Virtualize Everything but Time

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Introduction

Clock synchronization, who cares?

- Network monitoring / Traffic analysis
- Telecommunications Industry; Finance; Gaming, ...
- Distributed `scheduling': timestamps instead of message passing

Status quo under Xen

- Based on ntpd, amplifies its flaws
- Fails under live VM migration

We propose a new architecture

- Based on RADclock client synchronization solution
- Robust, accurate, scalable
- Enables dependent clock paradigm
- Seamless migration



Key Idea

Each physical host has a single clock which never migrates

Only a (stateless) clock read function migrates

Para-Virtualization and Xen

Hypervisor

minimal kernel managing physical resources

Para-virtualization

- Guest OS's have access to hypervisor via hypercalls
- Fully-virtualized more complex, not addressed here

Focus on Xen

- But approach has general applicability!
- Focus on Linux OS's (2.6.31.13 Xen pvops branch)
- Guest OS's:
 - Dom0: privileged access to hardware devices
 - DomU: access managed by Dom0
- Use Hypervisor 4.0 mainly



Hardware Counters

Clocks built on local hardware (oscillators → counters)

- HPET, ACPI, TSC
- Counters imperfect, they drift (temperature driven)
- Affected by OS
 - ticking rate
 - access latency

TSC (counts CPU cycles)

- Highest resolution and lowest latency preferred! but...
- May be unreliable
 - → multi-core → multiple unsynchronised TSCs
 - → power management → variable rate, including stopping!

HPET

- Reliable, but
- Lower resolution, higher latency



Xen Clocksource

A hardware/software hybrid timer provided by the hypervisor

Purpose

- Combine reliability of HPET with low latency of TSC
- Compensate for TSC unreliability
- Provides 1GHz 64-bit counter

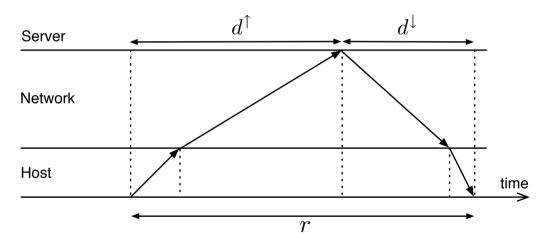
Performance of XCS versus HPET

- XCS performs well: low latency and high stability
- HPET not that far behind, and a lot simpler



Clock Fundamentals

- Timekeeping and timestamping are distinct
- Raw timestamps and clock timestamps are distinct
- A scaled counter is not a good clock: drift!
- Purpose of clock sync algo is to correct for drift
- Network based sync is convenient, exchange timing packets:



Two key problems

- Dealing with delay variability (complex, but possible)
- Path asymmetry (simple, but impossible)



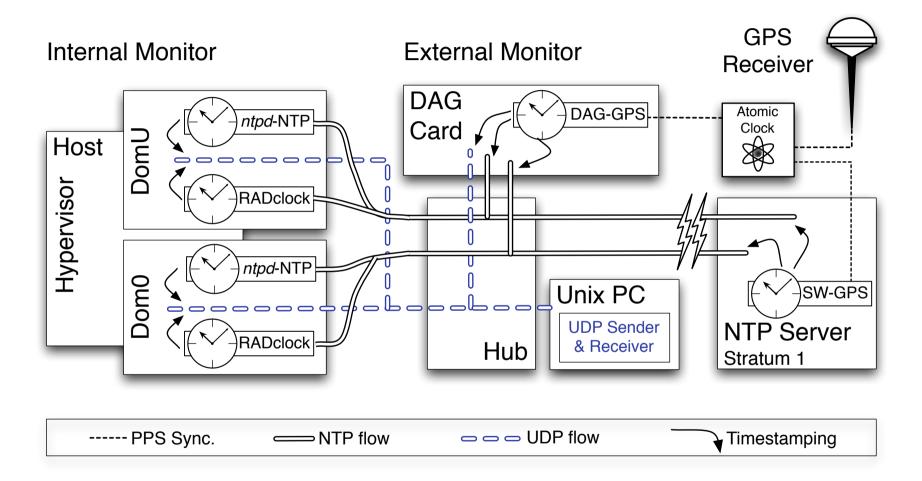
Synchronisation Algorithms

NTP (ntpd)

- Status Quo
- Feedback based
 - Event timestamps are system clock stamps
 - Feedback controller (PLL,FLL) tries to lock onto rate
- Intimate relationship with system clock (API, dynamics..)
- In Xen, ntpd uses Xen Clocksource
- RADclock (Robust Absolute and Difference Clock)
 - Algo developed in 2004, extensively tested
 - Feedforward based
 - Event timestamps are raw stamps
 - Clock error estimates made and removed when clock read
 - System clock' has no dynamics, just a function call
 - Can use any raw counter: here use HPET, Xen Clocksource



Experimental Methodology

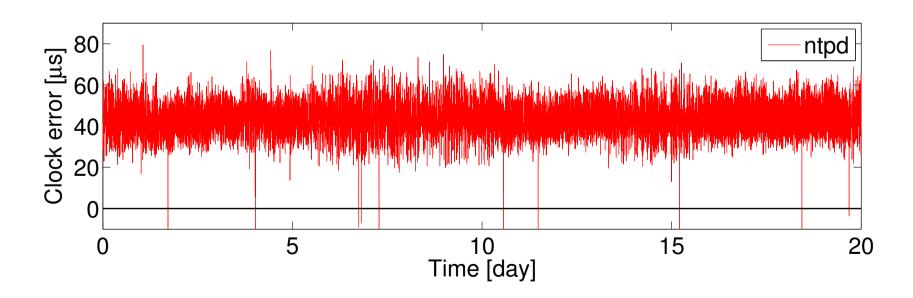




Wots the problem? ntpd can perform well

Ideal Setup

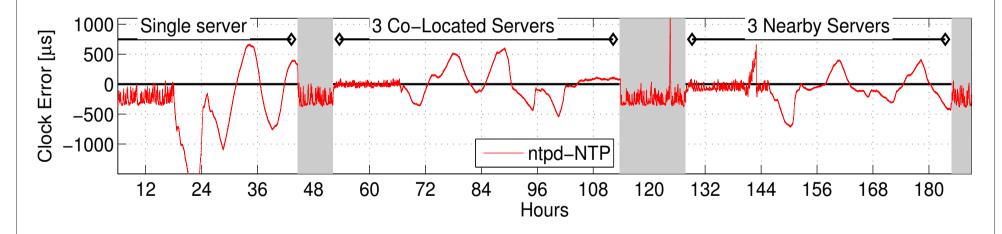
- Quality Stratum-1 time-server
- Client is on the same LAN, lightly loaded, barely any traffic
- Constrained and small polling period: 16 sec



Or less well...

Different configuration (ntpd recommended!)

- Multiple servers
- Relax constraint on polling period
- Still no load, no traffic, high quality servers



When/Why? Loss of stability a complex function of parameters ⇒ unreliable



The Xen Context

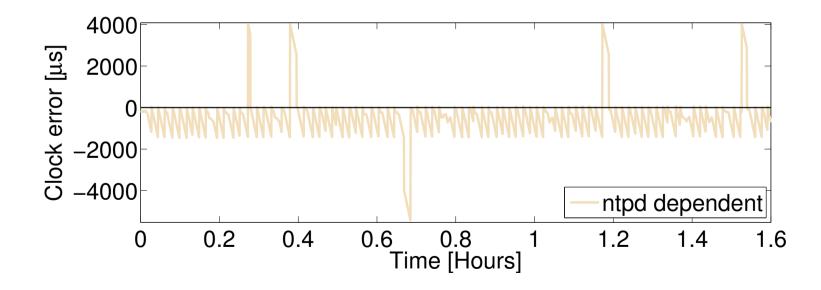
- Three examples of inadequacy of ntpd based solution
 - 1) Dependent *ntpd* clock
 - 2) Independent *ntpd* clock
 - 3) Migrating independent *ntpd* clock

1) Dependent ntpd Clock

The Solution

- Only Dom0 runs ntpd
- Periodically updates a `boot time' variable in hypervisor
- DomU uses Xen Clocksource to interpolate

■ The Result (2.6.26 kernel)





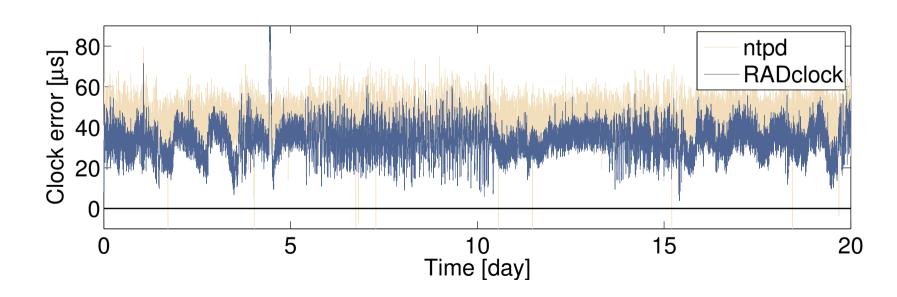
2) Independent ntpd Clock (current solution)

The Solution

- All guests run entirely separate ntpd daemons
- Resource hungry

The Result

- When all is well, works as before but with a bit more noise
- When works: (parallel comparison on Dom0, stratum-1 on LAN)



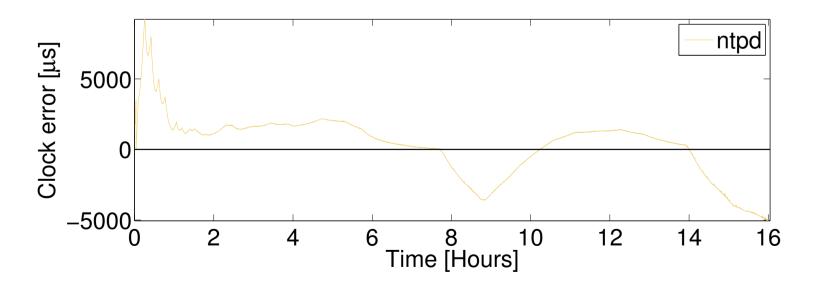
2) Independent ntpd Clock (current solution)

The Solution

- All guests run entirely separate ntpd daemons
- Resource hungry

The Result

- Increased noise makes instability more likely
- When fails: (DomU with some load, variable polling period, guest churn)





3) Migrating Independent ntpd Clock

- The Solution
 - Independent clock as before, migrates
 - Starts talking to new system clock, new counter
- The Result

Migration Shock!

More Soon

RADclock Architecture

Principles

Timestamping:

- raw counter reads, not clock reads
- independent of the clock algorithm

Synchronization Algorithm:

- based on raw timestamps and server timestamps (feedforward)
- estimates clock parameters and makes available
- concentrated in a single module (in userland)

Clock Reading

- combines a raw timestamp with retrieved clock parameters
- stateless



More Concretely

Timestamping

read chosen counter, say HPET(t)

Sync Algorithm maintains:

- Period: a long term average (barely changes) ⇒ rate stability
- K: sets origin to desired timescale (e.g. UTC)
- estimate of error ⇒ updates on each stamp exchange

Clock Reading

- Absolute clock: C_a(t) = Period *HPET(t) + K E(t)
 - used for absolute, and differences above critical scale
- Difference clock: $C_d(t_1,t_2) = \frac{Period}{Period} * (HPET(t_2) HPET(t_1))$
 - used for time differences under some critical time scale



Implementation

Timestamping `feedforward support'

- create cumulative and wide (64-bit) form of counter
- make accessible from both kernel and user context
 - under Linux, modify Clocksource abstraction

Sync Algorithm

Make clock parameters available via a user thread

Clock reading

- Read counter, retrieve clock data, compose
- Fixed-point code to enable clock to be read from kernel



On Xen

Feedforward paradigm a perfect match to para-virtualisation

Dependent Clock now very natural

- Dom0 maintains a RADclock daemon, talks to timeserver
- Makes Period, K, E available through Xenstore filesystem
- Each DomU can just reads counter, retrieve clockdata, compose

All Guest Clocks identically the same, but:

- Small delay (~1ms) in Xenstore update
 - stale data possible but very unlikely
 - small impact
- Latency to read counter higher on DomU

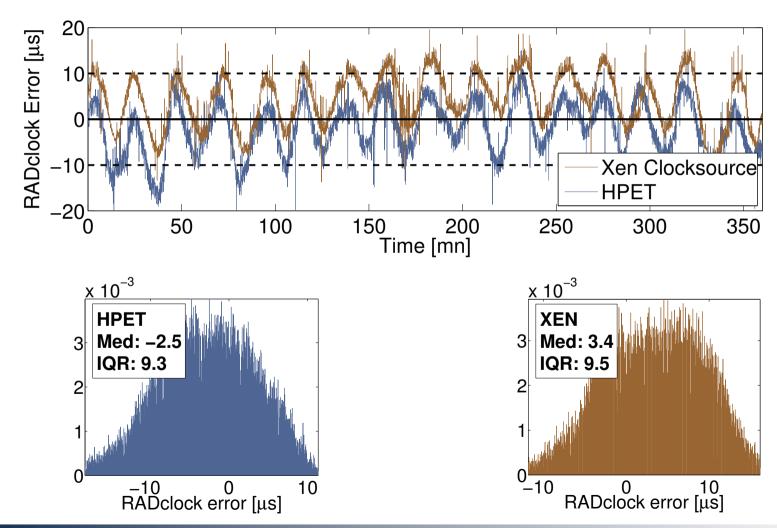
Support Needed

- Expose HPET to Clocksource in guest OSs
- Add hypercall to access platform timer (HPET here)
- Add read/right functions to access clockdata from Xenstore



Independent RADclock on Xen

Concurrent test on two DomU's, separate NTP streams





Migration On Xen

Feedforward paradigm a perfect match to migration

Clocks don't migrate, only a clock reading function does!

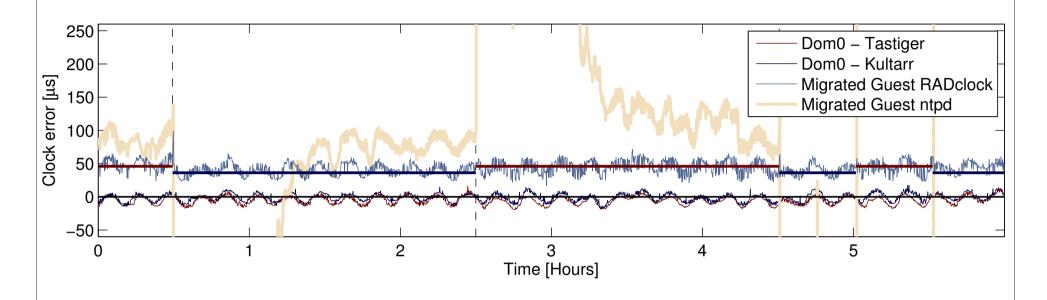
- Each Dom0 has its own RADclock daemon
- DomU only ever calls a function, no state is migrated

Caveats

- Local copy of clockdata used to limit syscalls needs refreshing
- Host asymmetry will change, result in small clock jump
 - asymmetry effects different for Dom0 (hence clock itself) and DomU



Migration Comparison

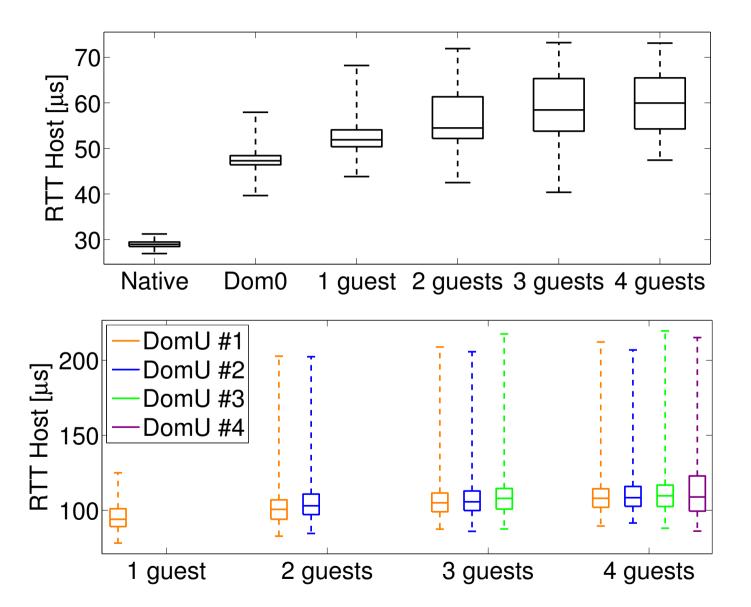


Setup

- Two machines, each Dom0 running a RADclock
- One DomU migrates with a
 - dependent RADclock
 - independent ntpd

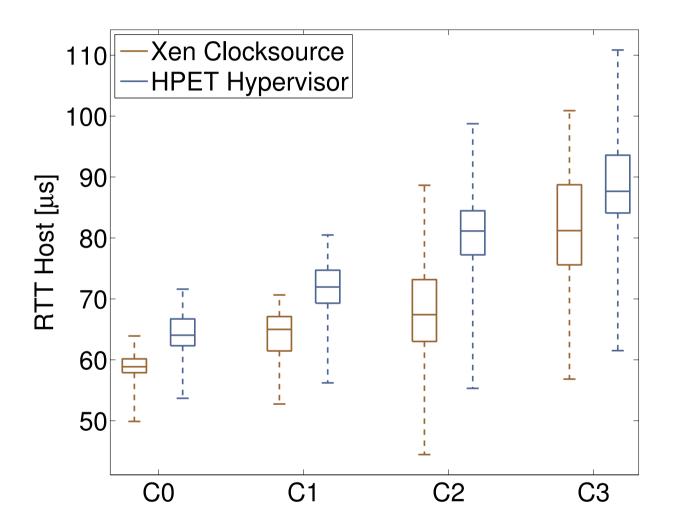


Noise Overhead of Xen and Guests



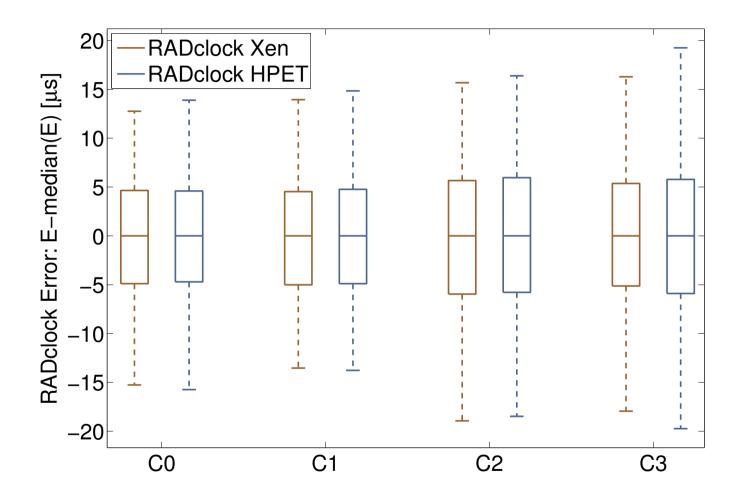


Noise Penalty Under C-States





Algo Performance Under C-States





Conclusion

Feed-Forward approach has many advantages

- Difference clock defined
- Absolute clock can be made much more robust
- Time can be replayed
- Simpler kernel support

Good match to needs of para-virtualisation

- Enables clock dependent mode that works
- Allows seamless live migration

RADclock project

- Aims to replace ntpd
- Client and Server code
- Packages for FreeBSD and Linux (Xen now supported)
- http://www.cubinlab.ee.unimelb.edu.au/radclock/

