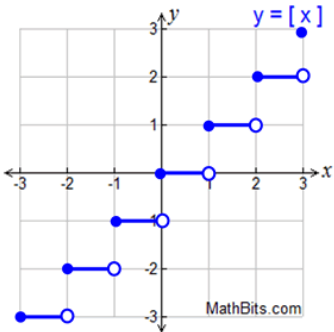
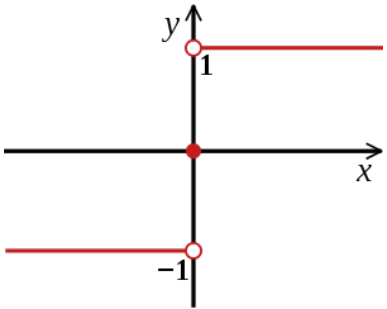
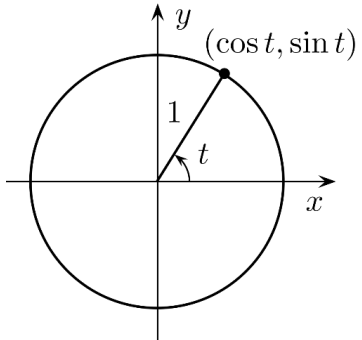


~~~~~ FUNCTIONS AND PROPERTIES ~~~~~

GREATEST INTEGER FUNCTION	
$f(x) = \llbracket g(x) \rrbracket$ and $n \in \mathbb{Z}$;	
$f(a) = n + 1$, if $n < g(a) \leq n + 1$	

SIGNUM FUNCTION	
$\text{sgn}(f(x)) = \begin{cases} -1, & \text{if } f(x) < 0 \\ 0, & \text{if } f(x) = 0 \\ 1, & \text{if } f(x) > 0 \end{cases}$	
$\rightarrow \text{sgn}(f(x)) = \frac{d}{dx} f(x) $ for $x \neq 0$	
$\rightarrow f(x) = \text{sgn}(f(x)) \cdot f(x) $	
$\rightarrow \text{sgn}(x^n) = \text{sgn}(x)^n$	

PERIODIC FUNCTIONS	
$f(x + T) = f(x)$. Then f is periodic function and T is called period of f .	

TRIGONOMETRIC FUNCTIONS			
Unit Circle	Perimeter of Unit Circle:	$2\pi r = 2\pi$, since $r = 1$	
	Arc length in Unit Circle: (t is central angle of arc)	$l = 2\pi r \cdot \frac{t}{2\pi} = t$ <p>So, arc length is equal to dimension of angle in a unit circle</p>	
Periods of Trigonometric Functions	$n \in \mathbb{N}$	$\sin^{2n+1}(ax + b)$, $\cos^{2n+1}(ax + b)$, $\sec^{2n+1}(ax + b)$, $\csc^{2n+1}(ax + b)$	$\frac{2\pi}{ a }$
		$\sin^{2n}(ax + b)$, $\cos^{2n}(ax + b)$, $\sec^{2n}(ax + b)$, $\csc^{2n}(ax + b)$, $\tan^n(ax + b)$, $\cot^n(ax + b)$	$\frac{\pi}{ a }$

LOGARITMIC FUNCTIONS AND PROPERTIES

1. $\log_a x$, $x \in \mathbb{R}^+$, $a \in \mathbb{R}^+ - \{1\}$	2. $f(x) = a^x \Rightarrow f^{-1}(x) = \log_a x$
3. $\log_a a = 1$	4. $\log_a 1 = 0$
5. $\log_a a^n = n$	6. $\log_a x^n = n \cdot \log_a x = n$
7. $\log_{a^m} x = \frac{1}{m} \cdot \log_a x = \frac{1}{m}$	8. $\log_{a^m} x^n = \frac{n}{m} \cdot \log_a x = \frac{n}{m}$
9. $\log x = \log_{10} x$	10. $\ln x = \log_e x$
11. $\log_a x \cdot y = \log_a x + \log_a y$	12. $\log_a \frac{x}{y} = \log_a x - \log_a y$
13. $\log_a x = \frac{\log x}{\log a} = \frac{\log_c x}{\log_c a}$	14. $\log_a x = \frac{1}{\log_x a}$
15. $\log_a y \cdot \log_y x = \log_a x$	16. $a^{\log_c x} = x^{\log_c a}$
17. $a^{\log_a x} = x^{\log_a a} = x$	18. $e^{\ln x} = x$

HYPERBOLIC AND INVERSE HYPERBOLIC FUNCTIONS

Hyperbolic Functions	Inverse Hyperbolic Functions	
$\sinh x = \frac{e^x - e^{-x}}{2}$	$\operatorname{arcsinh} x = \ln(x + \sqrt{x^2 + 1})$	$x \in \mathbb{R}$
$\cosh x = \frac{e^x + e^{-x}}{2}$	$\operatorname{arccosh} x = \ln(x + \sqrt{x^2 - 1})$	$x \geq 1$
$\tanh x = \frac{e^x - e^{-x}}{e^x + e^{-x}}$	$\operatorname{arctanh} x = \frac{1}{2} \ln \frac{1+x}{1-x}$	$ x < 1$
$\coth x = \frac{e^x + e^{-x}}{e^x - e^{-x}}$	$\operatorname{arcoth} x = \operatorname{arctanh} \frac{1}{x} = \frac{1}{2} \ln \frac{x+1}{x-1}$	$ x > 1$
$\operatorname{sech} x = \frac{2}{e^x + e^{-x}}$	$\operatorname{arcsech} x = \operatorname{arccosh} \frac{1}{x} = \ln \left(\frac{1 + \sqrt{1 - x^2}}{x} \right)$	$0 < x \leq 1$
$\operatorname{csch} x = \frac{2}{e^x - e^{-x}}$	$\operatorname{arccsch} x = \operatorname{arcsinh} \frac{1}{x} = \ln \left(\frac{1}{x} + \frac{1 + \sqrt{1 + x^2}}{ x } \right)$	$x \neq 0$
Properties of Hyperbolic Functions:		
$\rightarrow \cosh^2 x - \sinh^2 x = 1$ $\rightarrow \cosh(-x) = \cosh x$ $\rightarrow \sinh(-x) = -\sinh x$	$\rightarrow \sinh(x + y) = \sinh x \cosh y + \cosh x \sinh y$ $\rightarrow \cosh(x + y) = \cosh x \cosh y + \sinh x \sinh y$ $\rightarrow \cosh 2x = 2 \cosh^2 x - 1 = \sinh^2 x + \cosh^2 x = 2 \sinh^2 x + 1$	

POLYNOMIAL FUNCTIONS

$$f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_2 x^2 + a_1 x + a_0$$

Polynomial	Degree	Example	Number of Terms	Name Using Number of Terms
Constant or Zero Polynomial	0	6	1	Monomial
Linear Polynomial	1	$3x+1$	2	Binomial
Quadratic Polynomial (Parabola)	2	$3x^2$	1	Monomial
Cubic Polynomial	3	$6x^3 + 3x^2 - 5x + 7$	4	Polynomial of 4 terms
Quartic Polynomial	4	$2x^4 + 4x^3 - 1$	3	Trinomial
Quintic Polynomial	5	$x^5 + 16$	2	Binomial

~~~~~ LIMIT & DERIVATIVE ~~~~~

DEFINITION OF LIMIT

$M, N, \varepsilon, \delta > 0$	$x \rightarrow -\infty$	$x \rightarrow a$	$x \rightarrow \infty$
$f(x) \rightarrow -\infty$	$f(x) < -M$ ise; $x < -N(M)$	$f(x) < -M$ ise; $ x - a < \delta(M)$	$f(x) < -M$ ise; $x > N(M)$
$f(x) \rightarrow L$	$ f(x) - L < \varepsilon$ ise; $x < -N(\varepsilon)$	$ f(x) - L < \varepsilon$ ise; $ x - a < \delta(\varepsilon)$	$ f(x) - L < \varepsilon$ ise; $x > M(\varepsilon)$
$f(x) \rightarrow \infty$	$f(x) > M$ ise; $x < -N(M)$	$f(x) > M$ ise; $ x - a < \delta(M)$	$f(x) > M$ ise; $x > N(M)$

CONVERGENCE AND DIVERGENCE

If a limit of a thing is equal to a real number; (that is to say, the limit exist) "the thing is convergent"		If a limit of a thing is equal to infinity; (that is to say, the limit does not exist) "the thing is divergent"	
Types of Thing	Condition of Convergent Thing	Condition of Divergent Thing	
Sequence	$\lim_{n \rightarrow \infty} a_n = a$ where $a \in \mathbb{R}$ This means that the sequence converges to "a"	$\lim_{n \rightarrow \infty} a_n = \pm\infty$ This means that the sequence diverges to $\pm\infty$	
Function	$\lim_{x \rightarrow \pm\infty} f(x) = L$ where $L \in \mathbb{R}$ This means that the function converges to "L"	$\lim_{x \rightarrow \pm\infty} f(x) = \pm\infty$ This means that the function diverges to $\pm\infty$	
Infinite Series (Sum of Sequence)	$\lim_{n \rightarrow \infty} \sum_{i=0}^n a_n = \lim_{n \rightarrow \infty} S_n = S$ where $S \in \mathbb{R}$ This means that the series converges to "S"	$\lim_{n \rightarrow \infty} \sum_{i=0}^n a_n = \lim_{n \rightarrow \infty} S_n = \pm\infty$ This means that the series diverges to $\pm\infty$	
Improper Integrals (Sum of function)	$\lim_{n \rightarrow \infty} \int_m^n f(x)dx = S$ where $S \in \mathbb{R}$ This means the integral converges to "S"	$\lim_{n \rightarrow \infty} \int_m^n f(x)dx = \pm\infty$ This means that the integral diverges to $\pm\infty$	

SOME LIMIT CALCULATIONS

$$P(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_2 x^2 + a_1 x + a_0 \quad \text{and} \quad Q(x) = b_m x^m + b_{m-1} x^{m-1} + \dots + b_2 x^2 + b_1 x + b_0$$

$$\lim_{x \rightarrow \infty} \frac{P(x)}{Q(x)} = \begin{cases} \operatorname{sgn}\left(\frac{a_n}{b_m}\right) \cdot \infty, & n > m \\ \frac{a_n}{b_m}, & n = m \\ 0, & n < m \end{cases}$$

$$\lim_{x \rightarrow -\infty} \frac{P(x)}{Q(x)} = \begin{cases} \operatorname{sgn}\left(\frac{a_n x^n}{b_m x^m}\right) \cdot \infty, & n > m \\ \frac{a_n}{b_m}, & n = m \\ 0, & n < m \end{cases}$$

$$\lim_{x \rightarrow 0} \frac{\sin x}{x} = \lim_{x \rightarrow \infty} \frac{\sin(1/x)}{1/x} = \lim_{x \rightarrow \infty} x \cdot \sin(1/x) = 1$$

$$\lim_{x \rightarrow 0} \frac{\sin ax}{bx} = \lim_{x \rightarrow \infty} \frac{\sin(a/x)}{b/x} = \frac{a}{b}$$

$$\lim_{x \rightarrow 0} \frac{1 - \cos x}{x} = 0$$

$$\lim_{x \rightarrow \infty} \left(1 + \frac{1}{x}\right)^x = \lim_{x \rightarrow 0} (1+x)^{\frac{1}{x}} = \lim_{x \rightarrow \infty} \left(1 + \frac{a}{x}\right)^{\frac{x}{a}} = e$$

$$\lim_{x \rightarrow \infty} \left(1 + \frac{a}{cx+d}\right)^{bx} = e^{\frac{a \cdot b}{c}}$$

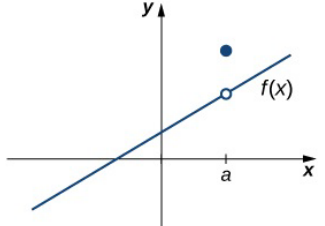
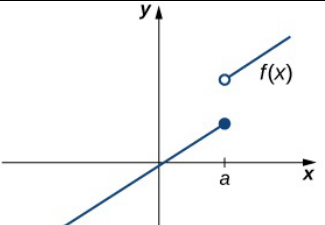
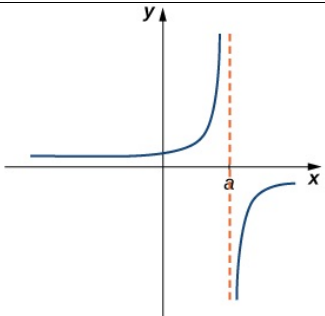
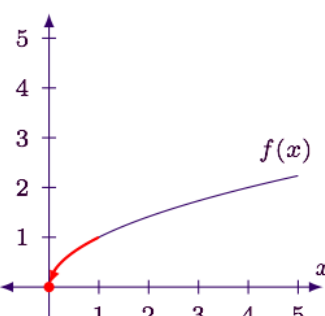
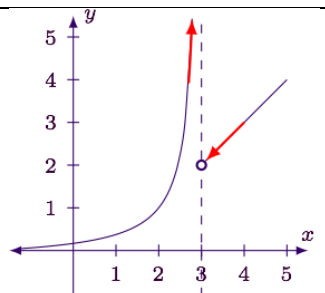
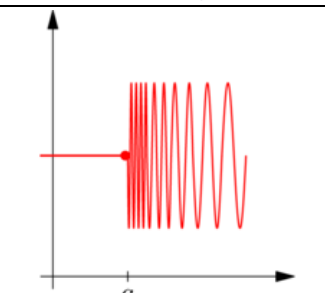
$$\lim_{x \rightarrow \infty} \left(1 + \frac{\alpha}{Q(x)}\right)^{P(x)} = \begin{cases} \infty, & n > m \text{ and } \operatorname{sgn}\left(\frac{a_n}{b_m}\right) = 1 \\ 0, & n > m \text{ and } \operatorname{sgn}\left(\frac{a_n}{b_m}\right) = -1 \\ e^{\alpha \frac{a_n}{b_m}}, & n = m \\ 1, & n < m \end{cases}$$

$$\lim_{x \rightarrow 0} \frac{x}{\log_a(1+x)} = \lim_{x \rightarrow 0} \frac{a^x - 1}{x} = \ln a \quad (a \neq 1, \quad a > 0)$$

CONDITION of DERIVATIVE, CONTINUITY AND LIMITS

Conditions of Derivative at Point "a"	Conditions of Continuity at Point "a"	Conditions of Limit at Point "a"	$\lim_{x \rightarrow a^-} f(x)$ exists
			$\lim_{x \rightarrow a^+} f(x)$ exists
			$\lim_{x \rightarrow a^-} f(x) = \lim_{x \rightarrow a^+} f(x) = L$ Then $\lim_{x \rightarrow a} f(x) = L$
			$f(a)$ exists (f must be defined at "a")
			$\lim_{x \rightarrow a} f(x) = L = f(a)$
			$f'_-(a) = \lim_{h \rightarrow 0^-} \frac{f(a+h) - f(a)}{h} = \lim_{h \rightarrow 0^+} \frac{f(a+h) - f(a)}{h} = f'_+(a)$
			$f'(a)$ exists (f' must be defined at a) (For example, $y = \sqrt[3]{x}$ then y' does not exist at "0")

TYPES OF DISCONTINUITIES

<p style="color: red; text-align: center;">Point/Removable Discontinuity</p>	$\lim_{x \rightarrow a^-} f(x) = \lim_{x \rightarrow a^+} f(x)$ <p style="text-align: center;">and</p> $\lim_{x \rightarrow a} f(x) \neq f(a) \text{ or } f \text{ is undefined at "a"}$	
<p style="color: red; text-align: center;">Jump Discontinuity</p>	$\lim_{x \rightarrow a^-} f(x) \neq \lim_{x \rightarrow a^+} f(x)$	
<p style="color: red; text-align: center;">Asymptotic/Infinite Discontinuity</p>	<p>At least one of the one-sided limits is (are) infinite;</p> $\lim_{x \rightarrow a} f(x) = \pm\infty,$ $\lim_{x \rightarrow a^+} f(x) = -\infty \text{ and } \lim_{x \rightarrow a^-} f(x) = \infty,$ $\lim_{x \rightarrow a^+} f(x) = \pm\infty \text{ and } \lim_{x \rightarrow a^-} f(x) = L,$ $\lim_{x \rightarrow a^+} f(x) = \pm\infty \text{ and } \lim_{x \rightarrow a^-} f(x) \text{ does not exist}$	
<p style="color: red; text-align: center;">Endpoint Discontinuity</p>	$\lim_{x \rightarrow a^+} f(x) = L \quad \lim_{x \rightarrow a^-} f(x) \text{ does not exist}$ <p style="text-align: center;">(This means that a is endpoint of f)</p>	
<p style="color: red; text-align: center;">Mixed Discontinuity</p>	$\lim_{x \rightarrow a^+} f(x) = \pm\infty \quad \lim_{x \rightarrow a^-} f(x) = L$	
<p style="color: red; text-align: center;">Oscillating Discontinuity</p>	<p>An oscillating discontinuity exists when the values of the function appear to be approaching two or more values simultaneously. A standard example of this situation is the function $f(x) = \sin \frac{1}{x}$</p>	

CONDITIONS OF CONTINUITY AT INTERVAL

- A function $f(x)$ is **continuous on the open interval** (a,b) if it is continuous;
 - ✓ at every point $x=c$ contained in that interval.
- A function $f(x)$ is **continuous on the closed interval** $[a,b]$ if it is continuous;
 - ✓ on the open interval (a,b) ,
 - ✓ from the right at $x=a$, and
 - ✓ from the left at $x=b$.
- A function $f(x)$ is **continuous everywhere** if it is continuous;
 - ✓ at every point on the interval $(-\infty, \infty)$.

IMPORTANT THEOREMS AND FORMULAS FOR DERIVATIVE & LIMITS

Squeeze:	$f(x) \leq g(x) \leq h(x)$ and $\lim_{x \rightarrow a} f(x) = \lim_{x \rightarrow a} h(x) = c$, then $\lim_{x \rightarrow a} g(x) = c$
Bolzano Intermediate Value:	Let $f: I \rightarrow \mathbb{R}$ be a continuous function. If $[a, b] \subset I$ and if $k \in \mathbb{R}$ is such that $f(a) < k < f(b)$ (or $f(b) < k < f(a)$), then there exists a point $c \in [a, b]$ such that $f(c) = k$
Bolzano Root Value:	Let $f: I \rightarrow \mathbb{R}$ be a continuous function. If $[a, b] \subset I$ and $f(a) < 0 < f(b)$ (or $f(b) < 0 < f(a)$), then there exists a point $c \in [a, b]$ such that $f(c) = 0$
Fermat Extreme Value:	Suppose that $a < c < b$. If a function f is defined on the interval (a, b) , and it has a maximum or a minimum at c , then either f' doesn't exist at c or $f'(c) = 0$.
If f is a continuous function on $[a, b]$ and differentiable on (a, b), then there exists a point c in (a, b) such that: (Let $A(a, f(a))$ and $B(b, f(b))$)	
Mean Value:	$f'(c) = \frac{f(b) - f(a)}{b - a}$ ([AB] ye paralel en az bir tane teğet vardır.)
Rolle:	If $f(a) = f(b)$, then $f'(c) = 0$ ([AB] ye ve aynı zamanda x eksenine paralel en az bir tane teğet vardır.)
L' Hospital's Rules:	
Linear Approximation:	$f(x) = f(x_0 + \Delta x) \cong L(x) = f(x_0) + f'(x_0) \cdot \Delta x = f(x_0) + f'(x_0) \cdot (x - x_0)$
	If $f'(x) > 0$ on interval I_1 , then f is increasing on the interval I_1 If $f'(x) < 0$ on interval I_2 , then f is decreasing on the interval I_2
	On interval I_1 ; if $f''(x) > 0$, then f' is increasing. Thus f is concave up On interval I_2 ; if $f''(x) < 0$, then f' is decreasing. Thus f is concave down
Newton's Method	If x_n is the n^{th} guess for the $\frac{\text{root}}{\text{solution}}$ of $f(x) = 0$ then $(n + 1)^{st}$ guess is $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$ provided $f'(x_n)$ exists.

DERIVATIVE AND NOTATIONS

If $y = f(x)$ then all of the following are equivalent notations for the derivative:

$$f'(x) = y' = \frac{df}{dx} = \frac{dy}{dx} = \frac{d}{dx}(f(x)) = Df(x)$$

$$f''(x) = y'' = \frac{d^2f}{dx^2} = \frac{d^2y}{dx^2} = D^2f(x)$$

If $y = f(x)$ all of the following are equivalent notations for the derivative evaluated at $x = a$:

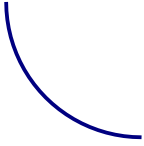
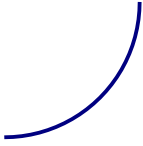
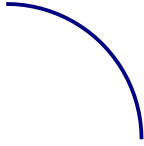
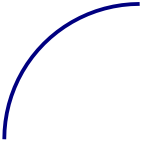
$$f'(a) = y' \Big|_{x=a} = \frac{df}{dx} \Big|_{x=a} = \frac{dy}{dx} \Big|_{x=a} = Df(a)$$

DERIVATION RULES

y	y'	Description/Comments
$\sin x$	$\cos x$	
$\cos x$	$-\sin x$	
$\tan x$	$1 + \tan^2 x = \frac{1}{\cos^2 x} = \sec^2 x$	
$\cot x$	$-(1 + \cot^2 x) = -\frac{1}{\sin^2 x} = -\csc^2 x$	
$\sec x$	$\sec x \tan x$	
$\csc x$	$-\csc x \cot x$	
$\arcsin x$	$\frac{1}{\sqrt{1-x^2}}$	
$\arccos x$	$\frac{-1}{\sqrt{1-x^2}}$	
$\arctan x$	$\frac{1}{1+x^2}$	
$\text{arccot } x$	$\frac{-1}{1+x^2}$	
$\text{arcsec } x$	$\frac{1}{ x \sqrt{x^2-1}}$	
$\text{arccsc } x$	$\frac{-1}{ x \sqrt{x^2-1}}$	
$\sinh x$	$\cosh x$	
$\cosh x$	$\sinh x$	
$\tanh x$	$1 + \tanh^2 x = \frac{1}{\cosh^2 x} = \text{sech}^2 x$	
$\coth x$	$-(1 + \coth^2 x) = -\frac{1}{\sinh^2 x} = -\text{csch}^2 x$	
$\text{sech } x$	$\text{sech } x \tanh x$	
$\text{csch } x$	$-\text{csch } x \coth x$	
$\text{arcsinh } x$	$\frac{1}{\sqrt{x^2+1}}$	$\text{for } \forall x$

$\operatorname{arccosh} x$	$\frac{1}{\sqrt{x^2 - 1}}$	<i>for</i> $x > 1$
$\operatorname{arctanh} x$	$\frac{1}{x^2 - 1}$	<i>for</i> $ x < 1$
$\operatorname{arccoth} x$	$\frac{1}{1 - x^2}$	<i>for</i> $x > 1$
$\operatorname{arcsech} x$	$\frac{-1}{ x \sqrt{1 - x^2}}$	<i>for</i> $0 < x < 1$
$\operatorname{arccsch} x$	$\frac{-1}{ x \sqrt{x^2 + 1}}$	<i>for</i> $x \neq 0$
\sqrt{x}	$\frac{1}{2\sqrt{x}}$	
e^x	e^x	
a^x	$a^x \cdot \ln a$	
$\ln x$	$\frac{1}{x}$	
$\log_a x$	$\frac{1}{x \cdot \ln a}$	
$f(x) \cdot g(x)$	$f'(x) \cdot g(x) + f(x) \cdot g'(x)$	
$f \circ g(x) = f(g(x))$	$f'(g(x)) \cdot g'(x)$	
$\frac{f(x)}{g(x)}$	$\frac{f'(x) \cdot g(x) - f(x) \cdot g'(x)}{g^2(x)}$	$g(x) \neq 0$
$f^{-1}(x)$	$\frac{1}{f'(y)} = \frac{1}{f'(f^{-1}(x))} = \frac{1}{f' \circ f^{-1}(x)}$	(Derivative of Inverse Function)
$[f(x)]^{g(x)}$	$[f(x)]^{g(x)} \cdot \left[g'(x) \cdot \ln f(x) + g(x) \cdot \frac{f'(x)}{f(x)} \right]$	$\ln y = g(x) \cdot \ln f(x)$
$y = f(u),$ $u = g(v),$ $v = h(t),$ $t = k(x),$	$\frac{dy}{dx} = \frac{dy}{du} \cdot \frac{du}{dv} \cdot \frac{dv}{dt} \cdot \frac{dt}{dx} = f'(u) \cdot g'(v) \cdot h'(t) \cdot k'(x)$	Chain Rule

ASYMPTOTES	
Horizontal Asymptote:	<p>The line $y = L$ is called a horizontal asymptote for $y = f(x)$ if and only if;</p> $\lim_{x \rightarrow \infty} f(x) = L, \quad \text{or} \quad \lim_{x \rightarrow -\infty} f(x) = L$
Vertical Asymptote:	<p>The line $x = a$ is called a vertical asymptote of f if at least one of the these exists:</p> $\begin{array}{lll} \lim_{x \rightarrow a^-} f(x) = \infty; & \lim_{x \rightarrow a^-} f(x) = -\infty; & \lim_{x \rightarrow a^-} f(x) = \infty \\ \lim_{x \rightarrow a^+} f(x) = -\infty; & \lim_{x \rightarrow a^+} f(x) = \infty; & \lim_{x \rightarrow a^+} f(x) = -\infty \end{array}$
Oblique Asymptote:	<p>The line $y = kx + l$ is called oblique asymptote for $y = f(x)$ if and only if;</p> $\lim_{x \rightarrow \infty} \frac{f(x)}{x} = k \quad \text{and} \quad \lim_{x \rightarrow \infty} [f(x) - kx] = l$

	$f'(x) < 0$	$0 < f'(x)$
$0 < f''(x)$	 <p>Here $y = f(x)$ is decreasing, while the rate itself is increasing. In this case the curve is concave up.</p>	 <p>Here $y = f(x)$ is increasing, while the rate itself is increasing. In this case the curve is concave up.</p>
$f''(x) < 0$	 <p>Here $y = f(x)$ is decreasing, while the rate itself is decreasing. In this case the curve is concave down.</p>	 <p>Here $y = f(x)$ is increasing, while the rate itself is decreasing. In this case the curve is concave down.</p>

SKETCHING GRAPH of CURVES

Cartesien Coordinates:

- Step 1: Determine the Domain and Range
- Step 2: Find the y-Intercept and x-Intercept(s)
- Step 3: Look for Symmetry and Periods
- Step 4: Find Asymptote(s)
- Step 5: First Derivative: Determine the Intervals of Increase and Decrease and Locate the Relative Extrema
- Step 6: Second Derivative: Determine the Intervals of Concavity and Locate the Inflection Points
- Step 7: Transfer these informations to the Table
- Step 8: Sketch the Graph

Polar Coordinates:

- Step 1: Determine the Domain and Range
- Step 2: Look for Periods
- Step 3: Look for Symmetry:

Cases:	Symmetry:
$f(\theta) = f(-\theta)$ $f(\pi - \theta) = -f(\theta)$	Polar axis ($\theta = 0$)
$f(\theta) = -f(-\theta)$ $f(\pi - \theta) = f(\theta)$	$\theta = \pi/2$
$f(\pi + \theta) = f(\theta)$	Origin
$f(\pi + \theta) = -f(\theta)$	T/2 kadar aralıkta çizim yeterlidir. (T: period)

$f(\theta - a) = f(\theta)$ ise $P(r, \theta), Q(r, \theta + a)$ aynı çember üzerinde. Q noktasını kutup noktası etrafında a kadar döndür.

$f(\theta + a) = f(\theta)$ ise $P(r, \theta), Q(-r, \theta + a) = Q(r, \theta + a - \pi)$. P noktasını Q açısının ters yönünde $\pi - a$ kadar döndür.

- Step 4: First Derivative: Determine the Intervals of Increase and Decrease and Locate the Relative Extrema
- Step 5: Find the particular values of the function
- Step 6: Transfer these informations to the Table
- Step 7: Sketch the Graph of periodic part according to table
- Step 8: Sketch the Graph completely

~~~~~

# ANTI-DERIVATIVE AND INTEGRALS

~~~~~

INTEGRATION RULES

y	$\int y \, dx$	Description
$\sin x$	$-\cos x + C$	
$\cos x$	$\sin x + C$	
$\sinh x$	$\cosh x + C$	
$\cosh x$	$\sinh x + C$	
$f'(g(x)) \cdot g'(x)$	$f(g(x)) + C$	Substitution Rule: $u = g(x)$
$f(x) \cdot g'(x)$	$f(x) \cdot g(x) - \int f'(x) \cdot g(x) dx$	Integration by Parts Rule (LAPTU): $u = f(x)$ and $dv = g'(x) dx$
$\sec^2 x = \frac{1}{\cos^2 x}$	$\tan x + C$	
$\csc^2 x = \frac{1}{\sin^2 x}$	$-\cot x + C$	
$\frac{1}{\sqrt{a^2 - x^2}}$	$\arcsin \frac{x}{a} + C$	
$\frac{1}{1 + x^2}$	$\arctan x + C$	
$\frac{1}{x}$	$\ln x + C$	
$\frac{1}{x + a}$	$\ln x + a + C$	
$\frac{1}{ax + b}$	$\frac{1}{a} \ln ax + b + C$	
$\frac{f'(x)}{f(x)}$	$\ln f(x) + C$	
$\frac{1}{\sqrt{a^2 + x^2}}$	$\operatorname{arcsinh} \frac{x}{a} + C = \ln \left(\frac{x + \sqrt{a^2 + x^2}}{a} \right) + C$	
$\frac{1}{\sqrt{x^2 - a^2}}$	$\operatorname{arccosh} \frac{x}{a} + C = \ln \left(\frac{x + \sqrt{x^2 - a^2}}{a} \right) + C$	
e^x	$e^x + C$	
a^x	$\frac{a^x}{\ln a} + C$	$a > 0$
$\tan x$	$-\ln \cos x + C = \ln \sec x + C$	
$\cot x$	$\ln \sin x + C$	
$\sec x$	$\ln \sec x + \tan x + C$	

$$\csc x \qquad \ln|\csc x - \cot x| + C$$

$$\sin^2 x \qquad \frac{1}{2}(x - \sin x \cos x) + C$$

$$\cos^2 x \qquad \frac{1}{2}(x + \sin x \cos x) + C$$

$$\sec^3 x \qquad \frac{1}{2}\sec x \tan x + \frac{1}{2}\ln|\sec x + \tan x| + C$$

$$\arcsin x \qquad x \cdot \arcsin x + \sqrt{1 - x^2} + C$$

$$\arccos x \qquad x \cdot \arccos x - \sqrt{1 - x^2} + C$$

$$\arctan x \qquad x \cdot \arctan x - \ln \sqrt{1 + x^2} + C$$

$$\operatorname{arcsec} x$$

$$\operatorname{arccsc} x$$

$$\tanh x$$

$$\coth x$$

$$\operatorname{sech} x$$

$$\operatorname{csch} x$$

$$\operatorname{arcsinh} x \qquad \text{for } \forall x$$

$$\operatorname{arccosh} x \qquad \text{for } x > 1$$

$$\operatorname{arctanh} x \qquad \text{for } |x| < 1$$

$$\operatorname{arccoth} x \qquad \text{for } x > 1$$

$$\operatorname{arcsech} x \qquad \text{for } 0 < x < 1$$

$$\operatorname{arccsch} x \qquad \text{for } x \neq 0$$

$$\ln x \qquad x \ln x - x + C$$

$$\log_a x \qquad \frac{1}{\ln a} (x \ln x - x) + C$$

INTEGRATION METHODS

1) Basit kesirlere ayırma yöntemi: $\int \frac{P(x)}{Q(x)} dx$ şeklinde bir integral verildiğinde eğer $P(x)$ 'in derecesi $Q(x)$

in derecesinden büyük ise ilk olarak polinom bölmesi yapılır: $\int \frac{P(x)}{Q(x)} dx = \int A(x) dx + \int \frac{K(x)}{Q(x)} dx$

$$\int \frac{K(x)}{Q(x)} dx = \int \frac{K(x)}{(x-c_1)(x-c_2) \dots (x-c_n)} dx = \int \frac{A_1}{x-c_1} dx + \int \frac{A_2}{x-c_2} dx + \dots + \int \frac{A_n}{x-c_n} dx \quad \text{If } \Delta > 0$$

$$\int \frac{K(x)}{Q(x)} dx = \int \frac{K(x)}{(x-c)^n} dx = \int \frac{A_1}{x-c} dx + \int \frac{A_2}{(x-c)^2} dx + \dots + \int \frac{A_n}{(x-c)^n} dx \quad \text{If } \Delta = 0$$

$$\begin{aligned} \int \frac{K(x)}{Q(x)} dx &= \int \frac{K(x)}{(a_1x^2 + b_1x - c_1)(a_2x^2 + b_2x - c_2) \dots (a_nx^2 + b_nx - c_n)} dx \\ &= \int \frac{A_1x + B_1}{a_1x^2 + b_1x - c_1} dx + \int \frac{A_2x + B_2}{a_2x^2 + b_2x - c_2} dx + \dots + \int \frac{A_nx + B_n}{a_nx^2 + b_nx - c_n} dx \end{aligned}$$

$$\int \frac{K(x)}{Q(x)} dx = \int \frac{K(x)}{(ax^2 + bx - c)^n} dx = \int \frac{A_1x + B_1}{ax^2 + bx - c} dx + \int \frac{A_2x + B_2}{(ax^2 + bx - c)^2} dx + \dots + \int \frac{A_nx + B_n}{(ax^2 + bx - c)^n} dx$$

2) $\int \sqrt[n]{(ax+b)^m} dx$ şeklinde bir integral verildiğinde $ax+b = u^n$ dönüşümüyle $adx = nu^{n-1} du$ olur.

$$\int \sqrt[n]{(ax+b)^m} dx = \frac{n}{a} \int u^m u^{n-1} du = \frac{nu^{m+n}}{a(m+n)} + C = \frac{n \sqrt[n]{(ax+b)^{m+n}}}{a(m+n)} + C$$

3) $\sqrt[n_i]{(ax+b)^m}$ şeklindeki ifadeleri içeren fonksiyonların intergalleri alınırken n_i kök kuvvetlerinin en küçük ortak katı p olmak üzere $ax+b = u^p$ değişken dönüşümüyle $adx = pu^{p-1} du$ elde edilir.

4) $\sqrt{a^2 - x^2}$ den başka köklü ifade içermeyen fonksiyonların intergalleri alınırken $x = a \sin t$ değişken dönüşümüyle $\sqrt{a^2 - x^2} = a \cos t$ ve $dx = a \cos t dt$ elde edilir. ($0 < t < \pi$)

5) $\sqrt{x^2 - a^2}$ den başka köklü ifade içermeyen fonksiyonların intergalleri alınırken $x = a \sec t$ değişken dönüşümüyle $\sqrt{x^2 - a^2} = a \tan t$ ve $dx = a \sec t \tan t dt$ elde edilir. ($0 < t < \frac{\pi}{2}$)

(Not: $x = a \cosh t$ dönüşümü de uygulanabilir.)

6) $\sqrt{a^2 + x^2}$ den başka köklü ifade içermeyen fonksiyonların intergalleri alınırken $x = a \tan t$ değişken dönüşümüyle $\sqrt{a^2 + x^2} = a \sec t$ ve $dx = a \sec^2 t dt$ elde edilir. ($-\frac{\pi}{2} < t < \frac{\pi}{2}$)

(Not: $x = a \sinh t$ dönüşümü de uygulanabilir.)

7) Trigonometrik fonksiyonlar cinsinden rasyonel olarak ifade edilen fonksiyonların integrasyonu için, yarım açı metodu denilen $\tan \frac{x}{2} = t$ değişken dönüşümüyle $\sin x = \frac{2t}{1+t^2}$, $\cos x = \frac{1-t^2}{1+t^2}$ ve $dx = \frac{2dt}{1+t^2}$ ifadeleri elde edilir.

TRIGONOMETRIC INTEGRALS AND SUBSTITUTION RULES

for all $m, n \in \mathbb{N}$

Trigonometric Integral

Substitution Rule

$$\int \sin^{2n+1} x \cos^{2m} x \, dx = \int (1-t^2)^n t^{2m} dt$$

$$\cos x = t$$

$$\int \sin^{2n} x \cos^{2m+1} x \, dx = \int t^{2n} (1-t^2)^m dt$$

$$\sin x = t$$

$$\int \sin^{2n+1} x \cos^{2m+1} x \, dx = \int (1-t^2)^n t^{2m+1} dt$$

$$\cos x = t$$

or

$$\int \sin^{2n+1} x \cos^{2m+1} x \, dx = \int t^{2n+1} (1-t^2)^m dt$$

$$\sin x = t$$

$$\int \sin^{2n} x \cos^{2m} x \, dx = \int \sin^{2n} x (1-\sin^2 x)^m dx$$

$$\cos^2 x = 1 - \sin^2 x, \text{ then } \sin^2 x = \frac{1 - \cos 2x}{2}$$

or

$$\int \sin^{2n} x \cos^{2m} x \, dx = \int (1-\cos^2 x)^n \cos^{2m} x \, dx$$

$$\sin^2 x = 1 - \cos^2 x, \text{ then } \cos^2 x = \frac{1 + \cos 2x}{2}$$

$$\int \tan^{2n} x \sec^{2m} x \, dx = \int t^{2n} (1+t^2)^{m-1} dt$$

$$\tan x = t \text{ (or } \tan^2 x = t)$$

$$\int \tan^{2n+1} x \sec^{2m} x \, dx = \int t^{2n+1} (1+t^2)^{m-1} dt$$

$$\int \tan^{2n+1} x \sec^{2m+1} x \, dx = \int (t^2-1)^n t^m dt$$

$$\sec x = t$$

$$\int \tan^{2n} x \sec^{2m+1} x \, dx$$

Each integral will be dealt with differently.

$$\int \cot^{2n} x \csc^{2m} x \, dx$$

$$\cot x = t$$

RECURRENCE FORMULAS

$$\int \sin^n x \, dx = -\frac{1}{n} \sin^{n-1} x \cos x + \frac{n-1}{n} \int \sin^{n-2} x \, dx$$

$$\int \cos^n x \, dx = \frac{1}{n} \cos^{n-1} x \sin x + \frac{n-1}{n} \int \cos^{n-2} x \, dx$$

$$\int \tan^n x \, dx = \frac{1}{n-1} \tan^{n-1} x - \int \tan^{n-2} x \, dx$$

$$\int (\ln x)^n \, dx = x(\ln x)^n - n \int (\ln x)^{n-1} \, dx =$$

$$\int x^n e^x \, dx = x^n e^x - n \int x^{n-1} e^x \, dx$$

$$\int \frac{dx}{(x^2 + a^2)^n} = \frac{1}{a^2(2n-2)} \left[\frac{x}{(x^2 + a^2)^{n-1}} - (2n-3) \int \frac{dx}{(x^2 + a^2)^{n-1}} \right]$$

PROPERTIES OF DEFINITE INTEGRALS	
$\rightarrow \int_a^b c dx = c(b-a)$ $\rightarrow \int_a^a f(x) dx = 0$	$\rightarrow \int_a^b f(x) dx = - \int_b^a f(x) dx$ $\rightarrow \int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx, \quad c \in (a,b)$ $\rightarrow \left \int_a^b f(x) dx \right \leq \int_a^b f(x) dx$

IMPORTANT THEOREMS AND FORMULAS FOR INTEGRALS		
Fundamental Theroom of Calculus Part 1	$F(x) = \int_a^x f(t) dt, \quad \text{then } F'(x) = f(x)$	
Fundamental Theroom of Calculus Part 2	$F'(x) = f(x), \quad \text{then } \int_a^b f(x) dx = F(b) - F(a)$	
	If $a \leq b$ and $m \leq f(x) \leq M$ for $a \leq x \leq b$, then; $m(b-a) \leq \int_a^b f(x) dx \leq M(b-a)$	
Mean Value of Integral:	The average value of $f(x)$ on $a \leq x \leq b$ is; $f_{avg} = \bar{f} = \frac{1}{b-a} \int_a^b f(x) dx$	
Upper and Lower Riemann:	$U(f, P) = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(u_i) \Delta x \quad L(f, P) = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(l_i) \Delta x$	
Riemann Sum:	$\int_a^b f(x) dx = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i^*) \Delta x, \quad x_i = a + i\Delta x, \quad \Delta x = \frac{b-a}{n}$	
Area:	$A = \int_a^b f(x) dx$	Between two curves: (If $f \geq g$) $A = \int_a^b [f(x) - g(x)] dx$
Volume by Disks for Rotation About the x-axis:	$V = \pi \int_a^b [f(x)]^2 dx$	
Volume by Washers for Rotation About the x-axis:	$V = \pi \int_a^b ([R(x)]^2 - [r(x)]^2) dx$	
Arc Length:	$s = \int_a^b \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$	for parametric curves: $s = \int_a^b \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt = \int_a^b \sqrt{[f'(t)]^2 + [g'(t)]^2} dt$
Surface Area:	$SA = 2\pi \int_a^b y ds = 2\pi \int_a^b y \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx, \quad (\text{rotate about } x - \text{axis})$	
	$SA = 2\pi \int_c^d x ds = 2\pi \int_c^d x \sqrt{1 + \left(\frac{dx}{dy}\right)^2} dy, \quad (\text{rotate about } y - \text{axis})$	

APPROXIMATING DEFINITE INTEGRALS

Tropezodial Rule:	$\int_a^b f(x)dx \approx T_n = \frac{\Delta x}{2} [f(x_0) + 2f(x_1) + 2f(x_2) + \cdots + 2f(x_{n-1}) + f(x_n)]$ <p>where $\Delta x = \frac{b-a}{n}$</p>
Simpson's Rule:	$\int_a^b f(x)dx \approx S_n = \frac{\Delta x}{2} [f(x_0) + 4f(x_1) + 2f(x_2) + 4f(x_3) + \cdots + 4f(x_{n-1}) + f(x_n)]$ <p>where $\Delta x = \frac{b-a}{n}$</p>
Midpoint Rule:	$\int_a^b f(x)dx \approx \Delta x \left[f\left(\frac{x_0+x_1}{2}\right) + f\left(\frac{x_1+x_2}{2}\right) + \cdots + f\left(\frac{x_{n-2}+x_{n-1}}{2}\right) + f\left(\frac{x_{n-1}+x_n}{2}\right) \right]$ <p>where $\Delta x = \frac{b-a}{n}$</p>

TYPES OF IMPROPER INTEGRALS

Type 1	<p>I. If f is continuous on $[a, \infty)$, then</p> $\int_a^{\infty} f(x) dx = \lim_{R \rightarrow \infty} \int_a^R f(x) dx$ <p>II. If f is continuous on $(-\infty, b]$, then</p> $\int_{-\infty}^b f(x) dx = \lim_{R \rightarrow -\infty} \int_R^b f(x) dx$ <p>III. If f is continuous on $(-\infty, \infty)$, then</p> $\int_{-\infty}^{\infty} f(x) dx = \int_0^{\infty} f(x) dx + \int_{-\infty}^0 f(x) dx = \lim_{R \rightarrow \infty} \int_0^R f(x) dx + \lim_{R \rightarrow -\infty} \int_R^0 f(x) dx$
Type 2	<p>I. If f is continous on $[a, b)$ and discontinuous at b, then</p> $\int_a^b f(x) dx = \lim_{R \rightarrow b^-} \int_a^R f(x) dx$ <p>II. If f is continuous on $(a, b]$ and discontinuous at a, then</p> $\int_a^b f(x) dx = \lim_{R \rightarrow a^+} \int_R^b f(x) dx$ <p>III. If f is continuous on $[a, b]$ and discontinuous at $c \in (a, b)$, then</p> $\int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx = \lim_{R \rightarrow c^-} \int_a^R f(x) dx + \lim_{R \rightarrow c^+} \int_R^b f(x) dx$
Type 3	<p style="color: red;">(Mixed Type)</p>

SUMMARY OF CONVERGENCE TESTS FOR IMPROPER INTEGRALS

Tests	For which Integral & When to Use	Conclusions	Comments
p – test	$\int_a^\infty \frac{dx}{x^p}$ or $\int_a^\infty x^{-p} dx$	$\begin{cases} \text{converges to } \frac{a^{1-p}}{p-1}, & \text{if } p > 1 \\ \text{diverges to } \infty, & \text{if } p \leq 1 \end{cases}$	Useful for comparison tests if general term is similar to $\frac{1}{x^p}$.
Direct Comparison	$\int_a^\infty f(x)dx$ and $\int_a^\infty g(x)dx$ $0 \leq f(x) \leq g(x)$ for all $x \geq a$	$\begin{aligned} \int_a^\infty g(x)dx \text{ converges} &\Rightarrow \int_a^\infty f(x)dx \text{ converges} \\ \int_a^\infty f(x)dx \text{ diverges} &\Rightarrow \int_a^\infty g(x)dx \text{ diverges} \end{aligned}$	<p>* f, g must be continuous on $[a, \infty)$.</p> <p>* If we prove divergence of $\int g(x)dx$, then $f(x)$ is chosen generally as $\frac{1}{x}$.</p> <p>* If we prove convergence of $\int f(x)dx$, then $g(x)$ is chosen generally as $\frac{1}{x^p}$ but p must be greater than 1.</p>
Limit Comparison	$\int_a^\infty f(x)dx$ and $\int_a^\infty g(x)dx$ $f(x), g(x) > 0$ for all x $\lim_{x \rightarrow \infty} \frac{f(x)}{g(x)} = L$	<p>If $L \neq 0 \Rightarrow$ both are same character</p> <p>If $L = 0$ and $\int_a^\infty g(x)dx$ converges $\Rightarrow \int_a^\infty f(x)dx$ converges</p> <p>If $L = \infty$ and $\int_a^\infty g(x)dx$ diverges $\Rightarrow \int_a^\infty f(x)dx$ diverges</p>	$\int_a^\infty g(x)dx$ is chosen generally as type of $\frac{1}{x^p}$.

~~~~~ SERIES ~~~~~

SOME PARTICULAR FINITE SERIES' SUM

$\sum_{i=1}^n i = \frac{n(n+1)}{2}$ $\sum_{i=1}^n (2i-1) = n^2$ $\sum_{i=1}^n i^2 = \frac{n(n+1)(2n+1)}{6}$ $\sum_{i=1}^n i^3 = \frac{n^2(n+1)^2}{2}$	$\sum_{i=1}^n i(i+1) = \frac{n(n+1)(n+2)}{3}$ $\sum_{i=1}^n i(i+1)(i+2) = \frac{n(n+1)(n+2)(n+3)}{4}$ $\sum_{i=1}^n \frac{1}{i(i+1)} = \frac{n}{n+1}$ $\sum_{i=1}^n \frac{1}{i(i+1)(i+2)} = \frac{n(n+3)}{4(n+1)(n+2)}$
---	---

SUMMARY OF CONVERGENCE TESTS FOR SERIES

Tests	For which Series & When to Use	Conclusions	Comments
n^{th} term test (or the zero test) (Divergence Test)	for any series $\sum a_n$	Diverges if $\lim_{n \rightarrow \infty} a_n \neq 0$	Inconclusive if $\lim_{n \rightarrow \infty} a_n = 0$ (Limit 0 ise yakınsaktır diyemeyiz)
Geometric Series	$\sum_{n=0}^{\infty} ax^n$ or $(\sum_{n=1}^{\infty} ax^{n-1})$	Converges to $\frac{a}{1-x}$ only if $ x < 1$ Diverges if $ x \geq 1$	Useful for comparison tests if general term is similar to ax^n
p – series (p – test)	$\sum_{n=1}^{\infty} \frac{1}{n^p}$	Converges if $p > 1$ Diverges if $p \leq 1$	Useful for comparison tests if general term is similar to $\frac{1}{n^p}$
Integral Test	$\sum_{n=c}^{\infty} a_n, c \geq 0$ $a_n = f(n)$ for all n	Converges if $\int_c^{\infty} f(x)dx$ converges Diverges if $\int_c^{\infty} f(x)dx$ diverges	The function $f(n)$ must be; ✓ continuous ✓ positive, ✓ decreasing ✓ readily integrable for $x \geq c$
Direct Comparison	$\sum a_n$ and $\sum b_n$ $0 \leq a_n \leq b_n$ for all n	$\sum b_n$ converges $\Rightarrow \sum a_n$ converges $\sum a_n$ diverges $\Rightarrow \sum b_n$ diverges	$\sum b_n$ is chosen generally as a geometric or a p series
Limit Comparison	$\sum a_n$ and $\sum b_n$ $a_n, b_n > 0$ for all n $\lim_{n \rightarrow \infty} \frac{a_n}{b_n} = L$	If $L \neq 0 \Rightarrow$ both are same character If $L = 0$ and $\sum b_n$ converges $\Rightarrow \sum a_n$ converges If $L = \infty$ and $\sum b_n$ diverges $\Rightarrow \sum a_n$ diverges	$\sum b_n$ is chosen generally as a geometric or a p series
Ratio (D'Alembert Test)	for any series $\sum a_n$ $\lim_{n \rightarrow \infty} \left \frac{a_{n+1}}{a_n} \right = L$	Converges (absolutely) if $L < 1$ Diverges if $L > 1$	Inconclusive if $L = 1$ The test useful if a_n involves factorials or n^{th} powers.
Root (Cauchy Test)	for any series $\sum a_n$ $\lim_{n \rightarrow \infty} \sqrt[n]{ a_n } = L$	Converges (absolutely) if $L < 1$ Diverges if $L > 1$	Inconclusive if $L = 1$ The test useful if a_n involves n^{th} powers.
Alternating Series (Leibnitz Test)	$\sum_{n=0}^{\infty} (-1)^n a_n \quad (a_n > 0)$	Converges if; ✓ $0 < a_{n+1} \leq a_n$ (a_n is decreasing) ✓ $\lim_{n \rightarrow \infty} a_n = 0$	Applicable only to series with alternate terms.
Absolute Convergence	for any series $\sum a_n$	Converges (abs.) if $\sum a_n $ converges	The test useful for series containing both positive and negative terms
Conditional Convergence	for any series $\sum a_n$	Converges while $\sum a_n $ diverges	

SOME PARTICULAR INFINITE AND MACLAURIN SERIES' SUM

Function	Expansion of the Series	Conditions	Radius of Convergence
$\frac{1}{1-x}$	$\frac{1}{1-x} = \sum_{n=0}^{\infty} x^n = 1 + x + x^2 + x^3 + \dots$	$-1 < x < 1$	$R = 1 \Rightarrow x < 1$
$\frac{a}{1-x}$	$\frac{\text{1st term}}{\text{1-ratio}} = \frac{a}{1-x} = \sum_{n=0}^{\infty} ax^n = a + ax + ax^2 + \dots$	$-1 < x < 1$	$R = 1 \Rightarrow x < 1$
$\frac{1}{1+x}$	$\frac{1}{1+x} = \sum_{n=0}^{\infty} (-x)^n = 1 - x + x^2 - x^3 + \dots$	$-1 < x < 1$	$R = 1 \Rightarrow x < 1$
$\frac{1}{(1-x)^2}$	$\frac{1}{(1-x)^2} = \sum_{n=0}^{\infty} (n+1)x^n = 1 + 2x + 3x^2 + 4x^3 + \dots$	$-1 < x < 1$	$R = 1 \Rightarrow x < 1$
$\frac{1}{(1+x)^2}$	$\frac{1}{(1+x)^2} = \sum_{n=0}^{\infty} (n+1)(-x)^n = 1 - 2x + 3x^2 - \dots$	$-1 < x < 1$	$R = 1 \Rightarrow x < 1$
$(1+x)^k$ Binomial series	$(1+x)^k = \sum_{n=0}^{\infty} \binom{k}{n} x^n = 1 + kx + \frac{k(k-1)}{2!} x^2 + \dots$	$-1 < x < 1$	$R = 1 \Rightarrow x < 1$
$\ln(1+x)$	$\ln(1+x) = \sum_{n=1}^{\infty} (-1)^{n-1} \frac{x^n}{n} = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots$	$-1 < x \leq 1$	$R = 1 \Rightarrow x < 1$
$-\ln(1-x)$	$-\ln(1-x) = \sum_{n=0}^{\infty} \frac{x^n}{n} = x + \frac{x^2}{2} + \frac{x^3}{3} + \frac{x^4}{4} + \dots$	$-1 \leq x < 1$	$R = 1 \Rightarrow x < 1$
$\sin x$	$\sin x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{(2n+1)!} = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots$	$-\infty < x < \infty$	$R = \infty \Rightarrow x < \infty$
$\cos x$	$\cos x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n)!} = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots$	$-\infty < x < \infty$	$R = \infty \Rightarrow x < \infty$
e^x	$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!} = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$	$-\infty < x < \infty$	$R = \infty \Rightarrow x < \infty$
$\tan^{-1} x$	$\tan^{-1} x = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n+1}}{2n+1} = x - \frac{x^3}{3} + \frac{x^5}{5} - \frac{x^7}{7} + \dots$	$-1 \leq x \leq 1$	$R = 1 \Rightarrow x < 1$
$\sinh x$	$\sinh x = \sum_{n=0}^{\infty} \frac{x^{2n+1}}{(2n+1)!} = x + \frac{x^3}{3!} + \frac{x^5}{5!} + \frac{x^7}{7!} + \dots$	$-\infty < x < \infty$	$R = \infty \Rightarrow x < \infty$
$\cosh x$	$\cosh x = \sum_{n=0}^{\infty} \frac{x^{2n}}{(2n)!} = 1 + \frac{x^2}{2!} + \frac{x^4}{4!} + \frac{x^6}{6!} + \dots$	$-\infty < x < \infty$	$R = \infty \Rightarrow x < \infty$

POWER, TAYLOR AND MACLAURIN SERIES

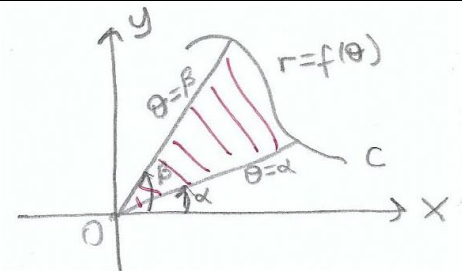
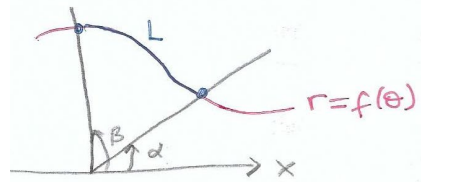
Power Series	$f(x) = \sum_{n=0}^{\infty} c_n(x-a)^n = c_0 + c_1(x-a) + c_2(x-a)^2 + \dots$
	<p>Cauchy – Hadamard Theorem: Let $L = \lim_{n \rightarrow \infty} \left \frac{c_{n+1}}{c_n} \right$ or $L = \lim_{n \rightarrow \infty} \sqrt[n]{ c_n }$, then;</p> <p>I. $L \neq 0 \Rightarrow R = \frac{1}{L}$. That is to say $R = \frac{1}{\lim_{n \rightarrow \infty} \left \frac{c_{n+1}}{c_n} \right }$ or $R = \frac{1}{\lim_{n \rightarrow \infty} \sqrt[n]{ c_n }}$</p> <p>II. $L = 0 \Rightarrow R = \infty$</p> <p>III. $L = \infty \Rightarrow R = 0$ (The means that f can be convergent only for $x = 0$)</p>
	<p>If "radius of convergence" of $f(x)$ is R;</p> $ x-a < R \Rightarrow a-R < x < a+R$ <p>In this interval $f(x)$ is already convergent. But on endpoints of this interval ($a-R$ and $a+R$), they should be checked whether f is convergent or not there</p>
	<p>If radius of $f(x)$ is R, radius of $f'(x)$ and radius of $\int f(x)$ are also R. (f must be differentiable)</p>
	<p>If radius of $\sum_{n=0}^{\infty} a_n x^n$ is R_a and radius of $\sum_{n=0}^{\infty} b_n x^n$ is R_b, then;</p> <p>radius of $\sum_{n=0}^{\infty} (a_n + b_n) x^n$ is $R \geq \min\{R_a, R_b\}$</p>
Taylor and Maclaurin Series	<p>If f can be presented by a power series, then f can be represented by a Taylor series form;</p> $f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x-a)^n = f(a) + \frac{f'(a)}{1!} (x-a) + \frac{f''(a)}{2!} (x-a)^2 + \frac{f'''(a)}{3!} (x-a)^3 + \dots$
	<p>For the special case $a = 0$ the Taylor series becomes Maclaurin series:</p> $f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(0)}{n!} x^n = f(0) + \frac{f'(0)}{1!} x + \frac{f''(0)}{2!} x^2 + \frac{f'''(0)}{3!} x^3 \dots$
	<p>Partial sum of Taylor series is $T_n(x)$, then $f(x) = \lim_{n \rightarrow \infty} T_n(x)$</p> <p>Remainder of Taylor series is $R_n(x)$, then $\lim_{n \rightarrow \infty} R_n(x) = 0$</p>
	<p>Taylor's Inequality: If $f^{(n+1)}(x) \leq M$ for $x-a \leq d$, then $R_n(x)$ satisfied the inequality;</p> $ R_n(x) \leq \frac{M}{(n+1)!} x-a ^{n+1} \text{ for } x-a \leq d$

ERROR ESTIMATE FOR ALTERNATING SERIES

$$\text{Error} = |s - s_n| \leq |s_{n+1} - s_n| \leq |a_{n+1}|$$

-----POLAR COORDINATES-----

$r = 0$	Orijin noktası
$r = a$	Merkezi (0,0) olan yarıçapı a olan çember
$r = a \sin \theta$	Merkezi (0,a/2) olan yarıçapı a/2 olan çember
$r = a \cos \theta$	Merkezi (a/2,0) olan yarıçapı a/2 olan çember
$r = a(1 \mp \sin \theta)$	Simetri eksenini y eksenini olan Kardioid
$r = a(1 \mp \cos \theta)$	Simetri eksenini x eksenini olan Kardioid
$r = a \sin 2\theta$	Simetri eksenleri $y = x$ ve $y = -x$ doğruları olan 4 yapraklı gül
$r = a \cos 2\theta$	Simetri eksenini x ve y eksenleri olan 4 yapraklı gül
$r = a \sin 3\theta$	Simetri eksenini y eksenini olan 3 yapraklı gül
$r = a \cos 3\theta$	Simetri eksenini x eksenini olan 3 yapraklı gül
$r = a \mp b \sin \theta$	Simetri eksenini y eksenini olan Limaçon (Snail)
$r = a \mp b \cos \theta$	Simetri eksenini x eksenini olan Limaçon (Snail)
$r = a\theta$	Spiral
$r = ae^{b\theta}$	Logaritmik Spiral

Tangent	$m = \frac{dy}{dx} \Big _{(r,\theta)} = \frac{f'(\theta) \sin \theta + f(\theta) \cos \theta}{f'(\theta) \cos \theta - f(\theta) \sin \theta}$	
	$\frac{dy}{d\theta} = 0$ and $\frac{dx}{d\theta} \neq 0$, then $m = 0$	
	$\frac{dx}{d\theta} = 0$ and $\frac{dy}{d\theta} \neq 0$, then $m = \infty$	
Area	$A = \frac{1}{2} \int_{\alpha}^{\beta} [f(\theta)]^2 d\theta = \frac{1}{2} \int_{\alpha}^{\beta} r^2 d\theta$	
Arc Length	$L = \int_{\alpha}^{\beta} \sqrt{\left(\frac{dx}{d\theta}\right)^2 + \left(\frac{dy}{d\theta}\right)^2} d\theta = \int_{\alpha}^{\beta} \sqrt{r^2 + \left(\frac{dr}{d\theta}\right)^2} d\theta$	

VEKTÖR DEĞERLİ FONKSİYONLAR			
$\vec{r} = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k}, \quad a \leq t \leq b$			
Hız: $\vec{v} = \frac{d\vec{r}}{dt} = \frac{df}{dt}\vec{i} + \frac{dg}{dt}\vec{j} + \frac{dh}{dt}\vec{k}$	Sürat: $ \vec{v} = \sqrt{\left(\frac{df}{dt}\right)^2 + \left(\frac{dg}{dt}\right)^2 + \left(\frac{dh}{dt}\right)^2}$	İvme: $\vec{a} = \frac{d\vec{v}}{dt}$	Yön: $\frac{\vec{v}}{ \vec{v} }$
Birim Teğet Vektör	$\vec{T} = \frac{\vec{v}}{ \vec{v} }$		
Arc Length	$L = \int_a^b \vec{v} dt$	$S(t) = \int_{t_0}^t \vec{v} dt$	

~~~~~ MULTI-VARIABLE FUNCTIONS ~~~~~

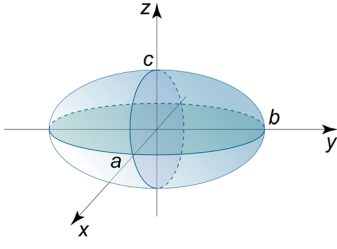
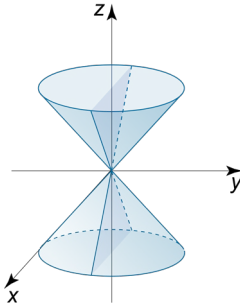
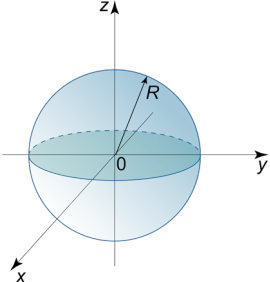
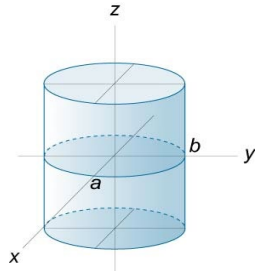
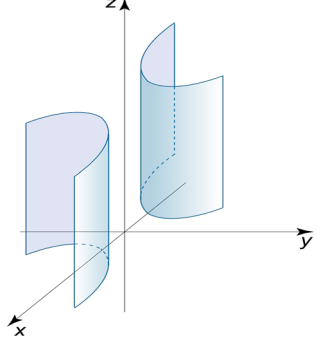
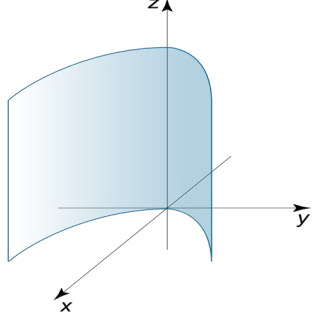
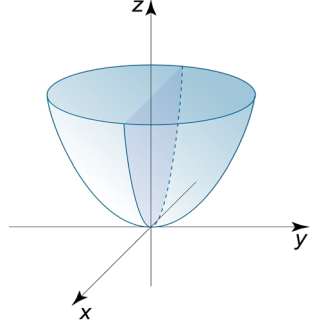
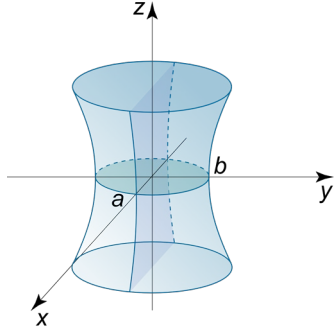
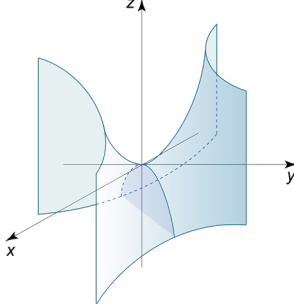
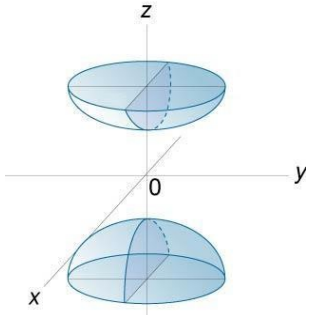
| PARTIAL DERIVATIVE AND NOTATIONS                                                              |                                                                                               |                                                                                                                                     |
|-----------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------|
| $F_x(x, y) = \frac{\partial F}{\partial x} = \frac{\partial}{\partial x}(F(x, y))$            | $F_y(x, y) = \frac{\partial F}{\partial y} = \frac{\partial}{\partial y}(F(x, y))$            |                                                                                                                                     |
| $F_{xx}(x, y) = \frac{\partial^2 F}{\partial x^2} = \frac{\partial^2}{\partial x^2}(F(x, y))$ | $F_{yy}(x, y) = \frac{\partial^2 F}{\partial y^2} = \frac{\partial^2}{\partial y^2}(F(x, y))$ | $F_{xy}(x, y) = \frac{\partial^2 F}{\partial y \partial x} = \frac{\partial}{\partial y}\left(\frac{\partial F}{\partial x}\right)$ |
| $F_x(a, b) = F_x(x, y) \Big _{(x, y) = (a, b)} = \frac{dF}{dx} \Big _{(x, y) = (a, b)}$       |                                                                                               |                                                                                                                                     |

| IMPORTANT THEOREMS AND FORMULAS FOR M-V FUNCTIONS |                                                                                                                                                                                                                                                                                                                                                                                             |                                 |
|---------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------|
| Divergence, Curl, and Laplacian                   |                                                                                                                                                                                                                                                                                                                                                                                             |                                 |
| (Fonksiyonel) Jakobian Determinant                | $F_1(x_1, x_2, \dots, x_n), F_2(x_1, x_2, \dots, x_n), F_3(x_1, x_2, \dots, x_n)$<br>$J = \frac{\partial(F_1, F_2, \dots, F_n)}{\partial(x_1, x_2, \dots, x_n)} = \begin{vmatrix} \frac{\partial F_1}{\partial x_1} & \dots & \frac{\partial F_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial F_n}{\partial x_1} & \dots & \frac{\partial F_n}{\partial x_n} \end{vmatrix}$ |                                 |
| Laplace Equation                                  | $F_{xx} + F_{yy} = 0$                                                                                                                                                                                                                                                                                                                                                                       | $F_{xx} + F_{yy} + F_{zz} = 0$  |
| Tam Diferensiyel                                  | $df = f_x dx + f_y dy$                                                                                                                                                                                                                                                                                                                                                                      | $df = f_x dx + f_y dy + f_z dz$ |

|                                                        |                                                                                                                                                      |                                                                                                                                                                   |
|--------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Gradient Vektörü</b>                                | $\nabla_f = \frac{df}{dx} \vec{i} + \frac{df}{dy} \vec{j}$                                                                                           | $\nabla_f = \frac{df}{dx} \vec{i} + \frac{df}{dy} \vec{j} + \frac{df}{dz} \vec{k}$                                                                                |
| <b>Doğrultu Türevi</b>                                 | $\vec{u} = u_1 \vec{i} + u_2 \vec{j} + u_3 \vec{k}, \quad P_0(x_0, y_0, z_0)$                                                                        |                                                                                                                                                                   |
|                                                        | $(D_u f)_{P_0} = \frac{dF}{ds} \Big _{\vec{u}, P_0} = \lim_{s \rightarrow 0} \frac{f(x_0 + su_1, y_0 + su_2, z_0 + su_3) - f(x_0, y_0, z_0)}{s}$     |                                                                                                                                                                   |
|                                                        | $(D_u f)_{P_0} = \frac{dF}{ds} \Big _{\vec{u}, P_0} = \nabla_f \Big _{P_0} \cdot \vec{u}$                                                            |                                                                                                                                                                   |
|                                                        | $(D_u f)_{P_0} =  \nabla_f  \cos \theta$                                                                                                             | $\cos \theta = 1$ ise f hızlı artar<br>$\cos \theta = -1$ ise f hızlı azalır<br>$\cos \theta = 0$ ise f in değişimi sıfırdır. ( $\nabla_f$ ile $\vec{u}$ dik ise) |
| <b>Leibnitz Formula: (İntegral Altında Türev Alma)</b> | $F(x) = \int_{u(x)}^{v(x)} f(x, y) dy \Rightarrow F'(x) = \int_{u(x)}^{v(x)} \frac{\partial f}{\partial x} dy + v'(x) f[x, v(x)] - u'(x) f[x, u(x)]$ |                                                                                                                                                                   |

| <b>GRADIENT</b>                                                          |                                                                                               |                                                                                    |
|--------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------|
| <b>Gradient Vector</b>                                                   | $\nabla_f = \frac{df}{dx} \vec{i} + \frac{df}{dy} \vec{j}$                                    | $\nabla_f = \frac{df}{dx} \vec{i} + \frac{df}{dy} \vec{j} + \frac{df}{dz} \vec{k}$ |
| <b>Gradient Rules</b>                                                    | $\nabla(kf) = k \nabla f$                                                                     | $\nabla(f \mp g) = \nabla f \mp \nabla g$                                          |
|                                                                          | $\nabla(fg) = f \nabla g + g \nabla f$                                                        | $\nabla \left( \frac{f}{g} \right) = \frac{g \nabla f - f \nabla g}{g^2}$          |
| <b>Seviye Eğrilerinin Granyenti</b>                                      | $\vec{r} = g(t) \vec{i} + h(t) \vec{j} \text{ and } F(x = g(t), y = h(t)) = c$                |                                                                                    |
| <b>Tangent Equaiton</b>                                                  | $\nabla_f \Big _{P_0} \cdot \overrightarrow{P_0 P} = 0$                                       | $f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0) = 0$                              |
|                                                                          | $f_x(x_0, y_0, z_0)(x - x_0) + f_y(x_0, y_0, z_0)(y - y_0) + f_z(x_0, y_0, z_0)(z - z_0) = 0$ |                                                                                    |
| <b>Tangent Plane</b>                                                     | $\nabla_f \cdot \frac{d\vec{r}}{dt} = 0$                                                      |                                                                                    |
| <b>Normal line at <math>P_0</math><br/><math>t \in \mathbb{R}</math></b> | $x = x_0 + f_x(P_0)t$<br>$y = y_0 + f_y(P_0)t$<br>$z = z_0 + f_z(P_0)t$                       |                                                                                    |
| <b>Tangent Plane of <math>z = f(x, y)</math> at <math>P_0</math></b>     | $f_x(x_0, y_0, z_0)(x - x_0) + f_y(x_0, y_0, z_0)(y - y_0) - (z - z_0) = 0$                   |                                                                                    |

## QUADRATIC SURFACES AND EQUATIONS

| Surface                                                                                                             | Equation                                                                                                                                                                                                          | Surface                                                                                                                  | Equation                                                                                                                                                                                                                                                     |
|---------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Ellipsoid</b><br>               | $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$ <p>All traces are ellipses.</p> <p>If <math>a = b = c = R</math>, the ellipsoid is a sphere whose radius is <math>R</math>.</p>                         | <b>Cone</b><br>                        | $\frac{z^2}{c^2} = \frac{x^2}{a^2} + \frac{y^2}{b^2}$ <p>Horizontal traces are ellipses.</p> <p>Vertical traces in planes <math>x = k</math> and <math>y = k</math> are hyperbolas if <math>k \neq 0</math> but are pairs of lines if <math>k = 0</math></p> |
| <b>Sphere</b><br>                  | $x^2 + y^2 + z^2 = R^2$ <p>All traces are circles.</p> <p>If centre is <math>(a, b, c)</math>, then</p> $(x - a)^2 + (y - b)^2 + (z - c)^2 = R^2$                                                                 | <b>Elliptic Cylinder</b><br>           | $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ <p>Horizontal traces are ellipses.</p> <p>Vertical traces are two parallel lines.</p>                                                                                                                                |
| <b>Hyperbolic Cylinder</b><br>    | $\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$ <p>Horizontal traces are hyperbolas.</p> <p>Vertical traces are two parallel lines.</p>                                                                                   | <b>Parabolic Cylinder</b><br>         | $\frac{x^2}{a^2} - y = 0$ <p>Horizontal traces are parabolas.</p> <p>Vertical traces are two parallel lines.</p>                                                                                                                                             |
| <b>Elliptic Paraboloid</b><br>   | $\frac{z}{c} = \frac{x^2}{a^2} + \frac{y^2}{b^2}$ <p>Horizontal traces are ellipses.</p> <p>Vertical traces are parabolas.</p> <p>The variable raised to the first power indicates the axis of the paraboloid</p> | <b>Hyperboloid of One Sheet</b><br>  | $\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$ <p>Horizontal traces are ellipses.</p> <p>Vertical traces are hyperbolas.</p> <p>The axis of symmetry corresponds to the variable whose coefficient is negative.</p>                               |
| <b>Hyperbolic Paraboloid</b><br> | $\frac{z}{c} = \frac{x^2}{a^2} - \frac{y^2}{b^2}$ <p>Horizontal traces are hyperbolas.</p> <p>Vertical traces are parabolas.</p> <p>The case where <math>c &lt; 0</math> is illustrated</p>                       | <b>Hyperboloid of Two Sheets</b><br> | $-\frac{x^2}{a^2} - \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$ <p>Horizontal traces in <math>z = k</math> are ellipses if <math> k  &gt; c</math>.</p> <p>Vertical traces are hyperbolas.</p> <p>The two minus signs indicate two sheets</p>                     |

## MAXIMUM AND MINIMUM

- |                        |                                                                                                                                                                                                                |
|------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Critical Points</b> | <ol style="list-style-type: none"> <li>1. <math>f_x = f_y = 0</math></li> <li>2. <math>f_x</math> or <math>f_y</math> does not exist</li> <li>3. The boundary points of the function <math>f</math></li> </ol> |
|------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|

|                                             |                                                                                                        |
|---------------------------------------------|--------------------------------------------------------------------------------------------------------|
| <b>Hessian Matrix and Discriminant of f</b> | $\Delta = \begin{vmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{vmatrix} = f_{xx} f_{yy} - f_{xy}^2$ |
|---------------------------------------------|--------------------------------------------------------------------------------------------------------|

$f_x(a, b) = f_y(a, b) = 0$ , then;

|                    | $\Delta _{(a,b)} > 0$             | $\Delta _{(a,b)} = 0$                                                            | $\Delta _{(a,b)} < 0$                                |
|--------------------|-----------------------------------|----------------------------------------------------------------------------------|------------------------------------------------------|
| $f_{xx}(a, b) > 0$ | $(a, b)$ is a local minimum point | We know nothing about the point $(a, b)$<br>The test is inconclusive at $(a, b)$ | $(a, b)$ is a saddle point<br>(Eyer / Semer noktası) |
| $f_{xx}(a, b) < 0$ | $(a, b)$ is a local maximum point |                                                                                  |                                                      |

- |                               |                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|-------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Kapalı Sınırlı Bölgede</b> | <ol style="list-style-type: none"> <li>1. Fonksiyonun bölgenin iç noktalarında kritik noktası varsa bu noktalarda aldığı değerler bulunur.</li> <li>2. Fonksiyonun bölgenin sınır noktalarında kritik noktası varsa bu noktalarda aldığı değerler bulunur.</li> <li>3. Tüm bu değerler içindeki en küçük değer fonksiyonun o kapalı bölgedeki en küçük değeri, en büyük değer ise fonksiyonun o kapalı bölgedeki en büyük değeri olur.</li> </ol> |
|-------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|

## LAGRANGE MULTIPLIERS

|                        | Equations                                                                                                                                                                                                                         | The Values What Must Be Find |
|------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------|
| <b>One Constraint</b>  | $\begin{aligned} \nabla f_x &= \lambda \nabla g_y \\ \nabla f_y &= \lambda \nabla g_y \\ \nabla f_z &= \lambda \nabla g_z \\ g(x, y, z) &= 0 \end{aligned}$                                                                       | $x, y, z, \lambda$           |
| <b>Two Constraints</b> | $\begin{aligned} \nabla f_x &= \lambda \nabla g_x + \mu \nabla h_x \\ \nabla f_y &= \lambda \nabla g_y + \mu \nabla h_y \\ \nabla f_z &= \lambda \nabla g_z + \mu \nabla h_z \\ g(x, y, z) &= 0 \\ h(x, y, z) &= 0 \end{aligned}$ | $x, y, z, \lambda, \mu$      |



# ~~~~~ MULTIPLE INTEGRALS ~~~~~

| DOUBLE INTEGRALS            |                                                                                                                                                                                                                                                |                                                                                                                                                                                                                           |
|-----------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Volume</b>               | Between f(x,y) and R on Oxy plane:<br>$V = \iint_R f(x,y) dA = \iint_R f(x,y) dx dy$                                                                                                                                                           | Between f(x,y) and g(x,y): (If $f \geq g$ )<br>$V = \iint_R [f(x,y) - g(x,y)] dA$                                                                                                                                         |
| <b>Area</b>                 | $A = \iint_R dA = \iint_R dx dy$                                                                                                                                                                                                               |                                                                                                                                                                                                                           |
| <b>Fubini Theorem</b>       | If f(x,y) is continuous on R whose bounds are $a \leq x \leq b$ and $c \leq y \leq d$ , the integral can be written as;<br>$\iint_R f(x,y) dA = \int_a^b \left( \int_c^d f(x,y) dy \right) dx = \int_c^d \left( \int_a^b f(x,y) dx \right) dy$ |                                                                                                                                                                                                                           |
|                             | If f(x,y) is continuous on R whose bounds are $a \leq x \leq b$ and $g_1(x) \leq y \leq g_2(x)$ , the integral can be written as;<br>$\iint_R f(x,y) dA = \int_a^b \left( \int_{g_1(x)}^{g_2(x)} f(x,y) dy \right) dx$                         |                                                                                                                                                                                                                           |
|                             | If f(x,y) is continuous on R whose bounds are $h_1(y) \leq x \leq h_2(y)$ and $c \leq y \leq d$ , the integral can be written as;<br>$\iint_R f(x,y) dA = \int_c^d \left( \int_{h_1(y)}^{h_2(y)} f(x,y) dx \right) dy$                         |                                                                                                                                                                                                                           |
| <b>Parametric Transform</b> | $J(u,v) = \frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} = x_u y_v - x_v y_u$                                                                                                                      | $dx dy =  J(u,v)  du dv =  x_u y_v - x_v y_u  du dv$                                                                                                                                                                      |
|                             | $\iint_R f(x,y) dx dy = \iint_{R'} f(g(u,v), h(u,v))  x_u y_v - x_v y_u  du dv$                                                                                                                                                                |                                                                                                                                                                                                                           |
| <b>Polar Transform</b>      | $\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \end{aligned}$                                                                                                                                                                       | $J(r,\theta) = \frac{\partial(x,y)}{\partial(r,\theta)} = \begin{vmatrix} x_r & x_\theta \\ y_r & y_\theta \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r$ |
|                             | $dx dy = r dr d\theta$                                                                                                                                                                                                                         | $\iint_R f(x,y) dx dy = \int_{\theta=\alpha}^{\beta} \left( \int_{r=g_1(\theta)}^{g_2(\theta)} f(r \cos \theta, r \sin \theta) r dr \right) d\theta$                                                                      |
|                             | $Area = A = \iint_R f(x,y) dx dy = \int_{\theta=\alpha}^{\beta} \left( \int_{r=g_1(\theta)}^{g_2(\theta)} f(r \cos \theta, r \sin \theta) r dr \right) d\theta$                                                                                |                                                                                                                                                                                                                           |

# TRIPLE INTEGRALS

**Volume**

$$V = \iiint_D dV = \iiint_D dx dy dz$$

**Fubini Theorem**

If  $F(x,y,z)$  is continuous on  $D$  whose bounds are  $a \leq x \leq b$ ,  $c \leq y \leq d$ , and  $e \leq z \leq f$ , the integral can be written as;

$$\iiint_D dV = \int_e^f \int_c^d \int_a^b F(x,y,z) dx dy dz$$

If  $F(x,y,z)$  is continuous on  $D$  whose bounds are  $a \leq x \leq b$ ,  $g_1(x) \leq y \leq g_2(x)$ , and  $f_1(x,y) \leq z \leq f_2(x,y)$ , the integral can be written as;

$$\iiint_D dV = \int_a^b \int_{g_1(x)}^{g_2(x)} \int_{f_1(x,y)}^{f_2(x,y)} F(x,y,z) dz dy dx$$

If  $F(x,y,z)$  is continuous on  $D$  whose bounds are  $h_1(y) \leq x \leq h_2(y)$ ,  $c \leq y \leq d$ , and  $f_1(x,y) \leq z \leq f_2(x,y)$ , the integral can be written as;

$$\iiint_D dV = \int_c^d \int_{h_1(y)}^{h_2(y)} \int_{f_1(x,y)}^{f_2(x,y)} F(x,y,z) dz dy dx$$

**Cylindrical Coordinates**

$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \\ z &= z \end{aligned}$$

$$J(r, \theta, z) = \frac{\partial(x, y, z)}{\partial(r, \theta, z)} = \begin{vmatrix} x_r & x_\theta & x_z \\ y_r & y_\theta & y_z \\ z_r & z_\theta & z_z \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix} = r$$

$$dV = r dz dr d\theta$$

$$\iiint_D dV = \int_{\theta=\alpha}^{\beta} \int_{g_1(\theta)}^{g_2(\theta)} \int_{z=f_1(r,\theta)}^{f_2(r,\theta)} F(r \cos \theta, r \sin \theta, z) r dz dr d\theta$$

**Spherical Coordinates**

$$\begin{aligned} x &= \rho \sin \varphi \cos \theta \\ y &= \rho \sin \varphi \sin \theta \\ z &= \rho \cos \varphi \end{aligned}$$

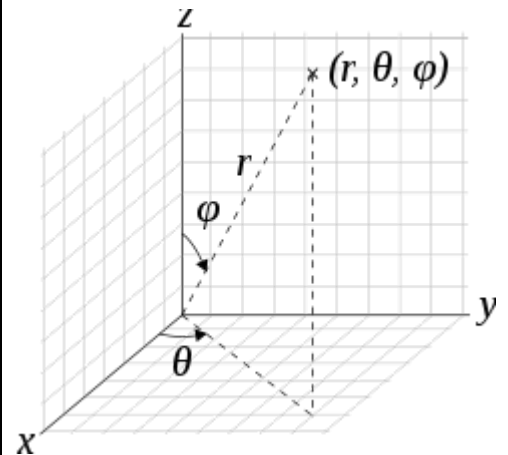
$$\begin{aligned} 0 &\leq \varphi \leq \pi \\ 0 &\leq \theta \leq 2\pi \\ x^2 + y^2 + z^2 &= \rho^2 \end{aligned}$$


$$J(\rho, \varphi, \theta) = \frac{\partial(x, y, z)}{\partial(\rho, \varphi, \theta)} = \begin{vmatrix} x_\rho & x_\varphi & x_\theta \\ y_\rho & y_\varphi & y_\theta \\ z_\rho & z_\varphi & z_\theta \end{vmatrix}$$

$$= \begin{vmatrix} \sin \varphi \cos \theta & \rho \cos \varphi & -\rho \sin \varphi \sin \theta \\ \sin \varphi \sin \theta & \rho \cos \varphi & \rho \sin \varphi \cos \theta \\ \cos \varphi & -\rho \sin \varphi & 0 \end{vmatrix} = \rho^2 \sin \varphi$$

$$dV = |J| d\rho d\varphi d\theta = (\rho^2 \sin \varphi) d\rho d\varphi d\theta$$

$$\iiint_D dV = \int_{\theta=\alpha}^{\beta} \int_{\varphi_{\min}}^{\varphi_{\max}} \int_{\rho=f_1(\theta,\varphi)}^{f_2(\theta,\varphi)} (\rho^2 \sin \varphi) d\rho d\varphi d\theta$$



| Kartesischer                                                                                                | Zylinder                                    | Kugel                                                                                                                                                                                                |
|-------------------------------------------------------------------------------------------------------------|---------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| $z = 3$ Ebene                                                                                               | $z = 3$                                     | $\rho \cos \phi = 3 \rightarrow \rho = \frac{3}{\cos \phi}$                                                                                                                                          |
| $z = x^2 + y^2$ Parabol                                                                                     | $z = r^2$                                   | $\rho \cos \phi = \rho^2 \sin^2 \phi \Rightarrow \rho = \frac{\cos \phi}{\sin^2 \phi}$<br>$\rho(\cos \phi - \rho \sin^2 \phi) = 0$                                                                   |
| $z = \sqrt{x^2 + y^2}$ Kegel                                                                                | $z = r$                                     | $\rho \cos \phi = \rho \sin \phi$<br>$\rho(\cos \phi - \sin \phi) = 0$<br>$\tan \phi = 1 \Rightarrow \phi = \frac{\pi}{4}$                                                                           |
| $z = x^2 + y^2$ Kegel<br> | $z^2 = r^2$<br>$z = \pm r$                  | $\rho^2 \cos^2 \phi = \rho^2 \sin^2 \phi$<br>$\rho^2(\cos^2 \phi - \sin^2 \phi) = 0$<br>$\sin^2 \phi = \cos^2 \phi$<br>$\tan^2 \phi = 1 \rightarrow \phi = \frac{\pi}{4}$<br>$\phi = \frac{3\pi}{4}$ |
| $x^2 + y^2 + z^2 = 4$ Kugel                                                                                 | $r^2 + z^2 = 4$<br>$z = \pm \sqrt{4 - r^2}$ | $\rho^2 = 4 \Rightarrow \rho = 2$<br>Kugel                                                                                                                                                           |
| $z = 0$                                                                                                     | $z = 0$                                     | $\rho \cos \phi = 0 \Rightarrow \phi = \frac{\pi}{2}$                                                                                                                                                |

$\uparrow z = \rho(r, \theta, z)$

$z = \rho \cos \phi$

## FONKSİYON DİZİLERİ

### Noktasal Yakınsaklık

$\forall \varepsilon > 0$  ve her  $x \in E$  için öyle bir  $N \in \mathbb{N}$  vardır ki;  $n \geq N(\varepsilon)$  için  $|f_n(x) - f(x)| < \varepsilon$  sağlanır.

### Düzgün Yakınsaklık

$\forall \varepsilon > 0$  için öyle bir  $N \in \mathbb{N}$  vardır ki; her  $x \in E$  ve  $n \geq N(\varepsilon)$  için  $|f_n(x) - f(x)| < \varepsilon$  sağlanır.

$E$  kümesi üzerinde  $f_n \xrightarrow{\text{noktasal}} f$  olsun ve  $M_n = \sup_{x \in E} |f_n(x) - f(x)|$  şeklinde tanımlansın.

$$f_n \xrightarrow{\text{düzgün}} f \Leftrightarrow \lim_{n \rightarrow \infty} M_n = 0$$