

Ex 1.2.4. Coord sys is orthogonal means  $g_{ij} \stackrel{\text{defn}}{=} \mathbf{e}_i \cdot \mathbf{e}_j = K_{ij} \delta_{ij}^i$ .  $\therefore G = \begin{pmatrix} K_{11} & 0 & 0 \\ 0 & K_{22} & 0 \\ 0 & 0 & K_{33} \end{pmatrix}$

Ex 1.2.6 In Example 1.2.1,  $\mu_1 = N\delta_1^1 - 4\delta_1^2 + \delta_1^3$ . Find  $\mu^1$ .

$$M^* = (\mu_i) = \begin{pmatrix} N \\ -4 \\ 1 \end{pmatrix}$$

$$(\mu^i) = M = \hat{G} M^* = \begin{pmatrix} \frac{1}{2} & 0 & -N \\ 0 & \frac{1}{2} & -4 \\ -N & -4 & 2u^2 + 2v^2 + 1 \end{pmatrix} \begin{pmatrix} N \\ -4 \\ 1 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2}N \\ -\frac{3}{2}4 \\ N^2 + 3u^2 + 1 \end{pmatrix}$$

$$\Rightarrow \mu^1 = -\frac{1}{2}N\delta_1^1 - \frac{3}{2}4\delta_1^2 + (N^2 + 3u^2 + 1)\delta_1^3$$

Ex 1.2.7 (a)  $\delta_1^1 = \delta_1^1 + \delta_2^2 + \delta_3^3 = 3$  (b)  $\delta_A^A = \delta_1^1 + \delta_2^2 = 2$

(c)  $\delta_a^a = \delta_{a_1}^{a_1} + \dots + \delta_{a_n}^{a_n} = n$  (d)  $\delta_\mu^\mu = \delta_1^1 + \dots + \delta_4^4 = 4$

Ex 1.4.1 Show  $U_i^k U_j^{k'} = \delta_j^{k'}$  and  $U_i^{k'} U_j^k = \delta_j^k$

$$\delta_j^k = \frac{\partial u^k}{\partial u^i} \frac{\partial u^i}{\partial u^{k'}} \frac{\partial u^{k'}}{\partial u^j} = U_i^k U_j^{k'}$$

Ex 1.6.2 Find line element  $ds^2$  for surfaces

(a) sphere of radius  $a$ :  $u = \theta$ ,  $v = \phi$

From Example 1.1.1

$$\vec{e}_\theta = a \cos \theta \cos \phi \vec{i} + a \cos \theta \sin \phi \vec{j} - a \sin \theta \vec{k}$$

$$\vec{e}_\phi = -a \sin \theta \sin \phi \vec{i} + a \sin \theta \cos \phi \vec{j}$$

$$d\vec{r} \stackrel{(1.3.74)}{=} du^A \vec{e}_A = d\theta \vec{e}_\theta + d\phi \vec{e}_\phi$$

$$ds^2 \stackrel{(1.6.5)}{=} d\vec{r} \cdot d\vec{r} = a^2 [(\cos^2 \theta \cos^2 \phi + \cos^2 \theta \sin^2 \phi + \sin^2 \theta) d\theta^2 + (\sin^2 \theta \sin^2 \phi + \sin^2 \theta \cos^2 \phi) d\phi^2]$$

$$= a^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

(b) cylinder of radius  $a$ :  $u = \phi$ ,  $v = z$

From Exercise 1.1.1

$$\vec{e}_\phi = a \sin \phi \vec{i} + a \cos \phi \vec{j}$$

$$\vec{e}_z = \vec{k}$$

$$d\vec{r} = \vec{e}_\phi d\phi + \vec{e}_z dz$$

$$ds^2 = d\vec{r} \cdot d\vec{r} = a^2 (\sin^2 \phi + \cos^2 \phi) d\phi^2 + dz^2 = a^2 d\phi^2 + dz^2$$

(c) Hyperbolic paraboloid of Example 1.6.1:

$$\begin{cases} \vec{e}_u = \vec{i} + \vec{j} + 2v\vec{k} \\ \vec{e}_v = \vec{i} - \vec{j} + 2u\vec{k} \end{cases} \quad d\vec{r} = \vec{e}_u du + \vec{e}_v dv$$

$$= (du + dv)\vec{i} + (du - dv)\vec{j} + 2(vdu + u dv)\vec{k}$$

$$ds^2 = d\vec{r} \cdot d\vec{r} = 2(1 + 2v^2) du^2 + 2(1 + 2u^2) dv^2 + 8uv du dv$$