

# Uluslararası Birim Sistemi (SI)

→ temel büyüklük

## Fiziksel nicelikler

### Birim

### Sembol

1) Uzunluk	metre	m
2) Kütle	kilogram	kg
3) Zaman	saniye	s
4) Elektrik akımı	ampir	A
5) Termodynamik (sicaklık)	Kelvin	K
6) Madde miktari	mol	mol
7) Işık强度 (intensity)	kandela	cd

1) Kütle yoğunluğu	$\text{kilogram}/(\text{metre})^3$	$\text{kg}/\text{m}^3$ → <u>density</u> <u>büyüklük</u>
2) Sıra / hız	$\text{metre}/\text{saniye}$	$\text{m}/\text{s}$
3) İume	$\frac{\text{metre}}{\text{saniye}}$	$\text{m}/\text{s}^2$
4) Kuvvet	$\text{kilogram} \cdot \frac{\text{metre}}{(\text{saniye})^2}$	$\frac{\text{kg} \cdot \text{m}}{\text{s}^2} \Rightarrow \text{Newton}$ (N)

## Birimlerin dönüştürülmesi

$$1 \text{ inç} = 2,54 \text{ cm}$$

$$1 \text{ mph} (\text{mi per hour}) \Rightarrow 1 \text{ h} = 3600 \text{ s}$$

$$\text{mi/h}$$

$$1 \text{ mi} = 1,609 \text{ km} = 1609 \text{ m}$$

$$1 \text{ mph} = \frac{1609}{3600} \frac{\text{m}}{\text{s}} = 0,447 \frac{\text{m}}{\text{s}}$$

## Boyu Anlatı

$$[L] = \text{uzunluk} \quad [M] = \text{kütle} \quad [T] = \text{süre}$$

$$x = x_0 + v_0 \cdot t + \frac{1}{2} \cdot a t^2$$

$$\downarrow$$

$$[L] = [L] \quad \frac{[L]}{[T]} \cdot [T] \quad \frac{1}{2} \cdot \frac{[L]}{[T]^2} \cdot [T]^2$$

$$[L] = [L] \quad [L] \quad [L]$$

## Bellişteğiz ve Aritmetik Basamaklar

$$\Delta = \text{mutlak bellişteğiz} \quad \Sigma = \text{yatırmalı bellişteğiz (binimsiz)}$$

Örnek:  $M = 3,3 \pm 0,2 \text{ kg} = 3,3 + 6,1\%$   $\Sigma = \frac{0,2}{3,3} \cdot 100 = 6,1\%$

Örnek:  $6,5 \pm 0,5 \text{ m}$  ve  $3,2 \pm 0,1 \text{ m}$

$$A = (6,5 \pm 0,5) + (3,2 \pm 0,1) = (9,8 \pm 0,6) \text{ m}$$

$$B = (6,5 \pm 0,5) - (3,2 \pm 0,1) = (3,2 \pm 0,6) \text{ m}$$

$\left. \begin{array}{l} \text{toplama ve} \\ \text{çıkarma} \end{array} \right\} \text{bellişteğiz}$

Örnek:  $5,0 \text{ m} \pm 4,0\%$  ve  $(3,0 \pm 3,3\%)$

Karpma ve bölmeye bellişteğiz

$$C = (5,0 \text{ m} \pm 4,0\%) \times (3,0 \pm 3,3\%) = (15,0 \text{ m} \cdot \text{s} \pm 7,2\%)$$

$$D = \frac{(5,0 \text{ m} \pm 4,0\%)}{(3,0 \pm 3,3\%)} = (1,7 \text{ m/s} \pm 7,3\%)$$

## Aritmetik basamaklar

Örnek:  $54,4 \text{ cm}$   
 $+ 3,02 \text{ cm}$   
 $-----$   
 $57,4 \text{ cm}$

Örnek:  $\frac{4,2 \cdot 10^3 \cdot 15,94}{2,255 \cdot 10^{-6}} = 2,9688692 \cdot 10^8$   
 $3,0 \cdot 10^8$

## Vektörler

skaler boyutlu:  $n = 93 \text{ kg} \rightarrow \text{birim}$

vektör boyutlu:  $v = 20 \text{ m/s}$  kuzey yandırma

$\rightarrow$  sağ,  $\downarrow$  birim yön

$$|\vec{A}| = A$$

$\left( \begin{array}{l} \text{sürekli} \\ \text{sayı} \end{array} \right)$

\*  $\uparrow \vec{c}$

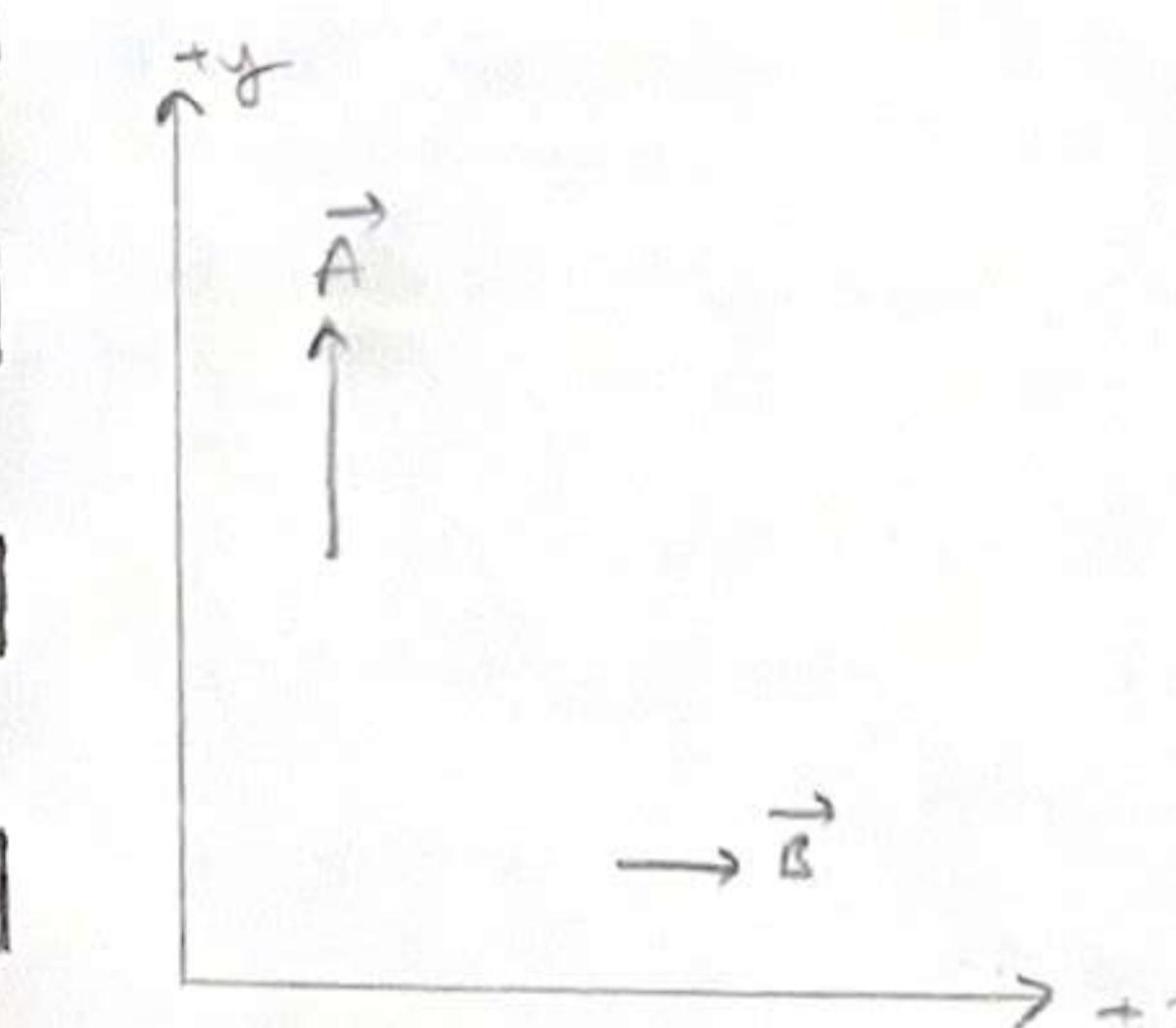
$\uparrow \vec{B}$

$\vec{c} = \vec{B}$

\*  $\uparrow \vec{u}$   $\downarrow \vec{-M}$

## Vektörlerin toplaması

### Paralelkenar yöntemi

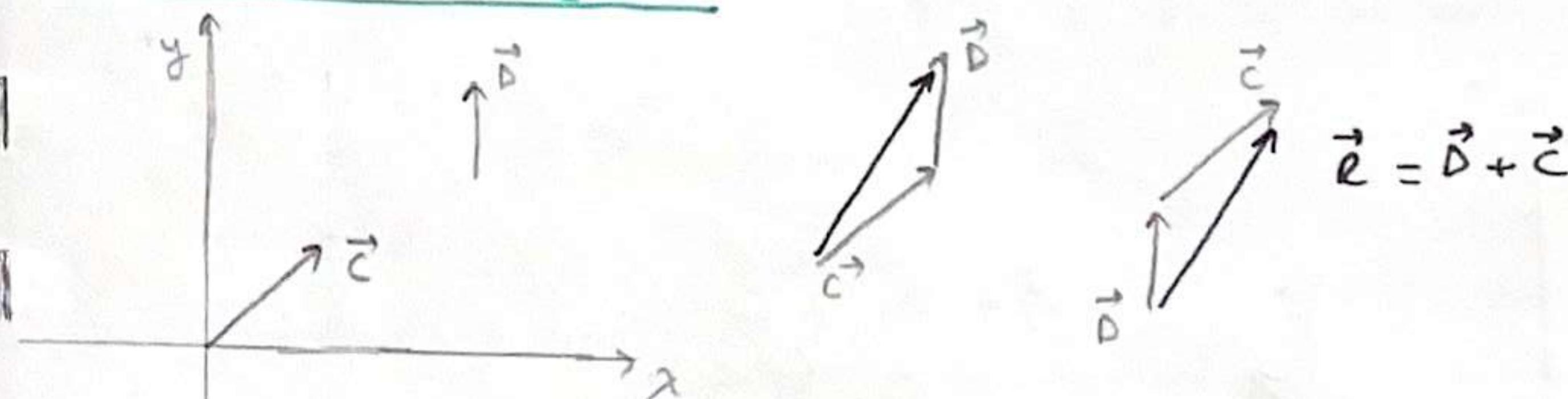


$$\vec{R} = \vec{A} + \vec{B}$$

Vektörlerin başlangıç noktaları biriktirilir ve paralelkenara tenevilerdir. Dısınak sıfırı koyulursa birleşme vektörleri

$$\vec{R}' = \vec{A} + (-\vec{B}) = \vec{A} - \vec{B}$$

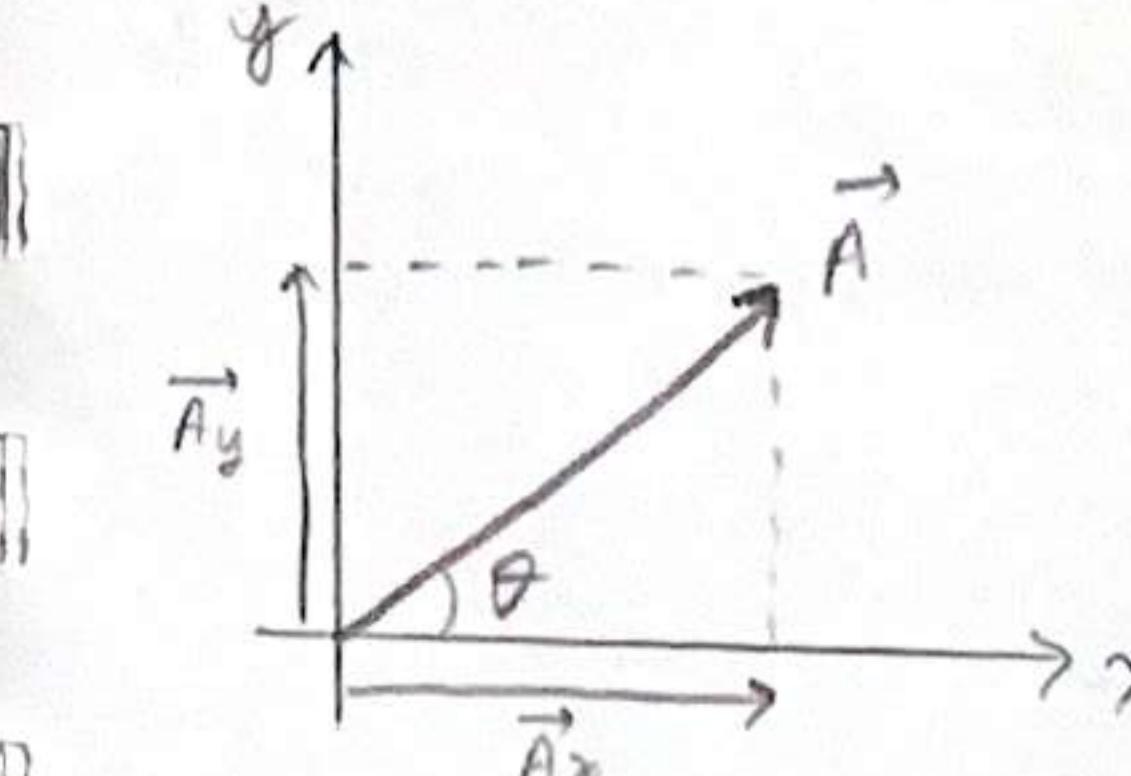
### Üç üçer etkileşimi yöntemi

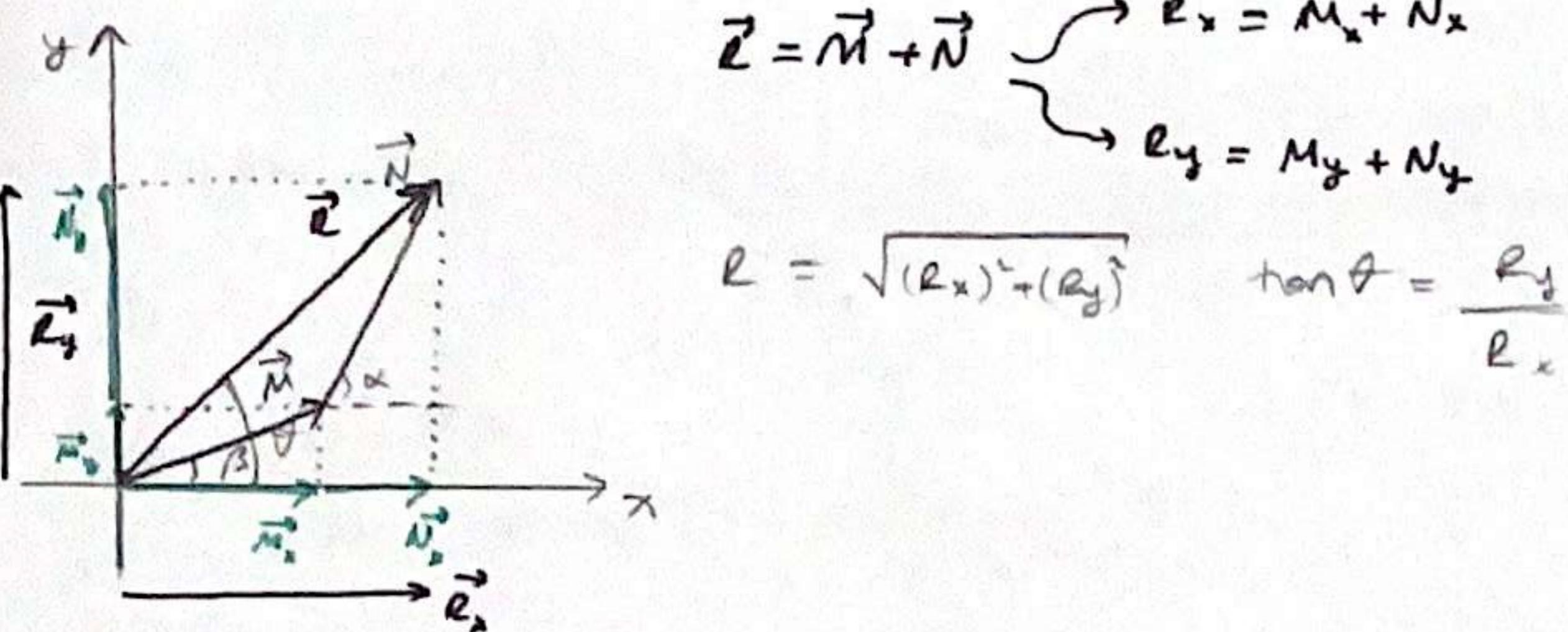


$$\cos \theta = \frac{A_x}{A} \Rightarrow A_x = A \cos \theta$$

$$\sin \theta = \frac{A_y}{A} \Rightarrow A_y = A \sin \theta$$

$$A = \sqrt{(A_x)^2 + (A_y)^2} \quad \tan \theta = \frac{A_y}{A_x}$$





Vektörlerin birim vektorler ile gösterimi

Birim vektor:  $|u_A| = 1$  ( $yani \vec{A}$  ile aynıdır)

$|\vec{i}| = |\vec{j}| = |\vec{k}| = 1$

$\vec{A} = A_x \cdot \vec{i} + A_y \cdot \vec{j} + A_z \cdot \vec{k}$

Soru:  $\vec{A} = 2\vec{i} + 3\vec{j} - 2\vec{k}$      $\vec{B} = 4\vec{j} + \vec{k}$

a)  $\vec{R} = \vec{A} + \vec{B}$

$$\vec{R} = (2\vec{i} + 3\vec{j} - 2\vec{k}) + (4\vec{j} + \vec{k})$$

$$\vec{R} = (2\vec{i} + 7\vec{j} - \vec{k})$$

$$R = \sqrt{2^2 + 7^2 + (-1)^2}$$

$$\sqrt{4 + 49 + 1} = \sqrt{54} = 3\sqrt{6} \text{ br}$$

b)  $\vec{R} = \vec{A} - \vec{B}$

$$\vec{R} = (2\vec{i} + 3\vec{j} - 2\vec{k}) - (4\vec{j} + \vec{k})$$

$$\vec{R} = 2\vec{i} - \vec{j} - 3\vec{k}$$

$$R = \sqrt{2^2 + (-1)^2 + (-3)^2}$$

$$\sqrt{4 + 1 + 9} = \sqrt{14} \text{ br}$$

### Vector Çarpımı

İki vektörün skaler çarpımı

$$\vec{A} \cdot \vec{B} = A \cdot B \cdot \cos \theta$$

skaler çarpma

$(A \cdot \cos \theta) \cdot B$

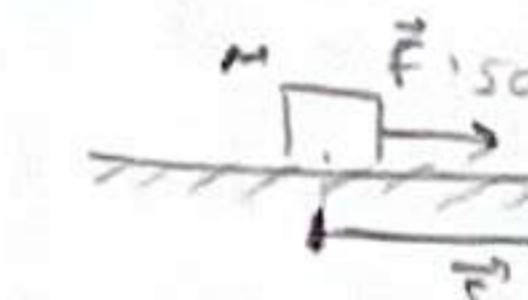
$A \cdot (B \cdot \cos \theta)$

Birbirine平行 bileşenlerin çarpımı

i) "+", "-" veya 0 olabilir cui skaler bir sonucu

ii)  $\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}$

Görmek: "S"



$$W = \vec{F} \cdot \vec{S}$$

$$1 \text{ Joule} = 1 \text{ Nm}$$

$$1 \text{ Joule} = 1 \text{ N} \cdot 1 \text{ m}$$

### Birim vektörlerin skalar çarpımı

$$\vec{A} \cdot \vec{B} = ?$$

$$\vec{A} = A_x \cdot \vec{i} + A_y \cdot \vec{j} + A_z \cdot \vec{k}$$

$$\vec{B} = B_x \cdot \vec{i} + B_y \cdot \vec{j} + B_z \cdot \vec{k}$$

$$\begin{aligned} \vec{i} \cdot \vec{i} &= 1 \cdot 1 \cdot \cos 0^\circ = 1 \\ \vec{i} \cdot \vec{j} &= 1 \cdot 1 \cdot \cos 90^\circ = 0 \end{aligned}$$

$$\vec{A} \cdot \vec{B} = (A_x \cdot \vec{i} + A_y \cdot \vec{j} + A_z \cdot \vec{k}) \cdot (B_x \cdot \vec{i} + B_y \cdot \vec{j} + B_z \cdot \vec{k})$$

$$\vec{A} \cdot \vec{B} = A_x \cdot B_x + 0 + 0 + A_y \cdot B_y + 0 + 0 + A_z \cdot B_z$$

$$\boxed{\vec{A} \cdot \vec{B} = A_x \cdot B_x + A_y \cdot B_y + A_z \cdot B_z}$$

Soru:  $\vec{A} = 2\vec{i} + 3\vec{j} - 2\vec{k}$  ve  $\vec{B} = 4\vec{j} + \vec{k}$

$$1) \vec{A} \cdot \vec{B} = A_x \cdot B_x + A_y \cdot B_y + A_z \cdot B_z$$

$$(2, 0) + (3, 4) + (-2, 1) = 0 + 12 + (-2) = 10$$

$$\boxed{\vec{A} \cdot \vec{B} = 10}$$

2)  $\vec{A}$  ile  $\vec{B}$  arasındaki açı ne kadardır?

$$\vec{A} \cdot \vec{B} = A \cdot B \cdot \cos \theta \quad \cos \theta = \frac{\vec{A} \cdot \vec{B}}{A \cdot B}$$

$$A = \sqrt{2^2 + 3^2 + (-2)^2}$$

$$B = \sqrt{4^2 + 1^2}$$

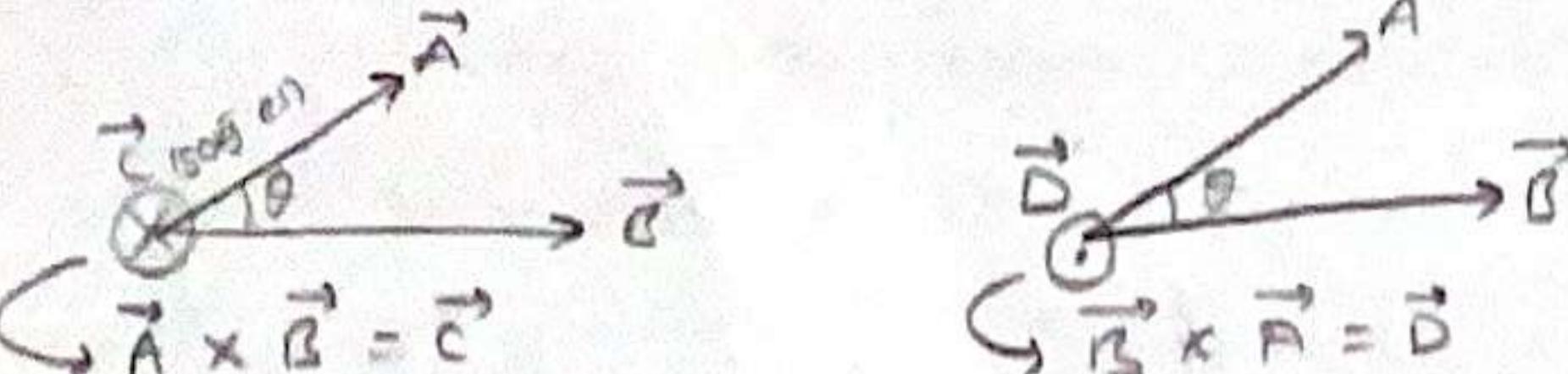
$$\cos \theta = \frac{10}{\sqrt{17} \cdot \sqrt{17}} = \frac{10}{17} = 0,588 \quad \boxed{B = \sqrt{17}}$$

$$\theta = 54^\circ$$

### İki vektörün vektörel çarpımı

$$\vec{A} \times \vec{B} = \vec{C}$$

vektör  
arasındaki açı

$$|\vec{C}| = |\vec{A} \times \vec{B}| = A \cdot B \cdot \sin \theta$$


$$|\vec{A} \times \vec{B}| = |\vec{B} \times \vec{A}|$$

$$\vec{A} \times \vec{B} = -(\vec{B} \times \vec{A})$$

Not: Birim vektör  $\vec{C}$  iki vektörün  $\vec{A}$  ve  $\vec{B}$ 'ye dikdir

$$\vec{A} \perp \vec{C} \quad \vec{B} \perp \vec{C} \quad / \vec{A} \perp \vec{D} \quad \vec{B} \perp \vec{D}$$

### Birim vektörlerle vektörel çarpım

$$\vec{A} \times \vec{B} = ?$$

$$|\vec{i} \times \vec{i}| = 1 \cdot 1 \cdot \sin 0^\circ = 0 \quad (\text{ayrı, doğrultuda})$$

$$|\vec{i} \times \vec{j}| = 1 \cdot 1 \cdot \sin 90^\circ = 1$$

$\vec{i}$

$\vec{j}$

$\vec{k}$

$$\vec{i} \times \vec{j} = \vec{k}$$

$$\vec{j} \times \vec{k} = \vec{i}$$

$$\vec{k} \times \vec{i} = \vec{j}$$

$$\vec{j} \times \vec{i} = -\vec{k}$$

Soru:  $\vec{A} \times \vec{B} = (A_x \cdot \vec{i} + A_y \cdot \vec{j} + A_z \cdot \vec{k}) \times (B_x \cdot \vec{i} + B_y \cdot \vec{j} + B_z \cdot \vec{k})$

$$[(A_x \cdot \vec{i}) \times (B_x \cdot \vec{i})] + [(A_x \cdot \vec{i}) \times (B_y \cdot \vec{j})] + [(A_x \cdot \vec{i}) \times (B_z \cdot \vec{k})] +$$

$$(A_x \cdot B_y) (\vec{k}) \quad (A_x \cdot B_z) (-\vec{j})$$

$$[(A_y \cdot \vec{j}) \times (B_x \cdot \vec{i})] + [(A_y \cdot \vec{j}) \times (B_y \cdot \vec{j})] + [(A_y \cdot \vec{j}) \times (B_z \cdot \vec{k})] +$$

$$(A_y \cdot B_x) (-\vec{k}) \quad (A_y \cdot B_z) (\vec{i})$$

$$[(A_z \cdot \vec{k}) \times (B_x \cdot \vec{i})] + [(A_z \cdot \vec{k}) \times (B_y \cdot \vec{j})] + [(A_z \cdot \vec{k}) \times (B_z \cdot \vec{k})]$$

$$(A_z \cdot B_x) (\vec{j}) \quad (A_z \cdot B_y) (-\vec{i})$$

$$= [(A_x \cdot B_y) \cdot (\vec{k})] + [(A_x \cdot B_z) \cdot (-\vec{j})] + [(A_y \cdot B_x) \cdot (-\vec{k})] + [(A_y \cdot B_z) \cdot (\vec{i})] +$$

$$[(A_z \cdot B_x) \cdot (\vec{j})] + [(A_z \cdot B_y) \cdot (-\vec{i})]$$

$$= [(A_y \cdot B_z) - (A_z \cdot B_y)] \vec{i} + [(A_z \cdot B_x) - (A_x \cdot B_z)] \vec{j} + [(A_x \cdot B_y) - (A_y \cdot B_x)] \vec{k}$$

(2.3.0)

$$\vec{A} \times \vec{B} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

$\Rightarrow +\vec{i} \cdot (A_y \cdot B_z - A_z \cdot B_y)$   
 $\Rightarrow -\vec{j} \cdot (A_z \cdot B_x - A_x \cdot B_z)$   
 $\Rightarrow +\vec{k} \cdot (A_x \cdot B_y - A_y \cdot B_x)$

$$C_x = A_y \cdot B_z - A_z \cdot B_y$$

$$C_y = A_z \cdot B_x - A_x \cdot B_z$$

$$C_z = A_x \cdot B_y - A_y \cdot B_x$$

$$\vec{C} = C_x \vec{i} + C_y \vec{j} + C_z \vec{k}$$

$$\text{Sonu} \vec{A} = 2\vec{i} + 4\vec{j} \quad \vec{B} = 2\vec{j} + 3\vec{k}$$

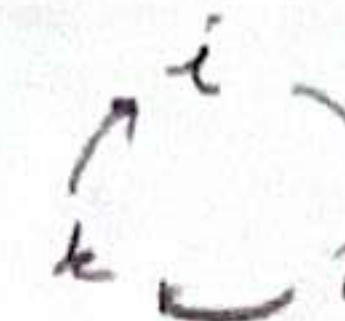
$$\textcircled{1} \quad \vec{C} = \vec{A} \times \vec{B}$$

$$(2\vec{i} \times 2\vec{j}) + (2\vec{i} \times 3\vec{k}) + (4\vec{j} \times 2\vec{j}) + (4\vec{j} \times 3\vec{k})$$

$$4\vec{k} + 6(-\vec{j}) + 0 + 12\vec{i}$$

$$\boxed{\vec{C} = 12\vec{i} - 6\vec{j} + 4\vec{k}}$$

$$\vec{A} \times \vec{B} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 2 & 4 & 0 \\ 0 & 2 & 3 \end{vmatrix} = +12\vec{i} - 6\vec{j} + 4\vec{k}$$



\textcircled{2}  $\vec{A}$  ve  $\vec{C}$  vektörlerinin direksiyon olutelerini gösteriniz

$$\vec{A} \cdot \vec{C} = (2\vec{i} + 4\vec{j}) \cdot (12\vec{i} - 6\vec{j} + 4\vec{k})$$

$$(2\vec{i} \cdot 12\vec{i}) + (2\vec{i} \cdot -6\vec{j}) + (2\vec{i} \cdot 4\vec{k}) + (4\vec{j} \cdot 12\vec{i}) + (4\vec{j} \cdot -6\vec{j}) + (4\vec{j} \cdot 4\vec{k})$$

$$(24, 1) + (-12, 0) + (8, 0) + (48, 0) + ((-24), 1) + (16, 0)$$

$$24 - 24 = 0$$

$$\vec{A} \cdot \vec{C} = A \cdot C \cdot \cos \theta$$

$$A = \sqrt{2^2 + 4^2} = \sqrt{20}$$

$$\frac{\vec{A} \cdot \vec{C}}{A \cdot C} = \cos \theta \quad \frac{0}{2\sqrt{5}} \Rightarrow 0$$

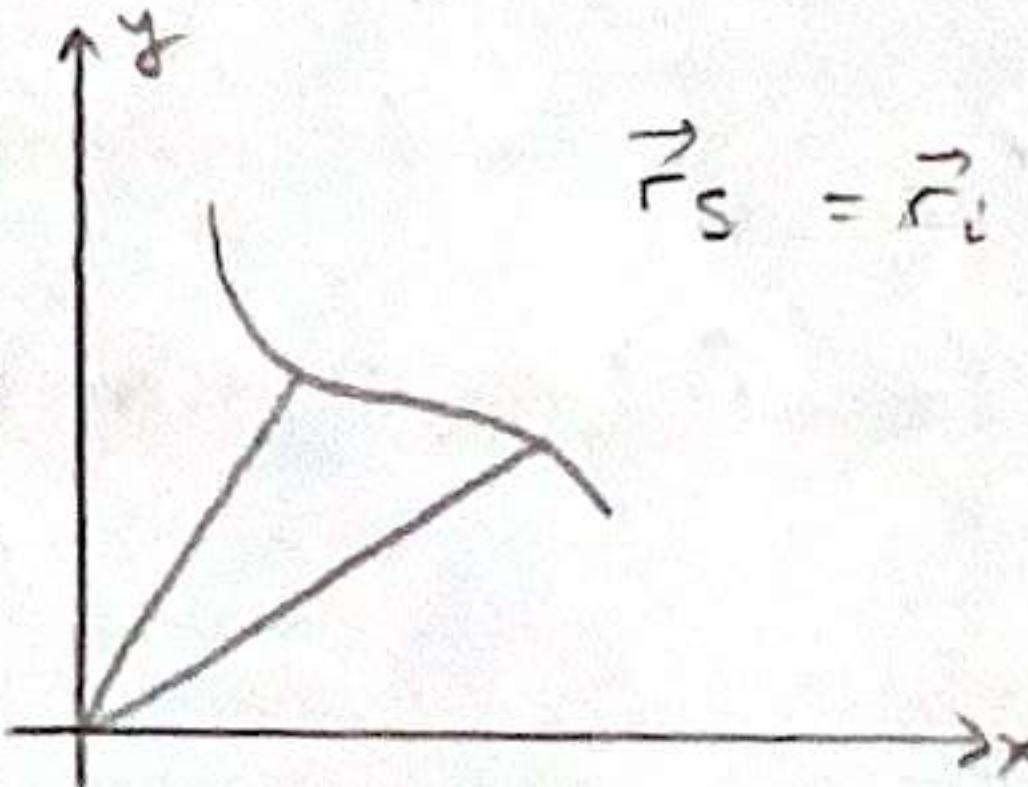
$$C = \sqrt{12^2 + (-6)^2 + 4^2} = 14$$

$$\boxed{\text{or} \cos 0 = 90^\circ}$$

13.10.2025 (devam)

Yer değiştirmeye, hitz ve time vektörleri

$$\vec{r} = x\vec{i} + y\vec{j} + z\vec{k}$$



$$\vec{r}_s = \vec{r}_i + \Delta \vec{r}$$

$$\vec{v} = \frac{\Delta \vec{r}}{\Delta t} = \frac{\vec{r}_s - \vec{r}_i}{t_s - t_i}$$

ortalama hız

$$\vec{v} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}}{\Delta t} = \frac{d\vec{r}}{dt} \rightarrow \text{anit hitz} \quad |\vec{v}| \Rightarrow \text{sırat}$$

$$\vec{a} = \frac{\vec{v}_s - \vec{v}_i}{t_s - t_i} = \frac{\Delta \vec{v}}{\Delta t}$$

ortalama hız

$$\vec{a} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{v}}{\Delta t} = \frac{d\vec{v}}{dt} \rightarrow \text{anit time}$$

$\rightarrow \vec{a}$  yerdeki  $\Delta \vec{v}$  hitz değişimini göstermek

Bu zamana sabit olusun da yine değişimse bu da herkeste varır

2 boyutlu

$$\vec{r} = x_s \vec{i} + y_s \vec{j}$$

$$\vec{v} = \frac{d\vec{r}}{dt} = \frac{dx}{dt} \vec{i} + \frac{dy}{dt} \vec{j} \Rightarrow \vec{v} = v_x \vec{i} + v_y \vec{j}$$

$$v_s = v_i + at \quad \vec{v}_i = v_{xi} \vec{i} + v_{yi} \vec{j}$$

$$v_{xi} = v_{xi} + a_{xt} \quad v_{yi} = v_{yi} + a_{yt}$$

$$\vec{v}_s = (v_{xi} + a_{xt}) \vec{i} + (v_{yi} + a_{yt}) \vec{j}$$

$$\vec{a} = a_x \vec{i} + a_y \vec{j} \quad \vec{v}_0 = v_{x0} \vec{i} + v_{y0} \vec{j} + v_{z0} \vec{k}$$

$$v_x = v_{x0} + a_{xt}; \quad v_y = v_{y0} + a_{yt}; \quad v_z = v_{z0} + a_{zt}$$

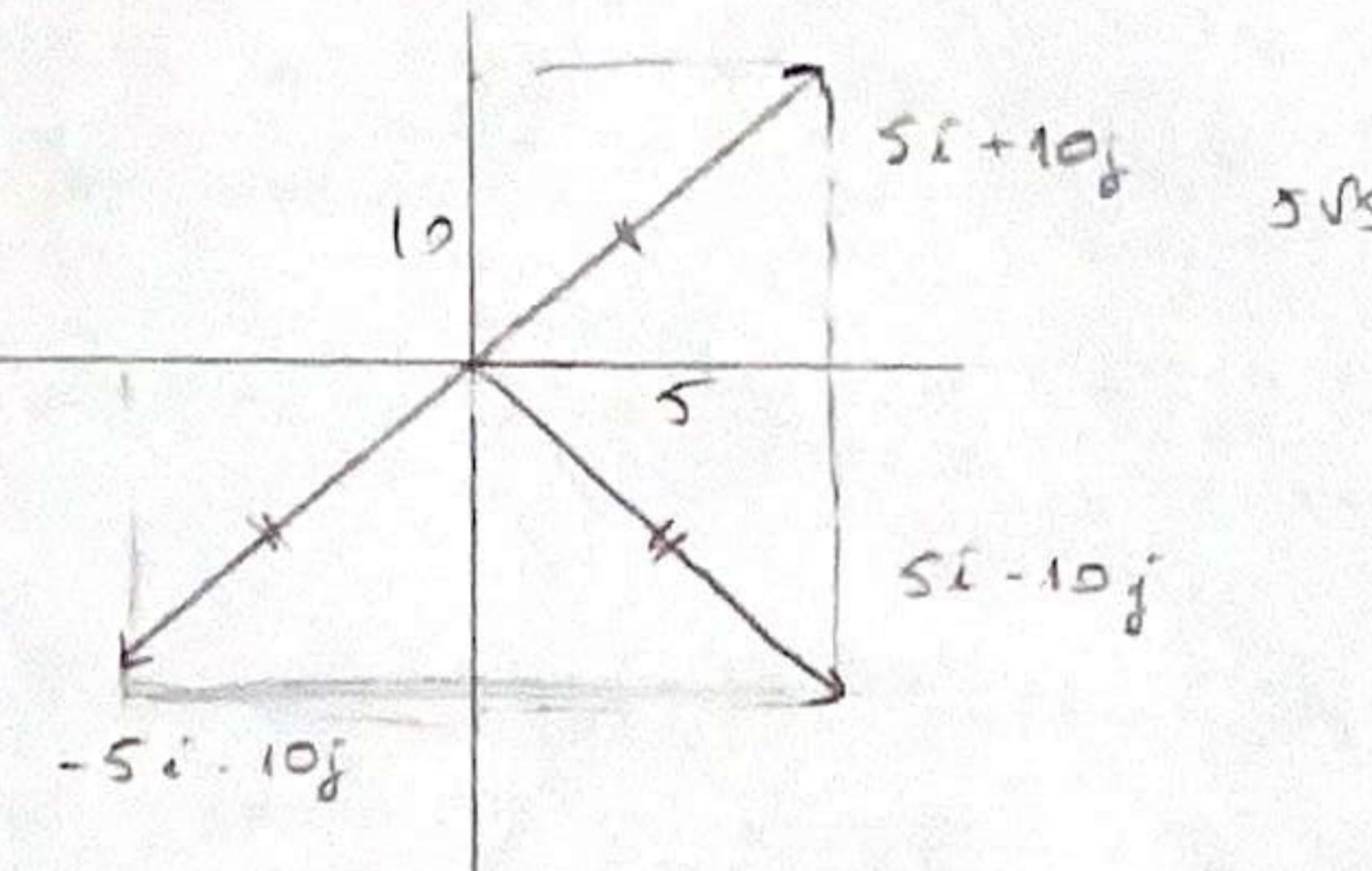
$$\vec{v} = (v_{x0} + a_{xt}) \vec{i} + (v_{y0} + a_{yt}) \vec{j} + (v_{z0} + a_{zt}) \vec{k}$$

$$\vec{v} = (v_{x0} \vec{i} + v_{y0} \vec{j} + v_{z0} \vec{k}) + (a_x \vec{i} + a_y \vec{j} + a_z \vec{k}) t$$

$$\vec{v} = \vec{v}_0 + \vec{a} \cdot t$$

$$\vec{a} = \frac{d\vec{v}}{dt} = \frac{d v_x}{dt} \vec{i} + \frac{d v_y}{dt} \vec{j} \quad \vec{a} = \frac{d^2 r}{dt^2} = \frac{d^2 x}{dt^2} \vec{i} + \frac{d^2 y}{dt^2} \vec{j}$$

$$\vec{a} = a_x \vec{i} + a_y \vec{j} \quad x_s = x_0 + v_{x0} t + \frac{1}{2} a_x t^2 \quad (\text{x bilisen})$$



$$\vec{r} = x \vec{i} + y \vec{j} \quad x = x_0 + v_{x0} t + \frac{1}{2} a_x t^2$$

$$y = y_0 + v_{y0} t + \frac{1}{2} a_y t^2$$

$$\vec{r} = (x_0 + v_{x0} t + \frac{1}{2} a_x t^2) \vec{i} + (y_0 + v_{y0} t + \frac{1}{2} a_y t^2) \vec{j}$$

$$\vec{r} = (x_0 \vec{i} + y_0 \vec{j}) + (v_{x0} \vec{i} + v_{y0} \vec{j}) t + \frac{1}{2} (a_x \vec{i} + a_y \vec{j}) t^2$$

$$= \vec{r}_0 + \vec{v}_0 t + \frac{1}{2} \vec{a} t^2$$

$$v_{x0} = 20 \text{ m/s} \quad v_{y0} = -15 \text{ m/s} \quad t = 3 \quad \begin{cases} x=0 \\ y=0 \end{cases}$$

$$a_x = 4 \text{ m/s}^2 \quad a_y = 0 \quad v_x = v_{x0} + a_x t$$

$$v_x = 20 + 4 \cdot 3 \quad | v_x = 40$$

$$v_y = v_{y0} + a_y t$$

$$v_y = -15 + 0 \quad | v_y = -15$$

$$\vec{v} = v_x \vec{i} + v_y \vec{j}$$

$$\vec{v} = 40 \vec{i} - 15 \vec{j}$$

$$\vec{v} = (40 + 4t) \vec{i} - 15 \vec{j} \text{ m/s}$$

Eğrilerde

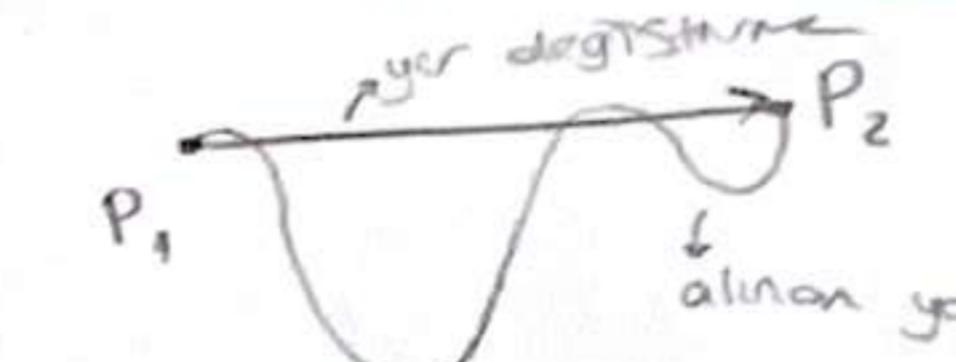
$$x = x_0 + v_{x0} t + \frac{1}{2} a_x t^2 \quad x = v_{x0} t + v_0 \cos \omega_0 t$$

$$y = y_0 + \frac{1}{2} a_y t^2 = v_{y0} t + v_0 \sin \omega_0 t - \frac{1}{2} a_y t^2$$

$$v_x = v_{x0} + a_x t = v_0 \cos \omega_0 t + a_y$$

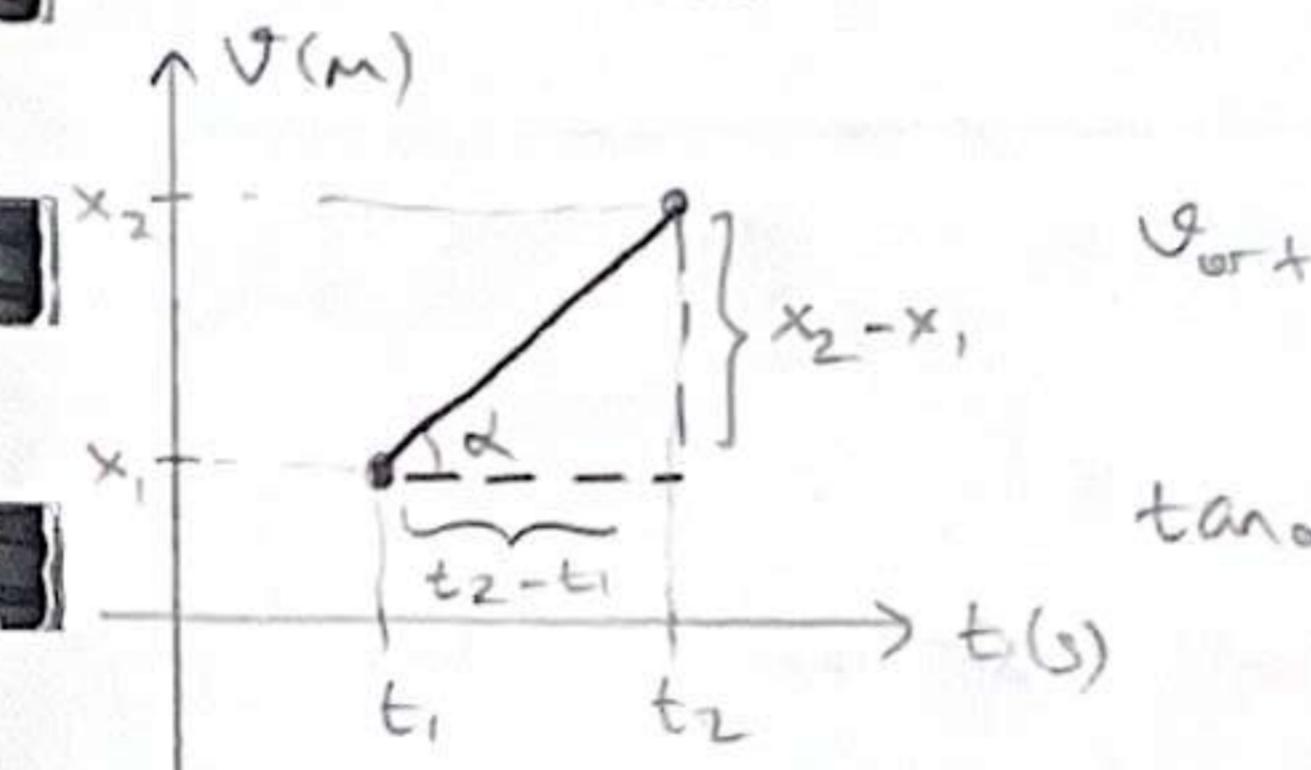
$$v_y = v_{y0} + a_y t = v_0 \sin \omega_0 t - a_x t \cos \omega_0$$

Bir boyutta hareket



$$\begin{aligned} & \Delta x = x_2 - x_1 \quad \boxed{\Delta \vec{x} = \vec{x}_2 - \vec{x}_1} \\ & \Delta \vec{x}: \text{vektör} \quad \rightarrow \vec{v}: \text{vektör (m/s)} \end{aligned}$$

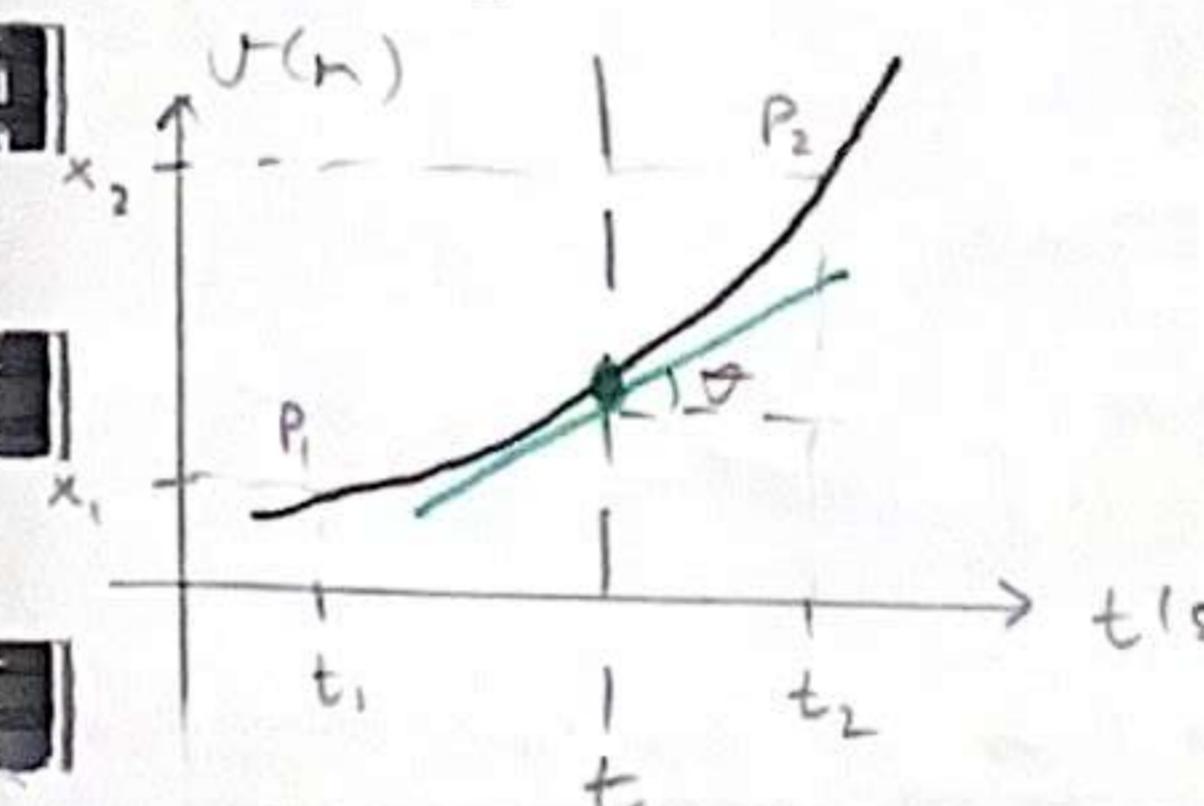
Ortalama hız



$$v_{\text{ort}} = \vec{v} = \frac{\Delta \vec{x}}{\Delta t} = \frac{\vec{x}_2 - \vec{x}_1}{t_2 - t_1}$$

$$\tan \alpha = \frac{\Delta x}{\Delta t}$$

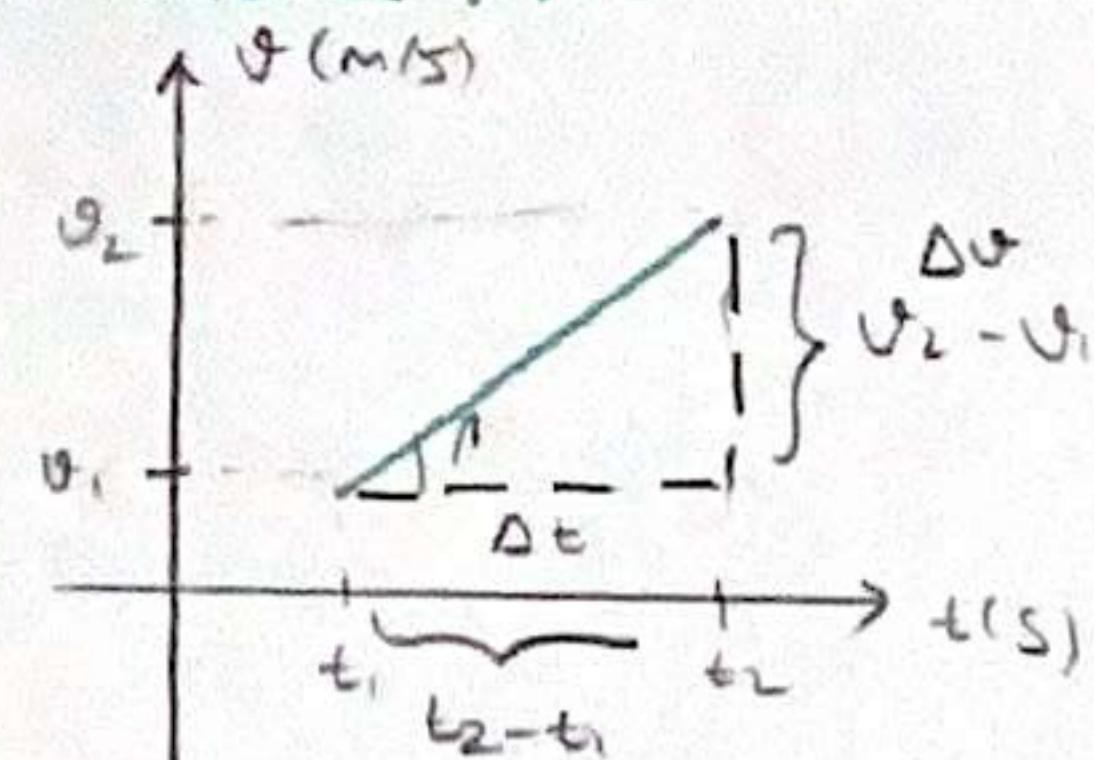
Ancı hız



$$\Delta t = t_2 - t_1 \rightarrow 0$$

$$v_x = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt} \quad \tan \theta = \frac{dx}{dt}$$

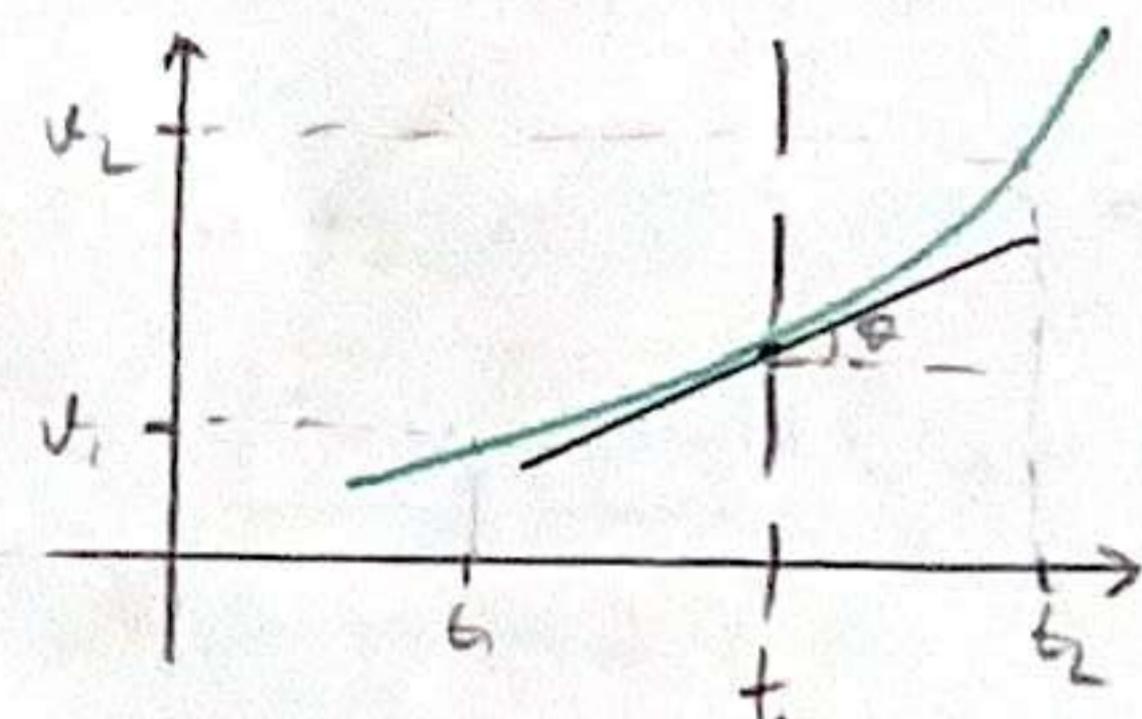
### Ortalama ivme



$$a_{\text{ort}} = \vec{a} = \frac{\Delta v}{\Delta t} = \frac{v_2 - v_1}{t_2 - t_1}$$

$$\tan \beta = \frac{\Delta v}{\Delta t} \quad \vec{\Delta v} \text{ vektör} \rightarrow \vec{a}: \text{ vektör}$$

### Ani ivme



$$\Delta t = t_2 - t_1 \rightarrow 0$$

$$a_x = \lim_{\Delta t \rightarrow 0} \frac{\Delta v}{\Delta t} = \frac{dv}{dt} \quad \tan \theta = \frac{dv}{dt}$$

**Örnek:** Bir CISM x-ekseni boyunca  $x(t) = (10t^2 + 2) \text{ m}$  denkleminde  
göre hareket etmektedir. ( $t: \text{saniye}$ )

a)  $t = 2 \text{ s}$ ,  $t = 4 \text{ s}$  arasındaki  $\Delta x = ?$   $v_{\text{ort}} = ?$

$$x(2) = 10 \cdot 2^2 + 2 = 42 \text{ m} \quad x(4) = 10 \cdot 4^2 + 2 = 162 \quad \Delta x = 162 - 42 = 120 \text{ m} = \Delta x$$

$$\frac{\Delta v}{\Delta t} = \frac{162 - 42}{4 - 2} = \frac{120}{2} = 60 \text{ m/s} = v_{\text{ort}}$$

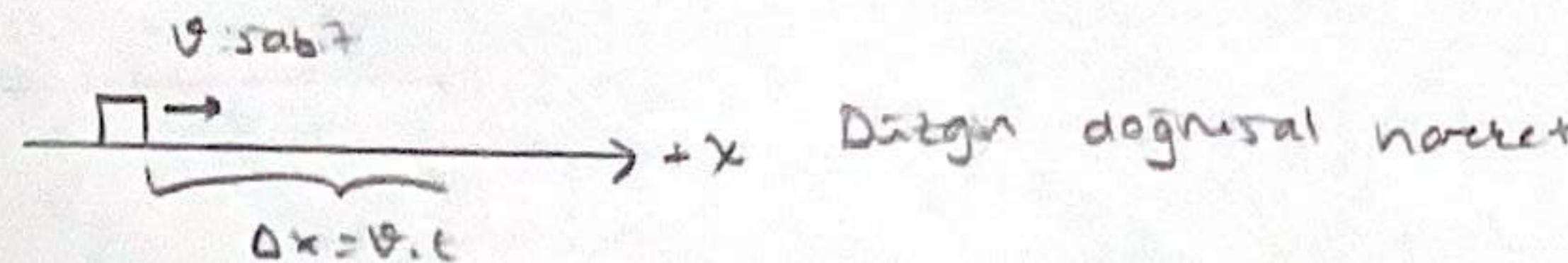
b)  $v$ ,  $a$  ani hiz ve ani itmevi ne dir?

$$v = \frac{dx}{dt} \Rightarrow 20t \quad v(2) = 40 \text{ m/s} \quad v(4) = 80 \text{ m/s}$$

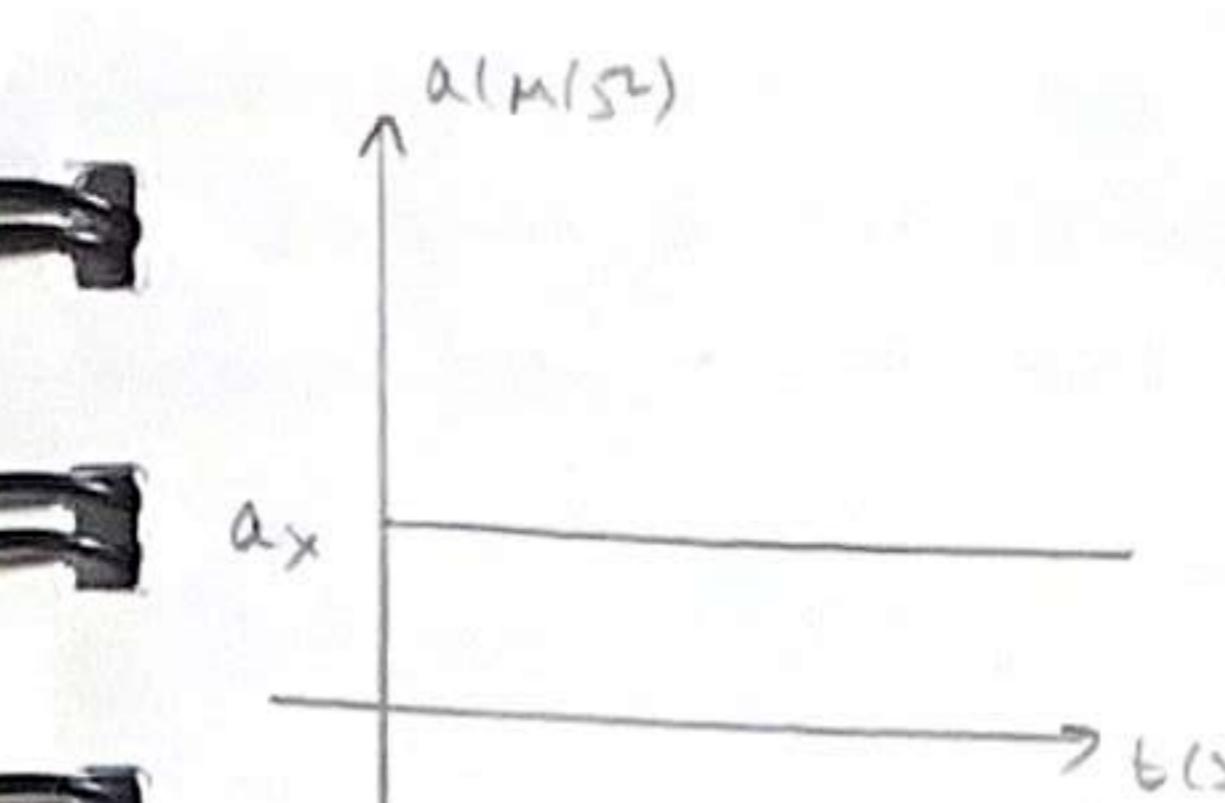
$$a = \frac{dv}{dt} = \frac{20t}{2} = 20 \text{ m/s}^2 \quad a(2) = 20 \text{ m/s}^2 \quad v(4) = 20 \text{ m/s}^2$$

ortalama ivme de esit cunku sabit

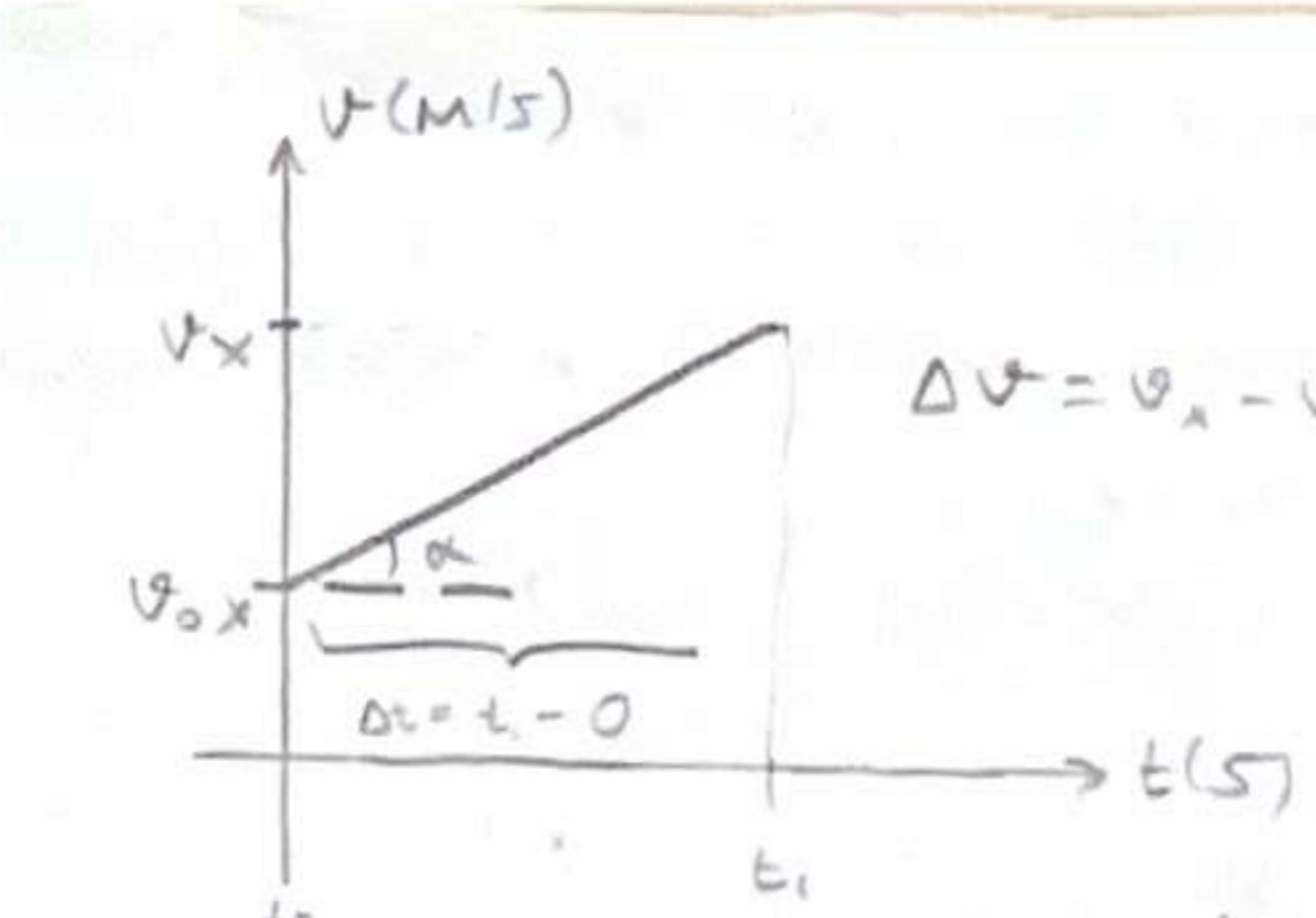
Bir bayutta hareket-kinematik



$$a_{\text{ort}} (\text{m/s}^2)$$



$$v(\text{m/s})$$



$$\Delta v = v_x - v_{0x}$$

$$a_x = \frac{\Delta v}{\Delta t} = \frac{v_x - v_{0x}}{t_2 - t_1}$$

$$a_x = \frac{v_x - v_{0x}}{t}$$

$$v_x = v_{0x} + a_x t$$

$$x = x_0 + v_{0x} t + \frac{1}{2} a_x t^2$$

$$\Delta x = v_{0x} t + \frac{1}{2} a_x t^2$$

$$v_x = v_{0x} + a_x t$$

$$a_x t = \frac{v_x - v_{0x}}{a_x}$$

$$\Delta x = v_{0x} \left( \frac{v_x - v_{0x}}{a_x} \right) + \frac{1}{2} a_x \left( \frac{v_x - v_{0x}}{a_x} \right)^2$$

$$\Delta x = \frac{v_x v_{0x} - (v_{0x})^2}{a_x} + \frac{1}{2} a_x \frac{(v_x - v_{0x})^2}{(a_x)^2} \quad | \quad 2v_x v_{0x} - 2v_{0x}^2 + v_x^2 - 2v_{0x} v_x + v_{0x}^2 = 2 \Delta x$$

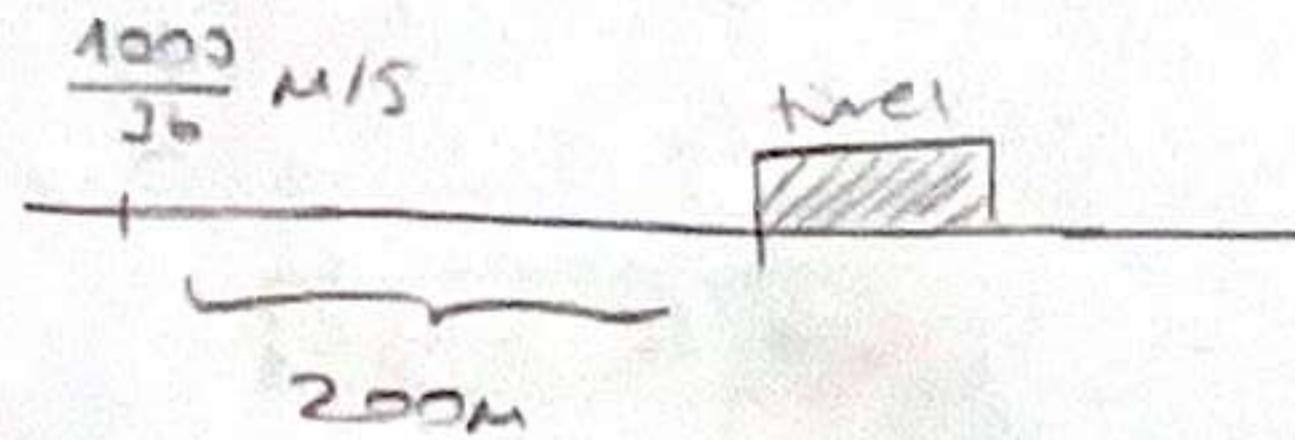
$$\frac{v_x^2 - v_{0x}^2}{a_x} = 2 \Delta x \Rightarrow v_x^2 = v_{0x}^2 + 2 a_x \Delta x$$

Soru: Hiz 100 km/h olan bir otomobilin hızının 200 m etrede belli tari  
görür ve sonra sabit bir time ile yavaşlayarak tari 70 km/h hizine getir.  
Sabit hizde hizet ederse 12 sn sonra tari 100 m/s2 time ile hız-  
lendirme 100 km/h hizine ulaşır.

a) Tari 100 km/h hizine kadar geçen süre?

b) Tari kaçtır?

c) Tari 100 km/h hizine kadar 12 sn içinde ulaşırsa ne hizde tari 100 km/h hizine ulaşır?



$$\Delta x = v_{0x}t + \frac{1}{2} a_x t^2$$

$$30 \cdot \frac{1000}{36} - \frac{300}{36} \text{ m/s} \Rightarrow \Delta v$$

$$200 = \frac{1000}{36} \cdot t - \frac{1}{2} \cdot \frac{300}{36} t^2$$

$$720 = 100t - 15t^2$$

$$7,35 = t ?$$

a)

$$v_x = v_{0x} + a_x t \quad \Delta x = v_{0x}t + \frac{1}{2} a_x t^2$$

$$\frac{v_x - v_{0x}}{a_x} = t$$

$$\Delta x = v_{0x} \cdot \left( \frac{v_x - v_{0x}}{a_x} \right) + \frac{1}{2} a_x \cdot \left( \frac{v_x - v_{0x}}{a_x} \right)^2$$

$$2a_x \left( \Delta x = \frac{v_{0x} \cdot v_x - (v_{0x})^2}{a_x} + \frac{1}{2} \frac{(v_x - v_{0x})^2}{a_x} \right)$$

$$2a_x \cdot \Delta x = \cancel{v_{0x} \cdot v_x} - \cancel{2v_{0x}^2} + v_x^2 - 2v_x v_{0x} + v_{0x}^2$$

$$2a_x \Delta x + v_{0x}^2 = v_x^2$$

$$2. a_x 200 + \left( \frac{1000}{36} \right)^2 = \left( \frac{700}{36} \right)^2$$

$$4a_x \cdot a_x = -17 \cdot \frac{300}{36}$$

$$a_x = -\frac{17 \cdot 300}{36 \cdot 36}$$

$$b) x = v \cdot t$$

$$x = \frac{700}{36} \cdot 12 \quad x = \frac{700}{3}$$

$$c) v_2^2 = v_1^2 + 2a_x \Delta x \Rightarrow \left( \frac{1000}{36} \right)^2 - \left( \frac{700}{36} \right)^2 = 2 \cdot \frac{1}{2} \cdot \Delta x$$

$$\frac{1700 \cdot 100}{36 \cdot 36} = 2 \cdot \Delta x$$

$$\frac{1700 \cdot 100}{72 \cdot 36} = \Delta x$$

$$v_2 = v_1 + a_t \quad \frac{1000}{36} - \frac{700}{36} = \frac{3}{2} \cdot t$$

$$\frac{300}{36} = \frac{3}{2} \quad \frac{100}{18} = t$$

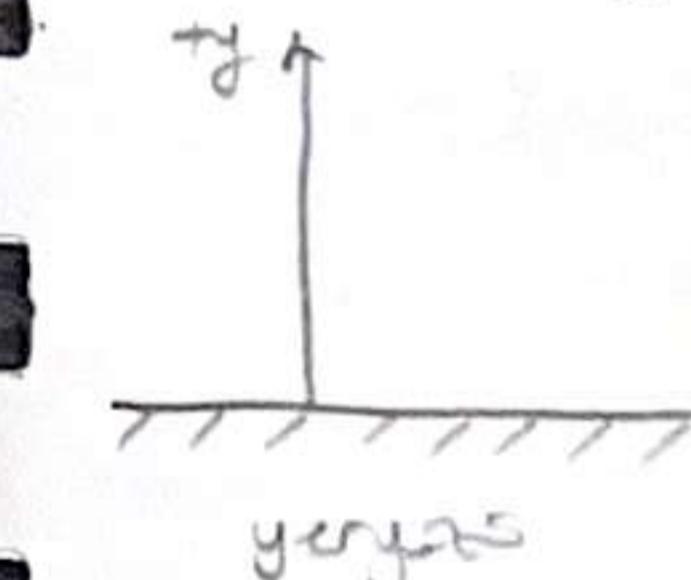
$$(w) \Delta x = v_{0x}t + \frac{1}{2} a_x t^2 \quad v_2 = v_1 + a_t$$

$$\frac{700}{36} \cdot t + \frac{1}{2} \cdot \frac{3}{2} \cdot t^2 \quad \frac{1000}{36} - \frac{700}{36} = \frac{3}{2} t \quad \frac{100}{18} = t$$

$$\Delta x = \frac{100}{18} \left( \frac{700}{36} + \frac{1}{2} \cdot \frac{3}{2} \cdot \frac{100}{18} \right)$$

$$\Delta x = \frac{100}{18} \cdot \frac{850}{36}$$

y-eksen: boyaca hizet



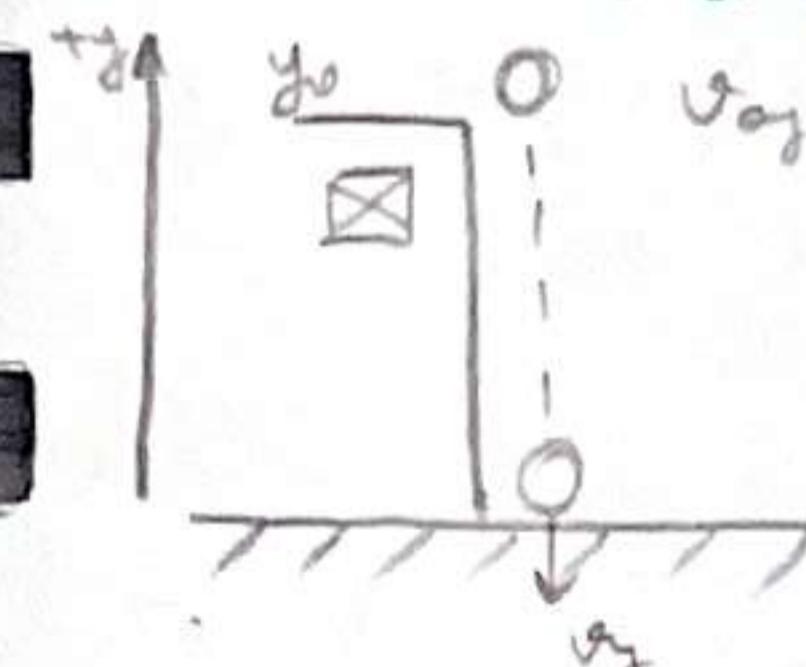
$$g = -9,8 \text{ m/s}^2$$

$$v_y = v_{0y} - gt$$

$$\Delta y = v_{0y}t - \frac{1}{2} g t^2$$

$$v_y^2 = v_{0y}^2 - 2g \Delta y$$

1) Serbest düşme ( $v_{0y} = 0$ )



$$v_y = v_{0y} - gt \Rightarrow v_y = -gt$$

$$\Delta y = v_{0y}t - \frac{1}{2} g t^2 \Rightarrow \Delta y = -\frac{1}{2} g t^2$$

$$v_y^2 = v_{0y}^2 - 2g \Delta y \Rightarrow v_y^2 = -2g \Delta x$$

2) Aşağıdan yekeri atış ( $v_{oy} > 0$ )

$$v_y = v_{oy} - gt$$

$$\Delta y = v_{oy}t - \frac{1}{2}gt^2$$

$$v_y^2 = v_{oy}^2 - 2g\Delta y$$

$$t_{\text{atm}} \Rightarrow v_y = v_{oy} - gt \quad \boxed{\frac{v_{oy}}{g} = t_{\text{atm}}}$$

$$t_{\text{atm}} \Rightarrow \Delta y = v_{oy}t - \frac{1}{2}gt^2 \quad \frac{1}{2}gt = v_{oy}$$

$$t_{\text{atm}} = \frac{2 \cdot v_{oy}}{g}$$

3) Yekeriden aşağıya atış ( $v_{oy} < 0$ )

$$v_y = -v_{oy} - gt$$

$$\Delta y = -v_{oy}t - \frac{1}{2}gt^2$$

$$v_y^2 = v_{oy}^2 - 2g\Delta y$$

BİRLİK: Yekeri 60 m olan bir binanın tepesinden serbest bırakılan bir cisim yerde zemine ve havada nereye düşer? ( $g = -9,8 \text{ m/s}^2$ )

$$v_y = v_{oy} - gt \quad \Delta y = v_{oy}t - \frac{1}{2}gt^2$$

$$v_y = 0 + 9,8t \quad 60 = \frac{9,8}{2}t^2$$

$$\boxed{v_y = \sqrt{9,8 \cdot 120}} \quad \boxed{\sqrt{\frac{120}{9,8}} = t}$$

BİRLİK: Yekeri 60 m olan bir binanın tepesinden yekeri degen 20 m/s hız ile atılan bir cisim yerde zemine ve havada nereye düşer?

( $g = 10 \text{ m/s}^2$ )

$$0 = v_{oy} - gt \quad 1) \quad \Delta y = v_{oy}t - \frac{1}{2}gt^2$$

$$0 = 20 - 10t \quad 2) \quad \Delta y = 20t - \frac{1}{2}10t^2$$

$$\boxed{\Delta y = 20t}$$

$$2) \quad 60 = v_{oy}t - \frac{1}{2} \cdot 10 \cdot t^2$$

$$v_{oy} = 10 \text{ m/s}$$

$$v_y = 0 - gt$$

$$60 = \frac{1}{2}10t^2 \quad \boxed{t=4}$$

BİRLİK: Yekeri 60 m olan bir binanın tepesinden asagi degen 20 m/s hız ile atılan bir cisim yerde zemine ve havada nereye düşer?

hesaplaması ( $g = 10 \text{ m/s}^2$ )

25 s sonra  $-40 \text{ m/s}$

$$v_y = v_{oy} - gt$$

$$\Delta y = v_{oy}t - \frac{1}{2}gt^2$$

$$60 = 20t + \frac{10}{2}t^2$$

$$12 = 4t + t^2 \quad t^2 + 4t - 12 = (t+6)(t-2)$$

$$\boxed{t=2 \text{ s}}$$

$$v_y = v_{oy} - gt$$

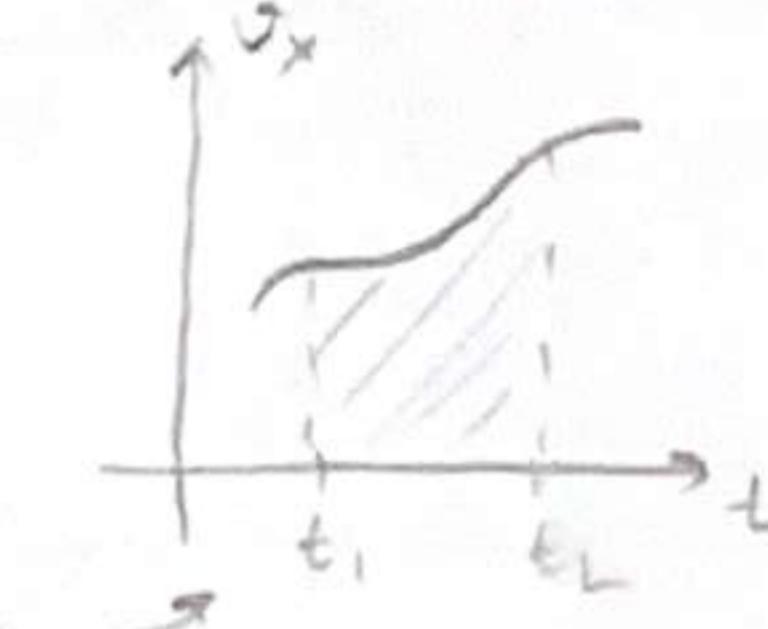
$$v_y = 20 - 10 \cdot 2 \Rightarrow \boxed{v_y = 40 \text{ m/s}}$$

Degişken hizmet hizmet

$$\Delta x = x_2 - x_1, \quad v_x = \frac{dx}{dt}, \quad a_x = \frac{dv_x}{dt}$$

$$\int_{x_1}^{x_2} dx = \int_{t_1}^{t_2} v_x dt$$

$$\cdot x \Big|_{x_1}^{x_2} = \int_{t_1}^{t_2} v_x dt$$



a)  $v_x$  sabit

$$\left. \begin{array}{l} v_x \\ t=0 \end{array} \right\} \int_{t_1}^{t_2} v_x dt = \int_{t_1}^{t_2} v_x \cdot dt = v_x \int_{t_1}^{t_2} dt = v_x (t_2 - t_1) = v_x \cdot t \quad \left. \begin{array}{l} v_x \\ t_2=t \end{array} \right\}$$

b)  $a_x$  sabit  $v_{ox}=0$

$$\left. \begin{array}{l} v_x \\ t=0 \end{array} \right\} \int_{t_1}^{t_2} v_x dt = \int_{t_1}^{t_2} (a_x t) dt = a_x \int_{t_1}^{t_2} t dt$$

$$\Delta x = x_2 - x_1 = \int_{t_1}^{t_2} v_x dt = \int_{t_1}^{t_2} (a_x t) dt = a_x \left( \frac{t^2}{2} \Big|_{t_1}^{t_2} \right) = \frac{1}{2} a_x t^2 \quad (v_{ox} = 0)$$

$$a_x = \frac{dv_x}{dt} \quad \int_{v_1}^{v_2} dv_x = \int_{t_1}^{t_2} a_x dt \quad \Delta v = v_2 - v_1 = \int_{t_1}^{t_2} a_x dt$$

Örnek: Bir cisim  $a_x = b + ct$  formesi ile hızının  $x$ -eşitinde hareket etmektedir. Cismin ilk hızı 5 m/s sonunda hız 40 m/s ve hizmet 18 m/s<sup>2</sup> ise  $b$  ve  $c$  nedir?

$$a_x = b + ct \quad 18 = b + c \cdot 4$$

$$v_2 - v_1 = \int_0^4 a_x dt$$

$$40 - 0 = \int_0^4 (b + ct) dt \Rightarrow 40 = bt \Big|_0^4 + \frac{ct^2}{2} \Big|_0^4$$

$$40 = 4b + 8c$$

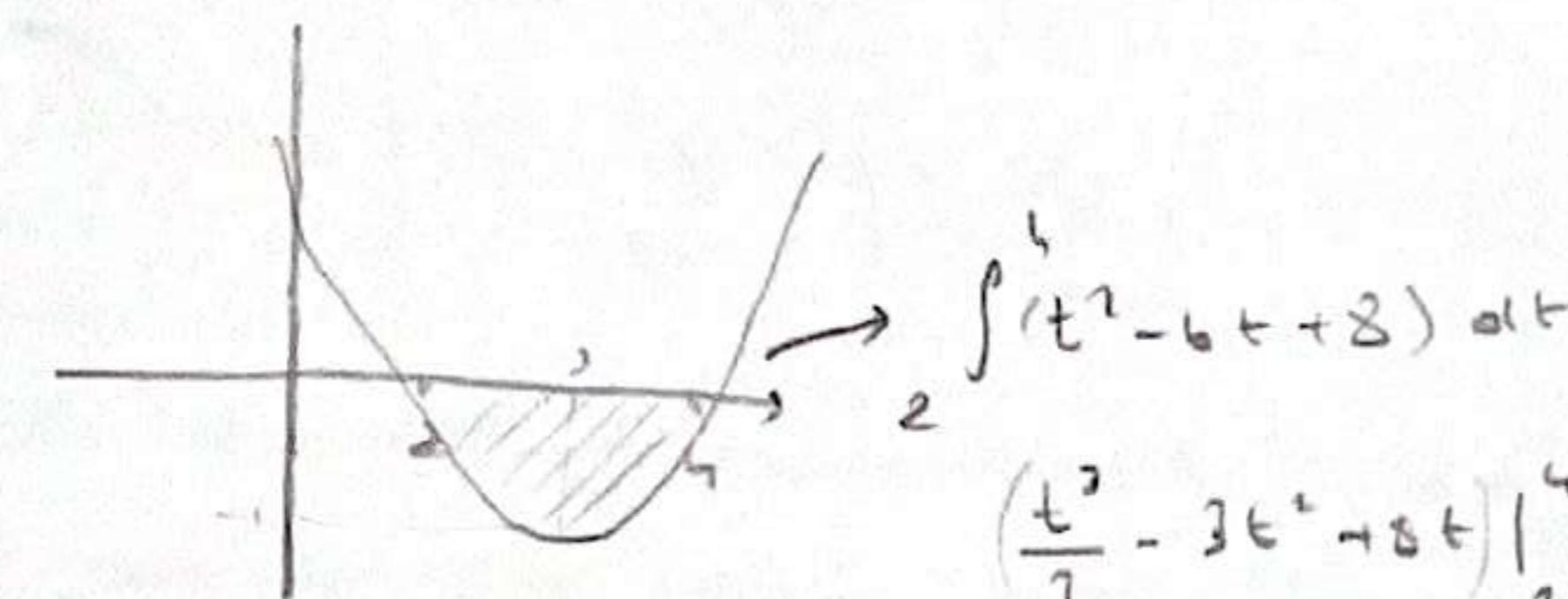
$$20 = 2b + 4c \quad [b=2] \quad [c=4]$$

Örnek: Bir cisim  $v_x = t^2 - 6t + 8$  hız denkleminde  $x$ -eşitinde hareket etmektedir.

a) Cismin hizi ne zaman sıfır olur? 2 ve 4 sn.

b)  $2 \leq t \leq 4$  aralığında yer değiştirmenin süresi nedir?

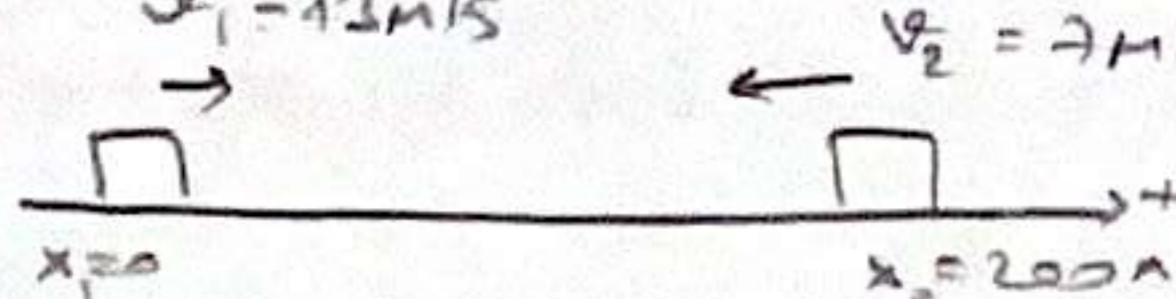
$$(t - 4)(t - 2)$$



$$\left( \frac{64}{3} - 48 + 32 \right) - \left( \frac{8}{3} - 12 + 8 \right)$$

$$\frac{64}{3} - 16 - \frac{8}{3} - 4 = \frac{56}{3} - 20 = -\frac{4}{3} \text{ m}$$

Örnek:  $v_1 = 12 \text{ m/s}$   $v_2 = 7 \text{ m/s}$  Ne zaman ve nereye konsoloslar?



$$\sqrt{x_1 - x_2} = t \Rightarrow (12+7) \cdot t = 200 \quad [t=10 \text{ s}]$$

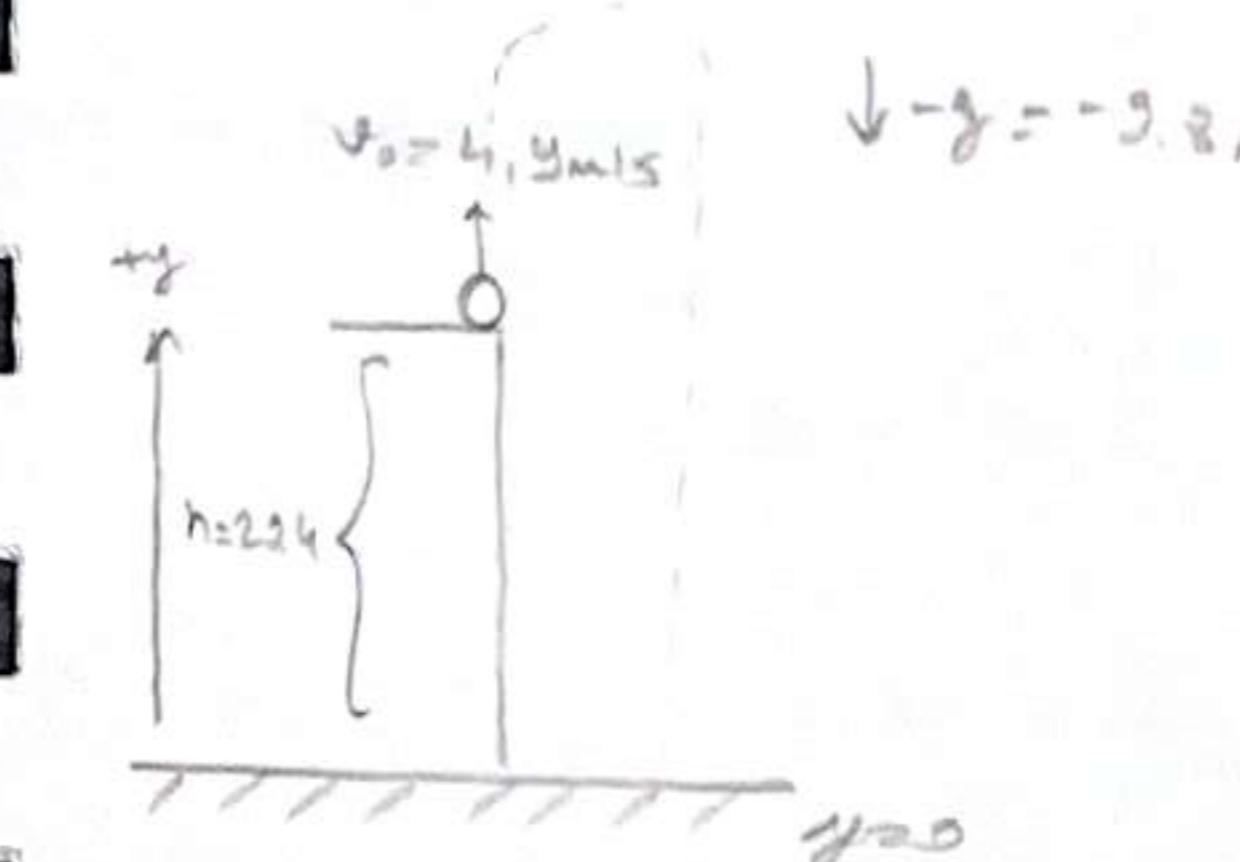
$$x_1(t) = v_1 \cdot t \\ x_2(t) = x_0 - v_2 t \quad x_1(t) = x_2(t) \quad 12t = 200 - 7t$$

Örnek: Bir BNR lokomotifin hızının  $x$ -eşitinde değişimi  $t=29.4 \text{ s}$  yararlaşılmıştır. İlk hızı  $v_0 = 4.9 \text{ m/s}$  boyunca 5 s ile 29.4 s arası 9.8 m/s<sup>2</sup> degerde yavaşlatılmıştır. Bu hızda  $g$  dir; ( $g = 9.8 \text{ m/s}^2$ )

a) Tazin hareket denklemini integral halinde bulunuz.

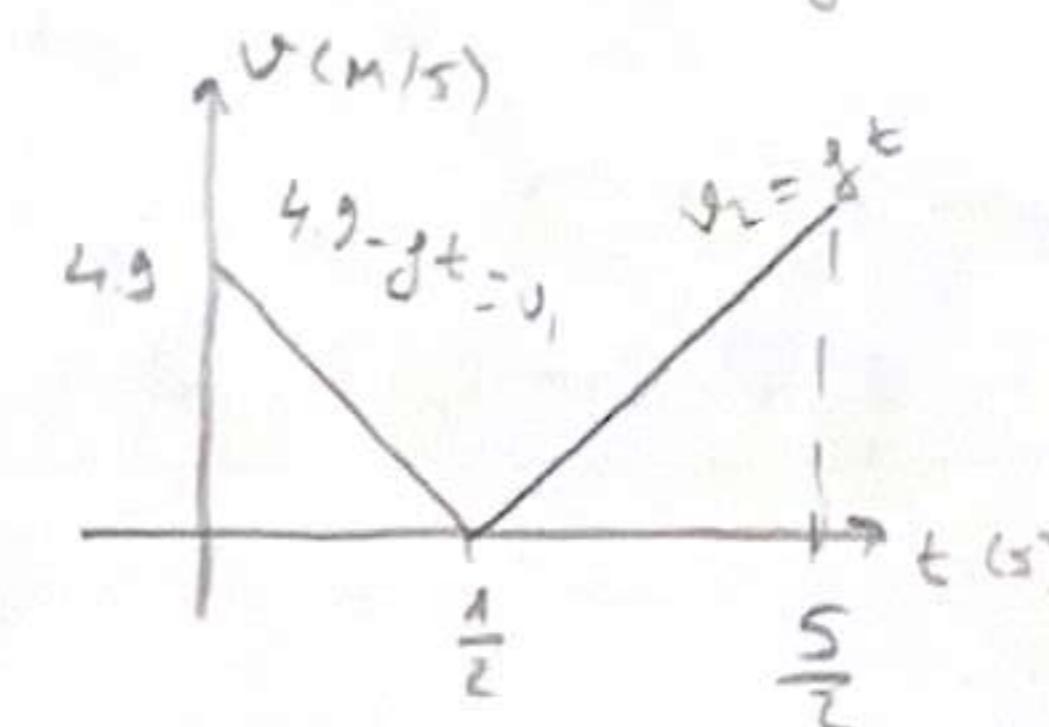
b) Tas yörüşe silm taze notasyonla ne kadar sürede ulaşır ve bu notasyonla yandan kaç metre yararlanmıştır?

c) Tas hızı düşürdüktan kaç saniye sonra yine aspor ve yine geriye dönüp nelerdir?



$$\text{I. durum } v_1 = v_0 - gt \quad v_1 = 4.9 - 9.8 \cdot 5$$

$$\text{II. durum } v_2 = 0 + gt \quad v_2 = 9.8 \cdot 5$$



$$\Delta x = v_{0x} t + \frac{1}{2} a t^2$$

$$\Delta x = (4.9) \frac{5}{2} + \frac{1}{2} (-9.8) \frac{25}{4}$$

$$\Delta x = \frac{(4.9)4 - (9.8)}{8} \cdot \frac{25}{4} = \frac{9.8 + 22.4}{4} = v_0 t - \frac{1}{2} g t^2$$

$$\Delta x = \frac{9.8}{4} \quad \frac{9.8 + 22.4}{4} = \frac{1}{2} (9.8) \cdot t^2$$

$$\frac{99.4}{19.6} = 1.56 \text{ s} \quad [t=2]$$

$$\text{a) } \int_{\frac{1}{2}}^{\frac{5}{2}} gt dt \Rightarrow \frac{(9.8) \cdot t^2}{2} \Big|_{\frac{1}{2}}^{\frac{5}{2}} = \frac{9.8 \cdot (\frac{5}{2})^2}{2} - \frac{9.8 \cdot (\frac{1}{2})^2}{2} = \frac{9.8}{2} (2.5) = 3.98 \Rightarrow 29.6 \text{ m}$$

$$\text{b) } \int_0^t (4.9 - gt) dt \Rightarrow (4.9) t - \frac{gt^2}{2} \Big|_0^{\frac{1}{2}} = (4.9) \cdot \frac{1}{2} - \frac{9.8 \cdot (1)^2}{2} = \frac{9.8}{2} - \frac{9.8}{8}$$

$$\text{b) } t = 1/2 \text{ sn} \quad x = \frac{9.8}{4} \cdot \frac{1}{4} + 29.4 = 1.245 + 29.4 \approx 30.6 \text{ m}$$

$$\text{c) } t = 5 \text{ sn} \quad |v| = 24.5 \text{ m/s} \quad -24.5 \text{ m/s}$$

$$a) t=0 \rightarrow v_0(0) = 4.9 \text{ m/s} \quad y(0) = h = 29.4 \text{ m}$$

$$\ddot{v} = \frac{dv}{dt} \quad a \cdot dt = dv \quad v = -g \int dt \Rightarrow -gt + A$$

$$v_0 = -g \cdot 0 + A \quad | A = v_0$$

$$v = \frac{dy}{dt} \quad dy = v \cdot dt \quad y^{(0)} = \int dy = \int v \cdot dt$$

$$= \int (v_0 - gt) dt$$

$$= v_0 t - \frac{1}{2} g t^2 + B$$

$$t=0 \text{ anında } y_0 = 29.4 \text{ m}$$

$$y(0) = v_0 \cdot 0 - \frac{1}{2} g \cdot 0 + B = h \quad | B = h \quad | y(t) = v_0 t - \frac{1}{2} g t^2 + 29.4$$

$$b) v(t) = v_0 - gt$$

$$0 = 4.9 - 9.8 t \quad 9.8 t = 4.9 \Rightarrow t = \frac{1}{2}$$

$$y(t) = v_0 t - \frac{1}{2} g t^2 + 29.4 \Rightarrow y(t) = (4.9) \frac{1}{2} - \frac{1}{2} (9.8) \frac{1}{4} + 29.4$$

$$\frac{9.8}{8} + 29.4 = 1.245 + 29.4$$

$$= 30.645$$

$$= 30.6 \text{ m}$$

$$c) t_{\text{hane}} = ?$$

$$y(t) = 29.4 + 4.9 t - 4.9 t^2 \Rightarrow v(t) = v_0 - gt$$

$$(t^2 - t - 6) \Rightarrow (t - 3)(t + 2)$$

$$t=3 \quad t=-2$$

$$= 4.9 - 9.8 \cdot 3 = -24.5 \text{ m/s}$$

iki veya üç boyutta hareket

$$\vec{r}_1 = x_1 \vec{i} + y_1 \vec{j} + z_1 \vec{k}$$

$$\vec{r}_2 = x_2 \vec{i} + y_2 \vec{j} + z_2 \vec{k}$$

$$\Delta \vec{r} = \vec{r}_2 - \vec{r}_1 = (x_2 - x_1) \vec{i} + (y_2 - y_1) \vec{j} + (z_2 - z_1) \vec{k}$$

$$\Delta x \quad \Delta y \quad \Delta z$$

ortalama hız

$$\vec{v}_{\text{ort}} = \vec{v} = \frac{\Delta \vec{r}}{\Delta t} = \frac{\Delta x}{\Delta t} \vec{i} + \frac{\Delta y}{\Delta t} \vec{j} + \frac{\Delta z}{\Delta t} \vec{k}$$

Arit米 hız

$$\vec{r} = x \vec{i} + y \vec{j} + z \vec{k} \quad \vec{r} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}}{\Delta t} = \frac{d \vec{r}}{dt}$$

$$\vec{v} = \frac{dx}{dt} \vec{i} + \frac{dy}{dt} \vec{j} + \frac{dz}{dt} \vec{k}$$

ortalama ivme

$$\vec{a}_{\text{ort}} = \vec{a} = \frac{\Delta \vec{v}}{\Delta t} = \frac{\vec{v}_2 - \vec{v}_1}{t_2 - t_1}$$

Arit米 ivme

$$\lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{v}}{\Delta t} = \frac{d \vec{v}}{dt}$$

$$\vec{a} = \frac{dv_x}{dt} \vec{i} + \frac{dv_y}{dt} \vec{j} + \frac{dv_z}{dt} \vec{k}$$

örnek Bir cisimin konum矢量  $\vec{r} = (10t^2 + 2) \vec{i} + (4t) \vec{j} + (2) \vec{k}$   $\text{m}$  olarla  
veriliyor Buna göre,

a)  $t=0$  ile  $t=2$  arasıda yer değiştirmesi,  $(40 \vec{i} + 8 \vec{j}) \text{ m}$

b)  $\text{t=0}$   $\Rightarrow$   $\text{t=2}$  arası ortalamama hızı,  $(20 \vec{i} + 4 \vec{j}) \text{ m/s}$

c)  $\text{t=0}$   $\Rightarrow$   $\text{t=2}$  arası hızı,  $t=0$ da  $(4 \vec{j}) \text{ m/s}$ ,  $t=2$ da  $(40 \vec{i} + 4 \vec{j}) \text{ m/s}$

d)  $\text{t=0}$   $\Rightarrow$   $\text{t=2}$  arası ortalamama ivmesi,  $20 \vec{i} \text{ m/s}^2$

e)  $\text{t=0}$   $\Rightarrow$   $\text{t=2}$  arası ivmesi bulunuz.  $\vec{a}_0 = \vec{a}_2 \Rightarrow$  Sabit

$$\begin{aligned} \text{a) } t=0 & \quad \vec{r}_0 = 2 \vec{i} + 2 \vec{k} & 42 \vec{i} + 8 \vec{j} + 2 \vec{k} \\ \text{b) } t=2 & \quad \vec{r}_2 = 42 \vec{i} + 8 \vec{j} + 2 \vec{k} & -2 \vec{i} - 2 \vec{k} \\ & & \hline 40 \vec{i} + 8 \vec{j} & = \Delta \vec{r} \end{aligned}$$

$$\text{b) } \vec{v}_{\text{ort}} = \frac{\Delta \vec{r}}{\Delta t} = \frac{40 \vec{i} + 8 \vec{j}}{2} = 20 \vec{i} + 4 \vec{j}$$

$$\text{c) } \vec{v} = \frac{d \vec{r}}{dt} = (20t) \vec{i} + 4 \vec{j} \quad \left. \begin{array}{l} t=0 \text{da } (4 \vec{j}) \text{ m/s} \\ t=2 \text{da } (40 \vec{i} + 4 \vec{j}) \text{ m/s} \end{array} \right\}$$

$$\text{d) } \frac{(40 \vec{i} + 4 \vec{j}) - (4 \vec{j})}{2} = (20 \vec{i}) \text{ m/s}^2$$

$$\text{e) } 20 \vec{i} \Rightarrow \vec{a}_0 = \vec{a}_2$$

↳ zamanla boyanır

Örnek: Bir cisimin ilk hizi  $\vec{V}_0 = 5\hat{j}$  m/s'ndir ve  $\vec{a} = (t+2)\hat{i} + 2\hat{j}$  m/s<sup>2</sup>'dir. İkinci hizet etdigi t=0 aninda cisim orjinde  $x_0=0$ ,  $y_0=0$  iki hizde sonraki konumunu ve hizini bulunuz.

$$\vec{a} = \frac{d\vec{v}}{dt} \Rightarrow \int d\vec{v} = \vec{a} \cdot dt \quad \vec{v} = \left(\frac{t^2}{2} + 2t + c_1\right) \hat{i} + (3t + c_2) \hat{j} \text{ m/s}$$

$$t=0 \quad \left(\frac{0^2}{2} + 2 \cdot 0 + c_1\right) \hat{i} + (3 \cdot 0 + c_2) \hat{j} \Rightarrow c_1 \hat{i} + c_2 \hat{j} = 5 \hat{j}$$

$c_1=0$        $c_2=5$

$$t=2 \quad \left(\frac{2^2}{2} + 2 \cdot 2 + 0\right) \hat{i} + (3 \cdot 2 + 5) \hat{j} \Rightarrow 6 \hat{i} + 11 \hat{j} \quad \boxed{\vec{v}_2 = 6\hat{i} + 11\hat{j}}$$

$$\vec{v} = \frac{d\vec{r}}{dt} \Rightarrow \int d\vec{r} = \int \vec{v} dt \quad \vec{r} = \left(\frac{t^3}{6} + t^2 + c_3\right) \hat{i} + \left(\frac{3t^2}{2} + 5t + c_4\right) \hat{j}$$

$$t=0 \quad (0 + 0 + c_3) \hat{i} + (0 + 0 + c_4) \hat{j} = c_3 \hat{i} + c_4 \hat{j} = 0 \hat{i} + 0 \hat{j}$$

$c_3=0$        $c_4=0$

$$t=2 \quad \left(\frac{2^3}{6} + 2^2\right) \hat{i} + \left(\frac{3 \cdot 2^2}{2} + 5 \cdot 2\right) \hat{j} = \frac{16}{3} \hat{i} + 16 \hat{j}$$

$$\boxed{\vec{r} = \frac{16}{3} \hat{i} + 16 \hat{j}}$$

Örnek: Bir parçacık 20 m/s'lik x bilesenli ve -15 m/s'lik y bilesenli ile nüfus t=0 anında baslangic hizetesinden hizetini hesaplayınız. Parçacık sadece  $a_x = 4 \text{ m/s}^2$  ile verilen ivmenin z bilesimli xy düzleminde hizet etmekte dir.

a) Zamanın fonksiyonu olarak hizetin bir anında hizini bilesenlerini ve toplan hiz sonrakini bulınız.  $\vec{v} = (20 + 4t) \hat{i} + (-15) \hat{j}$

b) t=5 anında parçacığın hizinin boyutları, yön ve doğrusal uzaklığı hesaplayınız.

$$v_{0x} = 20 \text{ m/s}, \quad a_x = 4 \text{ m/s}^2$$

$$v_{0y} = -15 \text{ m/s}, \quad a_y = 0 \text{ m/s}^2$$

$$\vec{v} = (20 + 4t) \hat{i} - 15 \hat{j}$$

$$\vec{v}_5 = (20 + 4 \cdot 5) \hat{i} - 15 \hat{j} \Rightarrow 40 \hat{i} - 15 \hat{j} \quad \frac{-15}{40} = -21^\circ \text{ 50m}$$

$$|v| = \sqrt{(-15)^2 + (40)^2} = \sqrt{225 + 1600} = 43 \text{ m/s}$$

Örnek: Bir cisimin ilk hiz bilesenleri  $v_{0x} = 12 \text{ m/s}$  ve  $v_{0y} = -9 \text{ m/s}$  olacak şekilde t=0 anında orjinde hizet etdigi  $x_0=0$ ,  $y_0=0$  iki hizde sonraki konumunu ve hizini bulunuz.

a) Cismin hizetin bir anında hizini ve denklemi bulınız.

b) Cismin hizetin bir anında konumunu ve denklemi bulınız.

$$\vec{v}_x = v_{0x} + a_x t \quad \vec{v}_x = (12 + 4t) \hat{i}$$

$$\vec{v}_y = v_{0y} + a_y t \quad \vec{v}_y = (-9 + 0 \cdot t) = (-9) \hat{j}$$

$$\boxed{\vec{v} = (12 + 4t) \hat{i} + (-9) \hat{j}}$$

1.ogel

$$\vec{r} = \frac{d\vec{r}}{dt} \Rightarrow \int d\vec{r} = \int \vec{v} dt \Rightarrow \vec{r} = (12t + 2t^2 + c_1) \hat{i} + (-9t + c_2) \hat{j}$$

$$\vec{r}_0 = (12 \cdot 0 + 2 \cdot 0^2 + c_1) \hat{i} + (-9 \cdot 0 + c_2) \hat{j}$$

$$\vec{r}_0 = c_1 \hat{i} + c_2 \hat{j} = 0 \hat{i} + 0 \hat{j}$$

$c_1=0$        $c_2=0$

$$\boxed{\vec{r} = (12t + 2t^2) \hat{i} + (-9t) \hat{j}}$$

2.yol  $\vec{r}(t) = x(t) \hat{i} + y(t) \hat{j} \quad t=0 \quad \begin{cases} x(0)=0 \\ y(0)=0 \end{cases} \quad \begin{cases} x = x_0 + v_{0x} t + \frac{1}{2} a_x t^2 \\ y = y_0 + v_{0y} t + \frac{1}{2} a_y t^2 \end{cases}$

$$\begin{cases} x(t) = 0 + 12t + \frac{1}{2} \cdot 4 \cdot t^2 \Rightarrow (12t + 2t^2) \hat{i} \\ y(t) = 0 + (-9t) + \frac{1}{2} \cdot 0 \cdot t^2 \Rightarrow (-9t) \hat{j} \end{cases} \quad \boxed{\vec{r}(t) = (12t + 2t^2) \hat{i} + (-9t) \hat{j}}$$

### Egit Atis

$$v_0 = v_0 \cos \theta_0 \hat{i} + v_0 \sin \theta_0 \hat{j}$$

$$v_x = v_0 \cos \theta_0$$

$$v_y = v_0 \sin \theta_0$$

$$\Delta x = v_x t = v_0 \cos \theta_0 t$$

$$y$$

$$a_y = -g$$

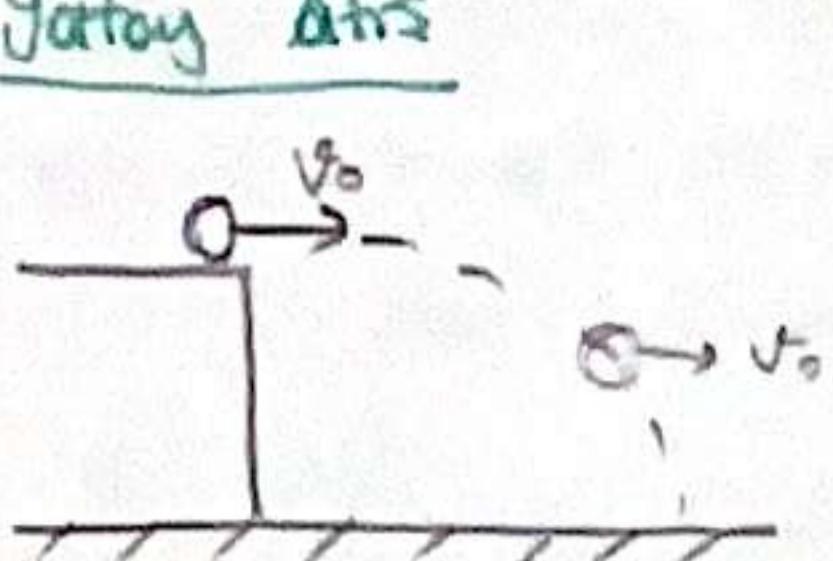
$$v_y = v_{0y} - g t$$

$$\Delta y = v_{0y} t - \frac{1}{2} g t^2$$

$$v_x^2 = v_{0x}^2 + 2 a_x \Delta x$$

$\rightarrow$  Sabit ivme hizet zomorit hiz denklemi

### Yatay Atış



$$x$$

$$v_x = v_{0x} = v_0$$

$$\Delta x = v_0 t$$

y

$$v_{y0} = 0 \quad (\theta = 0^\circ)$$

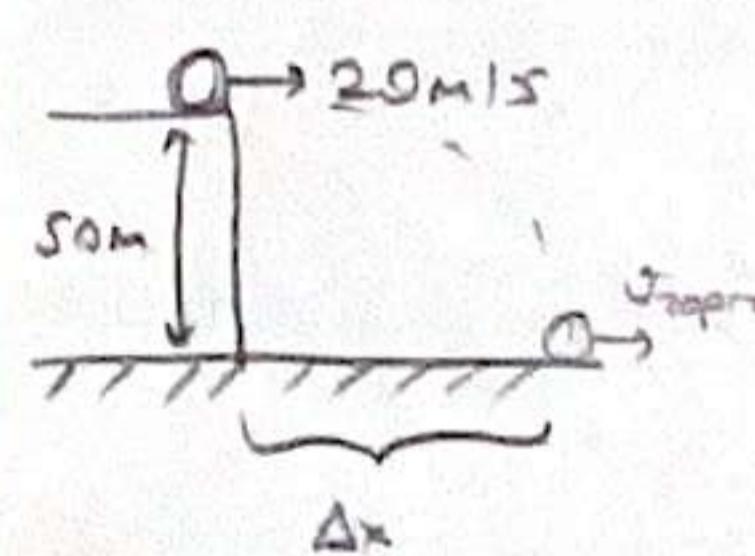
$$v_y = v_{y0} - gt$$

$$v_y = -gt$$

$$\Delta y = -\frac{1}{2}gt^2$$

Örnek: Bir cisim 50m yükseklikten yere paralel 20m/s hız ile atılıyor.

Cisimin havada kalma süresi ( $t_{wirs}$ ) ve x etekindeki toplam yarılabilirlik ( $\Delta x$ ) ve topraga çarpma zamanı ( $t_{topra}$ ) bulunuz ( $g \approx 10 \text{ m/s}^2$ )



$$x$$

$$v_x = v_0$$

$$20 \cdot t = \Delta x$$

$$\boxed{\Delta x = 20\sqrt{10} \text{ m}}$$

y

$$v_{y0} = -gt$$

$$\Delta y = -\frac{1}{2}gt^2$$

$$-50 = -\frac{1}{2} \cdot 10 \cdot t^2$$

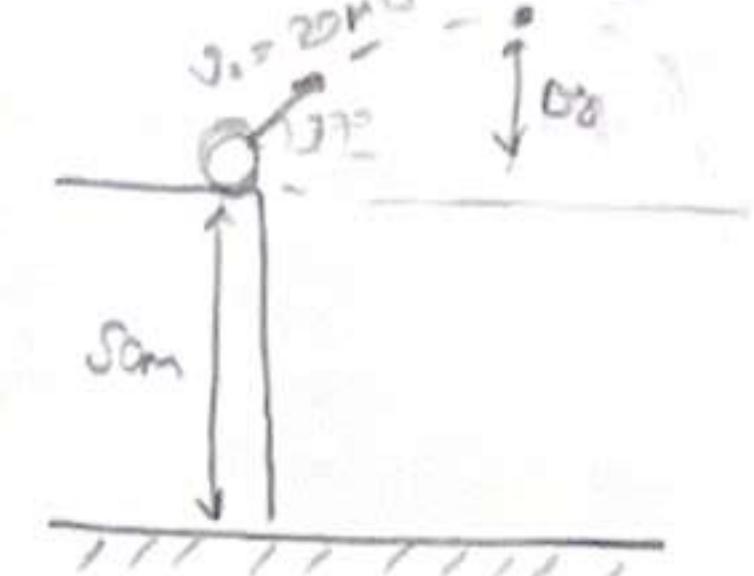
$$t = \sqrt{10} \text{ s}$$

$$v_y = -10\sqrt{10} \Rightarrow \boxed{v_y = -10\sqrt{10} \text{ m/s}}$$

Örnek: Bir cisim yerden  $50\text{m}$  yükseklikten ve yere göre  $37^\circ$  açı ile  $20\text{m/s}$

hızla atılıyor. Cisimin en üst noktası yukarı yukarı süresi ( $t_{wirs}$ ), atılabilirlik ( $\Delta x$ ), havada kalma süresi ( $t_{wirs}$ ) ve x-eksindeki alacağı yarım ( $\Delta y$ ) hesaplayınız ( $\cos 37^\circ = 0,8$ ;  $\sin 37^\circ = 0,6$ ;  $g \approx 10 \text{ m/s}^2$ )

yol ( $\Delta x$ ) hesaplayınız ( $\cos 37^\circ = 0,8$ ;  $\sin 37^\circ = 0,6$ ;  $g \approx 10 \text{ m/s}^2$ )



$$x$$

$$v_x = v_{0x} = v_0 \cos \theta$$

$$v_x = 20 \cdot 0,8$$

$$\boxed{v_x = 16 \text{ m/s}}$$

$$v_y = v_{0y} - gt$$

$$0 = 12 - 10 \cdot t$$

$$t = 1,2 \text{ s}$$

$$\Delta y = v_{0y} t - \frac{1}{2}gt^2$$

$$12 (1,2 - 0,6)$$

$$12 \cdot 0,6 = 7,2 \text{ m}$$

$$h_{max} = y_0 + \Delta y$$

$$= 50 + 7,2$$

$$\boxed{h_{max} = 57,2 \text{ m}}$$

$$\Delta y = v_{0y} \cdot t - \frac{1}{2}gt^2$$

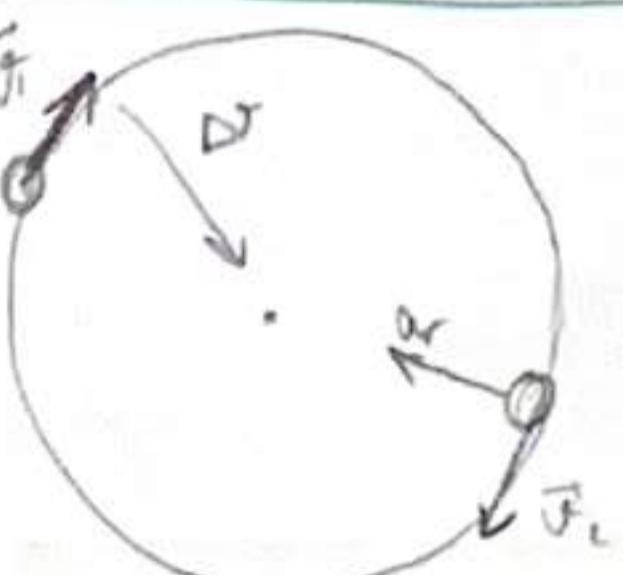
$$-50 = 12 \cdot t - \frac{1}{2} \cdot 10 \cdot t^2$$

$$5t^2 - 12t - 50 = 0$$

$$t = 4,58 \text{ s}$$

$$\Delta x = v_{0x} \cdot t \Rightarrow \Delta x = 16 \cdot 4,58 \Rightarrow \boxed{\Delta x = 73,28 \text{ m}}$$

### Düzen dairesel hareket



$$|\vec{v}_1| = |\vec{v}_2|$$

a radyan = a merkezden rme

$$ar = \frac{v^2}{r}$$

T: periyot

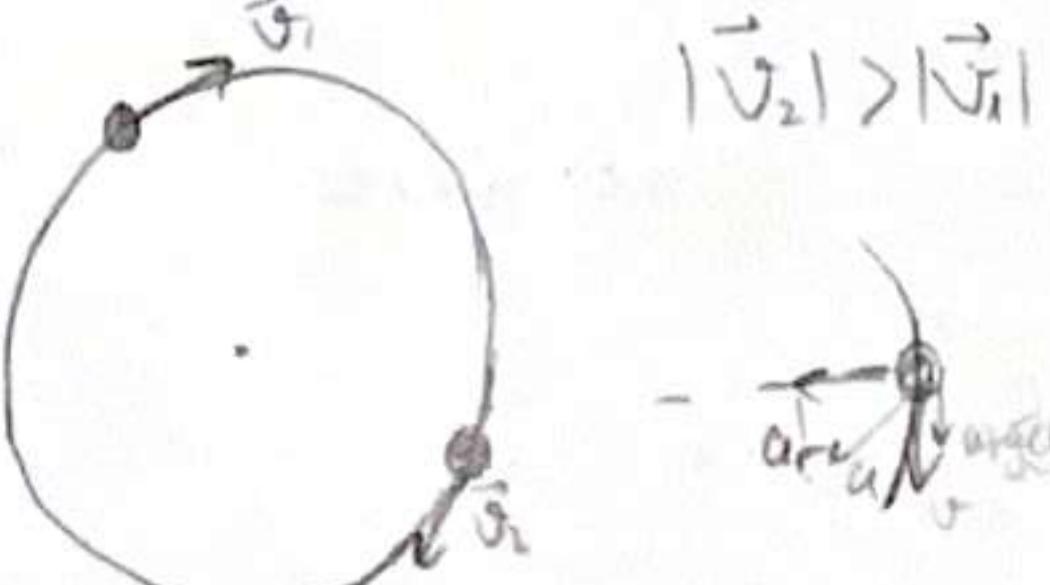
$$x = v \cdot t$$

$$2 \pi r = v \cdot T$$

$$T = \frac{2\pi r}{v}$$

$$f = \frac{v}{2\pi r}$$

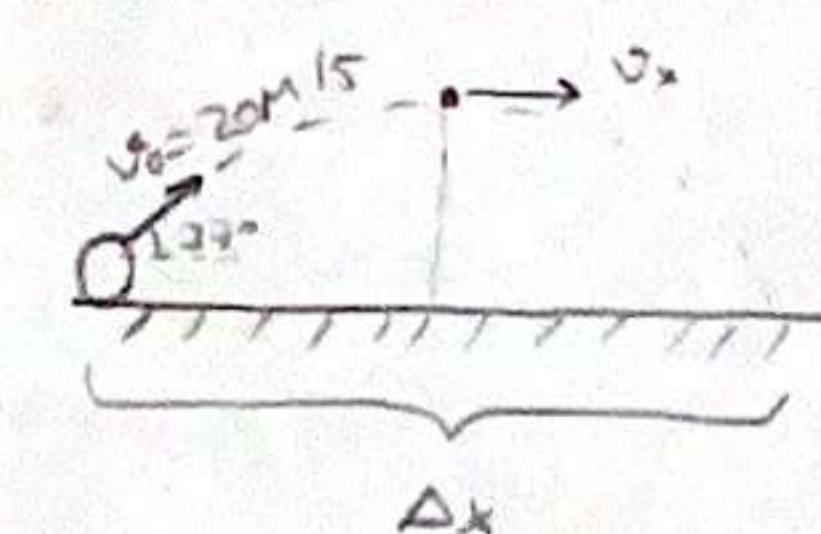
### Düzen olmayan dairesel hareket



$|\vec{v}_2| > |\vec{v}_1|$  se atıldıktan sonra, yine de hizla oynadı

$$a = \sqrt{a_r^2 + a_{tang}^2}$$

$|\vec{v}_2| < |\vec{v}_1|$  se atıldıktan sonra hizla durdu



$$x$$

$$v_x = v_{0x} = v_0 \cos \theta$$

$$v_x = 20 \cdot 0,8$$

$$\boxed{v_x = 16 \text{ m/s}}$$

$$\Delta x = v_x \cdot t_{wirs}$$

$$\Delta x = 16 \cdot$$

$$v_y = v_{0y} - gt$$

$$v_{y2} = v_{0y} - gt_{wirs}$$

$$\Delta y = -\frac{1}{2}gt^2$$

$$-12 = 12 - 10 \cdot t \quad t = 2,45$$

$$0 = 12 - 10 \cdot t_{wirs}$$

$$t_{wirs} = 1,25$$

$$\Delta y = -\frac{1}{2} \cdot 10 \cdot \frac{1}{2,45} \text{ m}$$

$$\Delta y = 7,2 \text{ m}$$

$$\boxed{h_{max} = 7,2 \text{ m}}$$

Örnek Bir cisim 40 m yükseklikte düşmesel bir yarımçık etrafında 20 m/s hız  
la dönmektedir. Cisimin üzerine etki eden radikal türdeki etkilerin he-  
saplanması.

$$\text{Ardal} = \frac{v^2}{r} \Rightarrow \frac{20 \cdot 20}{40} \Rightarrow \boxed{\text{Ardal} = 10 \text{ m/s}^2}$$

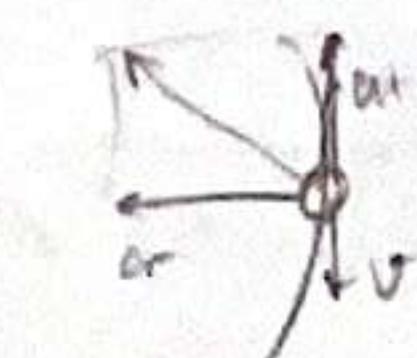
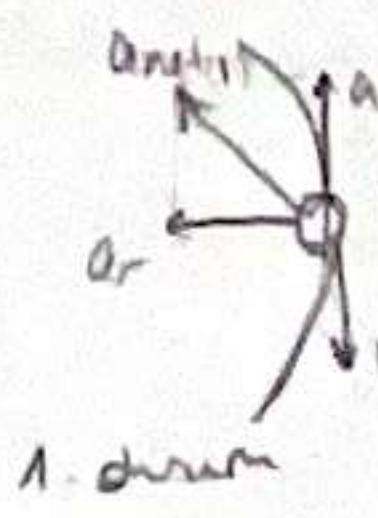
$$x = v \cdot t$$

$$2\pi r = v \cdot t$$

$$2 \cdot \pi \cdot 40^2 = 20 \cdot t \quad \boxed{t = 12.5 \text{ s}}$$

Örnek Bir cisim 40 m yükseklikte bir kemer etrafında sağa dönmekte paralel dönmektedir. Cisimin ortalama hızı olarak 20 m/s'den 10 m/s'ye değişmektedir. Hizmetin ortalama hızı 10 m/s'te olduğumuzda cisimin etrafında etki eden net türmeler hesaplanınız.

$$\text{Ardal} = \frac{v^2}{r} \Rightarrow \text{Ardal}_{(1)} = \frac{20 \cdot 20}{40} \Rightarrow \boxed{\text{Ardal}_{(1)} = 10 \text{ m/s}^2}$$



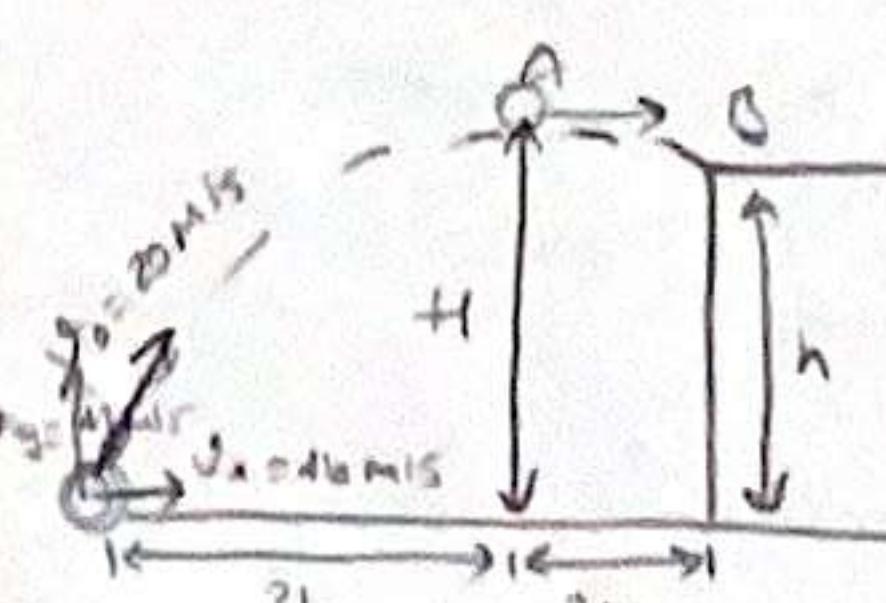
$$\text{Ardal}_{(1)} = \frac{10 \cdot 10}{40} = 2.5 \text{ m/s}^2$$

$$a_t = -2 \text{ m/s}^2$$

$$\text{Ardal}_{(2)} = \sqrt{\text{Ardal}_{(1)}^2 + a_t^2}$$

$$\sqrt{(2.5)^2 + (-2)^2} \Rightarrow \text{Ardal}_{(2)} = \sqrt{10.25} = \frac{\sqrt{41}}{2} \text{ m/s}^2$$

Örnek Yatayda  $37^\circ$  açılı yapan bir cisim 20 m/s hızla sağa doğru hareket etmektedir. Cisimin üzerine etki eden net türmelerin hesaplanması.



$$V_x = V_0 \cos 37^\circ$$

$$20 \cdot 0.8 = 16$$

$$V_y = V_0 \sin 37^\circ = 20 \cdot 0.6 = 12$$

$$V_x = V_0 \cos 37^\circ$$

$$0 = 12 - 9.8 t \quad \frac{60}{49} = t \Rightarrow 1.23 \text{ s}$$

$$\Delta y = V_{y0} t + \frac{1}{2} g t^2$$

$$\Delta y = 12 \cdot (1.23) - \frac{1}{2} (9.8) (1.23)^2$$

$$H = 7.35 \text{ m}$$

$$\Delta x = JL = V_0 \cdot 0.537 \cdot (1,23)$$

$$JL = 20 \cdot 0.8 \cdot 1.23$$

$$\frac{JL}{2L} = \frac{20 \cdot 0.8 \cdot t}{2 \cdot 0.8} \Rightarrow t = 0.325 \text{ s}$$

$$t_{\text{top}} = 1.23 + 0.325 = 2.055 \text{ s}$$

$$\Delta y = V_{y0} \cdot t - \frac{1}{2} g t^2 \Rightarrow \Delta y = 12 \cdot (2.05) - \frac{1}{2} \cdot (9.8) \cdot (2.05)^2 \Rightarrow \Delta y = 4.01 \text{ m}$$

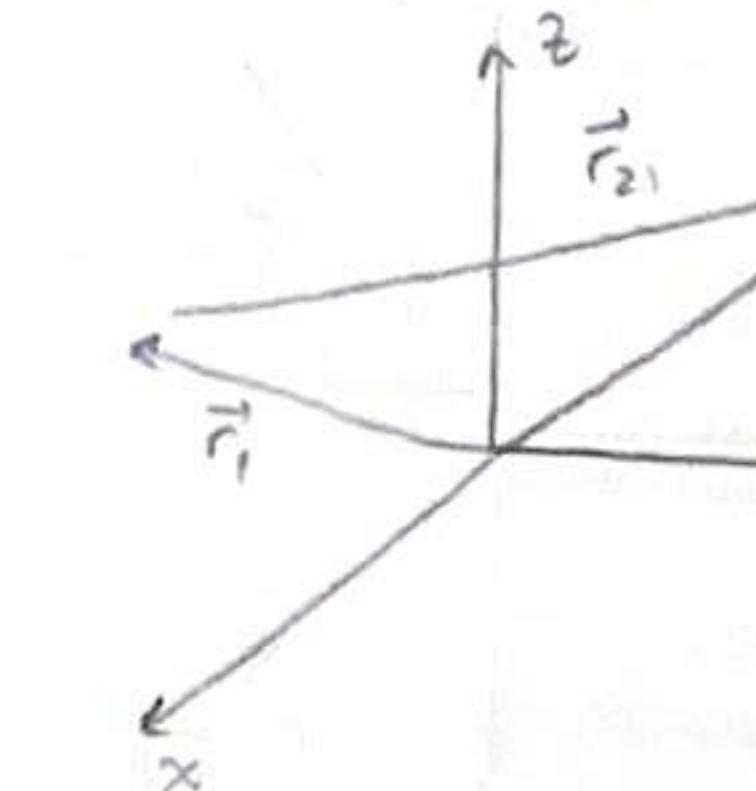
$$\frac{H}{h} = \frac{7.35}{4.01} = 1.83$$

$$\Delta y_{(1)} = V_{y0} \cdot t - \frac{1}{2} g t^2 \quad t = 0.325 \text{ s}$$

$$\Delta y_{(1)} = 0 - \frac{1}{2} (9.8) (0.325)^2$$

$$H - \Delta y_{(1)} = h$$

Örnek Birinin hızı  $v_1 = 200 \text{ m/s}$  boyunca sağa 53° koyduğu  
yandırma hizmeti olan bir uçağın pilotu, askeri bir helikopter  $v_2 = 70 \text{ m/s}$   
hızla gidey一起去 53° koyduğu uçağından geçer. Bu uçağın helikopterin  
birim-vektör notasyonunda bulunu  $v_2 = ?$

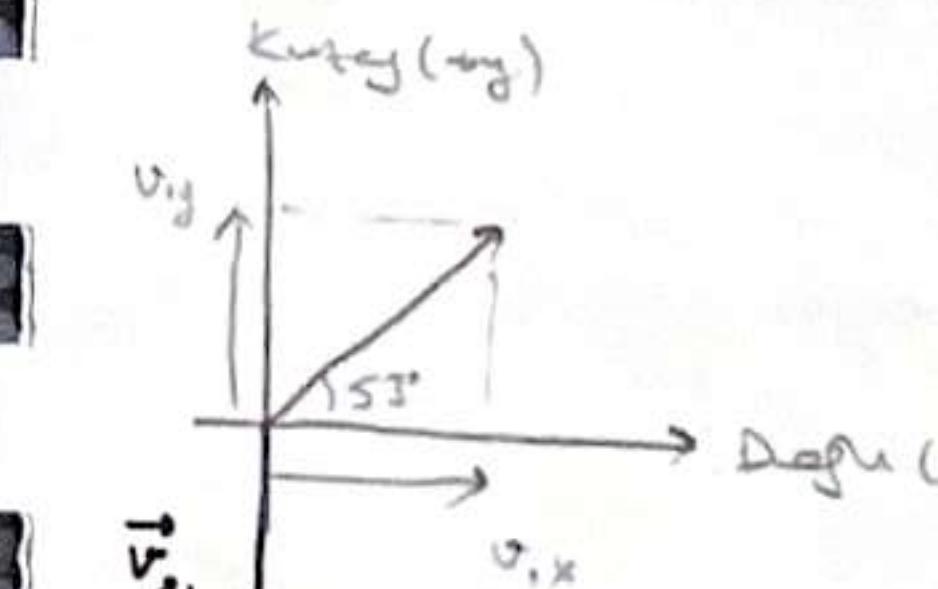


$$\vec{r}_1 + \vec{r}_{21} = \vec{r}_2$$

$$\vec{r}_{21} = \vec{r}_2 - \vec{r}_1$$

$$\frac{d \vec{r}_{21}}{dt} = \frac{d \vec{r}_2}{dt} - \frac{d \vec{r}_1}{dt} \quad \vec{v}_{21} = \vec{v}_2 - \vec{v}_1$$

helikopter  
bağlantıları



$$\vec{v}_1 = v_1 \cdot 0.537 \vec{i} + v_1 \cdot 0.866 \vec{j}$$

$$\vec{v}_1 = 120 \vec{i} + 160 \vec{j}$$

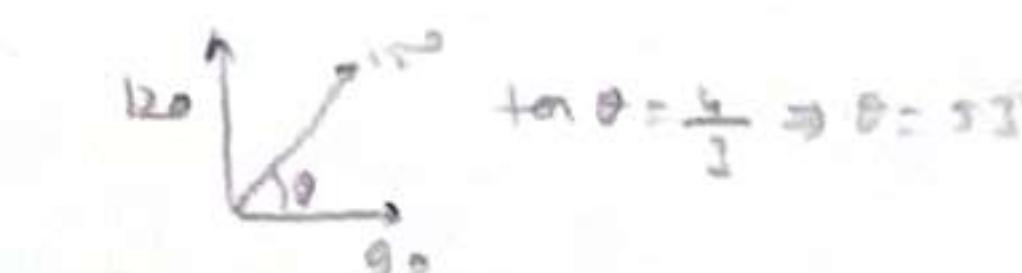
$$\vec{v}_{21} = -70 \vec{j}$$

$$\vec{v}_{21} = \vec{v}_2 - \vec{v}_1$$

$$-70 \vec{j} = \vec{v}_2 - (120 \vec{i} + 160 \vec{j})$$

$$\vec{v}_2 = (120 \vec{i} + 90 \vec{j})$$

$$v_2 = \sqrt{(120)^2 + (90)^2} = 150 \text{ m/s}$$



Örnek Üç boyutlu doğrultu hızının  $\vec{v} = 2t^2\vec{i} - 3t\vec{j} + 5\vec{k}$  (m/s) formülü veriliyor.  $t=2$  s zamanında hızının  $\vec{v}$  boyalı ifadesi:  $\vec{v} = 2t^2\vec{i} - 3t\vec{j} + 5\vec{k}$  (m/s) olmalıdır.

a) Hızının  $t=2$  s anında hizi:  $(8\vec{i} - 3\vec{j})$  m/s

b)  $t=0$  ve  $t=2$  s zaman aralığında ortalaması:  $(4\vec{i} - 3\vec{j})$  m/s

c)  $t=2$  s anında ivmesi:  $4\vec{i}$  m/s<sup>2</sup>

d)  $t=0$  ve  $t=2$  s zaman aralığında ortalamalı ivmesi:  $6\vec{i}$  m/s<sup>2</sup>

a)  $\frac{d\vec{v}}{dt} = 4t\vec{i} - 3\vec{j} \Rightarrow t=2 \quad 8\vec{i} - 3\vec{j}$  m/s

b)  $\vec{v}_{ort} = \vec{v} = \frac{\Delta\vec{v}}{\Delta t} = \frac{\vec{v}_{son} - \vec{v}_{ilk}}{t_{son} - t_{ilk}} \Rightarrow \vec{v}_2 = 8\vec{i} - 6\vec{j} + 5\vec{k}$   
 $\vec{v}_0 = 5\vec{i}$   
 $\frac{8\vec{i} - 6\vec{j}}{2-0} = (4\vec{i} - 3\vec{j})$  m/s

c)  $\frac{d\vec{v}}{dt} = 4\vec{i}$  m/s<sup>2</sup>

d)  $\vec{a}_{ort} = \vec{a} = \frac{\Delta\vec{v}}{\Delta t} = \frac{\vec{v}_{son} - \vec{v}_{ilk}}{t_{son} - t_{ilk}} = \frac{(8\vec{i} - 3\vec{j}) - (3\vec{j})}{2-0} = 4\vec{i}$  m/s<sup>2</sup>

Örnek  $t=0$  anında hızının  $\vec{v}_0 = -12\vec{i}$  m/s olan doğrultu bir parçacıkın ivmesinin zamanla boyalı ifadesi  $\vec{a} = 6t\vec{i} + 12t^2\vec{j}$  (m/s<sup>2</sup>) olmaktadır. Parçacık  $t=2$  anında hızının boyalı ifadesini bulınız.

a) Parçacık hızının  $t=2$  s zaman aralığının integrali ile elde ediniz.  
 $\vec{v} = (3t^2 - 12)\vec{i} + 4t^3\vec{j}$  (m/s) |  $\vec{v} = (t^2 - 12t)\vec{i} + t^4\vec{j}$  (m)

b) Parçacık P(-16, 16) koordinatlarında ne zaman geleceğini?

2 sn sonra ( $t=2$  anında)

c) Parçacık hızının  $x$  boyalı ifadesini ne zaman için degrasyon?

$t=2$  anında

a)  $\vec{a} = \frac{d\vec{v}}{dt} \Rightarrow \vec{a} \cdot dt = d\vec{v} \Rightarrow \int \vec{a} \cdot dt = \int d\vec{v}$

$\int (6t\vec{i} + 12t^2\vec{j}) dt = \int d\vec{v}$

$3t^2\vec{i} + 4t^3\vec{j} + \vec{A} = \vec{v} \Rightarrow t=0 \quad \vec{A} = -12\vec{i}$

$\boxed{\vec{v} = (3t^2 - 12)\vec{i} + 4t^3\vec{j}}$

$\vec{v} = \frac{d\vec{r}}{dt} \Rightarrow \vec{v} \cdot dt = d\vec{r} \Rightarrow \int \vec{v} \cdot dt = \int d\vec{r}$

$\int ((3t^2 - 12)\vec{i} + 4t^3\vec{j}) dt = \int d\vec{r}$

$\left( \frac{3t^3}{3} - 12t \right) \vec{i} + t^4\vec{j} + \vec{r}_0 = \vec{r} \quad \vec{r}_0 = 0 \quad \vec{r} = 0$

$\boxed{\vec{r} = (t^3 - 12t)\vec{i} + t^4\vec{j}}$

b)  $t^3 - 12t = -16 \quad t^4 = 16$   
 $\boxed{t=2}$

c)  $\vec{v} = (3t^2 - 12)\vec{i} + 4t^3\vec{j}$   
 $3t^2 - 12 = 0 \quad 3(t^2 - 4) = 0 \quad \boxed{t=2}$

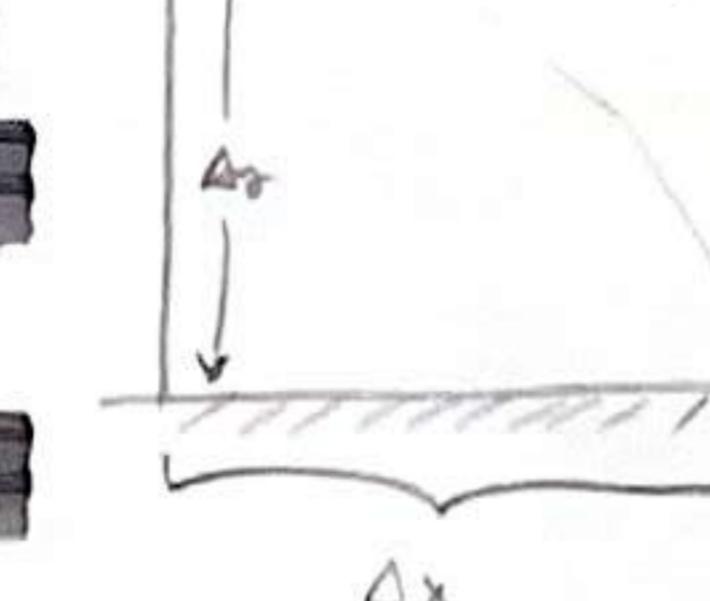
Örnek  $t=0$  anında, yandan hizasızlanan bir notasundan  $v_0 = 8$  m/s boyalı hızla yatağı olumsuz摩擦系数  $\mu$  ile taz, yere düşen taz yatağı boyalı hızla  $a = 2$  m/s<sup>2</sup> yol alıp gidiyor. Taz taz yatağı notasuna yataklaştıktan sonra yatağından kaçırılmıştır.

$\vec{v}_0 = 8\vec{i}$  |  $\vec{a} = 2\vec{i}$  |  $24 = v_0 \cdot t$  |  $24 = 8t$  |  $\boxed{t = 3}$  s

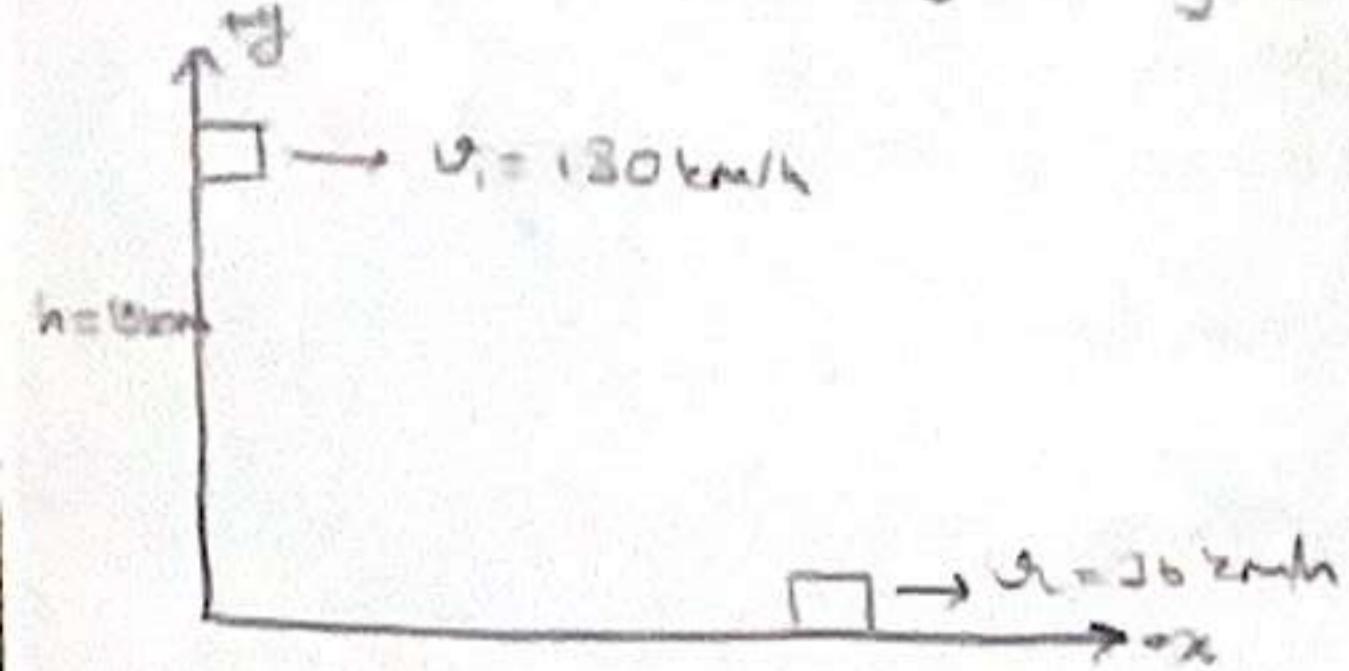
$\Delta y = v_0 y \cdot t - \frac{1}{2} g t^2$

$\Delta y = 0 \cdot 3 - \frac{1}{2} \cdot (9.8) \cdot 3^2 = \Delta y = 44.1$

$\frac{49 \cdot 9}{10}$

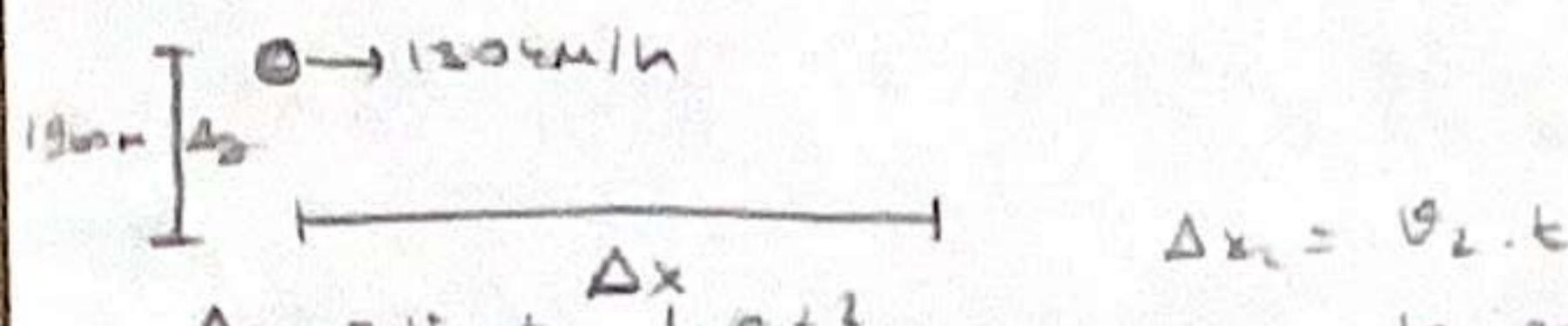


Örnek Bir savas ucu,  $v_1 = 180 \text{ km/h}$  boyutlukinden hizla yatacak degindende 10 s surede kendinden  $x$ -e utarla  $v_2 = 36 \text{ km/h}$  hizla merkezden etenin gecip bombasi, baska bir pilot bombasi yenden  $h = 1960 \text{ m}$  yatasurte birdeki tarihi tabiat koyulusturup girecektir.  $x$ -e utarligi nesnelerin.



$$180 \cdot \frac{10/60}{36/60} = 50 \text{ m/s} = v_1$$

$$36 \cdot \frac{10/60}{36/60} = 10 \text{ m/s} = v_2$$



$$\Delta x = v_0 \cdot t - \frac{1}{2} \cdot 9.8 \cdot t^2$$

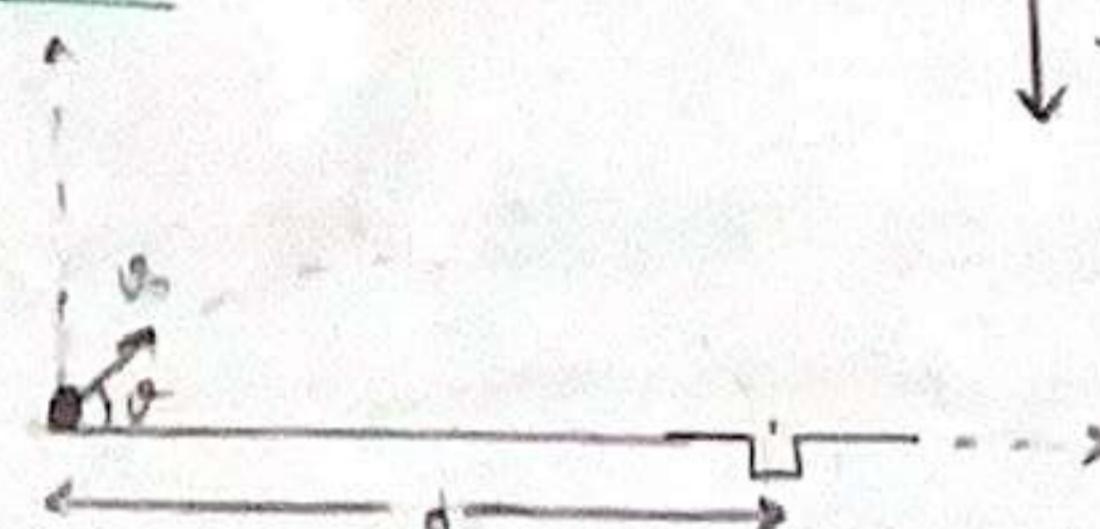
$$1960 = 0 \cdot t - \frac{1}{2} \cdot 9.8 \cdot t^2$$

$$t = 20$$

$$\Delta x = v_0 \cdot t$$

$$50 \cdot 20 = 1000$$

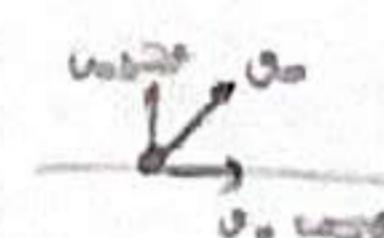
Örnek



a) Tasin atladiği nokteden d kadar utarltaki cisme girebilmesi için  $v_0$  ne olmalıdır? (Dirki degerlerle cinsinden)

$$b) d = 10 \text{ m}, g = 9.8 \text{ m/s}^2 \text{ ve } \theta = 15^\circ \text{ iki}$$

$v_0$  segizlik degerini bulunuz



$$(v_0 \cos \theta) \cdot t = d$$

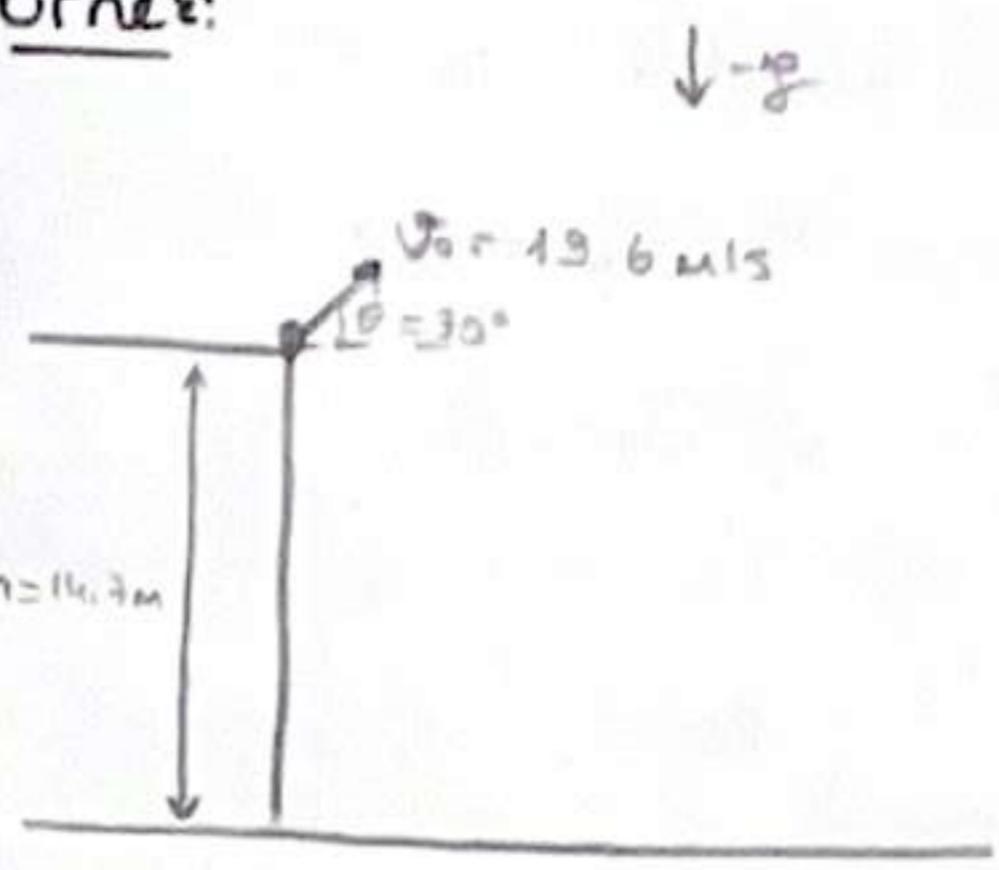
$$-v_0 \sin \theta = v_0 \sin \theta - gt$$

$$t = \frac{2v_0 \sin \theta}{g}$$

$$v_0 \cdot \cos \theta \cdot \frac{2v_0 \cdot \sin \theta}{g} = d \quad v_0 = \sqrt{\frac{d \cdot g}{2 \sin(2\theta)}}$$

$$\sqrt{\frac{10 \cdot 9.8}{2}} = \Rightarrow v_0 = 14 \text{ m/s}$$

Örnek:



$$v_0 = 19.6 \text{ m/s} \quad v_{oy} = 9.8 \text{ m/s} \quad v_{ox} = 9.8 \sqrt{3} \text{ m/s}$$

$$0 = 9.8 - gt = 9.8 \cdot t = 9.8 \Rightarrow t = 1$$

$$x = v_{oy} \cdot t - \frac{1}{2} \cdot g \cdot t^2$$

$$x = 9.8 \cdot 1 - \frac{1}{2} \cdot 9.8 \cdot 1 \quad x = 4.9 \text{ m}$$

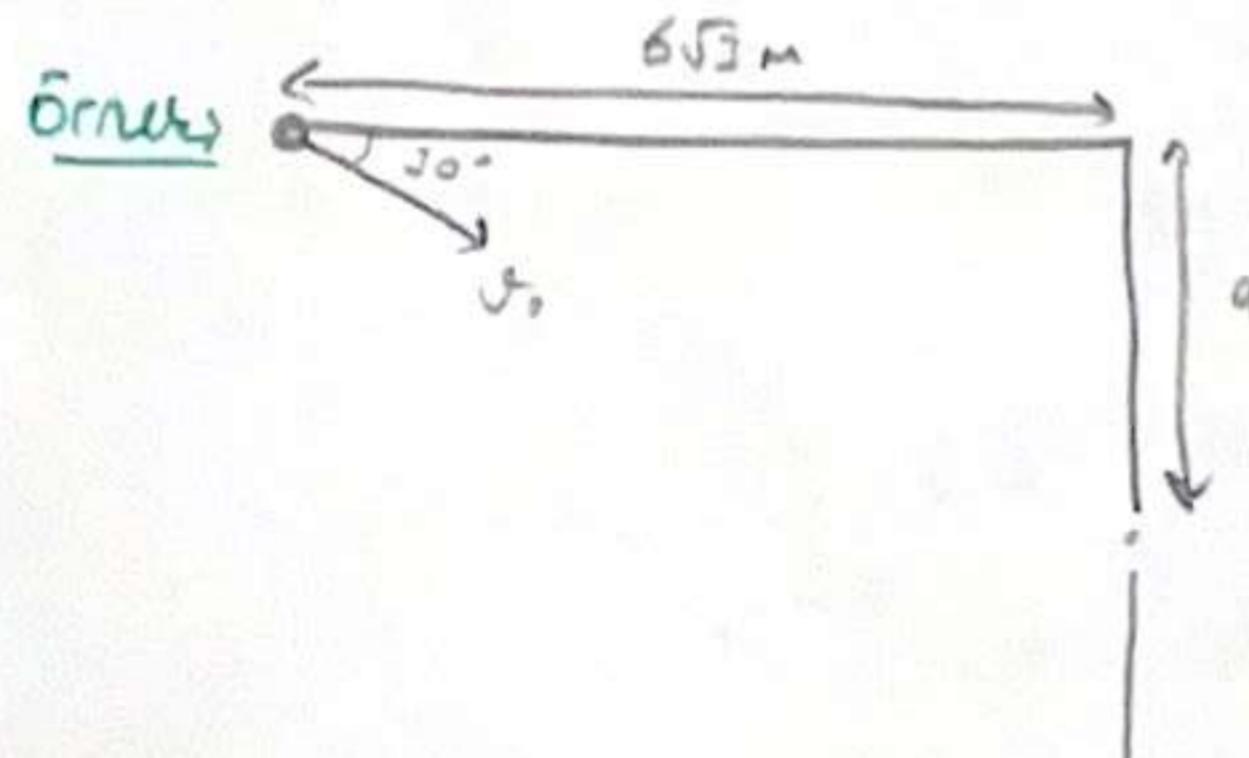
$$19.6 = v_{max}$$

$$19.6 = v_{yt} \cdot t + \frac{1}{2} \cdot 9.8 \cdot t^2 \quad | t=2 \quad x = 9.8 \sqrt{3}$$

$$9.8 \sqrt{3} \cdot 2 = \text{yatay yol} \quad 29.4 \sqrt{3} \text{ m}$$

$$19.6 \downarrow \sqrt{7}x$$

$$x(t) = (v_0 \cos \theta) \cdot t \quad y(t) = h + (v_0 \sin \theta) \cdot t - \frac{1}{2} g t^2$$



Tasin atladiği noktadan gecen hizin boyutu (nokta)  $v_0 = ?$

$$9.6 = \frac{v_0 t}{2} + \frac{1}{2} \cdot 9.8 \cdot t^2$$

$$\frac{v_0 \sqrt{3}}{2} \cdot t = 6.5 \quad | v_0 t = 12$$

$$19.2 = v_0 t + 9.8 t^2$$

$$7.2 = 9.8 t^2 \quad t = \frac{6}{7} \quad v_0 = 14$$

Dairesel hareket

Örnek:

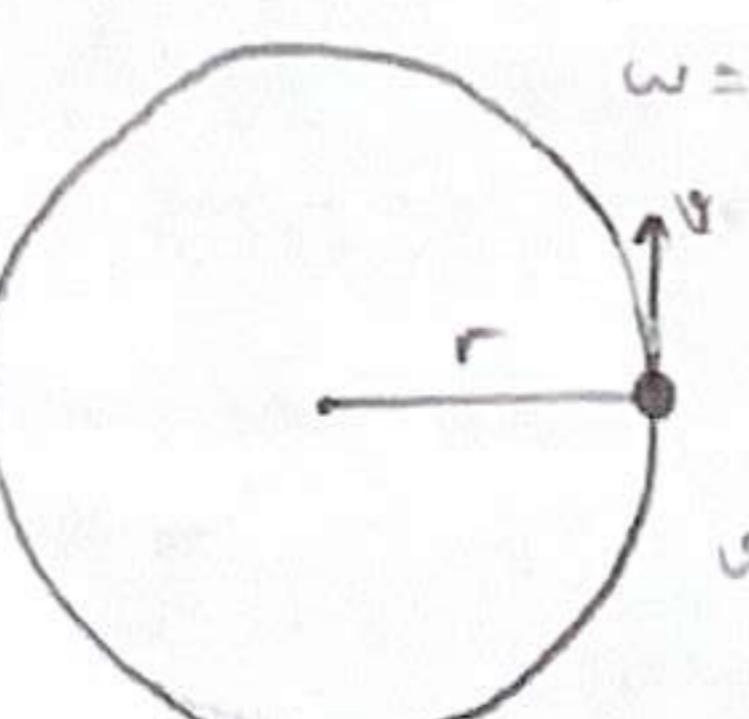
$$r = 0.5 \text{ m}, \text{ sonigode } \frac{2}{\pi} \text{ tur atiyer.}$$

$$\omega = ?, v = ?, a_r = ?$$

$$x = v \cdot t$$

$$2\pi r = v \cdot T$$

$$v = \frac{2\pi \cdot \frac{1}{2}}{\frac{\pi}{2}} = 2 \text{ m/s}$$



$$f = \frac{2}{\pi} \text{ s}^{-1} (\text{Hz})$$

$$T = \frac{\pi}{2} \text{ s}$$

$$w = \frac{2\pi}{T} = 2\pi f$$

$$a_r = \frac{v^2}{r} = \omega^2 r$$

$$S = \theta \cdot r$$

$$\theta = w \cdot t$$

a) Tas yatasurken en ut noksasna kon sonigode noksas? 15s

b) Tas ne kadar sure sonra yere carper? 3.5s

c) Tasin hareket boyunca tasin yatasurken oldigi yol nedir? 29.453 m

d) Tasin yere carpece hizinin yatasurken oldigi aci nedir? 49.11°

Tanımlıda 1.15'te ören motorun ucundakine  
kötüle bölgelerdeki düzgün dairesel hareket yorumlanır.  
Buna göre bölgelerdeki  $T$ ,  $w$ ,  $\alpha$ ,  $r$ ,  $a$  hesaplanır.

$$l = 0.4 \text{ m}$$

$$f_n = \frac{1.15}{1000} \quad T_n = \frac{1000}{1.15}$$

$$\frac{\sqrt{3}}{2} = \frac{r}{0.4}$$

$$\boxed{\frac{\sqrt{3}}{2} = r}$$

$$(2,23)^2 \cdot \frac{\sqrt{3}}{2} = a_r$$

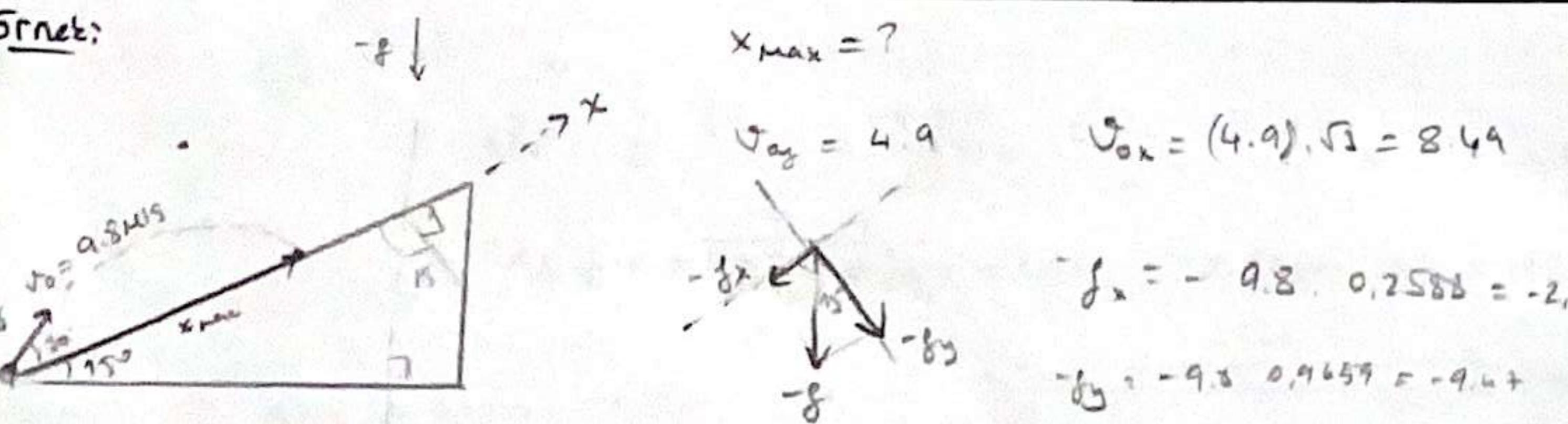
$$2\pi r = v \cdot T$$

$$2 \cdot \pi \cdot \frac{\sqrt{3}}{2} = v \cdot \frac{1000}{1.15}$$

$$\frac{4.46\sqrt{3}}{1000} \quad 0.446 \cdot \sqrt{3} = v$$

$$v = w \cdot r \\ \frac{0.446 \cdot \sqrt{3}}{2} = 2.230 \text{ rad/s}$$

Örnek:



$$x = v_{ox} t - \frac{1}{2} f_x t^2$$

$$x = 8.49 t - \frac{1}{2} 2.54 t^2$$

$$\boxed{x(t) = 8.49 t - 1.27 t^2}$$

$$y(t) = v_{oy} t - \frac{1}{2} g_3 t^2$$

$$\boxed{y(t) = (4.9)t - \frac{1}{2} 9.47 t^2}$$

$$9.8 = 9.47 t$$

$$\boxed{t = 1.03 \text{ s}}$$

$$x(1.03) = (8.49) (1.03) - 12.7 (1.03)^2$$

$$= 7.4 \text{ m}$$

$$\boxed{x_{max} = 7.4 \text{ m}}$$

## NEWTON HAREKET YASALARI

### 1) Eylemlerle prensibi

- Bir cisim üzerine etki eden net kuvvet 0 ise cisim

$\rightarrow v_0 = 0$  ise durmaya

$\rightarrow v_0 = \text{sabit}$

sabit hızla hareketine devam eder

$$\sum \vec{F}_{net} = 0 \quad \left. \begin{array}{l} v_0 = 0, v_0 = \text{sabit} \\ \Rightarrow \ddot{a} = 0 \end{array} \right\}$$

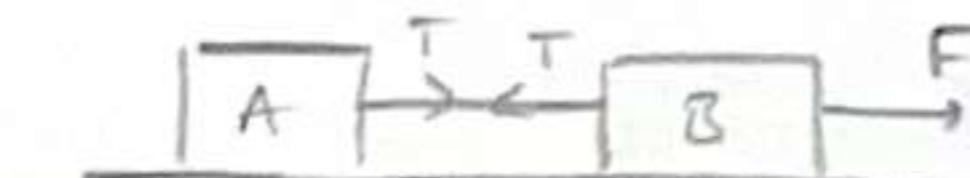
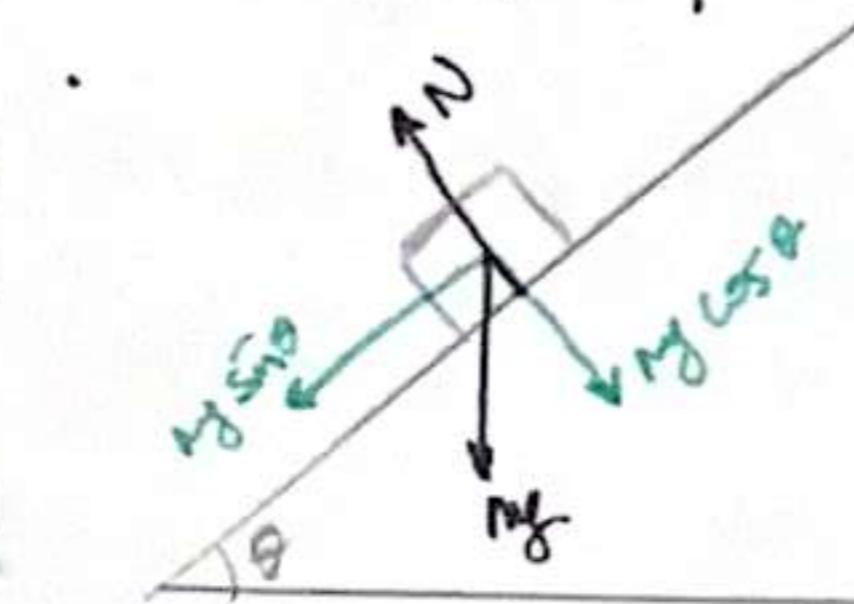
### 2) Temel prensip

- Bir cisim üzerine etki eden net kuvvet sıfırdan farklı ise cisim hareket etti.

$$\sum \vec{F}_{net} = m \cdot \vec{a} \quad 1 \text{ Newton} = 1 \text{ kg} \cdot \frac{\text{m}}{\text{s}^2}$$

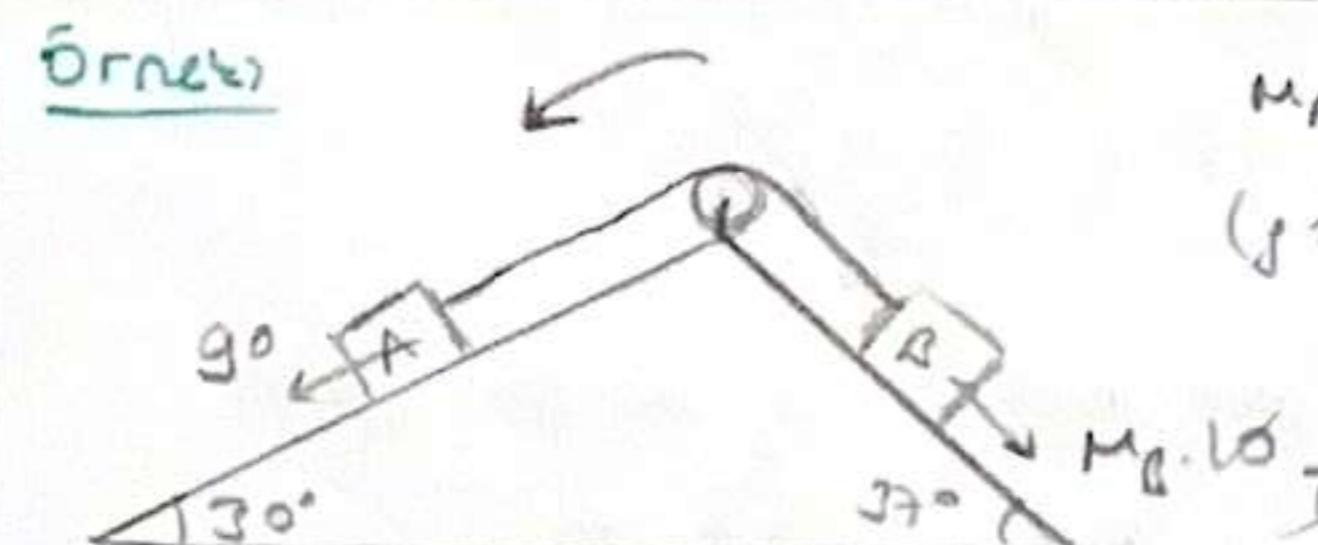
### 3) Etki - tepki prensibi

$$N = mg \cos \theta$$



Farklı cisimler farklıdır

Örnek:



$M_A = 18 \text{ N}$ , sola doğru sabit sıçrama ( $j \approx 10 \text{ rad/s}$ ) hareketi ve  $M_B = ?$

$$6M_B = 90 \quad \boxed{M_B = 15 \text{ N}}$$

Not: Normal kuvvet  $\vec{F}_N - \vec{F}_g = m \cdot \vec{a}_y \Rightarrow \vec{F}_N = m(g + a_y)$

### $\Sigma \rightarrow \text{Enerji}$

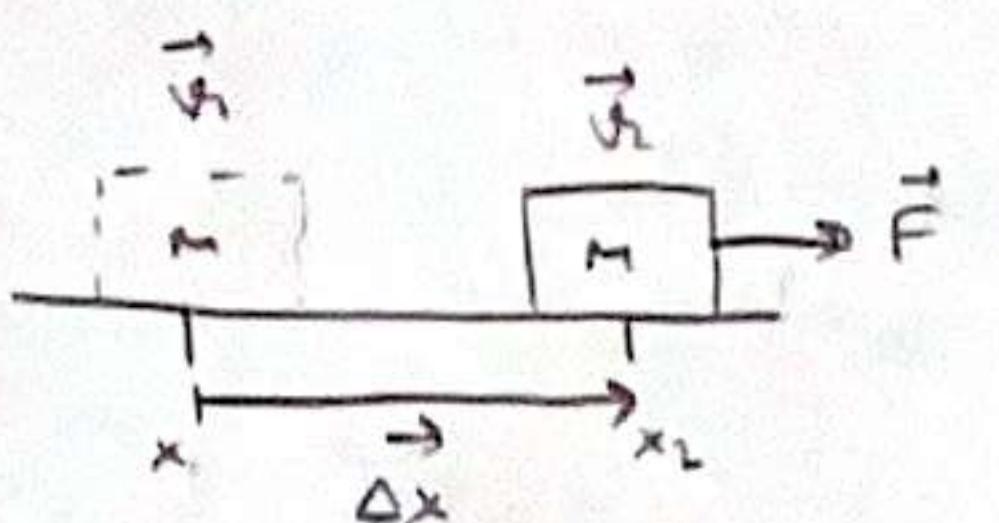
$W = \vec{F} \cdot \vec{\Delta x}$  hareket doğrultusundaki yer değiştirmesi ile做的 işin adı

$$W = (\vec{F} \cdot \cos \theta) \cdot |\vec{\Delta x}|$$

$$I_S = \text{Newton} \cdot \text{metre} \Rightarrow I_S = \frac{kg \cdot m^2}{s}$$

(m.a)

$I_S$  skalerdir pozitif, negatif veya 0 olabilir



$$v_2^2 = v_1^2 + 2 \alpha_x \Delta x$$

$$\alpha_x = \frac{v_2^2 - v_1^2}{2 \Delta x}$$

$$F = m \cdot \alpha_x = m \cdot \frac{v_2^2 - v_1^2}{2 \Delta x}$$

$$F \cdot \Delta x = \left( m \cdot \frac{v_2^2 - v_1^2}{2 \Delta x} \right) \cdot \Delta x = \frac{1}{2} m v_2^2 - \frac{1}{2} m v_1^2 \Rightarrow W = \Delta E_k$$

Kinetik enerji de sistemde yarlı degriviteler olmasa artıgını, negatif olmasa azaldığını 0 olması da degrivitelerini göster.

Durgun halden harekete geçen cisimlerde  $W = k_{\text{kin}} - k_{\text{rik}}$

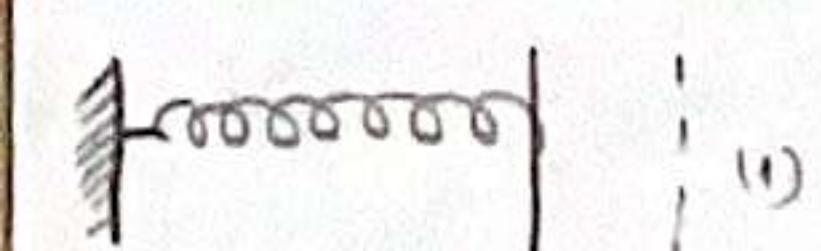
$$\Rightarrow W = k - 0 = \frac{1}{2} m v^2$$

$x_1 \rightarrow$  final pozisyon

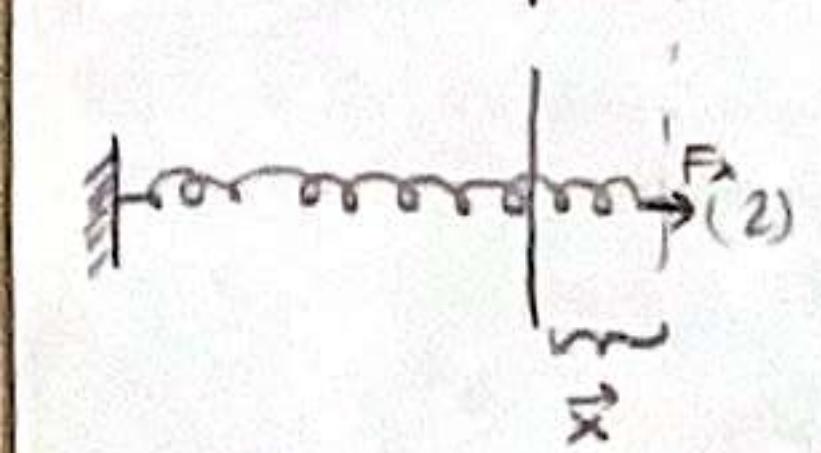
$$W = \int_{x_1}^{x_2} F_x dx \quad \begin{cases} \text{kütüklük bilgisi} \\ \text{integral} \end{cases}$$

$x_1 \rightarrow$  başlangıç pozisyon

### Yaydale genelleme kuvveti



(1)



(2)

$$F_x = k \cdot x \quad W = \int_0^x F_x dx = \int_0^x k \cdot x dx = \frac{1}{2} k x^2$$

$$W = \int_{x_1}^{x_2} F_x dx = \frac{1}{2} k x_2^2 - \frac{1}{2} k x_1^2 \quad \begin{cases} \text{Yer degirmine pozitif yüns} \\ (\text{Kırmızı ile aynı yön}) \end{cases}$$

$$W = \int_{x_1}^{x_2} k \cdot (-x) dx = \frac{1}{2} k x_1^2 - \frac{1}{2} k x_2^2$$

GÜC (watt =  $\frac{\text{Joul}}{\text{s}}$ )

$$P_{\text{kin}} = \frac{\Delta W}{\Delta t} \quad P_{\text{ari}} = \frac{\Delta W}{\Delta t}$$

$$P = \vec{F} \cdot \frac{\Delta \vec{x}}{\Delta t} \Rightarrow P = \vec{F} \cdot \vec{G}$$

$\downarrow$   
cisim hızlanırken harekete gelir



$$\begin{array}{c} \vec{F} \\ \left( \begin{array}{c} \Delta x \\ \downarrow \end{array} \right) \left[ \begin{array}{c} \vdots \\ \vec{F} \\ \vdots \end{array} \right] \left( \begin{array}{c} \Delta x \\ \downarrow \end{array} \right) \rightarrow \text{es negatif} \\ \left( \begin{array}{c} \Delta x \\ \downarrow \end{array} \right) \left[ \begin{array}{c} \vdots \\ \vec{F} \\ \vdots \end{array} \right] \left( \begin{array}{c} \Delta x \\ \downarrow \end{array} \right) \left. \begin{array}{l} y_2 - y_1 \\ \downarrow m g \end{array} \right\} \end{array}$$

a)  $\Delta U_{\text{gyr}} < 0$

$$\begin{array}{c} \vec{F} \\ \left( \begin{array}{c} \Delta x \\ \downarrow \end{array} \right) \left[ \begin{array}{c} \vdots \\ \vec{F} \\ \vdots \end{array} \right] \left( \begin{array}{c} \Delta x \\ \downarrow \end{array} \right) \rightarrow \text{es pozitif} \\ \left( \begin{array}{c} \Delta x \\ \downarrow \end{array} \right) \left[ \begin{array}{c} \vdots \\ \vec{F} \\ \vdots \end{array} \right] \left( \begin{array}{c} \Delta x \\ \downarrow \end{array} \right) \left. \begin{array}{l} y_2 - y_1 \\ \downarrow m g \end{array} \right\} \end{array}$$

b)  $\Delta U_{\text{gyr}} > 0$

$$W_g = \vec{F} \cdot \vec{\Delta x} = m \cdot \vec{g} \cdot (\vec{y}_1 - \vec{y}_2)$$

$$W_g = U_{g1} - U_{g2} = -(U_{g2} - U_{g1}) = -\Delta U_g$$

### Mekanik enerjinin korunumu

$$\Delta k = k_2 - k_1 = -\Delta U_g = -(U_{g2} - U_{g1})$$

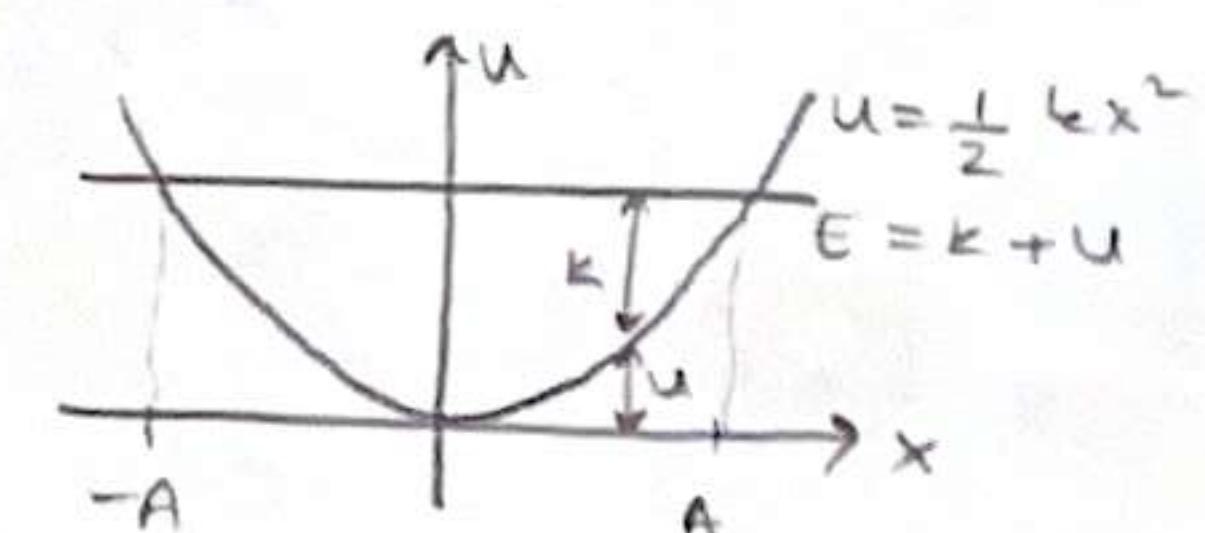
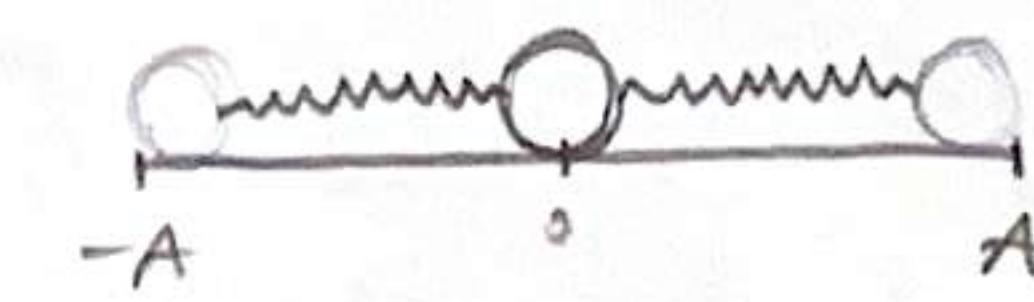
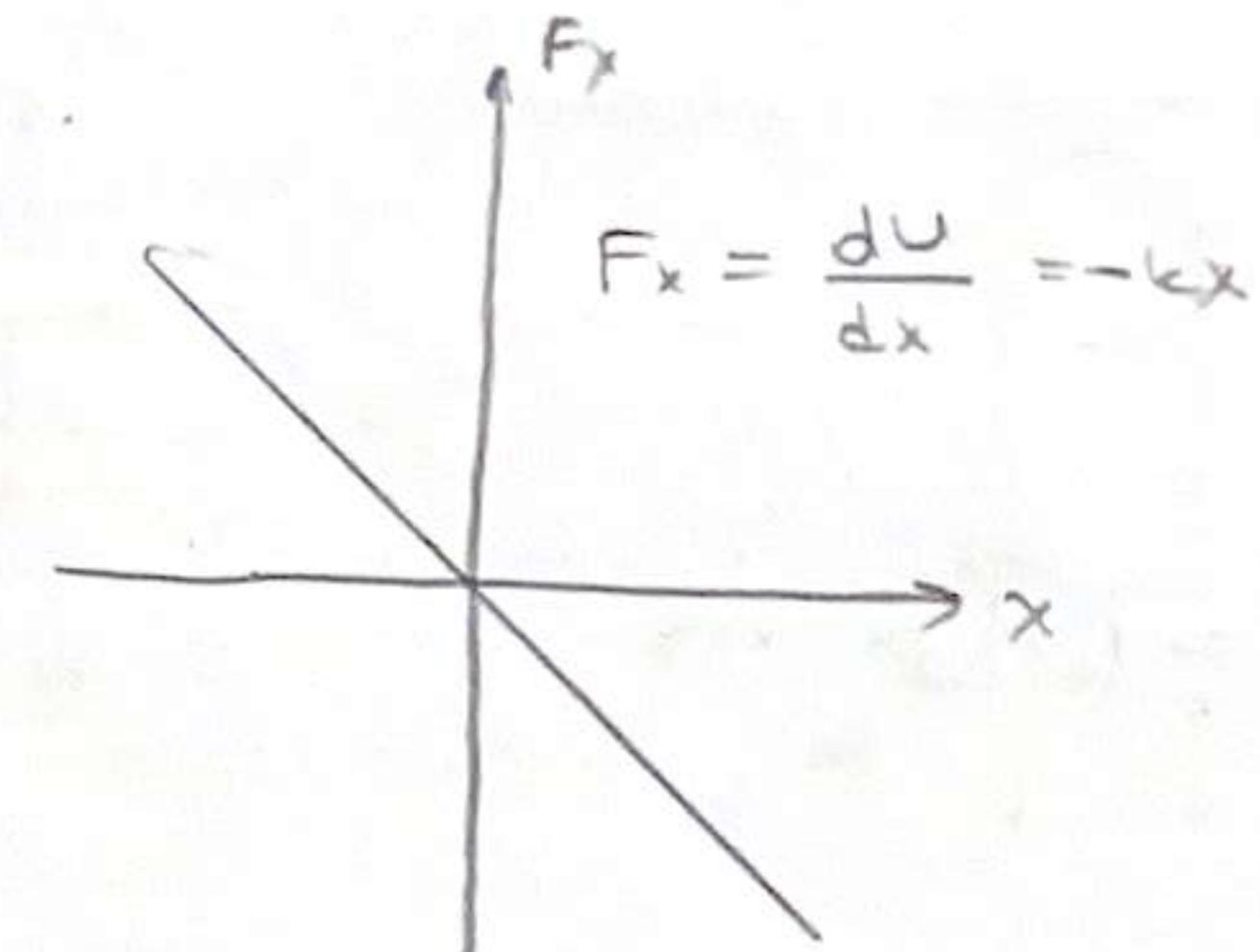
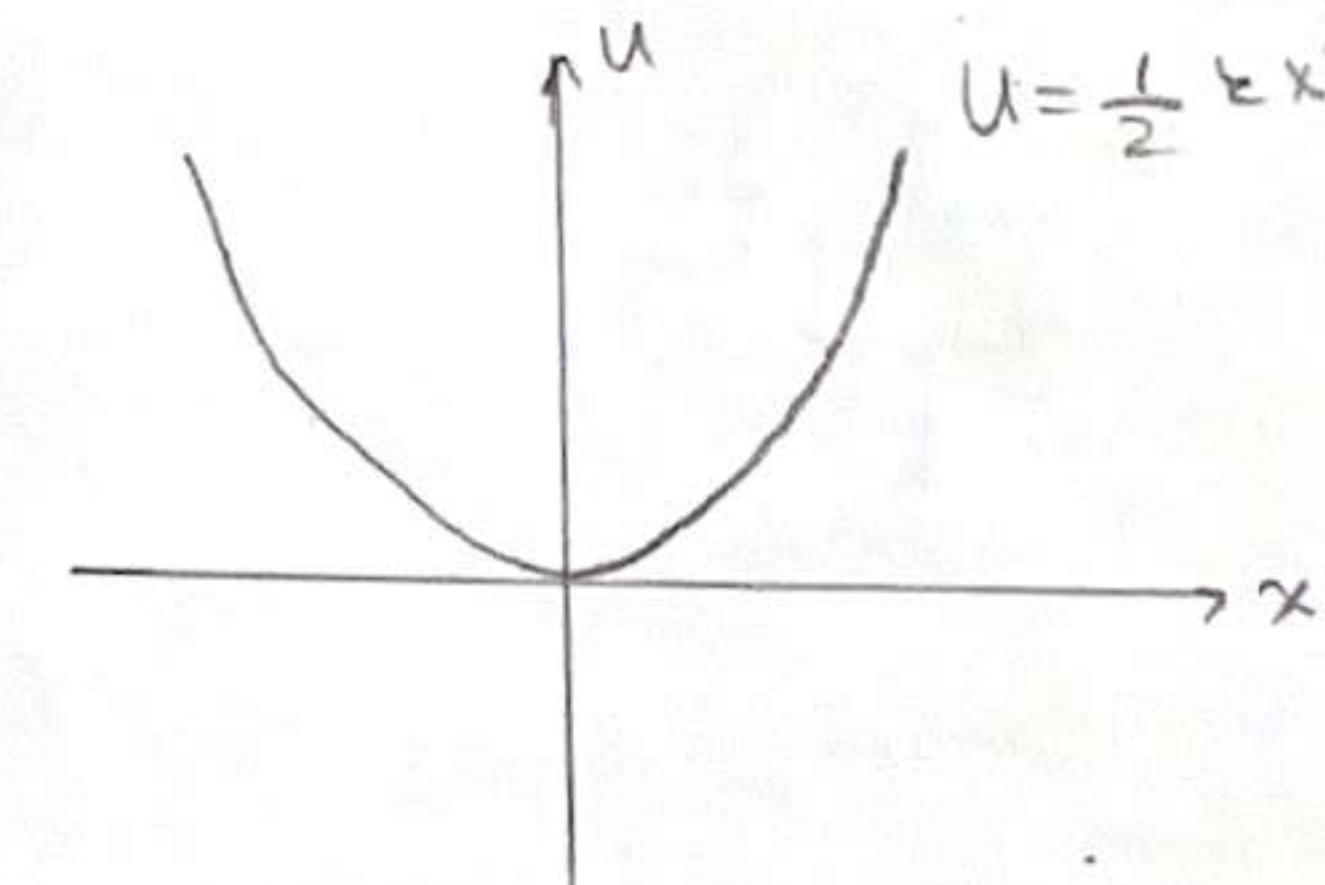
Sistemde yanıtla yer değişirse ise yapısında mekanik enerji korunacaktır.

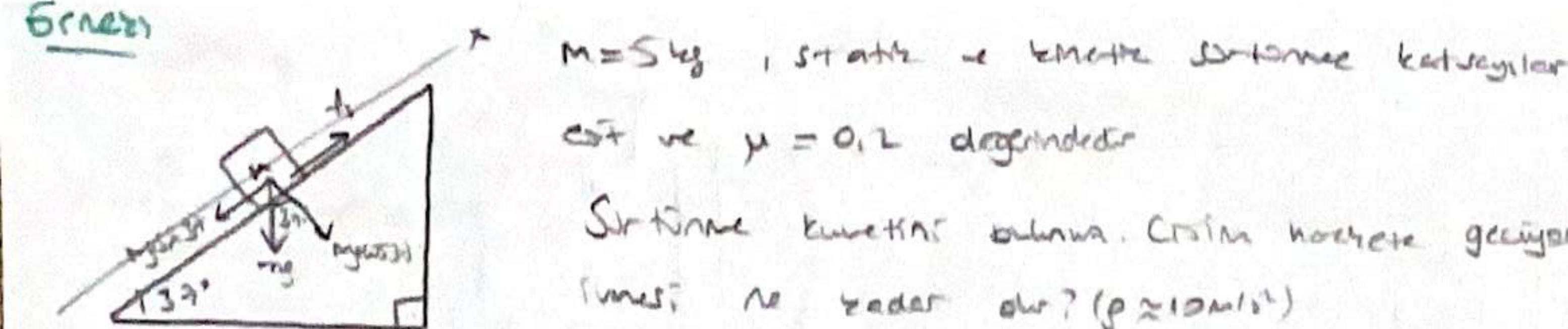
$$K_1 + U_{g1} = K_2 + U_{g2} \quad \frac{1}{2} m v_1^2 + m g y_1 = \frac{1}{2} m v_2^2 + m g y_2$$

$$\text{b) } W_g + W_d = k_2 - k_1 \quad \rightarrow \quad W_g = -\Delta U_g = -(U_{g2} - U_{g1})$$

$$W_d + U_{g1} - U_{g2} = k_2 - k_1 \Rightarrow U_{g1} + k_1 + W_d = U_{g2} + k_2$$

$W_d$  pozitif olursa  $U_{g2} + k_2 > U_{g1} + k_1 + W_d$

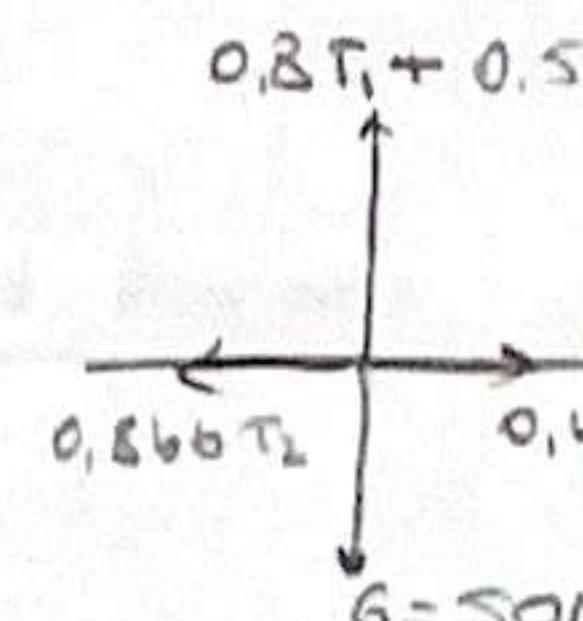
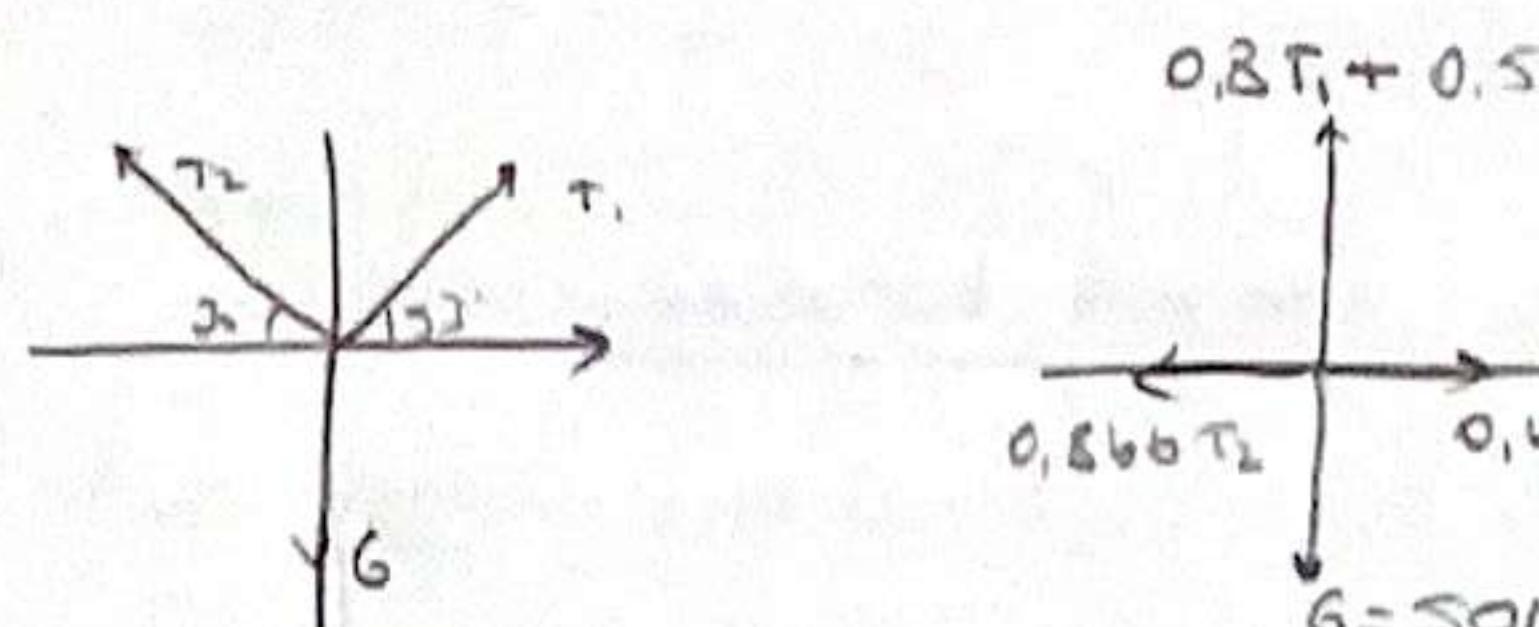
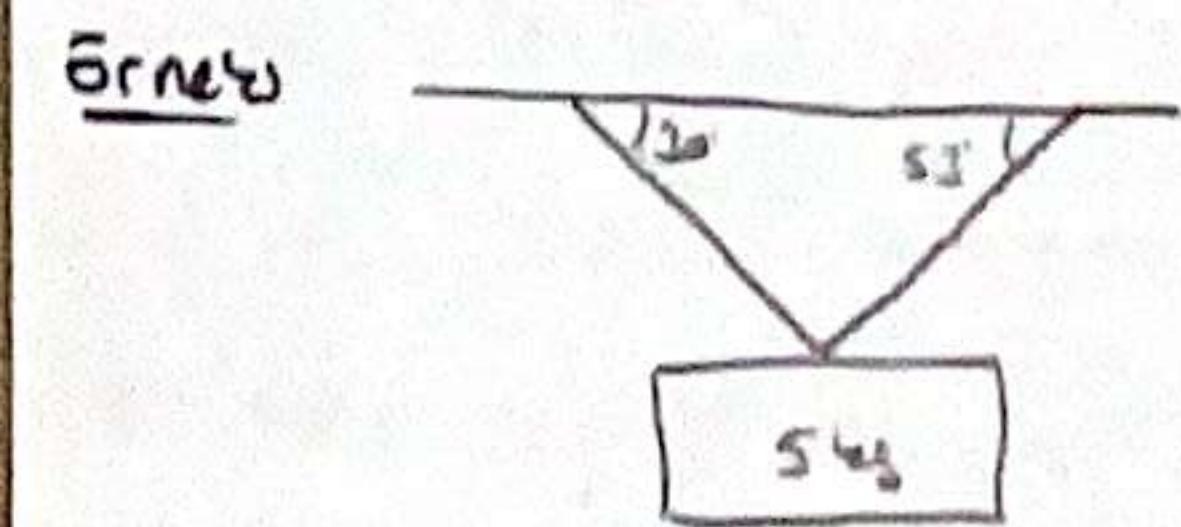




$M = 5 \text{ kg}$ , statisch  $\Rightarrow$  keine Sitzfläche kippt weg  
 $\cos \nu = \mu = 0.2$  abgeschrägt  
 Sitzfläche kippt abwärts. Cramm höchste geringe  
 Summe der Kräfte abwärts? ( $\rho \approx 10 \text{ m/s}^2$ )

$$Mg = 5 \cdot 10 = 50 \quad Mg \sin 37^\circ = 0.6 \cdot 50 = 30 \text{ N} \quad F_s = Mg \cdot \cos 37^\circ \cdot \mu = 50 \cdot 0.8 \cdot 0.2 = 8$$

$$F_g - F_s = F_{\text{net}} = M \cdot a \quad 50 - 8 = 5 \cdot a \Rightarrow a = 6.4 \text{ m/s}^2$$



$$\left(\frac{\sqrt{3}}{2} = 0.866\right)$$

$$0.6 T_1 = 0.866 T_2 \quad T_1 = \frac{0.866 T_2}{0.6}$$

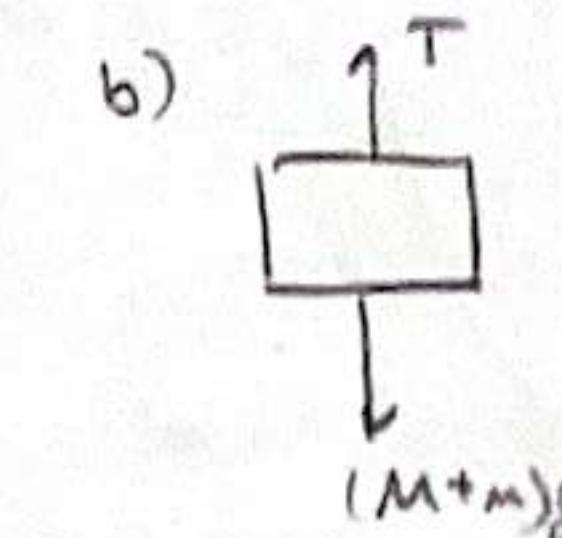
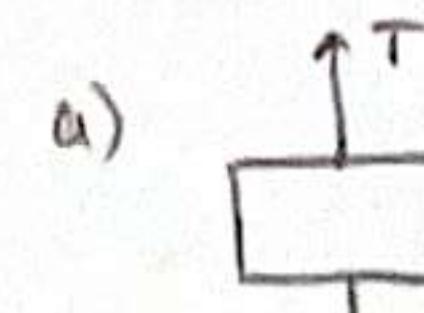
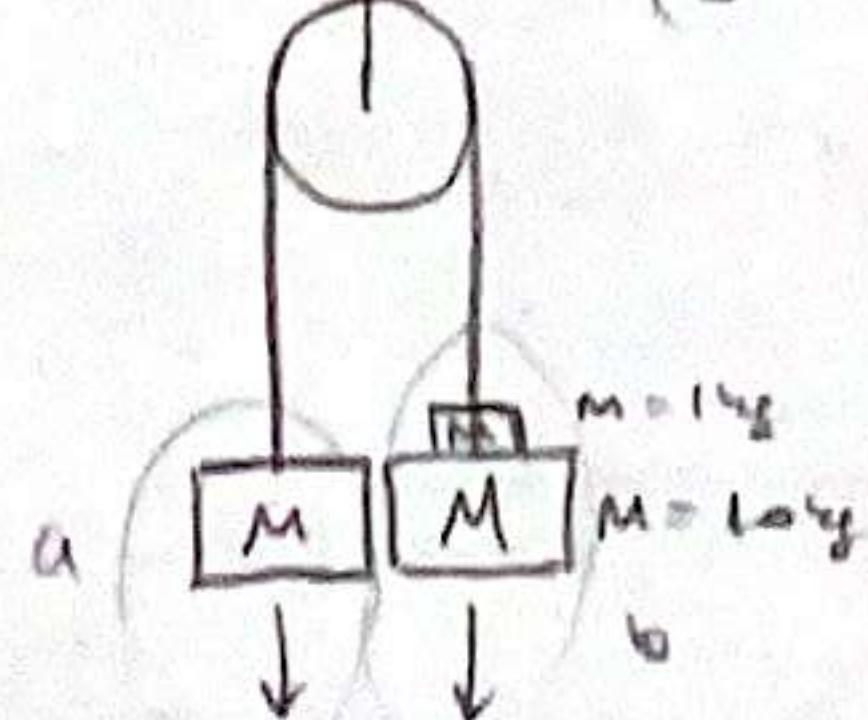
$$0.8 T_1 + 0.5 T_2 = 50 \text{ N} \quad T_2 = 1.44 T_1$$

$$0.8 \cdot (1.44) T_2 + 0.5 T_2 = 50 \text{ N}$$

$$1.155 T_2 \quad T_2 = \frac{50}{1.155} \text{ N} \Rightarrow T_2 = 30.2 \text{ N}$$

$$(1.44)(30.2) \Rightarrow T_1 = 43.5 \text{ N}$$

Fräne



$$T - Mg = Ma$$

$$(M+m) \cdot a = (M+m)g - T$$

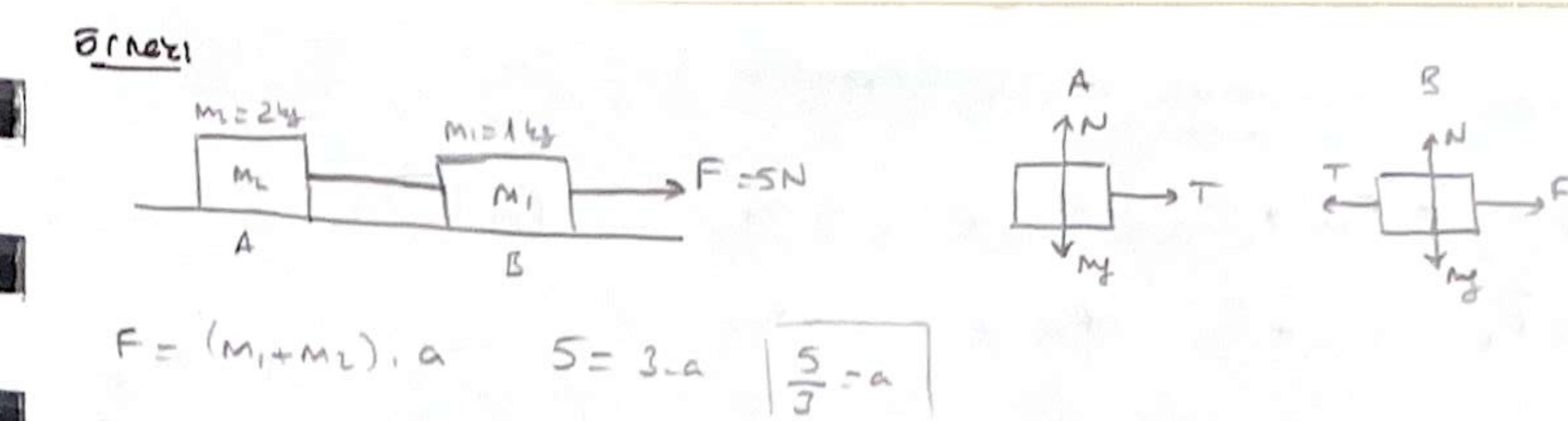
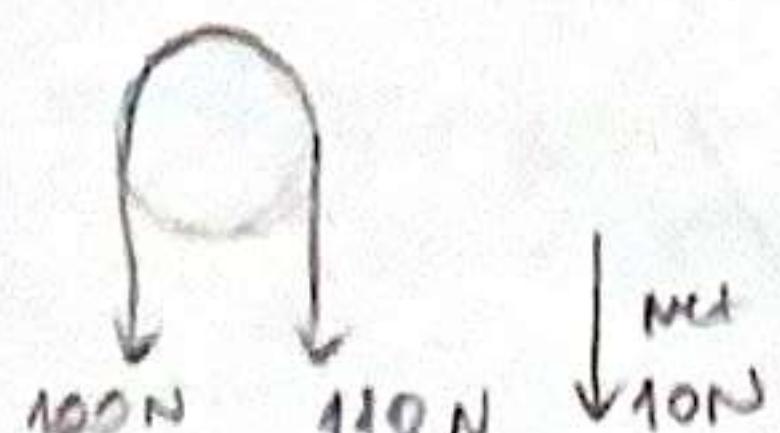
$$M(g+a) = (M+m)(g-a)$$

$$10 \cdot (10+a) = 11 \cdot (10-a)$$

$$100 + 10a = 110 - 11a$$

$$21a = 10$$

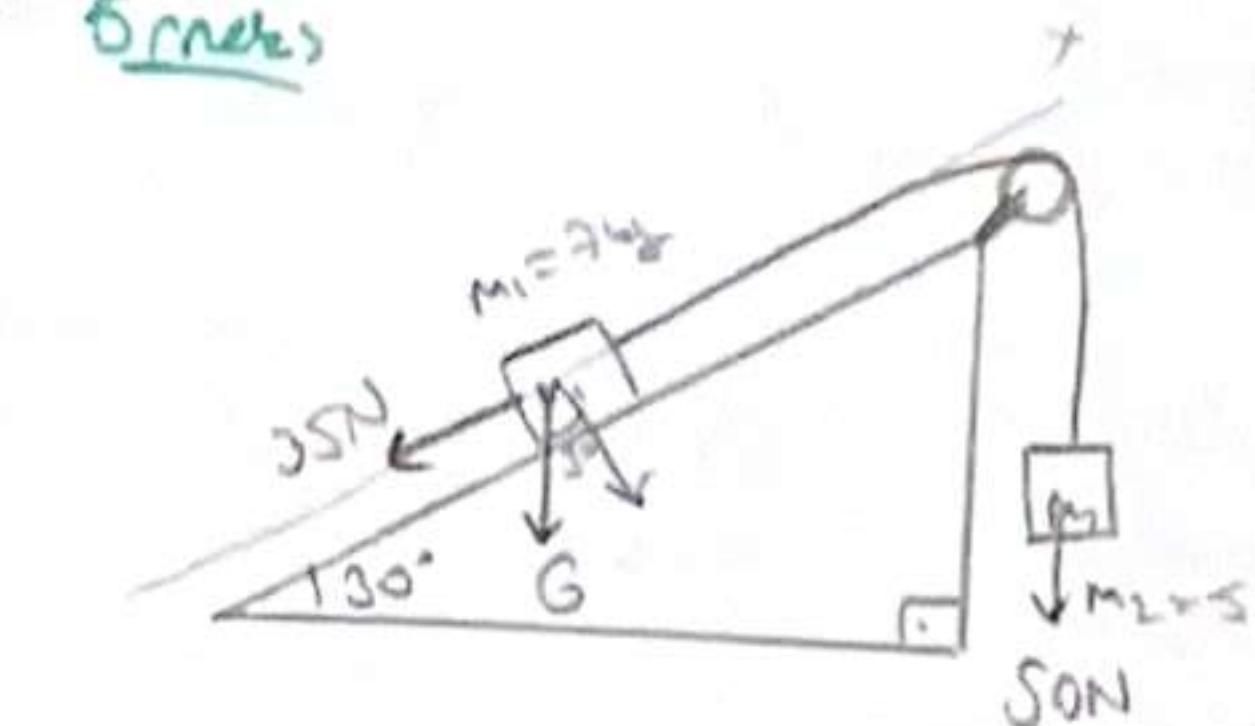
$$a = \frac{10}{21} \text{ m/s}^2$$



$$F = (M_1 + M_2) \cdot a \quad 5 = 3 \cdot a \quad \boxed{\frac{5}{3} = a}$$

$$[T = M_2 \cdot a \quad F - T = M_1 \cdot a] \quad T = 2 \cdot \frac{5}{3} \Rightarrow T = \frac{10}{3} \text{ N}$$

Fräne

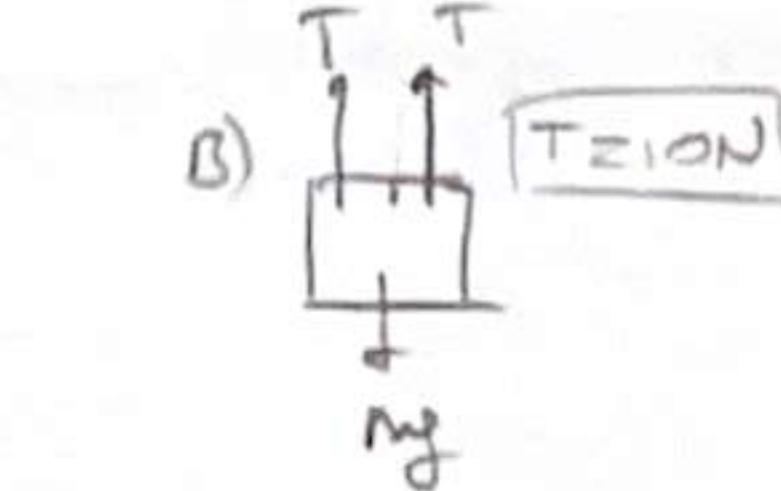
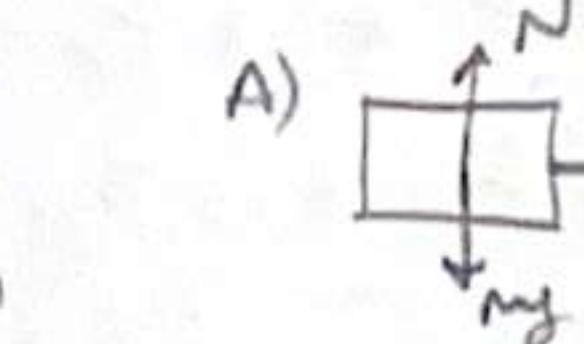
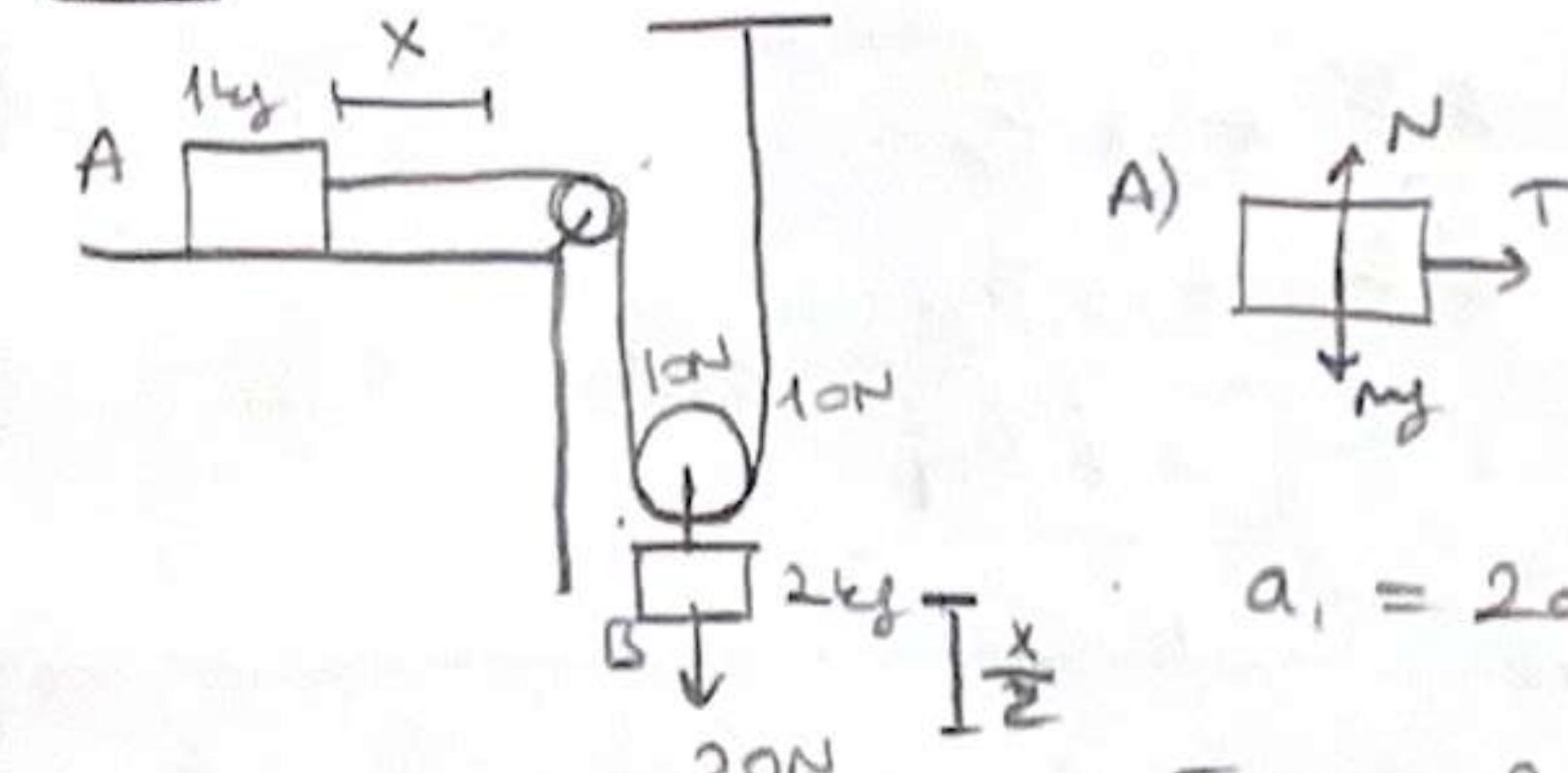


$$G = M_1 g = 2 \cdot 10 = 20 \text{ N} \quad 20 \cdot \sin 30^\circ = Mg \cos 30^\circ = 15$$

Fräne

$$50 - T = 5 \cdot (1.25) \Rightarrow 50 - 6.25 = T \Rightarrow T = 43.75 \text{ N}$$

Fräne

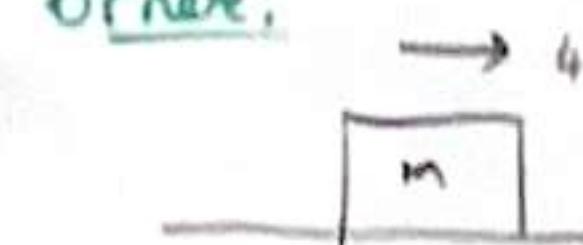


$$T = 1.2a$$

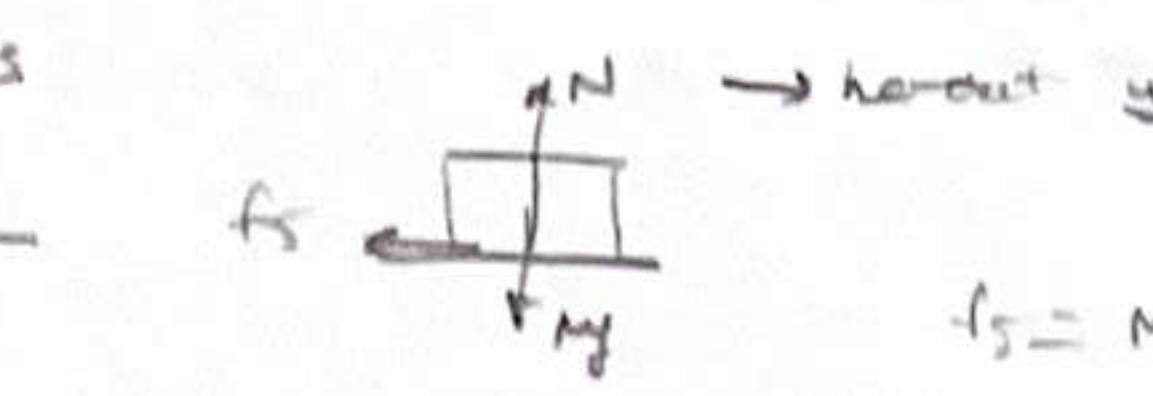
$$2T - 20 = 2 \cdot a$$

$$\boxed{T = 6.66 \text{ N}} \quad (a_1 = 6.66 \text{ m/s}^2, a_2 = 3.33 \text{ m/s}^2)$$

Fräne



$$\mu = 0.15$$



$$f_s = Mg \cdot \mu$$

$$10 \cdot \frac{1}{5} \Rightarrow f_s = 2 \text{ N}$$

$$f_s = M \cdot a$$

$$2.5 \text{ m} = M \cdot a \quad \boxed{a = 2.5}$$

$$x = b_1 t - \frac{1}{2} a t^2 \quad \boxed{x = 3.2 \text{ m}}$$

$$x = v_0 t + \frac{1}{2} a t^2 \quad \boxed{x = 4.6 - \frac{1}{2} \cdot \frac{5}{2} \cdot t^2}$$

$$v_{\text{end}} = v_0 - at \quad \left( \frac{5}{2} t = 4 \right) \quad \boxed{t = 1.6}$$

## Lineer momentum ve corpsmater

$$\sum \vec{F}_i = F_{21} + F_{31} + F_{41} + \dots + F_{n1}$$

$$\sum \vec{F}_2 = F_{12} + F_{22} + F_{32} + \dots + F_{n2}$$

⋮

$$\sum \vec{F}_n = F_{1n} + F_{2n} + \dots + F_{(n-1)n}$$

$$\sum \vec{F}_1 + \sum \vec{F}_2 + \dots + \sum \vec{F}_n = 0$$

$$m_1 \cdot a_1 + m_2 \cdot a_2 + \dots + m_n \cdot a_n = 0$$

$$m_1 \cdot \frac{d\vec{v}_1}{dt} + m_2 \cdot \frac{d\vec{v}_2}{dt} + \dots + m_n \cdot \frac{d\vec{v}_n}{dt} = 0$$

$$\frac{d}{dt} (m_1 \cdot \vec{v}_1 + m_2 \cdot \vec{v}_2 + \dots + m_n \cdot \vec{v}_n) = 0$$

$$\frac{d}{dt} (\underbrace{\vec{P}_1 + \vec{P}_2 + \dots + \vec{P}_n}_{\frac{d}{dt}(\sum \vec{P})}) = 0$$

$$\frac{d}{dt}(\sum \vec{P}) = 0 \rightarrow \sum \vec{P}_i = \sum \vec{P}_s$$

$$\sum \vec{P}_{ic} = \sum \vec{P}_{sc}$$

$$\sum \vec{P}_{ij} = \sum \vec{P}_{sj}$$

$$\sum \vec{P}_{is} = \sum \vec{P}_{ss}$$

$$\sum \vec{F} = m \cdot \frac{d\vec{v}}{dt} \Rightarrow \sum \vec{F} = \frac{d(m\vec{v})}{dt} \Rightarrow \sum \vec{F} = \frac{d\vec{P}}{dt}$$

$$\int_{P_i}^P \sum \vec{F} dt = \int_{t_1}^{t_2} d\vec{P} \Rightarrow \vec{P}_2 - \vec{P}_1 = \Delta \vec{P} = \int_{t_1}^{t_2} \sum \vec{F} dt$$

$$F_{\text{ort}} = \frac{1}{\Delta t} \int_{t_1}^{t_2} \sum \vec{F} dt \quad \Delta P = F_{\text{ort}} \cdot \Delta t$$

$$\vec{P}_i = m_1 \cdot \vec{v}_{1i} + m_2 \cdot \vec{v}_{2i} = m_1 \cdot \vec{v}_{1s} + m_2 \cdot \vec{v}_{2s} = \vec{P}_s$$

$$\frac{1}{2} m_1 (v_{1i})^2 + \frac{1}{2} m_2 (v_{2i})^2 = \frac{1}{2} m_1 (v_{1s})^2 + \frac{1}{2} m_2 (v_{2s})^2$$

$$m_1 (v_{1i} - v_{1s})(v_{1i} + v_{1s}) = m_2 (v_{2s} - v_{2i})(v_{2s} + v_{2i})$$

$$m_1 (v_{1i} - v_{1s}) = m_2 (v_{2s} - v_{2i})$$

$$m_2 (v_{2s} - v_{2i}) \cdot (v_{1i} + v_{1s}) = m_2 (v_{2s} - v_{2i}) (v_{2s} + v_{2i})$$

$$v_{1i} + v_{1s} = v_{2s} + v_{2i}$$

$$m_1 \cdot v_{1s} + m_2 \cdot v_{2s} = \frac{m_1 \cdot v_{1i} + m_2 (v_{1s} + v_{1s} - v_{2s})}{m_2 v_{1i} + m_2 v_{1s} - m_2 v_{2s}}$$

$$\frac{(m_1 - m_2) v_{1i} + 2m_2 v_{2s}}{(m_1 + m_2)} = (m_1 + m_2) v_{1s}$$

$$v_{1s} = \frac{m_1 - m_2}{m_1 + m_2} v_{1i} + \frac{2m_2 v_{2s}}{m_1 + m_2}$$

$$m_1 \cdot v_{1s} + m_2 \cdot v_{2s} = m_1 (v_{2s} + v_{2s} - v_{1s}) + m_2 v_{2s}$$

$$= m_1 v_{2s} + m_1 v_{2s} - m_1 v_{1s}$$

$$2m_1 v_{1s} + (m_2 - m_1) v_{2s} = (m_1 + m_2) v_{2s}$$

$$v_{2s} = \frac{2m_1}{m_1 + m_2} v_{1i} + \frac{m_2 - m_1}{m_1 + m_2} v_{2i}$$

## Kütte merkezi

$$x_{cm} = \frac{m_1 \cdot x_1 + m_2 \cdot x_2 + \dots + m_N \cdot x_N}{m_1 + m_2 + \dots + m_N}$$

$$M = m_1 + m_2 + m_3 + \dots + m_N$$

$$x_{cm} = \frac{1}{M} \sum_{i=1}^N m_i \cdot x_i$$

$$y_{cm} = \frac{1}{M} \sum_{i=1}^N m_i \cdot y_i$$

$$z_{cm} = \frac{1}{M} \sum_{i=1}^N m_i \cdot z_i$$

$$\vec{r}_{cm} = x_{cm} \cdot \hat{i} + y_{cm} \cdot \hat{j} + z_{cm} \cdot \hat{k}$$

$$\vec{r}_{cm} = \frac{1}{M} \sum_{i=1}^N [m_i \cdot x_i] \hat{i} + [m_i \cdot y_i] \hat{j} + [m_i \cdot z_i] \hat{k}$$

## Sürekli kütte dağılımı

$$x_{cm} \approx \frac{1}{M} \sum_{i=1}^N \Delta m_i \cdot x_i$$

$$x_{cm} = \frac{1}{M} \lim_{\Delta M \rightarrow 0} \sum_{i=1}^N \Delta m_i \cdot x_i \rightarrow \int x dm$$

$$x_{cm} = \frac{1}{M} \int x dm$$

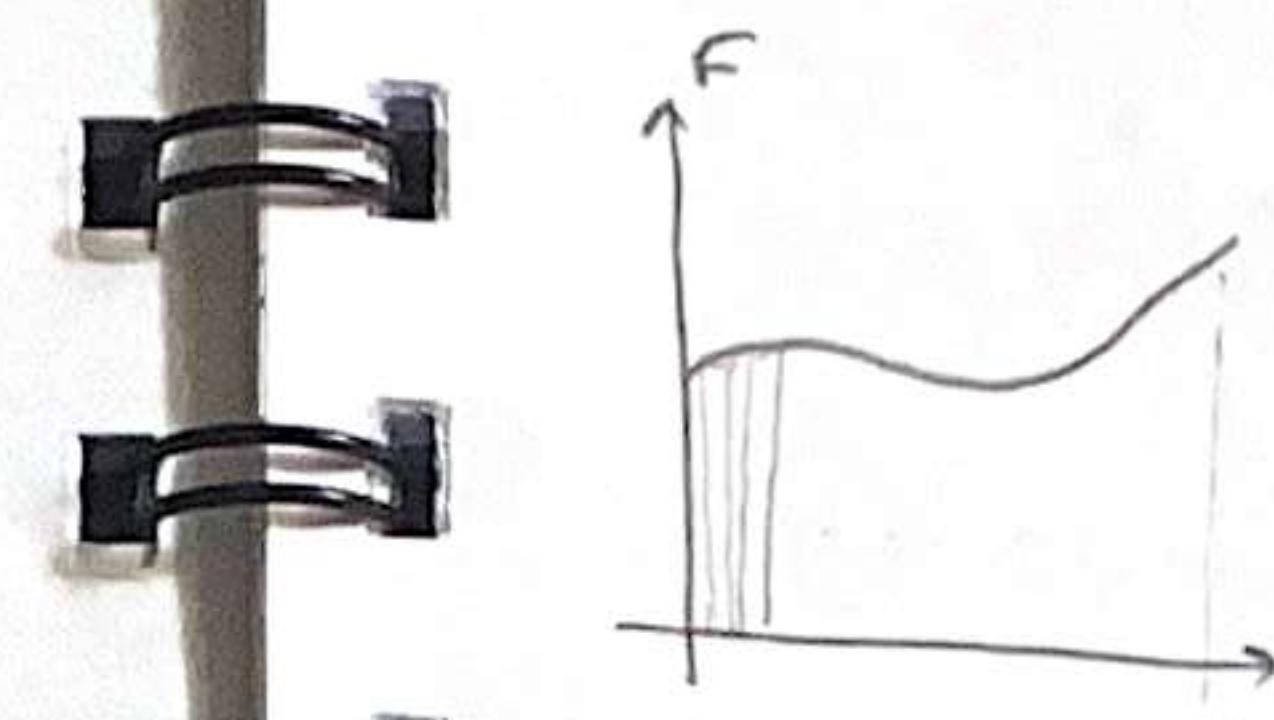
$$y_{cm} = \frac{1}{M} \int y dm$$

$$z_{cm} = \frac{1}{M} \int z dm$$

## Fizik - 1 (2. ora sinav)

$W = \vec{F} \cdot \Delta \vec{r} \Rightarrow W = F \Delta r \cos \theta$  Kuvvetin ne yerde ettiğine arastırıldığını

↪ sabit kuvvetin yaptığı iş



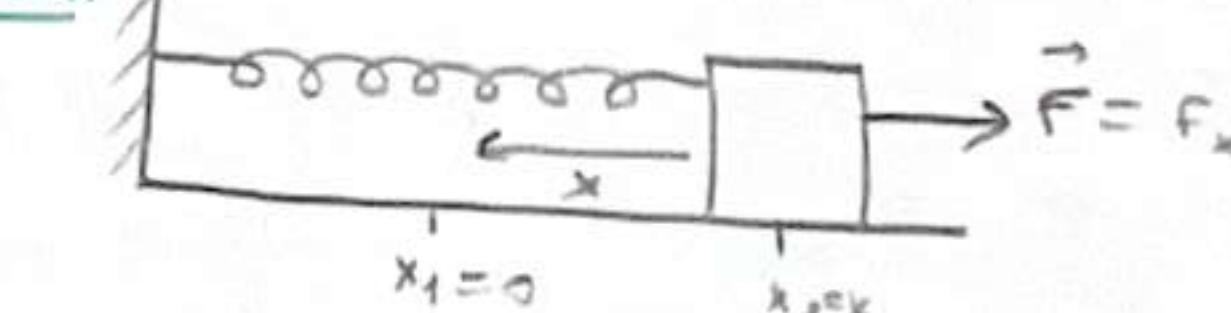
↪ değişken kuvvetin yaptığı iş

$$W_x = \lim_{\Delta x_i \rightarrow 0} \sum_{i=1}^{\infty} F_i \cdot \Delta x_i = \int_{x_1}^{x_2} F_x dx$$

$$W = \int_{\vec{r}_1}^{\vec{r}_2} F_x dx + f_y dy + F_z dz$$

$$W = \int_{\vec{r}_1}^{\vec{r}_2} \vec{F} \cdot d\vec{r}$$

### Örnek 1



$$\vec{F}_{yay} = -k \times \hat{z}$$

$$\sum \vec{F} = -kx \hat{i} \quad d\vec{r}_x = dx \hat{i}$$

$$W = \int_0^x -kx \hat{i} \cdot d\vec{r}_x = -k \cdot \int_0^x x dx \Rightarrow W = -\frac{1}{2} kx^2$$

### iş - kinetik enerji

$$W = \int \sum \vec{F} \cdot d\vec{r} \quad \sum \vec{F} = m \cdot \vec{a} = m \cdot \frac{d\vec{v}}{dt}$$

$$W = \int m \frac{d\vec{v}}{dt} \cdot d\vec{r}$$

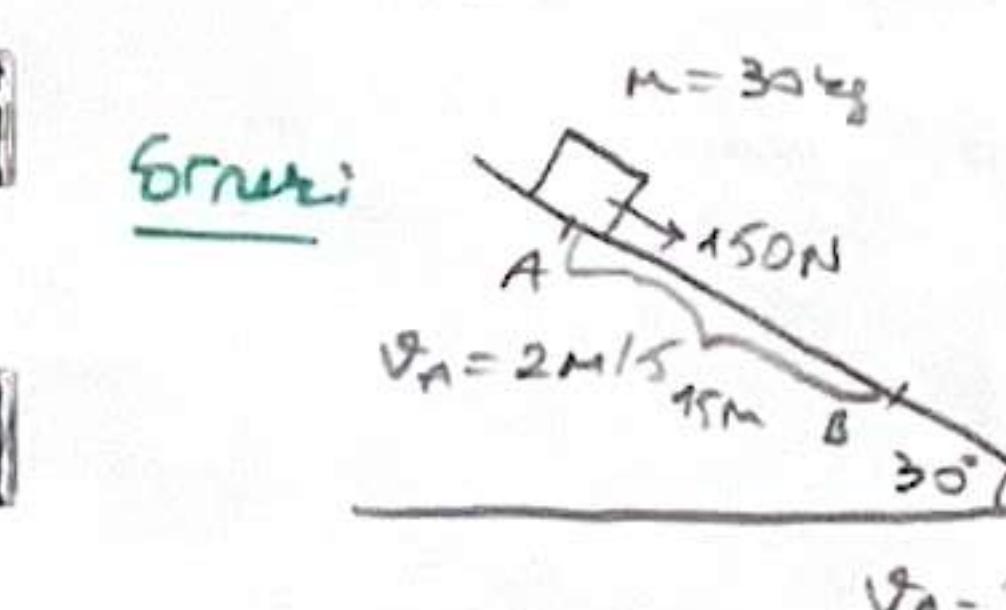
$$W = m \int \underbrace{d\vec{v} \cdot \vec{v}}$$

$$W = m \int_{v_i}^{v_f} v dv = \frac{1}{2} mv^2 \Big|_{v_i}^{v_f}$$

(öynü yemek) oradan da 0-safer carpmak

$$W = E_{ks} - E_{ki} = \Delta E_k$$

$$E_k = \frac{1}{2} mv^2$$

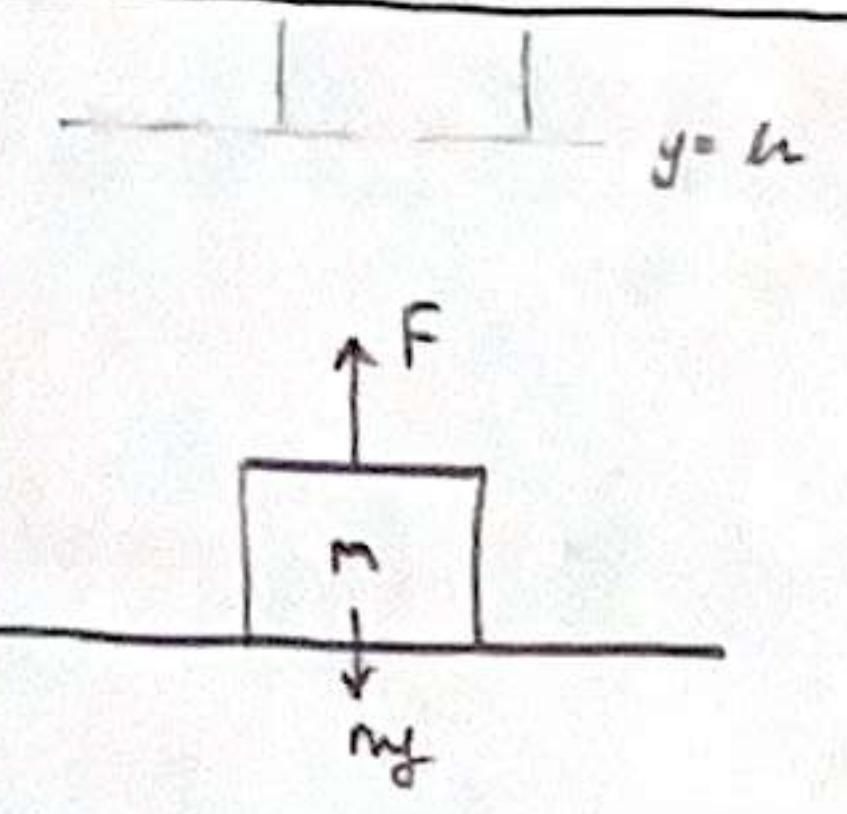


$$150 \cdot 15 = \frac{1}{2} 30 v_B^2 - \frac{1}{2} 30 \cdot 2^2$$

$$\sqrt{154} = \sqrt{v_B^2}$$

$$2\sqrt{39} = v_B$$

## Kötü adım potansiyel enerjisi



$$W = \int \Sigma \vec{F} d\vec{r}$$

$$\Sigma \vec{F} = F\hat{i} = mg\hat{j}$$

$$W = \int_0^h mg\hat{j} \cdot dy\hat{j}$$

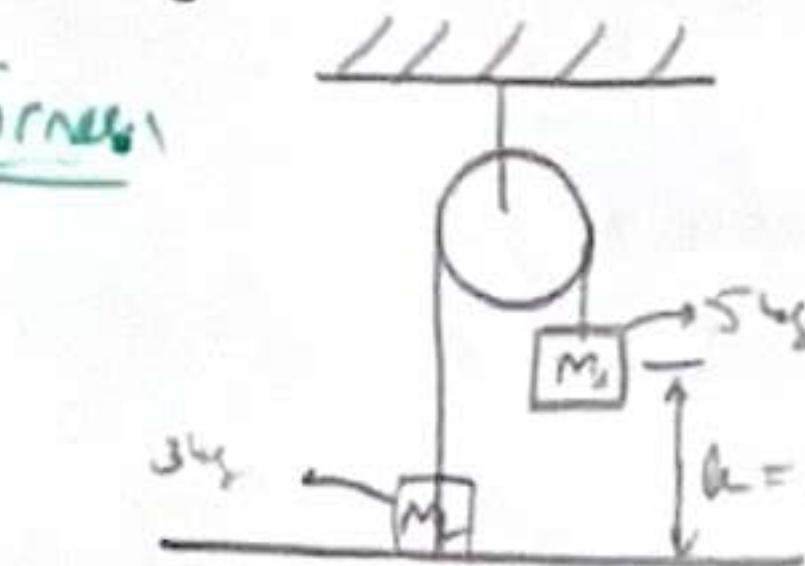
$$\boxed{W = mgh}$$

$$d\vec{r} = dy\hat{j}$$

$$W = mg \int_0^h dy$$

## Enerji Konservanı

Örnek



Yerden aynı yerdeki gelebileceğimiz hizları ne dir?

$$m_1 \Rightarrow 5 \cdot 10 \cdot 2 = 100$$

$$100 = \frac{1}{2} \cdot 5 \cdot v^2$$

$$\boxed{25\sqrt{2} = v_1}$$

$$60 = \frac{1}{2} \cdot 3 \cdot v_2^2$$

$$\boxed{25\sqrt{2} = v_2}$$

$$\Delta U_g + \Delta K = 0$$

$$(U_{g1} - U_{g2})_1 + (U_{g2} - U_{g1})_2 + (K_1 - K_2)_1 + (K_2 - K_1)_2 = 0$$

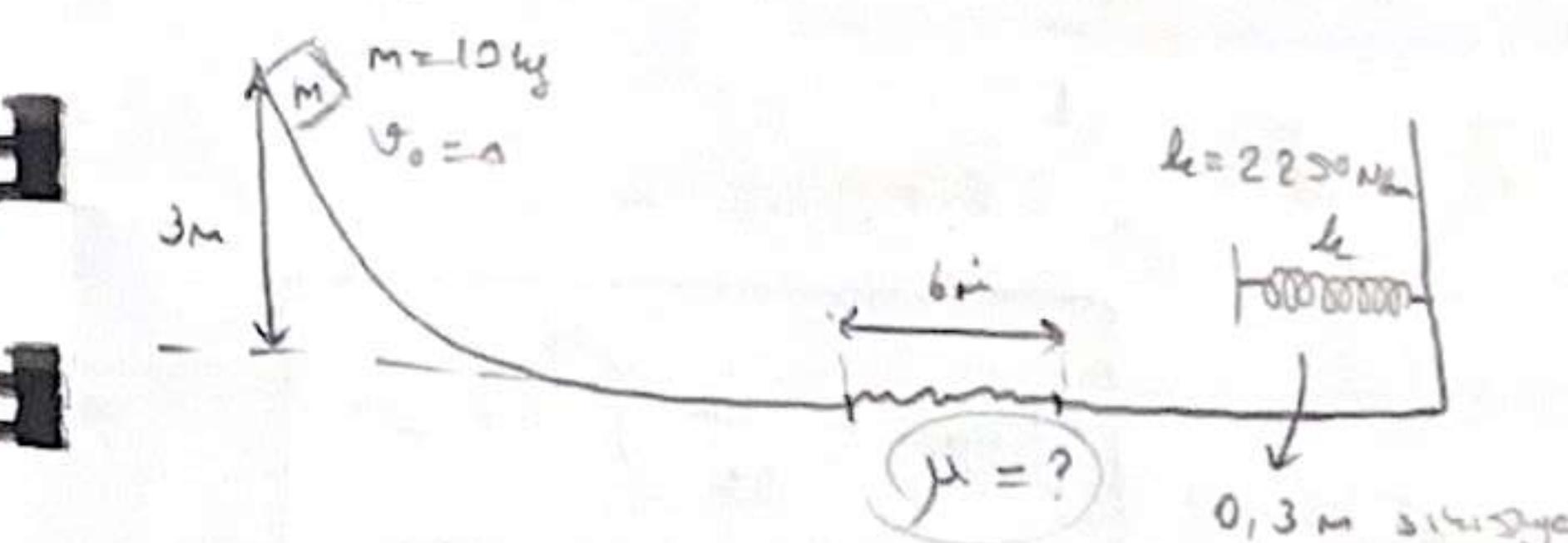
$$(m_1 g \frac{h}{2} - m_1 g h) + (m_2 g \frac{h}{2} - 0) + (\frac{1}{2} m_1 v_1^2 - 0) + (\frac{1}{2} m_2 v_2^2 - 0) = 0$$

$$\frac{1}{2} gh (m_2 - m_1)$$

$$+ \frac{1}{2} (m_1 + m_2) v^2 = 0$$

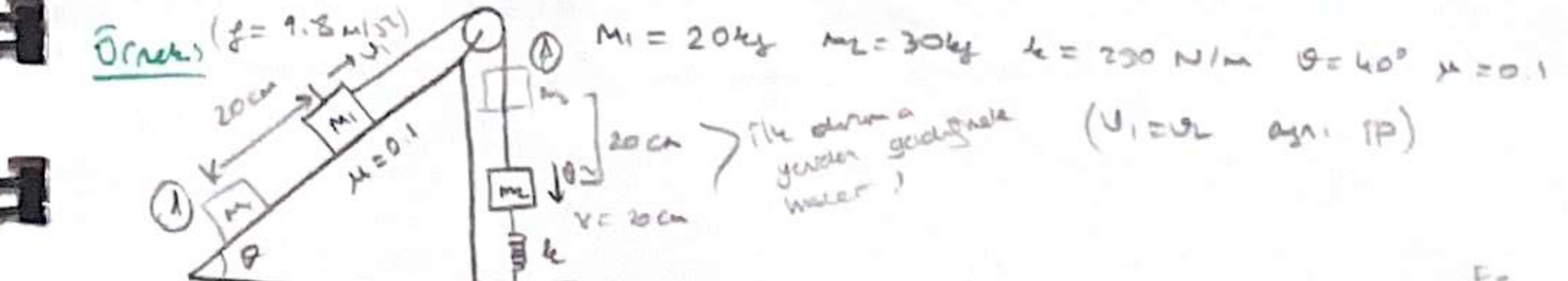
$$v = \sqrt{\frac{(m_1 - m_2) gh}{(m_1 + m_2)}}$$

Örnek ( $g = 9.8 \text{ m/s}^2$ )



$$E_{kin} = E_{sor}$$

$$10 \cdot (9.8) \cdot 3 = \frac{1}{2} \cdot 2250 \cdot \frac{9}{100} + 10 \cdot (9.8) \cdot \mu \cdot 6 \quad \mu = 0.33$$

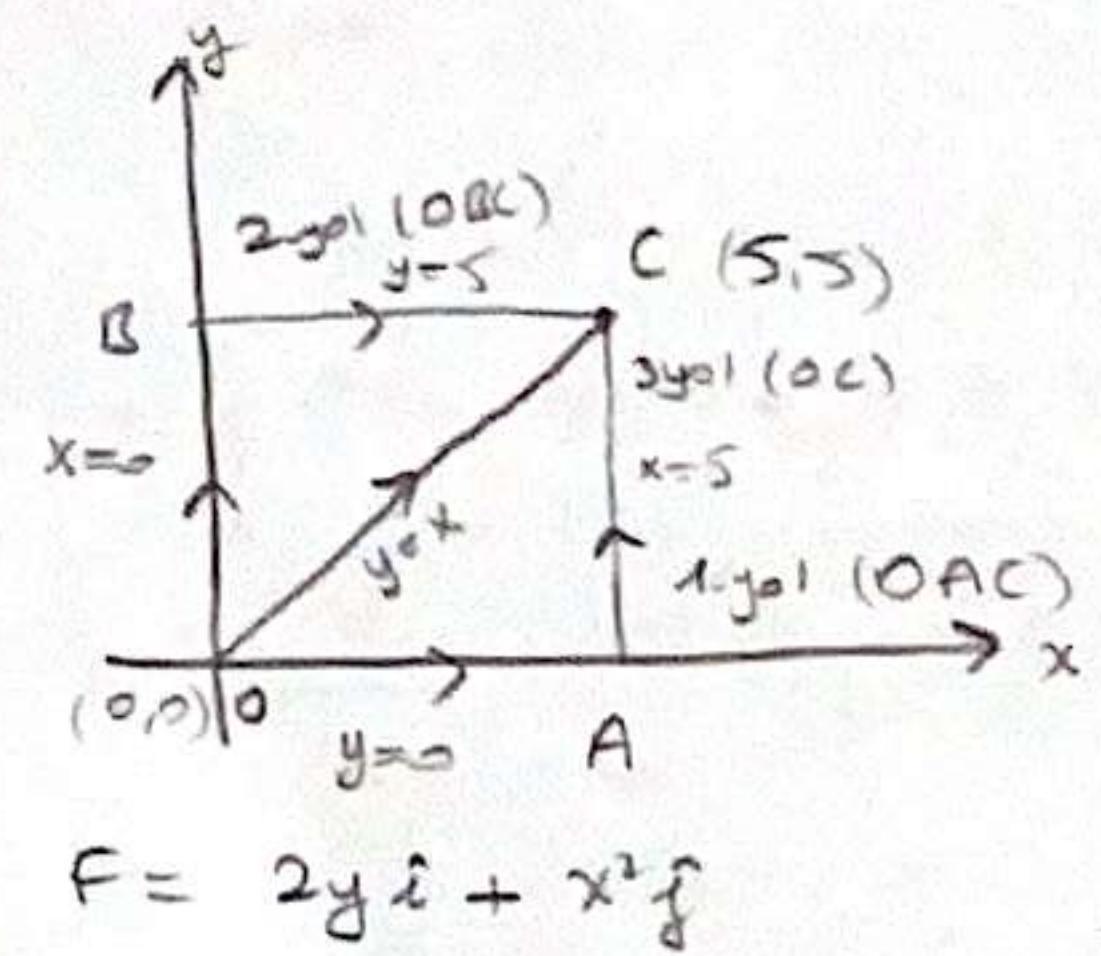


$$(U_{g1} - U_{g2})_1 + (U_{g2} - U_{g1})_2 + (K_1 - K_2)_1 + (K_2 - K_1)_2 + (E_{y1} - E_{y2}) = \frac{20 \cdot (9.8) \cdot 0.5 \cdot 0.2 \cdot 0.1}{0.64}$$

$$(20 \cdot 9.8 \cdot 0.2 \sin 40^\circ - 0) + (0 - 30 \cdot (9.8 \cdot 0.1)) + (\frac{1}{2} \cdot 20 \cdot 0.2^2 - 0) + (\frac{1}{2} \cdot 30 \cdot 0.2^2 - 0) + \frac{1}{2} \cdot 250 \cdot (0.2)^2 =$$

$$25.083 - 58.8 + 25 \cdot 0.2^2 + 5 = 3.028 \quad \boxed{v = 1.11 \text{ m/s}}$$

## Konstant-konstantlu kuvvetler



1-yol (OAC)

$$W_{OAC} = W_{OA} + W_{AC}$$

$$W_{OA} = \int (2yi + x^2j) dx\hat{i} = 0$$

$$W_{AC} = \int (2yi + x^2j) dy\hat{j}$$

$$W_{AC} = x^2 \int_0^5 dy\hat{j} = 25 \cdot 5 = 125$$

$$\boxed{W_{OAC} = 125 \text{ joule}}$$

2-yol (OBC)

$$W_{OBC} = W_{OB} + W_{BC}$$

$$W_{OB} = \int (2yi + x^2j) dx\hat{i} = 0$$

$$W_{OB} = x^2 \int dy\hat{j} = 0$$

$$\boxed{W_{OBC} = 50 \text{ joule}}$$

3-yol (OC)

$$W_{OC} = \int (2yi + x^2j) (dx\hat{i} + dy\hat{j}) = \int 2yidxi + \int x^2j dy\hat{j}$$

$$\int_0^5 2x dx\hat{i} + \int_0^5 y^2 j dy\hat{j}$$

$$\underbrace{x^2}_{25} \Big|_0^5 + \underbrace{\frac{y^3}{3}}_{125/3} \Big|_0^5 = 66.67 \text{ joule}$$

$$\boxed{W_{OC} = 66.67 \text{ joule}}$$

## Lineer momentum ve çarpışmalar

1 2 3 i  
j

$$\sum \vec{F}_1 = \vec{F}_{11} + \vec{F}_{21} + \vec{F}_{31} + \dots + \vec{F}_{i1} + \dots$$

$$\sum \vec{F}_2 = \vec{F}_{12} + \vec{F}_{22} + \vec{F}_{32} + \dots$$

$$+ \sum \vec{F}_i = \vec{F}_{1i} + \vec{F}_{2i} + \dots$$

$$\sum \vec{F}_1 + \sum \vec{F}_2 + \vec{F}_3 + \dots + \vec{F}_i = 0$$

$$m_1 \vec{a}_1 + m_2 \vec{a}_2 + m_3 \vec{a}_3 + \dots + m_i \vec{a}_i = 0$$

$$m_1 \frac{d\vec{v}_1}{dt} + m_2 \frac{d\vec{v}_2}{dt} + \dots + m_i \frac{d\vec{v}_i}{dt} = 0$$

$$\frac{d}{dt}(m_1 \vec{v}_1) + \frac{d}{dt}(m_2 \vec{v}_2) + \dots + \frac{d}{dt}(m_i \vec{v}_i) = 0$$

$$\frac{d}{dt}(m_1 \vec{v}_1 + m_2 \vec{v}_2 + \dots + m_i \vec{v}_i) = 0$$

$$\frac{d}{dt}(\vec{P}_{\text{toplam}}) = 0$$

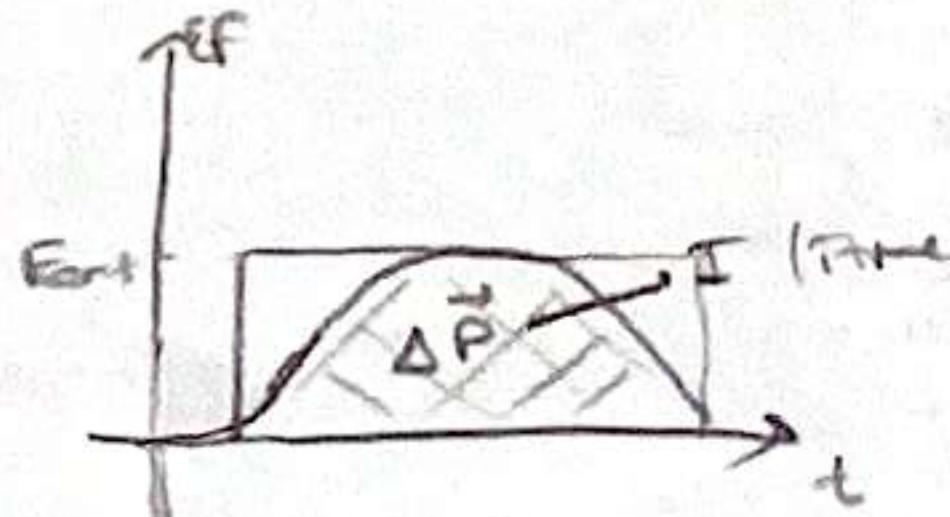
$$\sum \vec{p}_i = \vec{p}_s$$

$$\sum \vec{p}_{ix} = \sum p_{sx} \dots$$

$$\sum \vec{F} - m \cdot \frac{d\vec{v}}{dt} \Rightarrow \sum \vec{F} = \frac{d}{dt}(m \vec{v}) = \sum \vec{F} = \frac{d\vec{p}}{dt}$$

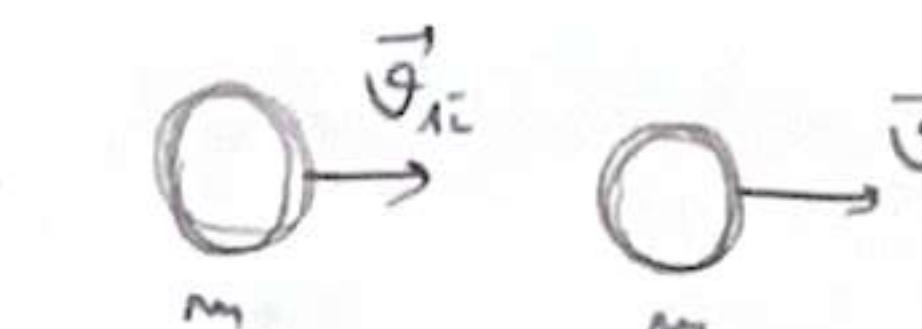
$$\int_{P_i}^{\vec{P}} d\vec{P} = \int_0^t \sum \vec{F} \cdot dt \Rightarrow \vec{P} - \vec{P}_i = \Delta \vec{P} = \int_0^t \sum \vec{F} dt$$

$$\Delta \vec{P} = \int_0^t \sum \vec{F} dt$$

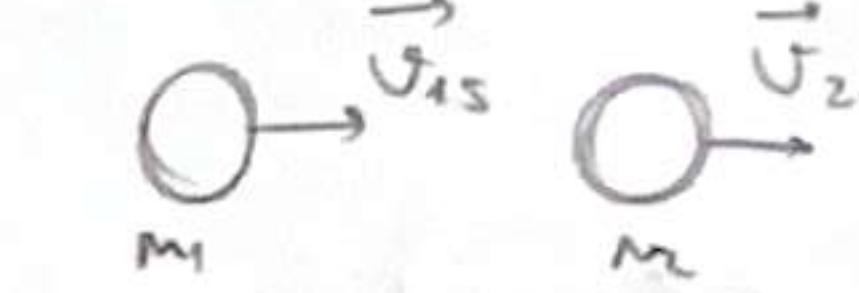


$$F_{\text{ort}} = \frac{1}{\Delta t} \int_{t_1}^{t_2} \sum F dt$$

$$F_{\text{ort}} \cdot \Delta t = \Delta \vec{P}$$



$$\sum \vec{p}_i = \sum \vec{p}_s$$



$$\sum \vec{v}_i = \sum \vec{v}_s$$

$$\textcircled{1} \quad m_1 \vec{v}_{1i} + m_2 \vec{v}_{2i} = m_1 \vec{v}_{1s} + m_2 \vec{v}_{2s} \quad \textcircled{2} \quad \frac{1}{2} m_1 (v_{1i})^2 + \frac{1}{2} m_2 (v_{2i})^2 = \frac{1}{2} m_1 (v_{1s})^2 + \frac{1}{2} m_2 (v_{2s})^2$$

$$m_1 (v_{1i} - v_{1s}) = m_2 (v_{2s} - v_{2i})$$

$$m_1 ((v_{1i})^2 - (v_{1s})^2) = m_2 ((v_{2s})^2 - (v_{2i})^2)$$

$$\textcircled{3} \quad m_1 (v_{1i} - v_{1s}) (v_{1i} + v_{1s}) = m_2 (v_{2s} - v_{2i}) (v_{2s} + v_{2i})$$

$$\textcircled{4} \quad m_1 (v_{1i} - v_{1s}) = m_2 (v_{2s} - v_{2i})$$

$$v_{1i} + v_{1s} = v_{2i} + v_{2s}$$

$$v_{2s} = v_{1i} + v_{1s} - v_{2i}$$

$$m_1 v_{1i} + m_2 v_{2i} = m_1 v_{1s} + m_2 (v_{1i} + v_{1s} - v_{2i})$$

$$(m_1 + m_2) v_{1s} = (m_1 + m_2) v_{1i} + 2m_2 v_{2i}$$

$$v_{1s} = \left( \frac{m_1 - m_2}{m_1 + m_2} \right) v_{1i} + \left( \frac{2m_2}{m_1 + m_2} \right) v_{2i}$$

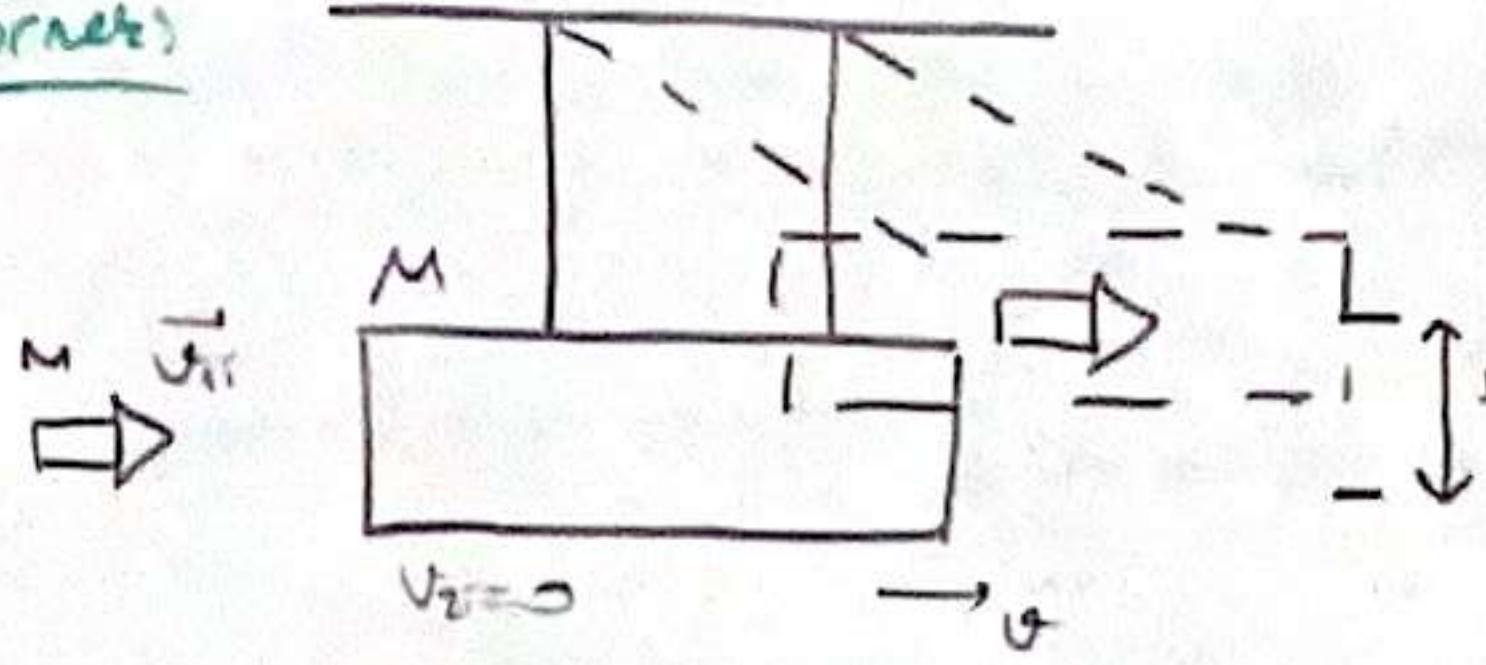
$$v_{1s} = v_{2i} + v_{2s} - v_{2i}$$

$$m_1 v_{1i} + m_2 v_{2i} = m_1 (v_{2i} + v_{2s} - v_{1s}) + m_2 v_{2s}$$

$$2m_1 v_{1i} + (m_2 - m_1) v_{2s} = (m_1 + m_2) v_{2s}$$

$$v_{2s} = \left( \frac{m_2 - m_1}{m_1 + m_2} \right) v_{1i} + \left( \frac{2m_1}{m_1 + m_2} \right) v_{2i}$$

Ornet



$$\sum \vec{P} = \sum \vec{P}_S$$

$$M \cdot \vec{v}_i = (m+M) \cdot v_S$$

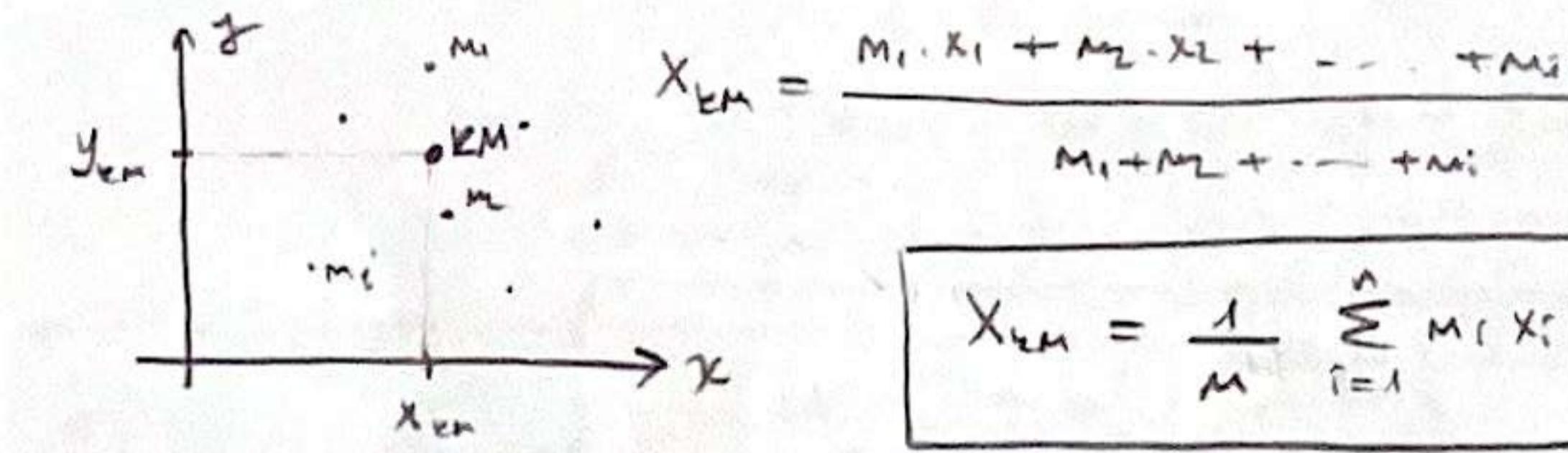
$$v_S = \left( \frac{M}{m+M} \right) v_i$$

$$\frac{1}{2}(m+M) v_S^2 = (m+M) g H$$

$$\frac{M^2}{2(m+M)^2} v_i^2 = gH$$

$$g_H = \left( \frac{m+M}{M} \right) \sqrt{2gH}$$

Koordinaten

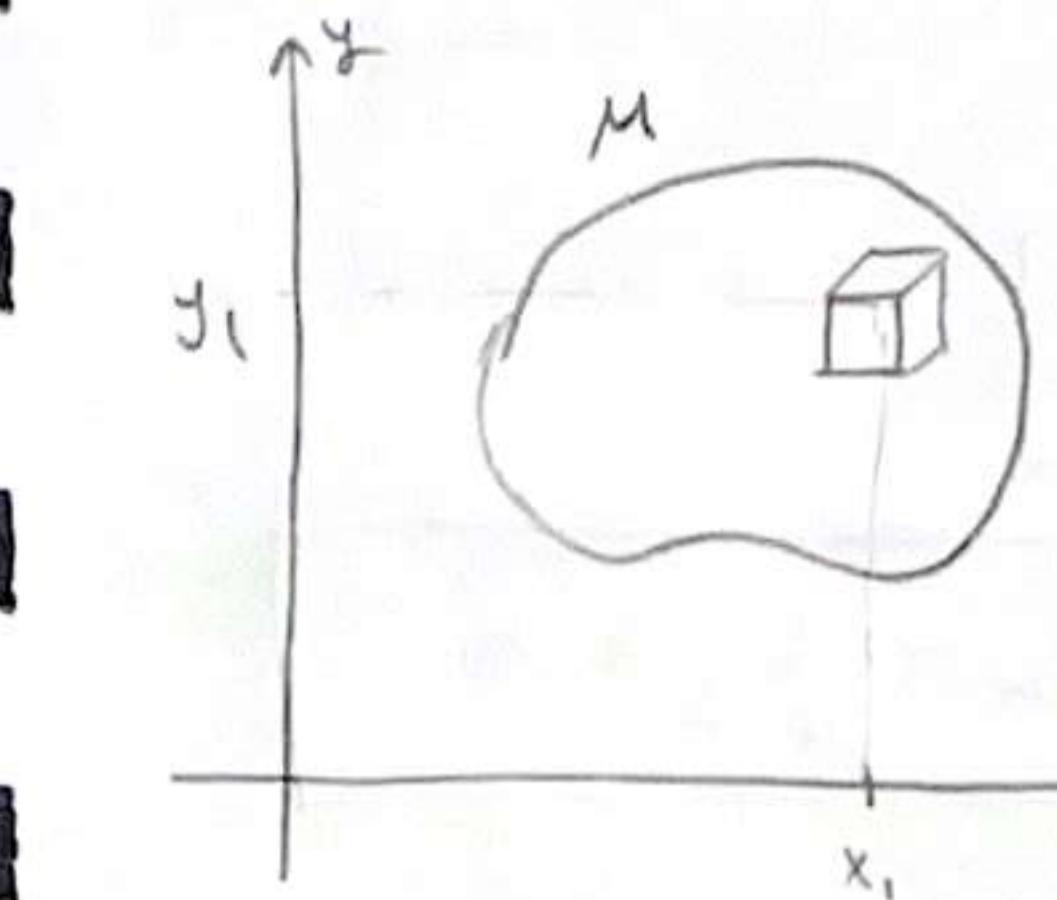


$$m_1 + m_2 + \dots + m_i = M$$

$$\vec{r}_{cm} = x_{cm} \cdot \hat{i} + y_{cm} \cdot \hat{j}$$

$$\vec{r}_{cm} = \frac{1}{M} \sum_{i=1}^M [(m_i x_i) \hat{i} + (m_i y_i) \hat{j}] \quad \text{zusammen}$$

Screen little depthwise small cylinder

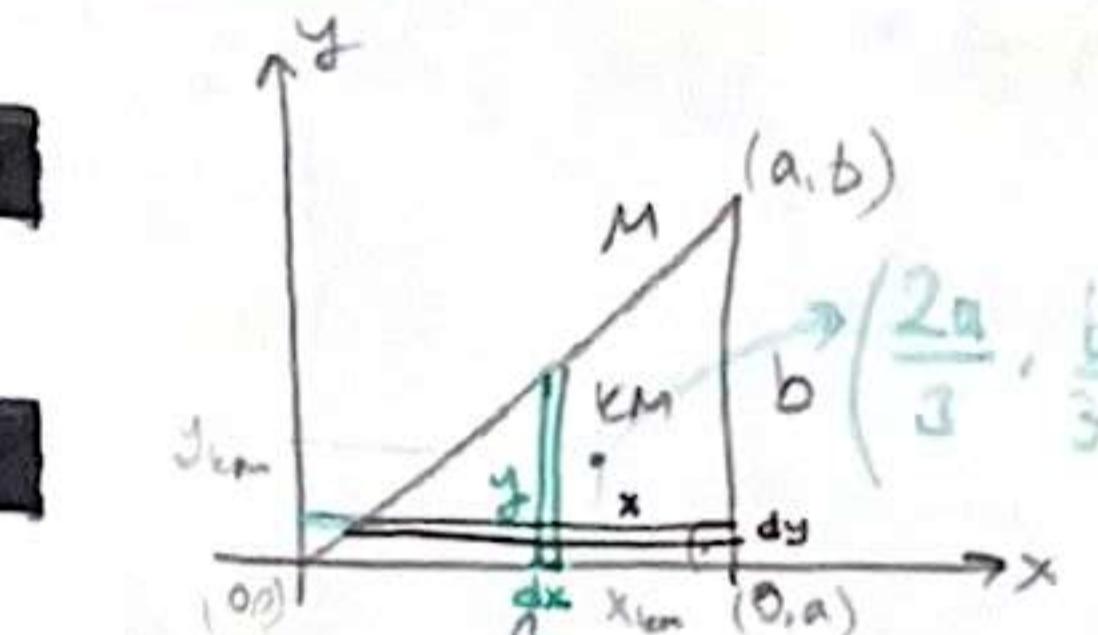


$$x_{cm} = \frac{1}{M} \lim_{\Delta m \rightarrow 0} \sum_{i=1}^{\infty} \Delta m_i x_i$$

$$x_{cm} = \frac{1}{M} \int x dm$$

$$y_{cm} = \frac{1}{M} \int y dm$$

Ornet:



$$x_{cm} = \frac{1}{M} \int \frac{2My}{ab} dx$$

$$x_{cm} = \frac{1}{M} \cdot \frac{2M}{ab} \cdot \frac{b}{a} \int x^2 dx$$

$$x_{cm} = \frac{2}{a^2} \left( -\frac{a^3}{3} \right) \Rightarrow x_{cm} = \frac{2a}{3}$$

$$\frac{ab}{2} \times M \quad dm = \frac{2My}{ab} dx \quad \frac{b}{a} = \frac{y}{x} \quad \frac{bX}{a} = y$$

$$y_{cm} = \frac{1}{M} \int y \cdot \frac{2MX}{ab} dy \quad x = a - \frac{a}{b} y$$

$$y_{cm} = \frac{1}{M} \cdot \frac{2M}{ab} \int_0^b \left( a - \frac{a}{b} y \right) y dy$$

$$\left. \frac{ay^2}{2} - \frac{ay^3}{3b} \right|_0^b = 3ab^3 - \frac{2ab^3}{6b} = \frac{ab^3}{6b} = \frac{ab^2}{6}$$

$$y_{cm} = \frac{2}{ab} \cdot \frac{ab^2}{6} \Rightarrow y_{cm} = \frac{b}{3}$$





Grund

$$I = \int x^2 dm$$

$$I = \lambda \int_0^L x^2 dx$$

$$I = \lambda \cdot \left( \frac{x^3}{3} \Big|_0^L \right) \quad \boxed{I = \frac{1}{2} M L^2}$$

$$dm = \lambda \cdot dx$$

$$\lambda = \frac{M}{L}$$

$$I = \int x^2 dm$$

$$I = \lambda \int_0^L x^2 dx$$

$$I = \lambda \cdot \left( \frac{x^3}{3} \Big|_0^L \right) \quad \boxed{I = \frac{1}{2} M L^2}$$

Tork

$$\sum F_{\text{torq}} = (\sum F_{\text{torq}}) \cdot d$$

$$\sum \tau = \vec{r} \times \vec{F}$$

$$|\vec{r}| = d$$

$$\sum \tau = \sum F_t \cdot r \cdot \sin 90^\circ$$

$$\sum \tau = \sum F_t \cdot r \quad \sum F_t = M \cdot a_t$$

$$\sum \tau = M \cdot a \cdot r^2 \quad a_t = a \cdot r$$

$$\sum \tau = I \cdot \alpha$$

Grund

$$\sum \tau = Mg \frac{L}{2} \quad I = \frac{1}{3} M L^2$$

$$\sum \tau = Mg \frac{L}{2} = I \cdot \alpha$$

$$Mg \frac{L}{2} = \frac{1}{3} M \cdot L^2 \cdot \alpha$$

$$\alpha = \frac{3g}{2L} \cdot k = \frac{3g}{2L} = a$$

$$\alpha = \frac{3g}{2L} \cdot k = \frac{3g}{2L} = a$$

Grund

$$\sum \tau = \frac{T}{mg} K = I \cdot \alpha \quad \frac{TR}{I} = \omega \quad \frac{IR^2}{I} = a$$

$$F = m \cdot a$$

$$\frac{mg - T}{m} = a = \frac{TR^2}{I}$$

$$mg - T = mTR^2 \quad mgI - TI = mTR^2$$

$$T = \frac{mgI}{I + mR^2} \quad a = \frac{mgI^2}{I + mR^2}$$

### Dönne hårda virande energi

$$W_{\text{net}} = \Delta E_k = \frac{1}{2} M v_f^2 - \frac{1}{2} M v_i^2$$

$$dS = r \cdot d\theta \quad dW = \vec{F} \cdot d\vec{S}$$

$$dW = F \cdot dS \cdot \cos \beta \quad \beta + \theta = 90^\circ$$

$$dW = F \cdot dS \cdot \sin \theta$$

$$dW = F \cdot r \cdot d\theta \cdot \sin \theta$$

$$dW = \tau \cdot d\theta$$

$$\tau = I \cdot \alpha = I \cdot \frac{d\omega}{dt}$$

$$dW = I \frac{d\omega}{dt} d\theta$$

$$\int dW = I \int \frac{d\omega}{dt} d\theta$$

$$W_{\text{net}} = I \left( \frac{\omega_f^2}{2} - \frac{\omega_i^2}{2} \right)$$

$$W_{\text{net}} = \frac{1}{2} I \omega_f^2 - \frac{1}{2} I \omega_i^2 \quad W_{\text{net}} = \Delta E_k$$

### Grund

$$I = \frac{1}{3} M L^2$$

$$V_{\text{kin}} = \frac{L}{2} \cdot \sqrt{\frac{3g}{L}}$$

$$V_{\text{kin}} = L \cdot \sqrt{\frac{3g}{L}}$$

a) Citera dvs. kanna ge lagrare  $\omega = ?$

b) Kom vi en ic relativt enligt viken?

$$(V_{\text{ss}} - V_{\text{gi}}) + (K_s - K_i)_{\text{dönre}} = 0$$

$$(Mg \frac{L}{2} - Mg \cdot L) + \left( \frac{1}{2} I \omega_f^2 - 0 \right) = 0$$

$$\frac{1}{2} \cdot \frac{1}{3} M L^2 \cdot \omega_f^2 = Mg \frac{L}{2}$$

$$\omega_f = \sqrt{\frac{3g}{L}}$$

Übung:  $\theta = (5 + 10t + 2t^2)$  rad  $t=3$  s n. räuml. aksial konv., aksial  
Wt w. aksial moment. erhalten

$$\theta(3) = 5 + 10 \cdot 3 + 2 \cdot 3^2 = 55$$

$$\omega(3) = 10 + 4 \cdot 3 = 22$$

Berech: Auseinander  $(10+6t)$  rad/s zu liefern in 2 Schritte S. anstreben  
ne. jeder an Hand?

$$\int (10+6t) dt = 10t + 3t^2 \quad \int (10t+3t^2) dt = \frac{5t^2 + t^3}{2} \Big|_0^3 \\ 5 \cdot 16 + 6 \cdot 9 = 144$$

Berech:

a) Auseinander drehen eben dyn. zentriert um  
durch eingesetzte momenta mit abgleichen ges.  
 $\mu = \frac{I}{M+m}$  (für  $I = \mu L^2$ ) abgleichen gesamt  
 $I = MX^2 + M(L-x)^2$

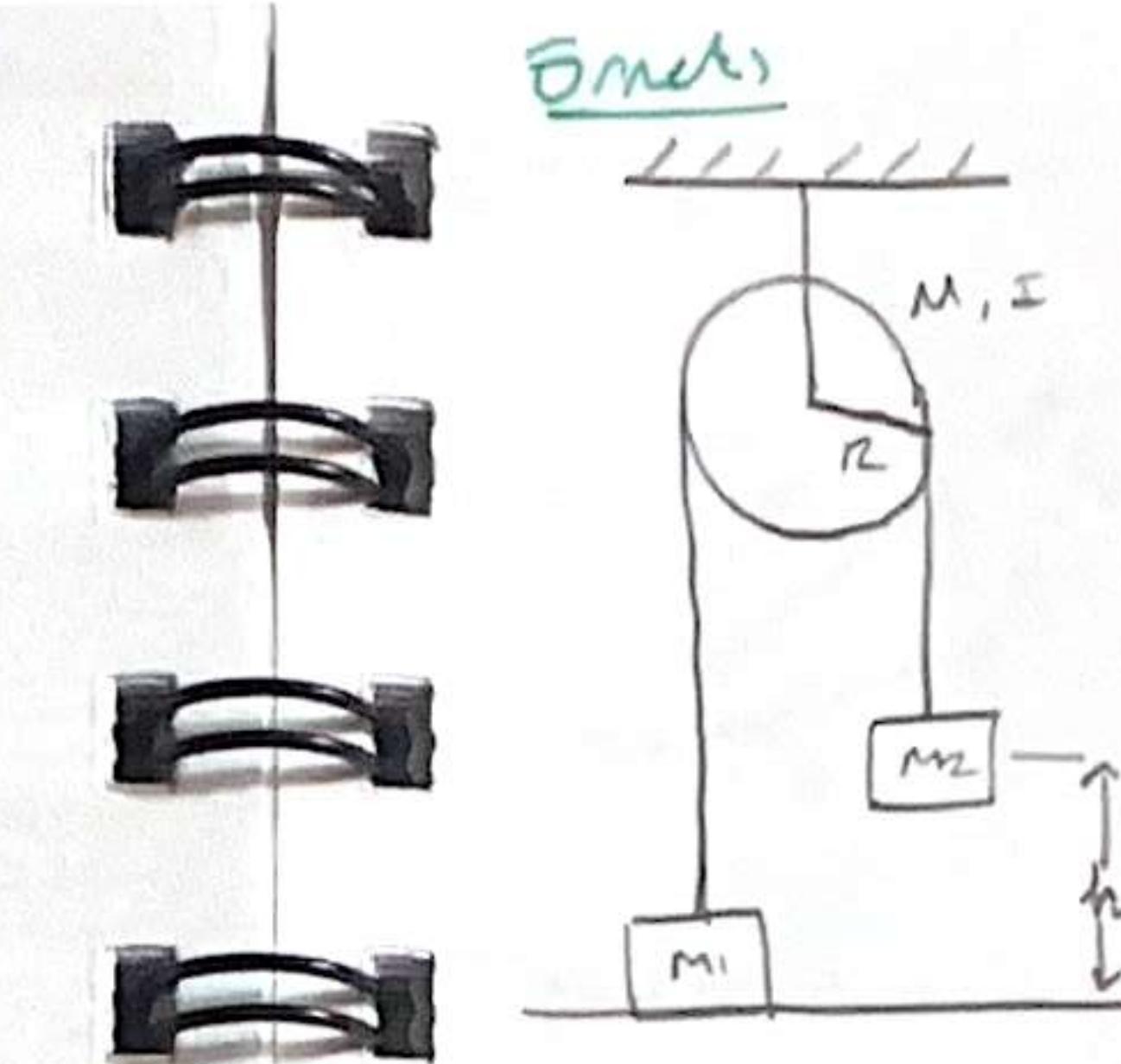
$$(I = MX^2 + M(L-x)^2 - 2mx + mx^2) \Rightarrow \frac{dI}{dx} = 2MX - 2ML + 2mx = 0$$

$$MX = ML - mx \quad x(M+m) = \frac{ML}{M+m}$$

Moment.

$$Mg \cdot \left(\frac{m}{M+m}\right) \cdot L = mg \left(L - \frac{ML}{M+m}\right) \quad \frac{Mm}{M+m} = \frac{ML}{M+m} \quad \checkmark$$

$$I = M \frac{m^2 L^2}{(M+m)^2} + m \left(L - \frac{ML}{M+m}\right)^2 \\ = \frac{m^2 L^2 M}{(M+m)^2} + \frac{m \cdot M^2 L^2}{(M+m)^2} = \frac{Mm L^2}{(M+m)^2} \cdot (M+m) \Rightarrow \frac{Mm L^2}{(M+m)} \mu$$



Übung:  $M_2 > M_1$  Agy. zwischen den geladenen Werten her bestimmen man  
bulova

$$\Delta U_g + \Delta K_D + \Delta K_S = 0$$

$$(U_{S2} - U_{S1})_1 + (U_{D2} - U_{D1})_2 + (K_{D2} - K_{D1})_1 + (K_{S2} - K_{S1})_2 = 0$$

$$(m_1 \cdot g \frac{h}{2} - m_1 \cdot g h) + (m_2 \cdot g \frac{h}{2} - 0) + (0 - \frac{1}{2} I \omega^2) + (\frac{1}{2} m_1 v^2 - 0) + (\frac{1}{2} m_2 v^2 - 0) = 0$$

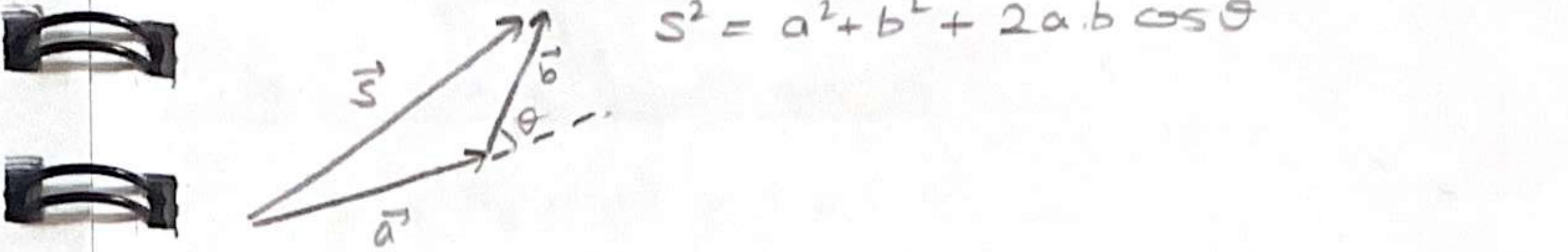
$$g \frac{h}{2} (m_2 - m_1) + \frac{g^2}{2} (m_1 + m_2) - \frac{1}{2} I \cdot \omega^2 = 0 \quad w.r.e. = \checkmark \quad w = \frac{v}{r}$$

$$g \frac{h}{2} (m_2 - m_1) + \frac{v^2}{2} (m_1 + m_2) - \frac{1}{2} \cdot I \cdot \frac{v^2}{R^2} = 0$$

$$\frac{v^2}{2} \left( m_1 + m_2 - \frac{I}{R^2} \right) = (m_1 - m_2) \cdot g \frac{h}{2}$$

$v = \sqrt{\frac{(m_1 - m_2) g h}{(m_1 + m_2 - I/R^2)}}$

# FİZİK-1 (FINAL ÖZET)



$$s^2 = a^2 + b^2 + 2a \cdot b \cos \theta$$

skaler çarpma:  $\vec{a} \cdot \vec{b} = a \cdot b \cos \phi = a_x b_x + a_y b_y + a_z b_z$

vektörel çarpma:  $\vec{c} = \vec{a} \times \vec{b} \Rightarrow c = a \cdot b \cdot \sin \phi$

$$\vec{c} = -(\vec{b} \times \vec{a})$$



kinematik denklemler:

$$v = v_0 + a \cdot t$$

$$x = x_0 + v_0 \cdot t + \frac{1}{2} a t^2 \quad v^2 = v_0^2 + 2a(x - x_0)$$

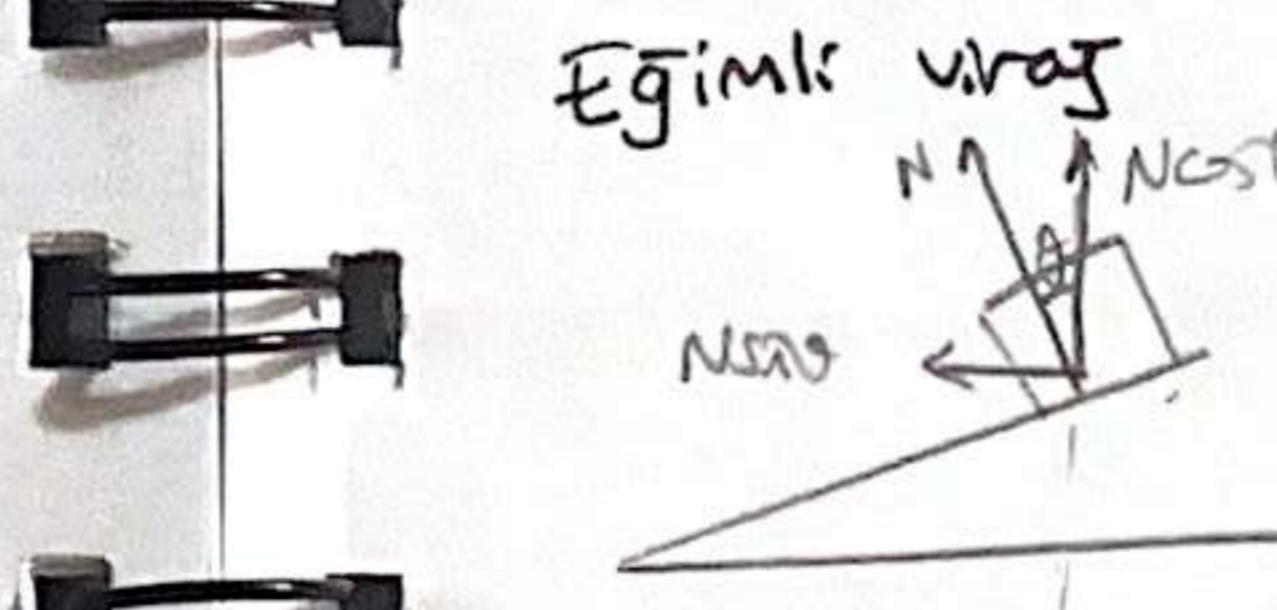
Dizgen dairesel hareket:

$$\text{Merkezdeki radyo} \quad a = \frac{v^2}{r} \quad T = \frac{2\pi r}{v}$$

Açılışçı senten

$$\text{Yukarı (umur)} \Rightarrow T - Mg = ma \Rightarrow T = M(g + a)$$

$$\text{Aşağı (umur)} \Rightarrow T - Mg = -ma \Rightarrow T = M(g - a)$$

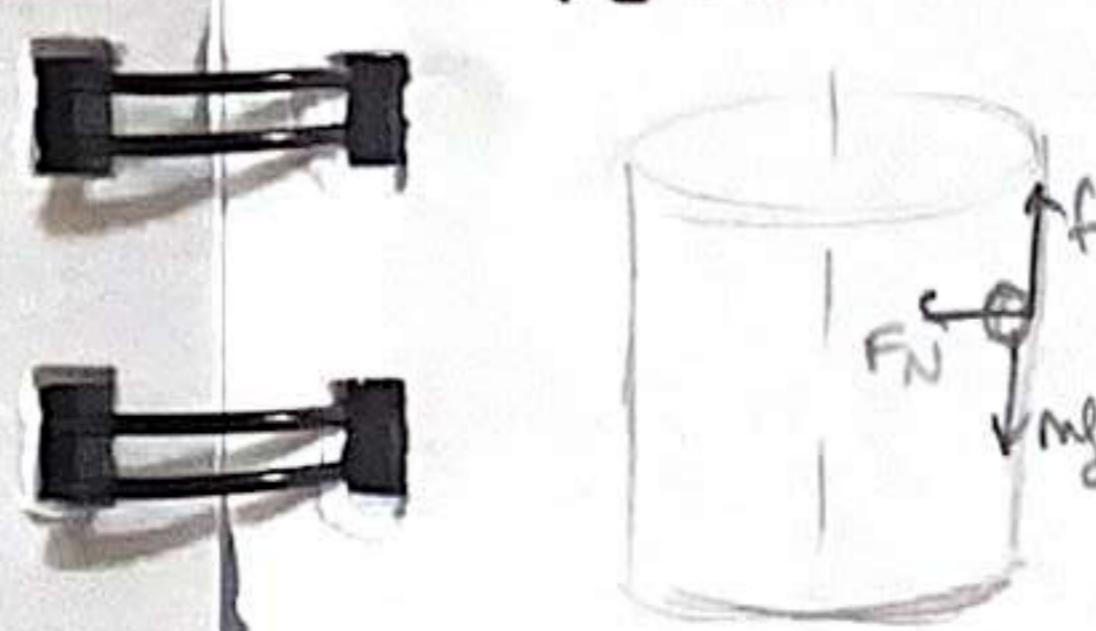


Eğimde viraj

$$N \sin \theta = \frac{mv^2}{r}$$

$$\tan \theta = \frac{v^2}{gr}$$

Rotor

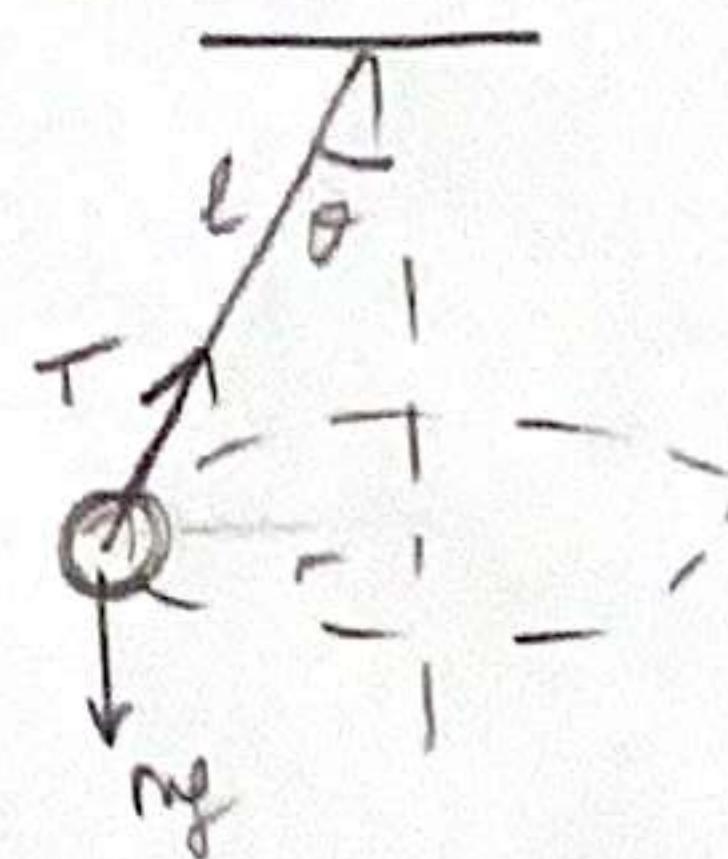


$$F_N = M \cdot a = \frac{Mv^2}{r}$$

$$v_{min} = \sqrt{\frac{rg}{\mu_s}}$$

$$f_s = \mu_s \cdot F_N = mg$$

## Konke sarkas



$$T \cos \theta = mg \quad T \sin \theta = \frac{mv^2}{r} \quad \tan \theta = \frac{v^2}{gr}$$

$$v = \sqrt{\tan \theta gr} = \sqrt{\tan \theta g r \omega^2}$$

Güç

$$P_{\text{net}} = \frac{W}{\Delta t} \quad P = \frac{dW}{dt} \quad P = \vec{F} \cdot \vec{v} \quad | \quad \vec{p} = \vec{v} \cdot \vec{p}$$

## Kütte merkezi

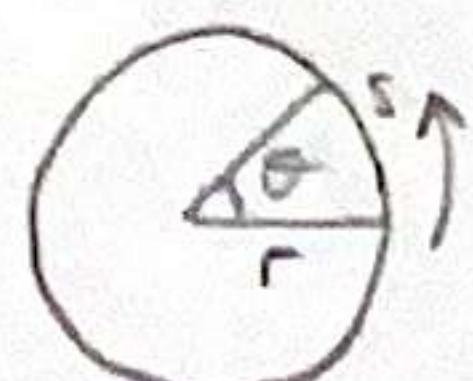
$$x_m = \frac{1}{M} \int x dm \quad (\text{homogen})$$

$$\lambda = \frac{dm}{dx} = \frac{M}{L} \quad x_m = \frac{1}{M} \int x \lambda dx$$

$$\sigma = \frac{dm}{dA} = \frac{M}{A} \quad x_m = \frac{1}{M} \int x \sigma dA$$

$$\rho = \frac{dm}{dv} = \frac{M}{V} \quad x_m = \frac{1}{M} \int x \rho dv$$

## Dönme hareketi



$$s = \theta \cdot r$$

$$\alpha_r = \frac{v^2}{r} \quad \text{rad/s}^2 \quad \text{time}$$

$$a = \sqrt{a_t^2 + a_r^2}$$

## Eylensitik moment

$$I = \int r^2 dm$$

$$I = I_{\text{em}} + M r^2$$

$r$  koder uatta eylensitik mom.

## Tork

$$T = I \alpha$$

İz ve dönme kütte enerjisi

$$dW = F_t r d\theta = r d\theta$$

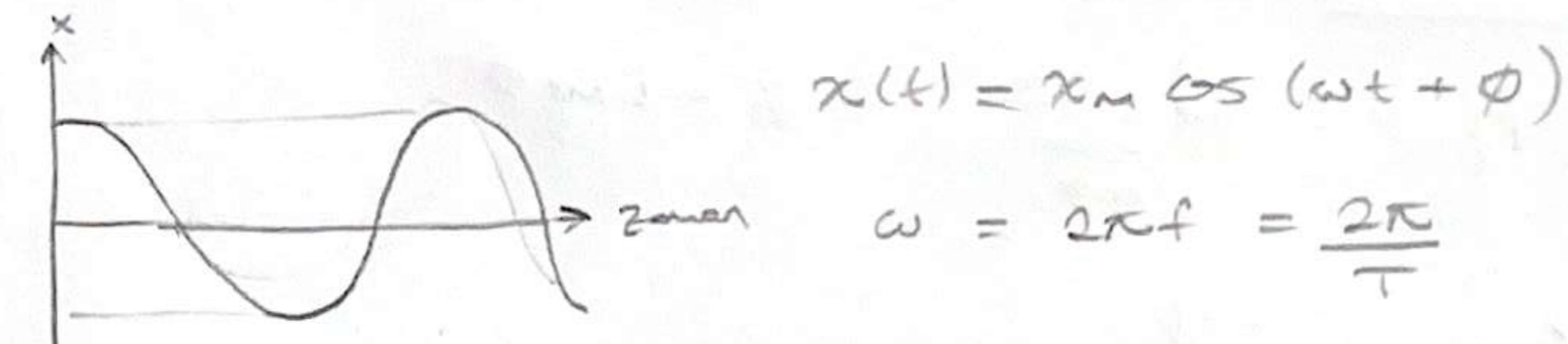
$$W = \int F_t r d\theta = \int_{\theta_i}^{\theta_f} r d\theta$$

## Açışal momentum

$$\vec{l} = \vec{r} \times \vec{p} \quad l = r \cdot m \cdot v \cdot \sin \phi$$

$$L = I \cdot \omega$$

## BHH



$$v(t) = \frac{d(x(t))}{dt} = -\omega x_m \sin(\omega t + \phi)$$

$$a(t) = \frac{d(v(t))}{dt} = -\omega^2 x_m \cos(\omega t + \phi) = -\omega^2 x(t)$$

$$F = m \cdot a = -m \omega^2 x$$

$$F = -k x \quad m \omega^2 = k \rightarrow T = 2\pi \sqrt{\frac{m}{k}}$$

$$\omega = \sqrt{\frac{k}{m}}$$

$$U = \frac{1}{2} k x^2 = \frac{1}{2} k x_m^2 \cos^2(\omega t + \phi)$$

$$K = \frac{1}{2} m v^2 = \frac{1}{2} m \omega^2 x_m^2 \sin^2(\omega t + \phi)$$

+  
 $\frac{k}{m} \Rightarrow K = \frac{1}{2} k x_m^2 \sin^2(\omega t + \phi)$

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Burukta sarkah

$$\tau = -k\theta \quad F = -Cx \quad C = k$$

$$\omega = \sqrt{\frac{C}{I}} = \sqrt{\frac{k}{I}} \quad T = 2\pi \sqrt{\frac{I}{C}} = 2\pi \sqrt{\frac{I}{k}}$$

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BASA sarkah

$$\tau = r_L f_g = -Lmg \underbrace{\sin \theta}_{\approx \theta} \approx -Lmg \theta$$

$$F = -Cx \quad C = Lmg$$

$$\omega = \sqrt{\frac{C}{I}} = \sqrt{\frac{mgL}{I}} \quad T = 2\pi \sqrt{\frac{I}{C}} = 2\pi \sqrt{\frac{ML^2}{Lmg}} = 2\pi \sqrt{\frac{L}{g}}$$