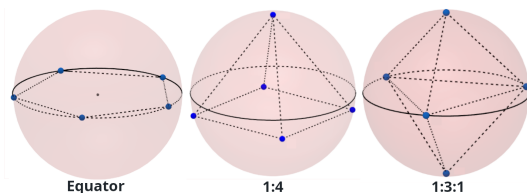


The different permutations of each kind are:

Conf.	Equator	1:4	1:3:1	4-simplex	Found	Existent
$\neq$ perms.	12	15	10	1	38	38
sphere	$S^1$	$S^2$		$S^3$		

# Finding solutions for $n = 5$ points (any sphere)

We can easily imagine other kind of solutions.



The different permutations of each kind are:

Conf.	Equator	1:4	1:3:1	4-simplex	Found	Existent
$\neq$ perms.	12	15	10	1	38	38
sphere	$S^1$	$S^2$		$S^3$		

**Theorem (For  $n = 5$  points)**

*The only kind of critical configurations are the ones we imagined.*

# Number of solutions for $n = 6$ (any sphere)

We find a Gröbner base with GRevLex monomial order (*msolve*), and then use it to determine the number of solutions (*Macaulay2*).

$n$	dim $I$	deg $I$
6	0	938

# Number of solutions for $n = 6$ (any sphere)

We find a Gröbner base with GRevLex monomial order (*msolve*), and then use it to determine the number of solutions (*Macaulay2*).

$n$	dim $I$	deg $I$
6	0	938

Next step: search for solutions until we match the existent 938.

# Possible values of dot product for $n = 6$

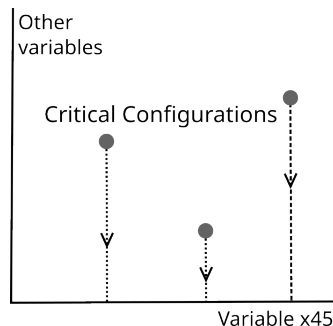
“Imaginable” solutions are not enough: as we will see, there are complex solutions.

# Possible values of dot product for $n = 6$

“Imaginable” solutions are not enough: as we will see, there are complex solutions.

## Approach to determine all the solutions

- Project solution set onto variable  $x_{45}$ .
- Gives possible values of  $x_{45}$ .
- Finding a Gröbner base of the ideal, with elimination order that eliminates all variables except  $x_{45}$ .



# Possible values of dot product for $n = 6$

Projected ideal is a PID:

$I \cap \mathbb{Q}[x_{45}] = (p)$ , some  $p$ .

Roots of generator  $p$  are the possible values of  $x_{45}$ .

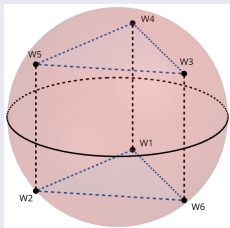
Generator Factor	Roots
$x_{45}$	0
$(x_{45} + 1)^2$	-1
$2x_{45} - 1$	1/2
$2x_{45} + 1$	-1/2
$(5x_{45} - 1)^2$	1/5
$5x_{45} + 1$	-1/5
$(5x_{45} + 7)^2$	-7/5
$(5x_{45}^2 + 1)^2$	$\pm \frac{i}{\sqrt{5}}$
$5x_{45}^2 - 22x_{45} + 5$	$\frac{11 \pm 4\sqrt{6}}{5}$
$5x_{45}^2 + 2x_{45} - 1$	$\frac{-1 \pm \sqrt{6}}{5}$
$5x_{45}^2 + 14x_{45} - 1$	$\frac{-7 \pm 3\sqrt{6}}{5}$
$25x_{45}^2 + 28x_{45} + 19$	$\frac{-14 \pm i3\sqrt{31}}{25}$
$125x_{45}^2 + 50x_{45} - 31$	$\frac{-5 \pm 6\sqrt{5}}{25}$
$100x_{45}^4 + 95x_{45}^3 - 21x_{45}^2 - 22x_{45} + 10$	4 complex
$250x_{45}^4 + 110x_{45}^3 - 21x_{45}^2 - 19x_{45} + 4$	4 complex
$400x_{45}^4 + 488x_{45}^3 - 111x_{45}^2 - 196x_{45} + 67$	4 complex
$3x_{45} + 1$	-1/3
$5x_{45} + 4$	-4/5
$10x_{45} - 1$	1/10
$25x_{45} - 1$	1/25
$25x_{45} + 11$	-11/25
$25x_{45} + 23$	-23/25



# Solutions for each coordinate value of $x_{45}$

For each factor  $p_i$  of the generator (each  $x_{45}$  value)

- ① Add  $p_i = 0$  to the original system.
- ② Find solutions of simplified system, and count permutations.

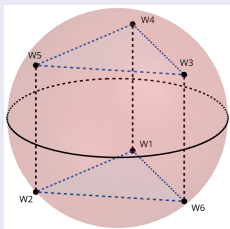


Configuration	# perms	Sphere
Equator	60	$S^1$
1:5	72	$S^2$
1:4:1	15	$S^2$
3:3	60+60	$S^2$
Complex 1	90	$S^2$
Complex 2	360	$S^2$
Real 1	15	$S^3$
Real 2	45	$S^3$
Real 3	60	$S^3$
Real 4	10	$S^3$
5-simplex	1	$S^4$
Found	848	
Existent	938	
Difference	$938 - 848 = 90$	

# Solutions for each coordinate value of $x_{45}$

For each factor  $p_i$  of the generator (each  $x_{45}$  value)

- ① Add  $p_i = 0$  to the original system.
- ② Find solutions of simplified system, and count permutations.



Configuration	# perms	Sphere
Equator	60	$S^1$
1:5	72	$S^2$
1:4:1	15	$S^2$
3:3	60+60	$S^2$
Complex 1	90	$S^2$
Complex 2	360	$S^2$
Real 1	15	$S^3$
Real 2	45	$S^3$
Real 3	60	$S^3$
Real 4	10	$S^3$
5-simplex	1	$S^4$
Found	848	
Existent	938	
Difference	$938 - 848 = 90$	

Complex 1 has multiplicity 2: +90.

# Classification of **real** critical configurations ( $n = 6$ )

Configuration	$S^1$	$S^2$	$S^3$	$S^4$
Equator	GM	S	S	S
1:5	-	S	S	S
1:4:1	-	GM	S	S
3:3 ( $\sqrt{6}$ )	-	S	S	S
Real 1	-	-	SM	S
Real 2	-	-	S	S
Real 3	-	-	S	S
Real 4	-	-	GM	S
5-simplex	-	-	-	GM

# Classification of **real** critical configurations ( $n = 6$ )

Configuration	$S^1$	$S^2$	$S^3$	$S^4$
Equator	GM	S	S	S
1:5	-	S	S	S
1:4:1	-	GM	S	S
3:3 ( $\sqrt{6}$ )	-	S	S	S
Real 1	-	-	SM	S
Real 2	-	-	S	S
Real 3	-	-	S	S
Real 4	-	-	GM	S
5-simplex	-	-	-	GM

- Global minima are classified comparing energy values.
- Other configurations classified with Hessian of the Lagrangian.
- It is known that problem does not admit local/global maxima.

# Conclusions and Future Work

- Formulate critical configurations as polynomial system sols.
- Obtain all critical configurations, and in particular all optimal configurations, for  $n \leq 6$ ,  $d \geq 1$ .
- Give first exhaustive list of critical configurations and classification for  $n = 6$  in  $S^2$ .

# Conclusions and Future Work

- Formulate critical configurations as polynomial system sols.
- Obtain all critical configurations, and in particular all optimal configurations, for  $n \leq 6$ ,  $d \geq 1$ .
- Give first exhaustive list of critical configurations and classification for  $n = 6$  in  $S^2$ .

## Pros and Cons of our Approach

- ✓ Unified framework (previous results are from different articles).
- ✓ Formulation useful for sphere  $S^d$  of any dimension  $d$ .

# Conclusions and Future Work

- Formulate critical configurations as polynomial system sols.
- Obtain all critical configurations, and in particular all optimal configurations, for  $n \leq 6$ ,  $d \geq 1$ .
- Give first exhaustive list of critical configurations and classification for  $n = 6$  in  $S^2$ .

## Pros and Cons of our Approach

- ✓ Unified framework (previous results are from different articles).
- ✓ Formulation useful for sphere  $S^d$  of any dimension  $d$ .
- ✗ Relies on calculating Gröbner basis in  $2\binom{n}{2}$  vars.

# Conclusions and Future Work

- Formulate critical configurations as polynomial system sols.
- Obtain all critical configurations, and in particular all optimal configurations, for  $n \leq 6$ ,  $d \geq 1$ .
- Give first exhaustive list of critical configurations and classification for  $n = 6$  in  $S^2$ .

## Pros and Cons of our Approach

- ✓ Unified framework (previous results are from different articles).
- ✓ Formulation useful for sphere  $S^d$  of any dimension  $d$ .
- ✗ Relies on calculating Gröbner basis in  $2\binom{n}{2}$  vars.

## Future Work

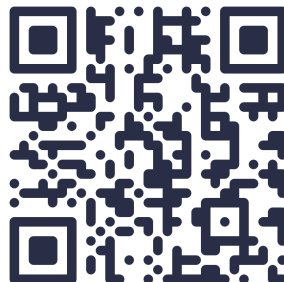
- prove optimal configuration for  $n = 7$  (numerical candidate  $\exists$ )
- “simplify” the system of equations, exploiting symmetries.



# Gracias por su atención

## Code and presentation

<http://www.github.com/matiasvd>



## Acknowledgments

- Cluster.UY for the hardware infrastructure.
- ANII and CAP for PhD grants.
- *msolve*, *Macaulay2* and *SymPy* developers for their great work

# References

- [1] Shub and Smale (1993). Complexity of bezout's theorem: iii. Condition number and packing. Journal of complexity.
- [2] Rakhmanov, Saff, Zhou (1995). Electrons on the sphere. In Computational Methods and Function Theory.
- [3] Kolushov, Yudin (1997). Extremal dispositions of points on the sphere. Analysis Mathematica.
- [4] Smale, Stephen (1998). Mathematical problems for the next century. The mathematical intelligencer.
- [5] J.C. Faugère (1999). A new efficient algorithm for computing Gröbner bases (F4). Journal of pure and applied algebra.
- [6] Dragnev, Legg, Townsend (2002). Discrete logarithmic energy on the sphere. Pacific journal of mathematics.
- [7] Horn, Johnson (2013). Matrix analysis. (2nd ed.). Cambridge university press.
- [8] Dragnev (2016). Log-optimal configurations on the sphere. In Modern trends in constructive function theory.
- [9] Bétermin, Sandier (2018). Renormalized energy and asymptotic expansion of optimal logarithmic energy on the sphere.
- [10] Dragnev, Musin (2023). Log-optimal  $(d + 2)$ -configurations in  $d$ -dimensions. Trans. AMS.
- [11] Constantineau, et. al (2023). Determination of stable branches of relative equilibria of the  $N$ -vortex problem on the sphere.

# *msolve* executions ( $n = 6$ points)

AVX512 instructions, 20 threads, Xeon-Gold 6138.

GRevLex monomial order (*msolve* 0.73) - With null CM equations

<i>msolve</i> GB in $\mathbb{Q}$		reduced GB size	
total time	RAM	# polys	# mons
1 hour, 6 minutes	37 GB	2473	xx

Elimination order to project to  $x_{45}$  (*msolve* 0.73)

*msolve* takes 10 hours and 190 GB of RAM.

# *msolve* executions ( $n = 6$ points)

AVX512 instructions, 20 threads, Xeon-Gold 6138.

GRevLex monomial order (*msolve* 0.73) - With null CM equations

<i>msolve</i> GB in $\mathbb{Q}$		reduced GB size	
total time	RAM	# polys	# mons
1 hour, 6 minutes	37 GB	2473	xx

Elimination order to project to  $x_{45}$  (*msolve* 0.73)

*msolve* takes 10 hours and 190 GB of RAM.

GRevLex without lifting GB to  $\mathbb{Q}$  (*msolve* 0.90)

	<i>msolve</i> GB		reduced GB size	
Null Center of Mass equations	total time	RAM	# polys	# mons
Yes	485 s	3.35 GB	2473	2.133.497
No	433 s	3.36 GB	2473	2.133.497

# Configurations for $n = 6$ points in $S^3 \subset \mathbb{R}^4$

## Optimal configuration: Real 4

Two equilateral triangles, each inscribed in a copy of  $S^1$  lying in orthogonal spaces.

## The other configurations

- Real 1 (SM): analogous to 1:4:1 of  $S^2$ : it has the poles, and then the optimal configuration for 4 points in the equatorial sphere.
- Real 3 (S): analogous to 1:5 of  $S^2$ : it has a pole, and then the optimal configuration for 5 points in the corresponding sphere.
- Real 2 (S): no analogous on  $S^2$ . Has 4 points on the Equator of a sphere and the optimal configuration for 2 points in another sphere. Line through these two points is orthogonal to the plane of the 4 point Equator.

## From $x_{ij}$ to $w_i$

Any solution in the variables  $w_i$  has an associated solution  $x_{ij} = w_i^T w_j$ . Reciprocal is also true in  $\mathbb{C}$ .

**Theorem (Autonne-Takagi factorization [7, Corollary 2.6.6])**

*If  $X \in \mathbb{C}^{n \times n}$  is symmetric, there is a unitary  $P \in \mathbb{C}^{n \times n}$ , and a non-negative diagonal matrix  $D \in \mathbb{R}^{n \times n}$ , such that:  $X = P^T D P$ . Furthermore, the entries of  $D$  are the singular values of  $X$ .*

### Corollary

*If  $X \in \mathbb{C}^{n \times n}$  is symmetric with rank  $d$ , and ones on its diagonal, there exists  $W \in \mathbb{C}^{d \times n}$ , such that:  $X = W^T W$ ,  $w_i^T w_i = 1$ ,  $\forall i$ .*

### Proof.

As  $X$  is symmetric:  $X = P^T D P$ . Take:  $W = \sqrt{\hat{D}} P$ ; where  $\hat{D} \in \mathbb{R}^{d \times n}$  is the submatrix of  $D$  with positive singular values. □