

~~~~~ FUNCTIONS AND PROPERTIES ~~~~~

<p>GREATEST INTEGER FUNCTION</p> <p>$f(x) = \lfloor g(x) \rfloor$ and $n \in \mathbb{Z}$;</p> <p>$f(a) = n + 1, \text{ if } n < g(a) \leq n + 1$</p>	<p style="text-align: right;">y = [x]</p> <p style="text-align: right;">MathBits.com</p>
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<p>SIGNUM FUNCTION</p> $sgn(f(x)) = \begin{cases} -1, & \text{if } f(x) < 0 \\ 0, & \text{if } f(x) = 0 \\ 1, & \text{if } f(x) > 0 \end{cases}$ $\rightarrow sgn(f(x)) = \frac{d}{dx} f(x) \text{ for } x \neq 0$ $\rightarrow f(x) = sgn(f(x)) \cdot f(x) $ $\rightarrow sgn(x^n) = sgn(x)^n$		
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<p>PERIODIC FUNCTIONS</p> <p>$f(x + T) = f(x)$. Then f is periodic function and T is called period of f.</p>	
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<p>TRIGONOMETRIC FUNCTIONS</p>			
Unit Circle	<p>Perimeter of Unit Circle:</p> $2\pi r = 2\pi, \text{ since } r = 1$	$l = 2\pi r \cdot \frac{t}{2\pi} = t$ <p>So, arc length is equal to dimension of angle in a unit circle</p>	
Periods of Trigonometric Functions	<p>Arc length in Unit Circle: (t is central angle of arc)</p>	$\sin^{2n+1}(ax + b), \cos^{2n+1}(ax + b), \sec^{2n+1}(ax + b), \csc^{2n+1}(ax + b)$	$\frac{2\pi}{ a }$
Periods of Trigonometric Functions	<p>$n \in \mathbb{N}$</p>	$\sin^{2n}(ax + b), \cos^{2n}(ax + b), \sec^{2n}(ax + b), \csc^{2n}(ax + b), \tan^n(ax + b), \cot^n(ax + b)$	$\frac{\pi}{ a }$

LOGARITMIC FUNCTIONS AND PROPERTIES

1. $\log_a x, \quad x \in \mathbb{R}^+, \quad a \in \mathbb{R}^+ - \{1\}$	2. $f(x) = a^x \Rightarrow f^{-1}(x) = \log_a x$
3. $\log_a a = 1$	4. $\log_a 1 = 0$
5. $\log_a a^n = n$	6. $\log_a x^n = n \cdot \log_a x = n$
7. $\log_{a^m} x = \frac{1}{m} \cdot \log_a x = \frac{1}{m}$	8. $\log_{a^m} x^n = \frac{n}{m} \cdot \log_a x = \frac{n}{m}$
9. $\log x = \log_{10} x$	10. $\ln x = \log_e x$
11. $\log_a x \cdot y = \log_a x + \log_a y$	12. $\log_a \frac{x}{y} = \log_a x - \log_a y$
13. $\log_a x = \frac{\log x}{\log a} = \frac{\log_c x}{\log_c a}$	14. $\log_a x = \frac{1}{\log_x a}$
15. $\log_a y \cdot \log_y x = \log_a x$	16. $a^{\log_c x} = x^{\log_c a}$
17. $a^{\log_a x} = x^{\log_a a} = x$	18. $e^{\ln x} = x$

HYPERBOLIC AND INVERSE HYPERBOLIC FUNCTIONS

Hyperbolic Functions	Inverse Hyperbolic Functions	
$\sinh x = \frac{e^x - e^{-x}}{2}$	$\operatorname{arcsinh} x = \ln(x + \sqrt{x^2 + 1})$	$x \in \mathbb{R}$
$\cosh x = \frac{e^x + e^{-x}}{2}$	$\operatorname{arccosh} x = \ln(x + \sqrt{x^2 - 1})$	$x \geq 1$
$\tanh x = \frac{e^x - e^{-x}}{e^x + e^{-x}}$	$\operatorname{arctanh} x = \frac{1}{2} \ln \frac{1+x}{1-x}$	$ x < 1$
$\coth x = \frac{e^x + e^{-x}}{e^x - e^{-x}}$	$\operatorname{arccoth} x = \operatorname{arctanh} \frac{1}{x} = \frac{1}{2} \ln \frac{x+1}{x-1}$	$ x > 1$
$\operatorname{sech} x = \frac{2}{e^x - e^{-x}}$	$\operatorname{arcsech} x = \operatorname{arccosh} \frac{1}{x} = \ln \left(\frac{1 + \sqrt{1 - x^2}}{x} \right)$	$0 < x \leq 1$
$\operatorname{csch} x = \frac{2}{e^x + e^{-x}}$	$\operatorname{arccsch} x = \operatorname{arcsinh} \frac{1}{x} = \ln \left(\frac{1}{x} + \frac{1 + \sqrt{1 + x^2}}{ x } \right)$	$x \neq 0$

Properties of Hyperbolic Functions:

$\rightarrow \cosh^2 x - \sinh^2 x = 1$ $\rightarrow \cosh(-x) = \cosh x$ $\rightarrow \sinh(-x) = -\sinh x$	$\rightarrow \sinh(x+y) = \sinh x \cosh y + \sinh y \cosh x$ $\rightarrow \cosh x + y = \cosh x \cosh y + \sinh x \sinh y$ $\rightarrow \cosh 2x = 2 \cosh^2 x - 1 = \sinh^2 x + \cosh^2 x = 2 \sinh^2 x + 1$
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POLYNOMIAL FUNCTIONS

$$f(x) = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_2 x^2 + a_1 x + a_0$$

Polynomial	Degree	Example	Number of Terms	Name Using Number of Terms
Constant or Zero Polynomial	0	6	1	Monomial
Linear Polynomial	1	$3x+1$	2	Binomial
Quadratic Polynomial (Parabola)	2	$3x^2$	1	Monomial
Cubic Polynomial	3	$6x^3 + 3x^2 - 5x + 7$	4	Polynomial of 4 terms
Quartic Polynomial	4	$2x^4 + 4x^3 - 1$	3	Trinomial
Quintic Polynomial	5	$x^5 + 16$	2	Binomial

~~~~~ LIMIT & DERIVATIVE ~~~~

DEFINITION OF LIMIT

M, N, ε , $\delta > 0$	$x \rightarrow -\infty$	$x \rightarrow a$	$x \rightarrow \infty$
$f(x) \rightarrow -\infty$	$f(x) < -M$ ise; $x < -N(M)$	$f(x) < -M$ ise; $ x - a < \delta(M)$	$f(x) < -M$ ise; $x > N(M)$
$f(x) \rightarrow L$	$ f(x) - L < \varepsilon$ ise; $x < -N(\varepsilon)$	$ f(x) - L < \varepsilon$ ise; $ x - a < \delta(\varepsilon)$	$ f(x) - L < \varepsilon$ ise; $x > M(\varepsilon)$
$f(x) \rightarrow \infty$	$f(x) > M$ ise; $x < -N(M)$	$f(x) > M$ ise; $ x - a < \delta(M)$	$f(x) > M$ ise; $x > N(M)$

CONVERGENCE AND DIVERGENCE

If a limit of a thing is equal to a real number; (that is to say, the limit exist) “the thing is convergent”		If a limit of a thing is equal to infinity; (that is to say, the limit does not exist) “the thing is divergent”
Types of Thing	Condition of Convergent Thing	Condition of Divergent Thing
Sequence	$\lim_{n \rightarrow \infty} a_n = a$ where $a \in \mathbb{R}$ This means that the sequence converges to “a”	$\lim_{n \rightarrow \infty} a_n = \pm\infty$ This means that the sequence diverges to $\pm\infty$
Function	$\lim_{n \rightarrow \pm\infty} f(x) = L$ where $L \in \mathbb{R}$ This means that the function converges to “L”	$\lim_{n \rightarrow \pm\infty} f(x) = \pm\infty$ This means that the function diverges to $\pm\infty$
Infinite Series (Sum of Sequence)	$\lim_{n \rightarrow \infty} \sum_{i=0}^n a_n = \lim_{n \rightarrow \infty} S_n = S$ where $S \in \mathbb{R}$ This means that the series converges to “S”	$\lim_{n \rightarrow \infty} \sum_{i=0}^n a_n = \lim_{n \rightarrow \infty} S_n = \pm\infty$ This means that the series diverges to $\pm\infty$
Improper Integrals (Sum of function)	$\lim_{n \rightarrow \infty} \int_m^n f(x) dx = S$ where $S \in \mathbb{R}$ This means the integral converges to “S”	$\lim_{n \rightarrow \infty} \int_m^n f(x) dx = \pm\infty$ This means that the integral diverges to $\pm\infty$

SOME LIMIT CALCULATIONS

$$P(x) = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_2 x^2 + a_1 x + a_0 \quad \text{and} \quad Q(x) = b_m x^m + b_{m-1} x^{m-1} + \cdots + b_2 x^2 + b_1 x + b_0$$

$$\lim_{x \rightarrow \infty} \frac{P(x)}{Q(x)} = \begin{cases} \operatorname{sgn}\left(\frac{a_n}{b_m}\right) \cdot \infty, & n > m \\ \frac{a_n}{b_m}, & n = m \\ 0, & n < m \end{cases}$$

$$\lim_{x \rightarrow -\infty} \frac{P(x)}{Q(x)} = \begin{cases} \operatorname{sgn}\left(\frac{a_n x^n}{b_m x^m}\right) \cdot \infty, & n > m \\ \frac{a_n}{b_m}, & n = m \\ 0, & n < m \end{cases}$$

$$\lim_{x \rightarrow 0} \frac{\sin x}{x} = \lim_{x \rightarrow \infty} \frac{\sin(1/x)}{1/x} = \lim_{x \rightarrow \infty} x \cdot \sin(1/x) = 1$$

$$\lim_{x \rightarrow 0} \frac{\sin ax}{bx} = \lim_{x \rightarrow \infty} \frac{\sin(a/x)}{b/x} = \frac{a}{b}$$

$$\lim_{x \rightarrow 0} \frac{1 - \cos x}{x} = 0$$

$$\lim_{x \rightarrow \infty} \left(1 + \frac{1}{x}\right)^x = \lim_{x \rightarrow 0} (1+x)^{\frac{1}{x}} = \lim_{x \rightarrow \infty} \left(1 + \frac{a}{x}\right)^{\frac{x}{a}} = e$$

$$\lim_{x \rightarrow \infty} \left(1 + \frac{a}{cx+d}\right)^{bx} = e^{\frac{ab}{c}}$$

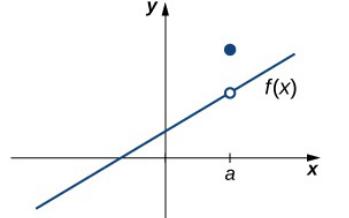
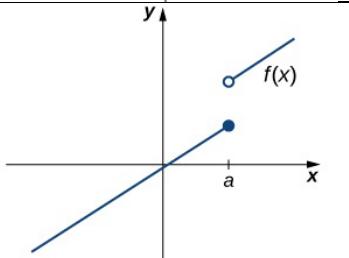
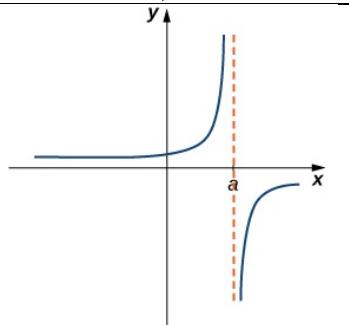
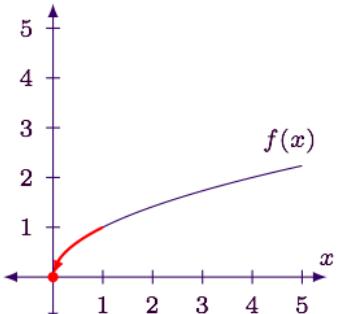
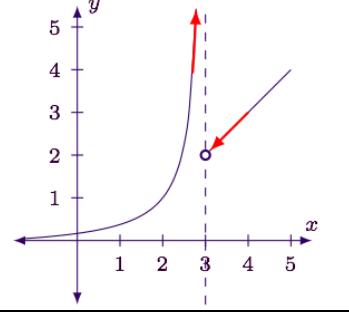
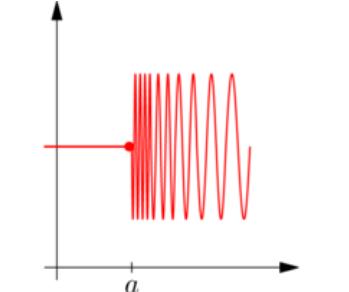
$$\lim_{x \rightarrow \infty} \left(1 + \frac{a}{Q(x)}\right)^{P(x)} = \begin{cases} \infty, & n > m \text{ and } \operatorname{sgn}\left(\frac{a_n}{b_m}\right) = 1 \\ 0, & n > m \text{ and } \operatorname{sgn}\left(\frac{a_n}{b_m}\right) = -1 \\ e^{a \cdot \frac{a_n}{b_m}}, & n = m \\ 1, & n < m \end{cases}$$

$$\lim_{x \rightarrow 0} \frac{x}{\log_a(1+x)} = \lim_{x \rightarrow 0} \frac{a^x - 1}{x} = \ln a \quad (a \neq 1, \quad a > 0)$$

CONDITION of DERIVATIVE, CONTINUITY AND LIMITS

Conditions of Derivative at Point " a "	Conditions of Continuity at Point " a "	Conditions of Limit at Point " a "	
		$\lim_{x \rightarrow a^-} f(x) \text{ exists}$	
		$\lim_{x \rightarrow a^+} f(x) \text{ exists}$	
		$\lim_{x \rightarrow a^-} f(x) = \lim_{x \rightarrow a^+} f(x) = L$	
		$\text{Then } \lim_{x \rightarrow a} f(x) = L$	
		$f(a) \text{ exists (f must be defined at "a")}$	
		$\lim_{x \rightarrow a} f(x) = L = f(a)$	
		$f'_-(a) = \lim_{h \rightarrow 0^-} \frac{f(a+h) - f(a)}{h} = \lim_{h \rightarrow 0^+} \frac{f(a+h) - f(a)}{h} = f'_+(a)$	
		$f'(a) \text{ exists (f' must be defined at a)}$	
		$(\text{For example, } y = \sqrt[3]{x} \text{ then } y' \text{ does not exist at "0"})$	

TYPES OF DISCONTINUITIES

Point/Removable Discontinuity	$\lim_{x \rightarrow a^-} f(x) = \lim_{x \rightarrow a^+} f(x)$ <i>and</i> $\lim_{x \rightarrow a} f(x) \neq f(a)$ or f is undefined at "a"	
Jump Discontinuity	$\lim_{x \rightarrow a^-} f(x) \neq \lim_{x \rightarrow a^+} f(x)$	
Asymptotic/Infinite Discontinuity	At least one of the one-sided limits is(are) infinite; $\lim_{x \rightarrow a} f(x) = \pm\infty$, $\lim_{x \rightarrow a^\pm} f(x) = -\infty$ and $\lim_{x \rightarrow a^\mp} f(x) = \infty$, $\lim_{x \rightarrow a^\pm} f(x) = \pm\infty$ and $\lim_{x \rightarrow a^\mp} f(x) = L$, $\lim_{x \rightarrow a^\pm} f(x) = \pm\infty$ and $\lim_{x \rightarrow a^\mp} f(x)$ does not exist	
Endpoint Discontinuity	$\lim_{x \rightarrow a^\pm} f(x) = L$ $\lim_{x \rightarrow a^+} f(x)$ does not exist <i>(This means that a is endpoint of f)</i>	
Mixed Discontinuity	$\lim_{x \rightarrow a^\pm} f(x) = \pm\infty$ $\lim_{x \rightarrow a^+} f(x) = L$	
Oscillating Discontinuity	An oscillating discontinuity exists when the values of the function appear to be approaching two or more values simultaneously. A standard example of this situation is the function $f(x) = \sin \frac{1}{x}$	

CONDITIONS OF CONTINUITY AT INTERVAL

- A function $f(x)$ is **continuous on the open interval** (a,b) if it is continuous;
✓ at every point $x=c$ contained in that interval.
- A function $f(x)$ is **continuous on the closed interval** $[a,b]$ if it is continuous;
✓ on the open interval (a,b) ,
✓ from the right at $x=a$, and
✓ from the left at $x=b$.
- A function $f(x)$ is **continuous everywhere** if it is continuous;
✓ at every point on the interval $(-\infty, \infty)$.

IMPORTANT THEOREMS AND FORMULAS FOR DERIVATIVE & LIMITS

Squeeze:	$f(x) \leq g(x) \leq h(x)$ and $\lim_{x \rightarrow a} f(x) = \lim_{x \rightarrow a} h(x) = c$, then $\lim_{x \rightarrow a} g(x) = c$
Bolzano Intermediate Value:	<i>Let $f: I \rightarrow \mathbb{R}$ be a continuous function. If $[a, b] \subset I$ and if $k \in \mathbb{R}$ is such that $f(a) < k < f(b)$ (or $f(b) < k < f(a)$), then there exists a point $c \in [a, b]$ such that $f(c) = k$</i>
Bolzano Root Value:	<i>Let $f: I \rightarrow \mathbb{R}$ be a continuous function. If $[a, b] \subset I$ and $f(a) < 0 < f(b)$ (or $f(b) < 0 < f(a)$), then there exists a point $c \in [a, b]$ such that $f(c) = 0$</i>
Fermat Extreme Value:	<i>Suppose that $a < c < b$. If a function f is defined on the interval (a, b), and it has a maximum or a minimum at c, then either f' doesn't exist at c or $f'(c) = 0$.</i>

If f is a continuous function on $[a, b]$ and differentiable on (a, b) , then there exists a point c in (a, b) such that: (Let $A(a, f(a))$ and $B(b, f(b))$)

Mean Value:	$f'(c) = \frac{f(b) - f(a)}{b - a}$ ($[AB]$ ye paralel en az bir tane teğet vardır.)
Rolle:	<i>If $f(a) = f(b)$, then $f'(c) = 0$ ($[AB]$ ye ve aynı zamanda x ekseniye paralel en az bir tane teğet vardır.)</i>
L' Hospital's Rules:	
Linear Approximation:	$f(x) = f(x_0 + \Delta x) \cong L(x) = f(x_0) + f'(x_0) \cdot \Delta x = f(x_0) + f'(x_0) \cdot (x - x_0)$
	<i>If $f'(x) > 0$ on interval I_1, then f is increasing on the interval I_1 If $f'(x) < 0$ on interval I_2, then f is decreasing on the interval I_2</i>
	<i>On interval I_1; if $f''(x) > 0$, then f' is increasing. Thus f is concave up On interval I_2; if $f''(x) < 0$, then f' is decreasing. Thus f is concave down</i>
Newton's Method	<i>If x_n is the n^{th} guess for the $\sqrt[n]{\text{solution}}$ of $f(x) = 0$ then $(n+1)^{st}$ guess is $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$ provided $f'(x_n)$ exists.</i>

DERIVATIVE AND NOTATIONS

If $y = f(x)$ then all of the following are equivalent notations for the derivative:

$f'(x) = y' = \frac{df}{dx} = \frac{dy}{dx} = \frac{d}{dx}(f(x)) = Df(x)$	$f''(x) = y'' = \frac{d^2f}{dx^2} = \frac{d^2y}{dx^2} = D^2f(x)$
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If $y = f(x)$ all of the following are equivalent notations for the derivative evaluated at $x = a$:

$$f'(a) = y'|_{x=a} = \frac{df}{dx}|_{x=a} = \frac{dy}{dx}|_{x=a} = Df(a)$$

DERIVATION RULES

y	y'	Description/Comments
$\sin x$	$\cos x$	
$\cos x$	$-\sin x$	
$\tan x$	$1 + \tan^2 x = \frac{1}{\cos^2 x} = \sec^2 x$	
$\cot x$	$-(1 + \cot^2 x) = -\frac{1}{\sin^2 x} = -\csc^2 x$	
$\sec x$	$\sec x \tan x$	
$\csc x$	$-\csc x \cot x$	
$\arcsin x$	$\frac{1}{\sqrt{1-x^2}}$	
$\arccos x$	$\frac{-1}{\sqrt{1-x^2}}$	
$\arctan x$	$\frac{1}{1+x^2}$	
$\operatorname{arccot} x$	$\frac{-1}{1+x^2}$	
$\operatorname{arcsec} x$	$\frac{1}{ x \sqrt{x^2-1}}$	
$\operatorname{arccsc} x$	$\frac{-1}{ x \sqrt{x^2-1}}$	
$\sinh x$	$\cosh x$	
$\cosh x$	$\sinh x$	
$\tanh x$	$1 + \tanh^2 x = \frac{1}{\cosh^2 x} = \operatorname{sech}^2 x$	
$\coth x$	$-(1 + \coth^2 x) = -\frac{1}{\sinh^2 x} = -\operatorname{csch}^2 x$	
$\operatorname{sech} x$	$\operatorname{sech} x \tanh x$	
$\operatorname{csch} x$	$-\operatorname{csch} x \coth x$	
$\operatorname{arcsinh} x$	$\frac{1}{\sqrt{x^2+1}}$	<i>for $\forall x$</i>

$\operatorname{arccosh} x$	$\frac{1}{\sqrt{x^2 - 1}}$	for $x > 1$
$\operatorname{arctanh} x$	$\frac{1}{x^2 - 1}$	for $ x < 1$
$\operatorname{arccoth} x$	$\frac{1}{1 - x^2}$	for $x > 1$
$\operatorname{arcsech} x$	$\frac{-1}{ x \sqrt{1 - x^2}}$	for $0 < x < 1$
$\operatorname{arccsch} x$	$\frac{-1}{ x \sqrt{x^2 + 1}}$	for $x \neq 0$
\sqrt{x}	$\frac{1}{2\sqrt{x}}$	
e^x	e^x	
a^x	$a^x \cdot \ln a$	
$\ln x$	$\frac{1}{x}$	
$\log_a x$	$\frac{1}{x \cdot \ln a}$	
$f(x) \cdot g(x)$	$f'(x) \cdot g(x) + f(x) \cdot g'(x)$	
$fog(x) = f(g(x))$	$f'(g(x)) \cdot g'(x)$	
$\frac{f(x)}{g(x)}$	$\frac{f'(x) \cdot g(x) - f(x) \cdot g'(x)}{g^2(x)}$	$g(x) \neq 0$
$f^{-1}(x)$	$\frac{1}{f'(y)} = \frac{1}{f'(f^{-1}(x))} = \frac{1}{f' \circ f^{-1}(x)}$	(Derivative of Inverse Function)
$[f(x)]^{g(x)}$	$[f(x)]^{g(x)} \cdot \left[g'(x) \cdot \ln f(x) + g(x) \cdot \frac{f'(x)}{f(x)} \right]$	$\ln y = g(x) \cdot \ln f(x)$
$y = f(u),$ $u = g(v),$ $v = h(t),$ $t = k(x),$	$\frac{dy}{dx} = \frac{dy}{du} \cdot \frac{du}{dv} \cdot \frac{dv}{dt} \cdot \frac{dt}{dx} = f'(u) \cdot g'(v) \cdot h'(t) \cdot k'(x)$	Chain Rule

ASYMPTOTES		
Horizontal Asymptote:	<i>The line $y = L$ is called a horizontal asymptote for $y = f(x)$ if and only if;</i> $\lim_{x \rightarrow \infty} f(x) = L$, or $\lim_{x \rightarrow -\infty} f(x) = L$	
Vertical Asymptote:	<i>The line $x = a$ is called a vertical asymptote of f if at least one of the these exists:</i> $\lim_{x \rightarrow a} f(x) = \infty$; $\lim_{x \rightarrow a} f(x) = -\infty$; $\lim_{x \rightarrow a^-} f(x) = \infty$ $\lim_{x \rightarrow a^-} f(x) = -\infty$; $\lim_{x \rightarrow a^+} f(x) = \infty$; $\lim_{x \rightarrow a^+} f(x) = -\infty$	
Oblique Asymptote:	<i>The line $y = kx + l$ is called oblique asymptote for $y = f(x)$if and only if;</i> $\lim_{x \rightarrow \infty} \frac{f(x)}{x} = k$ and $\lim_{x \rightarrow \infty} [f(x) - kx] = l$	

$f'(x) < 0$	$0 < f'(x)$
$0 < f''(x)$	Here $y = f(x)$ is decreasing, while the rate itself is increasing. In this case the curve is concave up .
$f''(x) < 0$	Here $y = f(x)$ is decreasing, while the rate itself is decreasing. In this case the curve is concave down .

SKETCHING GRAPH of CURVES

Cartesian Coordinates:

- Step 1: Determine the Domain and Range
- Step 2: Find the y-Intercept and x-Intercept(s)
- Step 3: Look for Symmetry and Periods
- Step 4: Find Asymptote(s)
- Step 5: First Derivative: Determine the Intervals of Increase and Decrease and Locate the Relative Extrema
- Step 6: Second Derivative: Determine the Intervals of Concavity and Locate the Inflection Points
- Step 7: Transfer these informations to the Table
- Step 8: Sketch the Graph

Polar Coordinates:

- Step 1: Determine the Domain and Range
- Step 2: Look for Periods
- Step 3: Look for Symmetry:

Cases:	Symmetry:
$f(\theta) = f(-\theta)$ $f(\pi - \theta) = -f(\theta)$	Polar axis ($\theta = 0$)
$f(\theta) = -f(-\theta)$ $f(\pi - \theta) = f(\theta)$	$\theta = \pi/2$
$f(\pi + \theta) = f(\theta)$	Origin
$f(\pi + \theta) = -f(\theta)$	T/2 kadar aralıktaki çizim yeterlidir. (T: period)

$f(\theta - a) = f(\theta)$ ise $P(r, \theta), Q(r, \theta + a)$ aynı çember üzerinde. Q noktasını kutup noktası etrafında a kadar döndür.

$f(\theta + a) = f(\theta)$ ise $P(r, \theta), Q(-r, \theta + a) = Q(r, \theta + a - \pi)$. P noktasını Q açısının ters yönünde $\pi - a$ kadar döndür.

Step 4: First Derivative: Determine the Intervals of Increase and Decrease and Locate the Relative Extrema

Step 5: Find the particular values of the function

Step 6: Transfer these informations to the Table

Step 7: Sketch the Graph of periodic part according to table

Step 8: Sketch the Graph completely

~~~~~ ANTI-DERIVATIVE AND INTEGRALS ~~~~~

**INTEGRATION RULES**

| $y$                             | $\int y \, dx$                                                                                   | Description                                                                                           |
|---------------------------------|--------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------|
| $\sin x$                        | $-\cos x + C$                                                                                    |                                                                                                       |
| $\cos x$                        | $\sin x + C$                                                                                     |                                                                                                       |
| $\sinh x$                       | $\cosh x + C$                                                                                    |                                                                                                       |
| $\cosh x$                       | $\sinh x + C$                                                                                    |                                                                                                       |
| $f'(g(x)) \cdot g'(x)$          | $f(g(x)) + C$                                                                                    | <i>Substitution Rule: <math>u = g(x)</math></i>                                                       |
| $f(x) \cdot g'(x)$              | $f(x) \cdot g(x) - \int f'(x) \cdot g(x) \, dx$                                                  | <i>Integration by Parts Rule (LAPTU):<br/><math>u = f(x)</math> and <math>dv = g'(x) \, dx</math></i> |
| $\sec^2 x = \frac{1}{\cos^2 x}$ | $\tan x + C$                                                                                     |                                                                                                       |
| $\csc^2 x = \frac{1}{\sin^2 x}$ | $-\cot x + C$                                                                                    |                                                                                                       |
| $\frac{1}{\sqrt{a^2 - x^2}}$    | $\arcsin \frac{x}{a} + C$                                                                        |                                                                                                       |
| $\frac{1}{1 + x^2}$             | $\arctan x + C$                                                                                  |                                                                                                       |
| $\frac{1}{x}$                   | $\ln x  + C$                                                                                     |                                                                                                       |
| $\frac{1}{x + a}$               | $\ln x + a  + C$                                                                                 |                                                                                                       |
| $\frac{1}{ax + b}$              | $\frac{1}{a} \ln ax + b  + C$                                                                    |                                                                                                       |
| $\frac{f'(x)}{f(x)}$            | $\ln f(x)  + C$                                                                                  |                                                                                                       |
| $\frac{1}{\sqrt{a^2 + x^2}}$    | $\operatorname{arcsinh} \frac{x}{a} + C = \ln \left( \frac{x + \sqrt{a^2 + x^2}}{a} \right) + C$ |                                                                                                       |
| $\frac{1}{\sqrt{x^2 - a^2}}$    | $\operatorname{arccosh} \frac{x}{a} + C = \ln \left( \frac{x + \sqrt{x^2 - a^2}}{a} \right) + C$ |                                                                                                       |
| $e^x$                           | $e^x + C$                                                                                        |                                                                                                       |
| $a^x$                           | $\frac{a^x}{\ln a} + C$                                                                          | $a > 0$                                                                                               |
| $\tan x$                        | $-\ln \cos x  + C = \ln \sec x  + C$                                                             |                                                                                                       |
| $\cot x$                        | $\ln \sin x  + C$                                                                                |                                                                                                       |
| $\sec x$                        | $\ln \sec x + \tan x  + C$                                                                       |                                                                                                       |

|                     |                                                                  |
|---------------------|------------------------------------------------------------------|
| $\csc x$            | $\ln \csc x - \cot x  + C$                                       |
| $\sin^2 x$          | $\frac{1}{2}(x - \sin x \cos x) + C$                             |
| $\cos^2 x$          | $\frac{1}{2}(x + \sin x \cos x) + C$                             |
| $\sec^3 x$          | $\frac{1}{2}\sec x \tan x + \frac{1}{2}\ln \sec x + \tan x  + C$ |
| $\arcsin x$         | $x \cdot \arcsin x + \sqrt{1 - x^2} + C$                         |
| $\arccos x$         | $x \cdot \arccos x - \sqrt{1 - x^2} + C$                         |
| $\arctan x$         | $x \cdot \arctan x - \ln \sqrt{1 + x^2} + C$                     |
| $\text{arcsec } x$  |                                                                  |
| $\text{arccsc } x$  |                                                                  |
| $\tanh x$           |                                                                  |
| $\coth x$           |                                                                  |
| $\text{sech } x$    |                                                                  |
| $\text{csch } x$    |                                                                  |
| $\text{arcsinh } x$ | <i>for </i> $\forall x$                                          |
| $\text{arccosh } x$ | <i>for </i> $x > 1$                                              |
| $\text{arctanh } x$ | <i>for </i> $ x  < 1$                                            |
| $\text{arccoth } x$ | <i>for </i> $x > 1$                                              |
| $\text{arcsech } x$ | <i>for </i> $0 < x < 1$                                          |
| $\text{arccsch } x$ | <i>for </i> $x \neq 0$                                           |
| $\ln x$             | $x \ln x - x + C$                                                |
| $\log_a x$          | $\frac{1}{\ln a} (x \ln x - x) + C$                              |

## INTEGRATION METHODS

1) Basit kesirlere ayırma yöntemi:  $\int \frac{P(x)}{Q(x)} dx$  şeklinde bir integral verildiğinde eğer  $P(x)$ in derecesi  $Q(x)$ in derecesinden büyük ise ilk olarak polinom bölmesi yapılır:

$$\int \frac{P(x)}{Q(x)} dx = \int A(x) dx + \int \frac{K(x)}{Q(x)} dx$$

$$\int \frac{K(x)}{Q(x)} dx = \int \frac{K(x)}{(x - c_1)(x - c_2) \dots (x - c_n)} dx = \int \frac{A_1}{x - c_1} dx + \int \frac{A_2}{x - c_2} dx + \dots + \int \frac{A_n}{x - c_n} dx \quad \text{If } \Delta > 0$$

$$\int \frac{K(x)}{Q(x)} dx = \int \frac{K(x)}{(x - c)^n} dx = \int \frac{A_1}{x - c} dx + \int \frac{A_2}{(x - c)^2} dx + \dots + \int \frac{A_n}{(x - c)^n} dx \quad \text{If } \Delta = 0$$

$$\begin{aligned} \int \frac{K(x)}{Q(x)} dx &= \int \frac{K(x)}{(a_1x^2 + b_1x - c_1)(a_2 + b_2x - c_2) \dots (a_nx^2 + b_nx - c_n)} dx \\ &= \int \frac{A_1x + B_1}{a_1x^2 + b_1x - c_1} dx + \int \frac{A_2x + B_2}{a_2x^2 + b_2x - c_2} dx + \dots + \int \frac{A_nx + B_n}{a_nx^2 + b_nx - c_n} dx \end{aligned}$$

$$\int \frac{K(x)}{Q(x)} dx = \int \frac{K(x)}{(ax^2 + bx - c)^n} dx = \int \frac{A_1x + B_1}{ax^2 + bx - c} dx + \int \frac{A_2x + B_2}{(ax^2 + bx - c)^2} dx + \dots + \int \frac{A_nx + B_n}{(ax^2 + bx - c)^n} dx$$

2)  $\int \sqrt[n]{(ax + b)^m} dx$  şeklinde bir integral verildiğinde  $ax + b = u^n$  dönüşümüyle  $adx = nu^{n-1} du$  olur.

$$\int \sqrt[n]{(ax + b)^m} dx = \frac{n}{a} \int u^m u^{n-1} du = \frac{nu^{m+n}}{a(m+n)} + C = \frac{\sqrt[n]{(ax + b)^{m+n}}}{a(m+n)} + C$$

3)  $\sqrt[n_i]{(ax + b)^m}$  şeklindeki ifadeleri içeren fonksiyonların intergalleri alınırken  $n_i$  kök kuvvetlerinin en küçük ortak katı  $p$  olmak üzere  $ax + b = u^p$  değişken dönüşümüyle  $adx = pu^{p-1} du$  elde edilir.

4)  $\sqrt{a^2 - x^2}$  den başka köklü ifade içermeyen fonksiyonların intergalleri alınırken  $x = a \sin t$  değişken dönüşümüyle  $\sqrt{a^2 - x^2} = a \cos t$  ve  $dx = a \cos t dt$  elde edilir. ( $0 < t < \pi$ )

5)  $\sqrt{x^2 - a^2}$  den başka köklü ifade içermeyen fonksiyonların intergalleri alınırken  $x = a \sec t$  değişken dönüşümüyle  $\sqrt{x^2 - a^2} = a \tan t$  ve  $dx = a \sec t \tan t dt$  elde edilir. ( $0 < t < \frac{\pi}{2}$ )

(Not:  $x = a \cosh t$  dönüşümü de uygulanabilir.)

6)  $\sqrt{a^2 + x^2}$  den başka köklü ifade içermeyen fonksiyonların intergalleri alınırken  $x = a \tan t$  değişken dönüşümüyle  $\sqrt{a^2 + x^2} = a \sec t$  ve  $dx = a \sec^2 t dt$  elde edilir. ( $-\frac{\pi}{2} < t < \frac{\pi}{2}$ )

(Not:  $x = a \sinh t$  dönüşümü de uygulanabilir.)

7) Trigonometrik fonksiyonlar cinsinden rasyonel olarak ifade edilen fonksiyonların integrasyonu için, yarımla açı metodu denilen  $\tan \frac{x}{2} = t$  değişken dönüşümüyle  $\sin x = \frac{2t}{1+t^2}$ ,  $\cos x = \frac{1-t^2}{1+t^2}$  ve  $dx = \frac{2dt}{1+t^2}$  ifadeleri elde edilir.

## TRIGONOMETRIC INTEGRALS AND SUBSTITUTION RULES

for all  $m, n \in \mathbb{N}$

### **Trigonometric Integral**

### **Substitution Rule**

|                                                                        |                                                                           |
|------------------------------------------------------------------------|---------------------------------------------------------------------------|
| $\int \sin^{2n+1} x \cos^{2m} x dx = \int (1-t^2)^n t^{2m} dt$         | $\cos x = t$                                                              |
| $\int \sin^{2n} x \cos^{2m+1} x dx = \int t^{2n}(1-t^2)^m dt$          | $\sin x = t$                                                              |
| $\int \sin^{2n+1} x \cos^{2m+1} x dx = \int (1-t^2)^n t^{2m+1} dt$     | $\cos x = t$<br>or<br>$\sin x = t$                                        |
| $\int \sin^{2n} x \cos^{2m} x dx = \int \sin^{2n} x (1-\sin^2 x)^m dx$ | $\cos^2 x = 1 - \sin^2 x$ , then $\sin^2 x = \frac{1 - \cos 2x}{2}$<br>or |
| $\int \sin^{2n} x \cos^{2m} x dx = \int (1-\cos^2 x)^n \cos^{2m} x dx$ | $\sin^2 x = 1 - \cos^2 x$ , then $\cos^2 x = \frac{1 + \cos 2x}{2}$       |
| $\int \tan^{2n} x \sec^{2m} x dx = \int t^{2n}(1+t^2)^{m-1} dt$        | $\tan x = t$ (or $\tan^2 x = t$ )                                         |
| $\int \tan^{2n+1} x \sec^{2m} x dx = \int t^{2n+1}(1+t^2)^{m-1} dt$    |                                                                           |
| $\int \tan^{2n+1} x \sec^{2m+1} x dx = \int (t^2-1)^n t^m dt$          | $\sec x = t$                                                              |
| $\int \tan^{2n} x \sec^{2m+1} x dx$                                    | Each integral will be dealt with differently.                             |
| $\int \cot^{2n} x \csc^{2m} x dx$                                      | $\cot x = t$                                                              |

## RECURRENCE FORMULAS

$$\int \sin^n x dx = -\frac{1}{n} \sin^{n-1} x \cos x + \frac{n-1}{n} \int \sin^{n-2} x dx$$

$$\int \cos^n x dx = \frac{1}{n} \cos^{n-1} x \sin x + \frac{n-1}{n} \int \cos^{n-2} x dx$$

$$\int \tan^n x dx = \frac{1}{n-1} \tan^{n-1} x - \int \tan^{n-2} x dx$$

$$\int (\ln x)^n dx = x(\ln x)^n - n \int (\ln x)^{n-1} dx =$$

$$\int x^n e^x dx = x^n e^x - n \int x^{n-1} e^x dx$$

$$\int \frac{dx}{(x^2+a^2)^n} = \frac{1}{a^2(2n-2)} \left[ \frac{x}{(x^2+a^2)^{n-1}} - (2n-3) \int \frac{dx}{(x^2+a^2)^{n-1}} \right]$$

## PROPERTIES OF DEFINITE INTEGRALS

|                                                                              |                                                                                                                                                                                                                          |
|------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $\rightarrow \int_a^b c dx = c(b - a)$<br>$\rightarrow \int_a^a f(x) dx = 0$ | $\rightarrow \int_a^b f(x) dx = - \int_b^a f(x) dx$<br>$\rightarrow \int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx, \quad c \in (a, b)$<br>$\rightarrow \left  \int_a^b f(x) dx \right  \leq \int_a^b  f(x)  dx$ |
|------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|

## IMPORTANT THEOREMS AND FORMULAS FOR INTEGRALS

|                                                         |                                                                                                                                                               |                                                                                                                                                                  |
|---------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Fundamental Therom of Calculus Part 1</b>            | $F(x) = \int_a^x f(t) dt, \quad \text{then } F'(x) = f(x)$                                                                                                    |                                                                                                                                                                  |
| <b>Fundamental Therom of Calculus Part 2</b>            | $F'(x) = f(x), \quad \text{then } \int_a^b f(x) dx = F(b) - F(a)$                                                                                             |                                                                                                                                                                  |
|                                                         | <i>If <math>a \leq b</math> and <math>m \leq f(x) \leq M</math> for <math>a \leq x \leq b</math>, then;</i><br>$m(b - a) \leq \int_a^b f(x) dx \leq M(b - a)$ |                                                                                                                                                                  |
| <b>Mean Value of Integral:</b>                          | <i>The average value of <math>f(x)</math> on <math>a \leq x \leq b</math> is;</i><br>$f_{avg} = \bar{f} = \frac{1}{b - a} \int_a^b f(x) dx \leq$              |                                                                                                                                                                  |
| <b>Upper and Lower Riemann:</b>                         | $U(f, P) = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(u_i) \Delta x \quad L(f, P) = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(l_i) \Delta x$                 |                                                                                                                                                                  |
| <b>Riemann Sum:</b>                                     | $\int_a^b f(x) dx = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i^*) \Delta x, \quad x_i = a + i\Delta x, \quad \Delta x = \frac{b - a}{n}$                  |                                                                                                                                                                  |
| <b>Area:</b>                                            | $A = \int_a^b f(x) dx$                                                                                                                                        | <i>Between two curves: (If <math>f \geq g</math>)</i><br>$A = \int_a^b [f(x) - g(x)] dx$                                                                         |
| <b>Volume by Disks for Rotation About the x-axis:</b>   | $V = \pi \int_a^b [f(x)]^2 dx$                                                                                                                                |                                                                                                                                                                  |
| <b>Volume by Washers for Rotation About the x-axis:</b> | $V = \pi \int_a^b ([R(x)]^2 - [r(x)]^2) dx$                                                                                                                   |                                                                                                                                                                  |
| <b>Arc Length:</b>                                      | $s = \int_a^b \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$                                                                                                     | <i>for parametric curves:</i><br>$s = \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt = \int_a^b \sqrt{[f'(t)]^2 + [g'(t)]^2} dt$ |
| <b>Surface Area:</b>                                    | $SA = 2\pi \int_a^b  y  ds = 2\pi \int_a^b  y  \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx, \quad (\text{rotate about } x - \text{axis})$                      |                                                                                                                                                                  |
|                                                         | $SA = 2\pi \int_c^d  x  ds = 2\pi \int_c^d  x  \sqrt{1 + \left(\frac{dx}{dy}\right)^2} dy, \quad (\text{rotate about } y - \text{axis})$                      |                                                                                                                                                                  |

## APPROXIMATING DEFINITE INTEGRALS

|                                                                                                                                                                                                                                                                                                                          |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Trapezoidal Rule:</b> $\int_a^b f(x)dx \approx T_n = \frac{\Delta x}{2} [f(x_0) + 2f(x_1) + 2f(x_2) + \cdots + 2f(x_{n-1}) + f(x_n)]$ <p style="margin-left: 100px;"><i>where <math>\Delta x = \frac{b-a}{n}</math></i></p>                                                                                           |
| <b>Simpson's Rule:</b> $\int_a^b f(x)dx \approx S_n = \frac{\Delta x}{2} [f(x_0) + 4f(x_1) + 2f(x_2) + 4f(x_3) + \cdots + 4f(x_{n-1}) + f(x_n)]$ <p style="margin-left: 100px;"><i>where <math>\Delta x = \frac{b-a}{n}</math></i></p>                                                                                   |
| <b>Midpoint Rule:</b> $\int_a^b f(x)dx \approx \Delta x \left[ f\left(\frac{x_0+x_1}{2}\right) + f\left(\frac{x_1+x_2}{2}\right) + \cdots + f\left(\frac{x_{n-2}+x_{n-1}}{2}\right) + f\left(\frac{x_{n-1}+x_n}{2}\right) \right]$ <p style="margin-left: 100px;"><i>where <math>\Delta x = \frac{b-a}{n}</math></i></p> |

## TYPES OF IMPROPER INTEGRALS

|        |                                                                                                                                                                                                                                                  |
|--------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Type 1 | I. If $f$ is continuous on $[a, \infty)$ , then<br>$\int_a^{\infty} f(x) dx = \lim_{R \rightarrow \infty} \int_a^R f(x) dx$                                                                                                                      |
|        | II. If $f$ is continuous on $(-\infty, b]$ , then<br>$\int_{-\infty}^b f(x) dx = \lim_{R \rightarrow -\infty} \int_R^b f(x) dx$                                                                                                                  |
|        | III. If $f$ is continuous on $(-\infty, \infty)$ , then<br>$\int_{-\infty}^{\infty} f(x) dx = \int_0^{\infty} f(x) dx + \int_{-\infty}^0 f(x) dx = \lim_{R \rightarrow \infty} \int_0^R f(x) dx + \lim_{R \rightarrow -\infty} \int_R^0 f(x) dx$ |
| Type 2 | I. If $f$ is continuous on $[a, b]$ and discontinuous at $b$ , then<br>$\int_a^b f(x) dx = \lim_{R \rightarrow b^-} \int_a^R f(x) dx$                                                                                                            |
|        | II. If $f$ is continuous on $(a, b]$ and discontinuous at $a$ , then<br>$\int_a^b f(x) dx = \lim_{R \rightarrow a^+} \int_R^b f(x) dx$                                                                                                           |
|        | III. If $f$ is continuous on $[a, b]$ and discontinuous at $c \in (a, b)$ , then<br>$\int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx = \lim_{R \rightarrow c^-} \int_a^R f(x) dx + \lim_{R \rightarrow c^+} \int_R^b f(x) dx$             |
| Type 3 | <b>(Mixed Type)</b>                                                                                                                                                                                                                              |

## SUMMARY OF CONVERGENCE TESTS FOR IMPROPER INTEGRALS

| Tests                    | For which Integral & When to Use                                                                                                               | Conclusions                                                                                                                                                                                                                                                  | Comments                                                                                                                                                                                                                                                                                              |
|--------------------------|------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>p-test</b>            | $\int_a^\infty \frac{dx}{x^p}$ or $\int_a^\infty x^{-p} dx$                                                                                    | $\begin{cases} \text{converges to } \frac{a^{1-p}}{p-1}, & \text{if } p > 1 \\ \text{diverges to } \infty, & \text{if } p \leq 1 \end{cases}$                                                                                                                | Useful for comparison tests if general term is similar to $\frac{1}{x^p}$ .                                                                                                                                                                                                                           |
| <b>Direct Comparison</b> | $\int_a^\infty f(x)dx$ and<br>$\int_a^\infty g(x)dx$<br>$0 \leq f(x) \leq g(x)$<br>for all $x \geq a$                                          | $\int_a^\infty g(x)dx \text{ converges} \Rightarrow \int_a^\infty f(x)dx \text{ converges}$<br>$\int_a^\infty f(x)dx \text{ diverges} \Rightarrow \int_a^\infty g(x)dx \text{ diverges}$                                                                     | * $f, g$ must be continuous on $[a, \infty)$ .<br>* If we prove divergence of $\int_a^\infty g(x)dx$ , then $f(x)$ is chosen generally as $\frac{1}{x}$ .<br>* If we prove convergence of $\int_a^\infty f(x)dx$ , then $g(x)$ is chosen generally as $\frac{1}{x^p}$ but $p$ must be greater than 1. |
| <b>Limit Comparison</b>  | $\int_a^\infty f(x)dx$ and<br>$\int_a^\infty g(x)dx$<br>$f(x), g(x) > 0$<br>for all $x$<br>$\lim_{x \rightarrow \infty} \frac{f(x)}{g(x)} = L$ | If $L \neq 0 \Rightarrow$ both are same character<br><br>If $L = 0$ and $\int_a^\infty g(x)dx$ converges $\Rightarrow \int_a^\infty f(x)dx$ converges<br><br>If $L = \infty$ and $\int_a^\infty g(x)dx$ diverges $\Rightarrow \int_a^\infty f(x)dx$ diverges | $\int_a^\infty g(x)dx$<br>is chosen generally as type of $\frac{1}{x^p}$ .                                                                                                                                                                                                                            |

## ~~~~~ SERIES ~~~~

### SOME PARTICULAR FINITE SERIES' SUM

|                                                                                                                                                       |                                                                                                                                                                                                                         |
|-------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $\sum_{i=1}^n i = \frac{n(n+1)}{2}$ $\sum_{i=1}^n (2i-1) = n^2$ $\sum_{i=1}^n i^2 = \frac{n(n+1)(2n+1)}{6}$ $\sum_{i=1}^n i^3 = \frac{n^2(n+1)^2}{2}$ | $\sum_{i=1}^n i(i+1) = \frac{n(n+1)(n+2)}{3}$ $\sum_{i=1}^n i(i+1)(i+2) = \frac{n(n+1)(n+2)(n+3)}{4}$ $\sum_{i=1}^n \frac{1}{i(i+1)} = \frac{n}{n+1}$ $\sum_{i=1}^n \frac{1}{i(i+1)(i+2)} = \frac{n(n+3)}{4(n+1)(n+2)}$ |
|-------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|

## SUMMARY OF CONVERGENCE TESTS FOR SERIES

| Tests                                                                               | For which Series & When to Use                                                                               | Conclusions                                                                                                  | Comments                                                                                                           |
|-------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------|
| <b><i>n<sup>th</sup> term test<br/>(or the zero test)<br/>(Divergence Test)</i></b> | for any series $\sum a_n$                                                                                    | Diverges if $\lim_{n \rightarrow \infty}  a_n  \neq 0$                                                       | Inconclusive if $\lim_{n \rightarrow \infty}  a_n  = 0$<br>(Limit 0 ise yakınsaktır diyemeyiz)                     |
| <b><i>Geometric Series</i></b>                                                      | $\sum_{n=0}^{\infty} ax^n$ or $(\sum_{n=1}^{\infty} ax^{n-1})$                                               | Converges to $\frac{a}{1-x}$ only if $ x  < 1$<br>Diverges if $ x  \geq 1$                                   | Useful for comparison tests if general term is similar to $ax^n$                                                   |
| <b><i>p – series<br/>(p – test)</i></b>                                             | $\sum_{n=1}^{\infty} \frac{1}{n^p}$                                                                          | Converges if $p > 1$<br>Diverges if $p \leq 1$                                                               | Useful for comparison tests if general term is similar to $\frac{1}{n^p}$                                          |
| <b><i>Integral Test</i></b>                                                         | $\sum_{n=c}^{\infty} a_n, c \geq 0$<br>$a_n = f(n)$ for all $n$                                              | Converges if $\int_c^{\infty} f(x)dx$ converges<br>Diverges if $\int_c^{\infty} f(x)dx$ diverges             | The function $f(n)$ must be;<br>✓ continuous<br>✓ positive,<br>✓ decreasing<br>✓ readily integrable for $x \geq c$ |
| <b><i>Direct Comparison</i></b>                                                     | $\sum a_n$ and $\sum b_n$<br>$0 \leq a_n \leq b_n$ for all $n$                                               | $\sum b_n$ converges $\Rightarrow \sum a_n$ converges<br>$\sum a_n$ diverges $\Rightarrow \sum b_n$ diverges | $\sum b_n$ is chosen generally as a geometric or a p series                                                        |
| <b><i>Limit Comparison</i></b>                                                      | $\sum a_n$ and $\sum b_n$<br>$a_n, b_n > 0$ for all $n$<br>$\lim_{n \rightarrow \infty} \frac{a_n}{b_n} = L$ | If $L \neq 0 \Rightarrow$ both are same character                                                            | $\sum b_n$ is chosen generally as a geometric or a p series                                                        |
|                                                                                     | If $L = 0$ and $\sum b_n$ converges $\Rightarrow \sum a_n$ converges                                         |                                                                                                              |                                                                                                                    |
|                                                                                     | If $L = \infty$ and $\sum b_n$ diverges $\Rightarrow \sum a_n$ diverges                                      |                                                                                                              |                                                                                                                    |
| <b><i>Ratio<br/>(D'Alembert Test)</i></b>                                           | for any series $\sum a_n$<br>$\lim_{n \rightarrow \infty} \left  \frac{a_{n+1}}{a_n} \right  = L$            | Converges (absolutely) if $L < 1$<br>Diverges if $L > 1$                                                     | Inconclusive if $L = 1$<br>The test useful if $a_n$ involves factorials or $n^{\text{th}}$ powers.                 |
| <b><i>Root<br/>(Cauchy Test)</i></b>                                                | for any series $\sum a_n$<br>$\lim_{n \rightarrow \infty} \sqrt[n]{ a_n } = L$                               | Converges (absolutely) if $L < 1$<br>Diverges if $L > 1$                                                     | Inconclusive if $L = 1$<br>The test useful if $a_n$ involves $n^{\text{th}}$ powers.                               |
| <b><i>Alternating Series<br/>(Leibnitz Test)</i></b>                                | $\sum_{n=0}^{\infty} (-1)^n a_n \quad (a_n > 0)$                                                             | Converges if;<br>✓ $0 < a_{n+1} \leq a_n$ ( $a_n$ is decreasing)<br>✓ $\lim_{n \rightarrow \infty} a_n = 0$  | Applicable only to series with alternating terms.                                                                  |
| <b><i>Absolute Convergence</i></b>                                                  | for any series $\sum a_n$                                                                                    | Converges (abs.) if $\sum  a_n $ converges                                                                   | The test useful for series containing both positive and negative terms                                             |
| <b><i>Conditional Convergence</i></b>                                               | for any series $\sum a_n$                                                                                    | Converges while $\sum  a_n $ diverges                                                                        |                                                                                                                    |

## SOME PARTICULAR INFINITE AND MACLAURIN SERIES' SUM

| Function                     | Expansion of the Series                                                                                                       | Conditions             | Radius of Convergence                 |
|------------------------------|-------------------------------------------------------------------------------------------------------------------------------|------------------------|---------------------------------------|
| $\frac{1}{1-x}$              | $\frac{1}{1-x} = \sum_{n=0}^{\infty} x^n = 1 + x + x^2 + x^3 + \dots$                                                         | $-1 < x < 1$           | $R = 1 \Rightarrow  x  < 1$           |
| $\frac{a}{1-x}$              | $\frac{1^{st} \text{ term}}{1 - \text{ratio}} = \frac{a}{1-x} = \sum_{n=0}^{\infty} ax^n = a + ax + ax^2 + \dots$             | $-1 < x < 1$           | $R = 1 \Rightarrow  x  < 1$           |
| $\frac{1}{1+x}$              | $\frac{1}{1+x} = \sum_{n=0}^{\infty} (-x)^n = 1 - x + x^2 - x^3 + \dots$                                                      | $-1 < x < 1$           | $R = 1 \Rightarrow  x  < 1$           |
| $\frac{1}{(1-x)^2}$          | $\frac{1}{(1-x)^2} = \sum_{n=0}^{\infty} (n+1)x^n = 1 + 2x + 3x^2 + 4x^3 + \dots$                                             | $-1 < x < 1$           | $R = 1 \Rightarrow  x  < 1$           |
| $\frac{1}{(1+x)^2}$          | $\frac{1}{(1+x)^2} = \sum_{n=0}^{\infty} (n+1)(-x)^n = 1 - 2x + 3x^2 - \dots$                                                 | $-1 < x < 1$           | $R = 1 \Rightarrow  x  < 1$           |
| $(1+x)^k$<br>Binomial series | $(1+x)^k = \sum_{n=0}^{\infty} \binom{k}{n} x^n = 1 + kx + \frac{k(k-1)}{2!}x^2 + \dots$                                      | $-1 < x < 1$           | $R = 1 \Rightarrow  x  < 1$           |
| $\ln(1+x)$                   | $\ln(1+x) = \sum_{n=1}^{\infty} (-1)^{n-1} \frac{x^n}{n} = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots$         | $-1 < x \leq 1$        | $R = 1 \Rightarrow  x  < 1$           |
| $-\ln(1-x)$                  | $-\ln(1-x) = \sum_{n=0}^{\infty} \frac{x^n}{n} = x + \frac{x^2}{2} + \frac{x^3}{3} + \frac{x^4}{4} + \dots$                   | $-1 \leq x < 1$        | $R = 1 \Rightarrow  x  < 1$           |
| $\sin x$                     | $\sin x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!} = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots$ | $-\infty < x < \infty$ | $R = \infty \Rightarrow  x  < \infty$ |
| $\cos x$                     | $\cos x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!} = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots$     | $-\infty < x < \infty$ | $R = \infty \Rightarrow  x  < \infty$ |
| $e^x$                        | $e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!} = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$                       | $-\infty < x < \infty$ | $R = \infty \Rightarrow  x  < \infty$ |
| $\tan^{-1} x$                | $\tan^{-1} x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{2n+1} = x - \frac{x^3}{3} + \frac{x^5}{5} - \frac{x^7}{7} + \dots$  | $-1 \leq x \leq 1$     | $R = 1 \Rightarrow  x  < 1$           |
| $\sinh x$                    | $\sinh x = \sum_{n=0}^{\infty} \frac{x^{2n+1}}{(2n+1)!} = x + \frac{x^3}{3!} + \frac{x^5}{5!} + \frac{x^7}{7!} + \dots$       | $-\infty < x < \infty$ | $R = \infty \Rightarrow  x  < \infty$ |
| $\cosh x$                    | $\cosh x = \sum_{n=0}^{\infty} \frac{x^{2n}}{(2n)!} = 1 + \frac{x^2}{2!} + \frac{x^4}{4!} + \frac{x^6}{6!} + \dots$           | $-\infty < x < \infty$ | $R = \infty \Rightarrow  x  < \infty$ |

## POWER, TAYLOR AND MACLAURIN SERIES

### Power Series

$$f(x) = \sum_{n=0}^{\infty} c_n (x-a)^n = c_0 + c_1(x-a) + c_2(x-a)^2 + \dots$$

**Cauchy – Hadamard Theorem:** Let  $L = \lim_{n \rightarrow \infty} \left| \frac{c_{n+1}}{c_n} \right|$  or  $L = \lim_{n \rightarrow \infty} \sqrt[n]{|c_n|}$ , then;

I.  $L \neq 0 \Rightarrow R = \frac{1}{L}$ . That is to say  $R = \frac{1}{\lim_{n \rightarrow \infty} \left| \frac{c_{n+1}}{c_n} \right|}$  or  $R = \frac{1}{\lim_{n \rightarrow \infty} \sqrt[n]{|c_n|}}$

II.  $L = 0 \Rightarrow R = \infty$

III.  $L = \infty \Rightarrow R = 0$  (The means that  $f$  can be convergent only for  $x = 0$ )

If "radius of convergence" of  $f(x)$  is  $R$ ;

$$|x - a| < R \Rightarrow a - R < x < a + R$$

In this interval  $f(x)$  is already convergent. But on endpoints of this interval ( $a - R$  and  $a + R$ ), they should be checked whether  $f$  is convergent or not there

If radius of  $f(x)$  is  $R$ , radius of  $f'(x)$  and radius of  $\int f(x) dx$  are also  $R$ . ( $f$  must be differentiable)

If radius of  $\sum_{n=0}^{\infty} a_n x^n$  is  $R_a$  and radius of  $\sum_{n=0}^{\infty} b_n x^n$  is  $R_b$ , then;

radius of  $\sum_{n=0}^{\infty} (a_n + b_n) x^n$  is  $R \geq \min\{R_a, R_b\}$

If  $f$  can be presented by a power series, then  $f$  can be represented by a Taylor series form;

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x-a)^n = f(a) + \frac{f'(a)}{1!}(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \frac{f'''(a)}{3!}(x-a)^3 + \dots$$

For the special case  $a = 0$  the Taylor series becomes Maclaurin series:

$$f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^n = f(0) + \frac{f'(0)}{1!} x + \frac{f''(0)}{2!} x^2 + \frac{f'''(0)}{3!} x^3 \dots$$

Partial sum of Taylor series is  $T_n(x)$ , then  $f(x) = \lim_{n \rightarrow \infty} T_n(x)$

Remainder of Taylor series is  $R_n(x)$ , then  $\lim_{n \rightarrow \infty} R_n(x) = 0$

**Taylor's Inequality:** If  $|f^{(n+1)}(x)| \leq M$  for  $|x - a| \leq d$ , then  $R_n(x)$  satisfied the inequality;

$$|R_n(x)| \leq \frac{M}{(n+1)!} |x-a|^{n+1} \text{ for } |x-a| \leq d$$

### Taylor and Maclaurin Series

## ERROR ESTIMATE FOR ALTERNATING SERIES

$$\text{Error} = |s - s_n| \leq |s_{n+1} - s_n| \leq |a_{n+1}|$$

# -----POLAR COORDINATES-----

|                            |                                                                            |
|----------------------------|----------------------------------------------------------------------------|
| $r = 0$                    | Orijin noktası                                                             |
| $r = a$                    | Merkezi (0,0) olan yarıçapı a olan çember                                  |
| $r = a \sin \theta$        | Merkezi (0,a/2) olan yarıçapı a/2 olan çember                              |
| $r = a \cos \theta$        | Merkezi (a/2,0) olan yarıçapı a/2 olan çember                              |
| $r = a(1 \mp \sin \theta)$ | Simetri eksenin y eksenini olan <b>Kardiyoid</b>                           |
| $r = a(1 \mp \cos \theta)$ | Simetri eksenin x eksenini olan <b>Kardiyoid</b>                           |
| $r = a \sin 2\theta$       | Simetri eksenleri $y = x$ ve $y = -x$ doğruları olan <b>4 yapraklı gül</b> |
| $r = a \cos 2\theta$       | Simetri eksenin x ve y eksenlerini olan <b>4 yapraklı gül</b>              |
| $r = a \sin 3\theta$       | Simetri eksenin y eksenini olan <b>3 yapraklı gül</b>                      |
| $r = a \cos 3\theta$       | Simetri eksenin x eksenini olan <b>3 yapraklı gül</b>                      |
| $r = a \mp b \sin \theta$  | Simetri eksenin y eksenini olan <b>Limaçon (Snail)</b>                     |
| $r = a \mp b \cos \theta$  | Simetri eksenin x eksenini olan <b>Limaçon (Snail)</b>                     |
| $r = a\theta$              | <b>Spiral</b>                                                              |
| $r = ae^{b\theta}$         | <b>Logaritmik Spiral</b>                                                   |

|                   |                                                                                                                                                                                                 |  |
|-------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|
| <b>Tangent</b>    | $m = \frac{dy}{dx} \Big _{(r, \theta)} = \frac{f'(\theta) \sin \theta + f(\theta) \cos \theta}{f'(\theta) \cos \theta - f(\theta) \sin \theta}$                                                 |  |
|                   | $\frac{dy}{d\theta} = 0$ and $\frac{dx}{d\theta} \neq 0$ , then $m = 0$                                                                                                                         |  |
|                   | $\frac{dx}{d\theta} = 0$ and $\frac{dy}{d\theta} \neq 0$ , then $m = \infty$                                                                                                                    |  |
| <b>Area</b>       | $A = \frac{1}{2} \int_{\alpha}^{\beta} [f(\theta)]^2 d\theta = \frac{1}{2} \int_{\alpha}^{\beta} r^2 d\theta$                                                                                   |  |
| <b>Arc Length</b> | $L = \int_{\alpha}^{\beta} \sqrt{\left(\frac{dx}{d\theta}\right)^2 + \left(\frac{dy}{d\theta}\right)^2} d\theta = \int_{\alpha}^{\beta} \sqrt{r^2 + \left(\frac{dr}{d\theta}\right)^2} d\theta$ |  |

## VEKTÖR DEĞERLİ FONKSİYONLAR

$$\vec{r} = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k}, \quad a \leq t \leq b$$

Hız:

$$\vec{v} = \frac{d\vec{r}}{dt} = \frac{df}{dt}\vec{i} + \frac{dg}{dt}\vec{j} + \frac{dh}{dt}\vec{k}$$

Sürat:

$$|\vec{v}| = \sqrt{\left(\frac{df}{dt}\right)^2 + \left(\frac{dg}{dt}\right)^2 + \left(\frac{dh}{dt}\right)^2}$$

İvme:

$$\vec{a} = \frac{d\vec{v}}{dt}$$

Yön:

$$\frac{\vec{v}}{|\vec{v}|}$$

Birim Teğet Vektör

$$\vec{T} = \frac{\vec{v}}{|\vec{v}|}$$

Arc Length

$$L = \int_a^b |\vec{v}| dt$$

$$S(t) = \int_{t_0}^t |\vec{v}| dt$$

## ~~~~~ MULTI-VARIABLE FUNCTIONS ~~~~~

### PARTIAL DERIVATIVE AND NOTATIONS

$$F_x(x, y) = \frac{\partial F}{\partial x} = \frac{\partial}{\partial x}(F(x, y))$$

$$F_y(x, y) = \frac{\partial F}{\partial y} = \frac{\partial}{\partial y}(F(x, y))$$

$$F_{xx}(x, y) = \frac{\partial^2 F}{\partial x^2} = \frac{\partial^2}{\partial x^2}(F(x, y)) \quad F_{yy}(x, y) = \frac{\partial^2 F}{\partial y^2} = \frac{\partial^2}{\partial y^2}(F(x, y)) \quad F_{xy}(x, y) = \frac{\partial^2 F}{\partial y \partial x} = \frac{\partial}{\partial y} \left( \frac{\partial F}{\partial x} \right)$$

$$F_x(a, b) = F_x(x, y) \Big|_{(x, y) = (a, b)} = \frac{dF}{dx} \Big|_{(x, y) = (a, b)}$$

### IMPORTANT THEOREMS AND FORMULAS FOR M-V FUNCTIONS

Divergence, Curl,  
and Laplacian

$$F_1(x_1, x_2, \dots, x_n), F_2(x_1, x_2, \dots, x_n), F_3(x_1, x_2, \dots, x_n)$$

(Fonksiyonel)  
Jakobian  
Determinant

$$J = \frac{\partial(F_1, F_2, \dots, F_n)}{\partial(x_1, x_2, \dots, x_n)} = \begin{vmatrix} \frac{\partial F_1}{\partial x_1} & \dots & \frac{\partial F_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial F_n}{\partial x_1} & \dots & \frac{\partial F_n}{\partial x_n} \end{vmatrix}$$

Laplace Equation

$$F_{xx} + F_{yy} = 0$$

$$F_{xx} + F_{yy} + F_{zz} = 0$$

Tam Diferensiyel

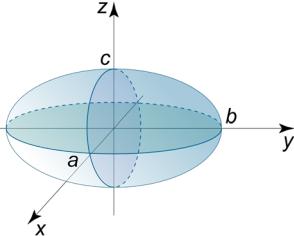
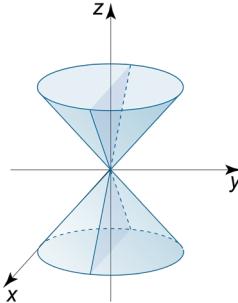
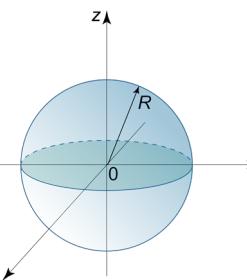
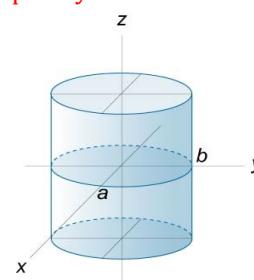
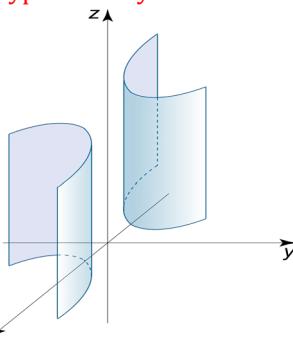
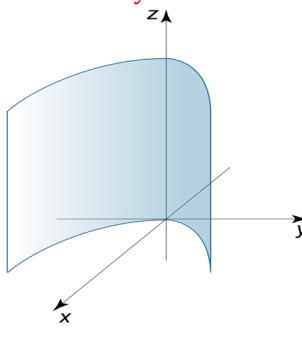
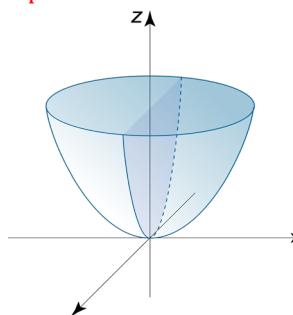
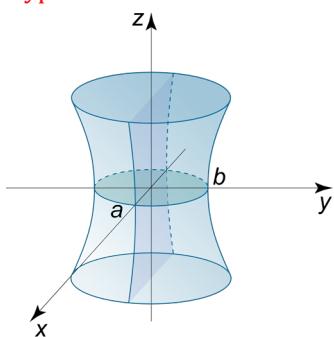
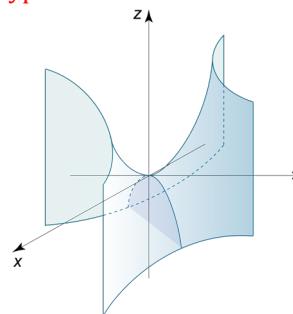
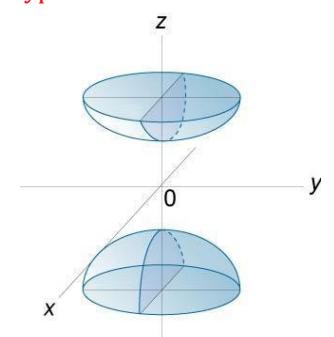
$$df = f_x dx + f_y dy$$

$$df = f_x dx + f_y dy + f_z dz$$

|                                                                |                                                                                                                                                                                                                                |                                                                                    |
|----------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------|
| <b>Gradient Vektörü</b>                                        | $\nabla_f = \frac{df}{dx} \vec{i} + \frac{df}{dy} \vec{j}$                                                                                                                                                                     | $\nabla_f = \frac{df}{dx} \vec{i} + \frac{df}{dy} \vec{j} + \frac{df}{dz} \vec{k}$ |
| <b>Doğrultu Türevi</b>                                         | $\vec{u} = u_1 \vec{i} + u_2 \vec{j} + u_3 \vec{k}, \quad P_0(x_0, y_0, z_0)$ $(D_u f)_{P_0} = \frac{dF}{ds} \Big _{\vec{u}, P_0} = \lim_{s \rightarrow 0} \frac{f(x_0 + su_1, y_0 + su_2, z_0 + su_3) - f(x_0, y_0, z_0)}{s}$ |                                                                                    |
|                                                                | $(D_u f)_{P_0} = \frac{dF}{ds} \Big _{\vec{u}, P_0} = \nabla_f \Big _{P_0} \cdot \vec{u}$                                                                                                                                      |                                                                                    |
|                                                                | $(D_u f)_{P_0} =  \nabla_f  \cos \theta$                                                                                                                                                                                       | $\cos \theta = 1$ ise $f$ hızlı artar                                              |
|                                                                |                                                                                                                                                                                                                                | $\cos \theta = -1$ ise $f$ hızlı azalır                                            |
| <b>Leibnitz Formula:<br/>(Integral Altında<br/>Türev Alma)</b> | $F(x) = \int_{u(x)}^{v(x)} f(x, y) dy \Rightarrow F'(x) = \int_{u(x)}^{v(x)} \frac{\partial f}{\partial x} dy + v'(x)f[x, v(x)] - u'(x)f[x, u(x)]$                                                                             |                                                                                    |

| <b>GRADIENT</b>                                                          |                                                                                               |                                                                                    |
|--------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------|
| <b>Gradient Vector</b>                                                   | $\nabla_f = \frac{df}{dx} \vec{i} + \frac{df}{dy} \vec{j}$                                    | $\nabla_f = \frac{df}{dx} \vec{i} + \frac{df}{dy} \vec{j} + \frac{df}{dz} \vec{k}$ |
| <b>Gradient Rules</b>                                                    | $\nabla(kf) = k\nabla f$                                                                      | $\nabla(f \mp g) = \nabla f \mp \nabla g$                                          |
|                                                                          | $\nabla(fg) = f\nabla g + g\nabla f$                                                          | $\nabla\left(\frac{f}{g}\right) = \frac{g\nabla f - f\nabla g}{g^2}$               |
| <b>Seviye Eğrilerinin<br/>Granyenti</b>                                  | $\vec{r} = g(t)\vec{i} + h(t)\vec{j}$ and $F(x = g(t), y = h(t)) = c$                         | $\nabla_f \cdot \frac{d\vec{r}}{dt} = 0$                                           |
| <b>Tangent Equaiton</b>                                                  | $\nabla_f \Big _{P_0} \cdot \overrightarrow{P_0 P} = 0$                                       | $f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0) = 0$                              |
|                                                                          | $f_x(x_0, y_0, z_0)(x - x_0) + f_y(x_0, y_0, z_0)(y - y_0) + f_z(x_0, y_0, z_0)(z - z_0) = 0$ |                                                                                    |
| <b>Tangent Plane</b>                                                     | $\nabla_f \cdot \frac{d\vec{r}}{dt} = 0$                                                      |                                                                                    |
| <b>Normal line at <math>P_0</math><br/><math>t \in \mathbb{R}</math></b> | $x = x_0 + f_x(P_0)t$<br>$y = y_0 + f_y(P_0)t$<br>$z = z_0 + f_z(P_0)t$                       |                                                                                    |
| <b>Tangent Plane of<br/><math>z = f(x, y)</math> at <math>P_0</math></b> | $f_x(x_0, y_0, z_0)(x - x_0) + f_y(x_0, y_0, z_0)(y - y_0) - (z - z_0) = 0$                   |                                                                                    |

## QUADRATIC SURFACES AND EQUATIONS

| Surface               | Equation                                                                                                                                                                                                                                                                                        | Surface                   | Equation                                                                                                                                                                                                                                                                                                                |
|-----------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Ellipsoid             | $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$ <p>All traces are ellipses.<br/>If <math>a = b = c = R</math>, the ellipsoid is a sphere whose radius is <math>R</math>.</p>                         | Cone                      | $\frac{z^2}{c^2} = \frac{x^2}{a^2} + \frac{y^2}{b^2}$ <p>Horizontal traces are ellipses.</p>                                                                                                                                          |
| Sphere                | $x^2 + y^2 + z^2 = R^2$ <p>All traces are circles.<br/>If centre is <math>(a,b,c)</math>, then<br/><math>(x - a)^2 + (y - b)^2 + (z - c)^2 = R^2</math></p>                                                    | Elliptic Cylinder         | $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ <p>Horizontal traces are ellipses.<br/>Vertical traces are two parallel lines.</p>                                                                                                            |
| Hyperbolic Cylinder   | $\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$ <p>Horizontal traces are hyperbolas.<br/>Vertical traces are two parallel lines.</p>                                                                                  | Parabolic Cylinder        | $\frac{x^2}{a^2} - y = 0$ <p>Horizontal traces are parabolas.<br/>Vertical traces are two parallel lines.</p>                                                                                                                        |
| Elliptic Paraboloid   | $\frac{z}{c} = \frac{x^2}{a^2} + \frac{y^2}{b^2}$ <p>Horizontal traces are ellipses.<br/>Vertical traces are parabolas.<br/>The variable raised to the first power indicates the axis of the paraboloid</p>  | Hyperboloid of One Sheet  | $\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$ <p>Horizontal traces are ellipses.<br/>Vertical traces are hyperbolas.<br/>The axis of symmetry corresponds to the variable whose coefficient is negative.</p>            |
| Hyperbolic Paraboloid | $\frac{z}{c} = \frac{x^2}{a^2} - \frac{y^2}{b^2}$ <p>Horizontal traces are hyperbolas.<br/>Vertical traces are parabolas.<br/>The case where <math>c &lt; 0</math> is illustrated</p>                        | Hyperboloid of Two Sheets | $-\frac{x^2}{a^2} - \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$ <p>Horizontal traces in <math>z = k</math> are ellipses if <math> k  &gt; c</math>.<br/>Vertical traces are hyperbolas.<br/>The two minus signs indicate two sheets</p>  |

## MAXIMUM AND MINIMUM

|                                                          |                                                                                                       |                                                                                  |                                                      |
|----------------------------------------------------------|-------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------|------------------------------------------------------|
| <b>Critical Points</b>                                   | 1. $f_x = f_y = 0$<br>2. $f_x$ or $f_y$ does not exist<br>3. The boundary points of the function $f$  |                                                                                  |                                                      |
| <b>Hessian Matrix and Discriminant of <math>f</math></b> | $\Delta = \begin{vmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{vmatrix} = f_{xx}f_{yy} - f_{xy}^2$ |                                                                                  |                                                      |
| $f_x(a, b) = f_y(a, b) = 0, \text{ then};$               |                                                                                                       |                                                                                  |                                                      |
|                                                          | $\Delta _{(a, b)} > 0$                                                                                | $\Delta _{(a, b)} = 0$                                                           | $\Delta _{(a, b)} < 0$                               |
| $f_{xx}(a, b) > 0$                                       | $(a, b)$ is a local minimum point                                                                     | We know nothing about the point $(a, b)$<br>The test is inconclusive at $(a, b)$ | $(a, b)$ is a saddle point<br>(Eyer / Semer noktası) |
| $f_{xx}(a, b) < 0$                                       | $(a, b)$ is a local maximum point                                                                     |                                                                                  |                                                      |

|                               |                                                                                                                                                                                                                                                                                                                                                                                                                                          |
|-------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Kapalı Sınırlı Bölgede</b> | <ol style="list-style-type: none"> <li>Fonksiyonun bölgenin iç noktalarında kritik noktası varsa bu noktalarda aldığı değerler bulunur.</li> <li>Fonksiyonun bölgenin sınır noktalarında kritik noktası varsa bu noktalarda aldığı değerler bulunur.</li> <li>Tüm bu değerler içindeki en küçük değer fonksiyonun o kapalı bölgedeki en küçük değeri, en büyük değer ise fonksiyonun o kapalı bölgedeki en büyük değeri olur.</li> </ol> |
|-------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|

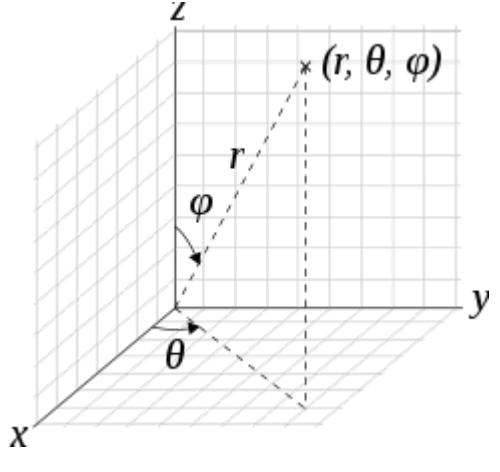
## LAGRANGE MULTIPLIERS

|                        | <b>Equations</b>                                                                                                                                                                                       | <b>The Values What Must Be Find</b> |
|------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------|
| <b>One Constraint</b>  | $\nabla f_x = \lambda \nabla g_y$<br>$\nabla f_y = \lambda \nabla g_y$<br>$\nabla f_z = \lambda \nabla g_z$<br>$g(x, y, z) = 0$                                                                        | $x, y, z, \lambda$                  |
| <b>Two Constraints</b> | $\nabla f_x = \lambda \nabla g_x + \mu \nabla h_x$<br>$\nabla f_y = \lambda \nabla g_y + \mu \nabla h_y$<br>$\nabla f_z = \lambda \nabla g_z + \mu \nabla h_z$<br>$g(x, y, z) = 0$<br>$h(x, y, z) = 0$ | $x, y, z, \lambda, \mu$             |

# ~~~~~ MULTIPLE INTEGRALS ~~~~~

| <b>DOUBLE INTEGRALS</b>     |                                                                                                                                                                                                                              |                                                                                                                                                                                                                                                                      |
|-----------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Volume</b>               | Between $f(x,y)$ and $R$ on Oxy plane:<br>$V = \iint_R f(x, y) dA = \iint_R f(x, y) dx dy$                                                                                                                                   | Between $f(x,y)$ and $g(x,y)$ : (If $f \geq g$ )<br>$V = \iint_R [f(x, y) - g(x, y)] dA$                                                                                                                                                                             |
| <b>Area</b>                 | $A = \iint_R dA = \iint_R dx dy$                                                                                                                                                                                             |                                                                                                                                                                                                                                                                      |
|                             |                                                                                                                                                                                                                              | If $f(x,y)$ is continuous on $R$ whose bounds are $a \leq x \leq b$ and $c \leq y \leq d$ , the integral can be written as;<br>$\iint_R f(x, y) dA = \int_a^b \left( \int_c^d f(x, y) dy \right) dx = \int_c^d \left( \int_a^b f(x, y) dx \right) dy$                |
| <b>Fubini Theorem</b>       | If $f(x,y)$ is continuous on $R$ whose bounds are $a \leq x \leq b$ and $g_1(x) \leq y \leq g_2(x)$ , the integral can be written as;<br>$\iint_R f(x, y) dA = \int_a^b \left( \int_{g_1(x)}^{g_2(x)} f(x, y) dy \right) dx$ |                                                                                                                                                                                                                                                                      |
|                             |                                                                                                                                                                                                                              | If $f(x,y)$ is continuous on $R$ whose bounds are $h_1(y) \leq x \leq h_2(y)$ and $c \leq y \leq d$ , the integral can be written as;<br>$\iint_R f(x, y) dA = \int_c^d \left( \int_{h_1(y)}^{h_2(y)} f(x, y) dx \right) dy$                                         |
| <b>Parametric Transform</b> | $J(u, v) = \frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} = x_u y_v - x_v y_u$                                                                                                 | $dx dy =  J(u, v)  du dv =  x_u y_v - x_v y_u  du dv$                                                                                                                                                                                                                |
|                             |                                                                                                                                                                                                                              | $\iint_R f(x, y) dx dy = \iint_{R'} f(g(u, v), h(u, v))  x_u y_v - x_v y_u  du dv$                                                                                                                                                                                   |
| <b>Polar Transform</b>      |                                                                                                                                                                                                                              | $x = r \cos \theta$ $y = r \sin \theta$ $J(r, \theta) = \frac{\partial(x, y)}{\partial(r, \theta)} = \begin{vmatrix} x_r & x_\theta \\ y_r & y_\theta \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r$ |
|                             |                                                                                                                                                                                                                              | $dx dy = r dr d\theta$                                                                                                                                                                                                                                               |
|                             |                                                                                                                                                                                                                              | $\iint_R f(x, y) dx dy = \int_{\theta=\alpha}^{\beta} \left( \int_{r=g_1(\theta)}^{g_2(\theta)} f(r \cos \theta, r \sin \theta) r dr \right) d\theta$                                                                                                                |
|                             |                                                                                                                                                                                                                              | $Area = A = \iint_R f(x, y) dx dy = \int_{\theta=\alpha}^{\beta} \left( \int_{r=g_1(\theta)}^{g_2(\theta)} f(r \cos \theta, r \sin \theta) r dr \right) d\theta$                                                                                                     |

## TRIPLE INTEGRALS

|                                    |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |                                                                                                                                                                                                                                                                                                |
|------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Volume</b>                      | $V = \iiint_D dV = \iiint_D dx dy dz$                                                                                                                                                                                                                                                                                                                                                                                                                                                    |                                                                                                                                                                                                                                                                                                |
| <b>Fubini<br/>Theorem</b>          | If $F(x,y,z)$ is continuous on $D$ whose bounds are $a \leq x \leq b$ , $c \leq y \leq d$ , and $e \leq z \leq f$ , the integral can be written as;<br>$\iiint_D dV = \int_a^b \int_c^d \int_e^f F(x, y, z) dx dy dz$                                                                                                                                                                                                                                                                    |                                                                                                                                                                                                                                                                                                |
|                                    | If $F(x,y,z)$ is continuous on $D$ whose bounds are $a \leq x \leq b$ , $g_1(x) \leq y \leq g_2(x)$ , and $f_1(x, y) \leq z \leq f_2(x, y)$ , the integral can be written as;<br>$\iiint_D dV = \int_a^b \int_{g_1(x)}^{g_2(x)} \int_{f_1(x,y)}^{f_2(x,y)} F(x, y, z) dz dy dx$                                                                                                                                                                                                          |                                                                                                                                                                                                                                                                                                |
|                                    | If $F(x,y,z)$ is continuous on $D$ whose bounds are $h_1(y) \leq x \leq h_2(y)$ , $c \leq y \leq d$ , and $f_1(x, y) \leq z \leq f_2(x, y)$ , the integral can be written as;<br>$\iiint_D dV = \int_c^d \int_{h_1(y)}^{h_2(y)} \int_{f_1(x,y)}^{f_2(x,y)} F(x, y, z) dz dy dx$                                                                                                                                                                                                          |                                                                                                                                                                                                                                                                                                |
| <b>Cylindrical<br/>Coordinates</b> | $x = r \cos \theta$<br>$y = r \sin \theta$<br>$z = z$                                                                                                                                                                                                                                                                                                                                                                                                                                    | $J(r, \theta, z) = \frac{\partial(x, y, z)}{\partial(r, \theta, z)} = \begin{vmatrix} x_r & x_\theta & x_z \\ y_r & y_\theta & y_z \\ z_r & z_\theta & z_z \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix} = r$ |
|                                    | $dV = r dz dr d\theta$                                                                                                                                                                                                                                                                                                                                                                                                                                                                   | $\iiint_D dV = \int_{\theta=\alpha}^{\beta} \int_{g_1(\theta)}^{g_2(\theta)} \int_{f_1(r,\theta)}^{f_2(r,\theta)} F(r \cos \theta, r \sin \theta, z) r dz dr d\theta$                                                                                                                          |
| <b>Spherical<br/>Coordinates</b>   | $x = \rho \sin \varphi \cos \theta$<br>$y = \rho \sin \varphi \sin \theta$<br>$z = \rho \cos \varphi$                                                                                                                                                                                                                                                                                                                                                                                    | $0 \leq \varphi \leq \pi$<br>$0 \leq \theta \leq 2\pi$<br>$x^2 + y^2 + z^2 = \rho^2$                                                                                                                                                                                                           |
|                                    | $J(\rho, \varphi, \theta) = \frac{\partial(x, y, z)}{\partial(\rho, \varphi, \theta)} = \begin{vmatrix} x_\rho & x_\varphi & x_\theta \\ y_\rho & y_\varphi & y_\theta \\ z_\rho & z_\varphi & z_\theta \end{vmatrix}$<br>$= \begin{vmatrix} \sin \varphi \cos \theta & \rho \cos \varphi & -\rho \sin \varphi \sin \theta \\ \sin \varphi \sin \theta & \rho \cos \varphi & \rho \sin \varphi \cos \theta \\ \cos \varphi & -\rho \sin \varphi & 0 \end{vmatrix} = \rho^2 \sin \varphi$ |                                                                                                                                                                                                           |
|                                    | $dV =  J  d\rho d\varphi d\theta = (\rho^2 \sin \varphi) d\rho d\varphi d\theta$                                                                                                                                                                                                                                                                                                                                                                                                         | $\iiint_D dV = \int_{\theta=\alpha}^{\beta} \int_{\varphi_{min}}^{\varphi_{max}} \int_{\rho=f_1(\theta,\varphi)}^{f_2(\theta,\varphi)} (\rho^2 \sin \varphi) d\rho d\varphi d\theta$                                                                                                           |

| Kartesien                                                                                                    | Silindirik                                  | Kugel                                                                                                                                                                                                                      |
|--------------------------------------------------------------------------------------------------------------|---------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $z = 3$ . drehbar                                                                                            | $z = 3$                                     | $\rho \cos \phi = 3 \rightarrow \rho = \frac{3}{\cos \phi}$                                                                                                                                                                |
| $z = x^2 + y^2$ parallel                                                                                     | $z = r^2$                                   | $\rho \cos \phi = \rho^2 \sin^2 \phi \Rightarrow \rho = \frac{\cos \phi}{\sin^2 \phi}$<br>$\rho(\cos \phi - \sin^2 \phi) = 0$                                                                                              |
| $z = \sqrt{x^2 + y^2}$ koni                                                                                  | $z = r$                                     | $\rho \cos \phi = \rho \sin \phi$<br>$\rho(\cos \phi - \sin \phi) = 0$<br>$\tan \phi = 1 \Rightarrow \phi = \frac{\pi}{4}$                                                                                                 |
| $z^2 = x^2 + y^2$ hori<br> | $r^2 = r^2$<br>$z = \pm r$                  | $\rho^2 \cos^2 \phi = \rho^2 \sin^2 \phi \quad \tan \phi = \pm 1$<br>$\rho^2 (\cos^2 \phi - \sin^2 \phi) = 0$<br>$\sin \phi = \cos \phi \quad \phi = \frac{\pi}{4}$<br>$\tan^2 \phi = 1 \rightarrow \phi = \frac{3\pi}{4}$ |
| $x^2 + y^2 + z^2 = 4$<br>kugel                                                                               | $r^2 + z^2 = 4$<br>$z = \pm \sqrt{4 - r^2}$ | $\rho^2 = 4 \Rightarrow \rho = 2$<br>kugel                                                                                                                                                                                 |
| $z = 0$                                                                                                      | $z = 0$                                     | $\rho(\cos \phi) = 0 \Rightarrow \phi = \frac{\pi}{2}$                                                                                                                                                                     |
|                                                                                                              | $r^2 = \rho^2 \cdot P(r, \theta, z)$        | $z_1 \dots z_n$                                                                                                                                                                                                            |

## FONKSİYON DİZİLERİ

|                             |                                                                                                                                                                                                                                                                                                                                                                                             |
|-----------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Noktasal Yakınsaklık</b> | $\forall \varepsilon > 0$ ve her $x \in E$ için öyle bir $N \in \mathbb{N}$ vardır ki; $n \geq N(\varepsilon)$ için $ f_n(x) - f(x)  < \varepsilon$ sağlanır.                                                                                                                                                                                                                               |
| <b>Düzgün Yakınsaklık</b>   | $\forall \varepsilon > 0$ için öyle bir $N \in \mathbb{N}$ vardır ki; her $x \in E$ ve $n \geq N(\varepsilon)$ için $ f_n(x) - f(x)  < \varepsilon$ sağlanır.<br>$E$ kümesi üzerinde $f_n \xrightarrow{\text{noktasal}} f$ olsun ve $M_n = \sup_{x \in E}  f_n(x) - f(x) $ şeklinde tanımlansın.<br>$f_n \xrightarrow{\text{düzgün}} f \Leftrightarrow \lim_{n \rightarrow \infty} M_n = 0$ |