# GPU Accelerated Fast Fourier Transform

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**Abstract** We empirically investigate the performance benefits of parallel fast Fourier transform running on the GPU over a sequential version running on the GPU.

## 1 Background

#### 1.1 Discrete Fourier Transform

The discrete Fourier transform is a mathematical transformation that takes a set of Complex-valued signals and outputs a set of Complex-valued frequencies. For an n-dimensional Complex-valued vector  $\mathbf{X}$ , the discrete Fourier transform  $\mathbf{Y} = \mathcal{F}(X)$  is given by

$$Y_j = \sum_{k=0}^n x_k \omega^{jk}$$

where  $\omega$  is the *n*-th root of unity,  $e^{2\pi i/n}$ . Since **Y** is an *n*-dimensional, Complex-valued vector, we can see that the discrete Fourier transform has a complexity of  $\Theta(n^2)$ .

#### 1.2 Fast Fourier Transform

Furthermore, we can split the discrete Fourier transform into even and odd sums for n = 2m, yielding

$$Y_j = \sum_{k=0}^{m} x_{2k} \omega^{2jk} + \omega^j \sum_{k=0}^{m} x_{2k+1} \omega^{2jk}$$

which is two separate discrete Fourier transforms. Suppose  $n=2^k$ . If we iterate this process, we get the following algorithm called the one-dimensional, unordered radix 2, fast Fourier transform.

```
1: function R-FFT(\mathbf{X}, \mathbf{Y}, n, \omega)
2: if n=1 then
```

```
y_0 = x_0
 4:
            else
                  Let \mathbf{Q} = \mathbf{0}, \mathbf{T} = \mathbf{0} \in \mathbb{C}^n
 5:
                  Let \mathbf{X_e} = (x_0, x_2, \dots, x_{n-2})
 6:
                  Let \mathbf{X_o} = (x_1, x_3, \dots, x_{n-1})
 7:
                  R-FFT(\mathbf{X_e}, \mathbf{Q_e}, n/2, \omega^2)
 8:
                  R-FFT(\mathbf{X}_{\mathbf{0}}, \mathbf{T}_{\mathbf{0}}, n/2, \omega^2)
 9:
                  for all j \in \{0, 1, ..., n-1\} do
10:
                        y_i = q_{i \mod n/2} + \omega^i t_{i \mod n/2}
11:
                  end for
12:
            end if
13:
14: end function
```

#### 1.2.1 Cooley Tukey

Furthermore, we have an iterative formulation of the prior algorithm, called the Cooley Tukey algorithm for one-dimensional, unordered radix 2, fast Fourier transforms.

```
1: function I-FFT(\mathbf{X},\mathbf{Y},n)
          t := \lg n
 2:
          \mathbf{R} = \mathbf{X}
 3:
          for m = 0 to t - 1 do
 4:
                S = R
 5:
                for l = 0 to n - 1 do
 6:
                     Let (b_0b_1 \dots b_{t-1}) be the binary expan-
 7:
     sion of l
 8:
                     j := (b_0 \dots b_{m-1} 0 b_{m+1} \dots b_{t-1})
                     k := (b_0 \dots b_{m-1} 1 b_{m+1} \dots b_{t-1})
r_i := s_j + s_k \omega^{(b_m b_{m-1} \dots b_0 0 \dots 0)}
 9:
10:
                end for
11:
          end for
13:
          Y := R
14: end function
```

From this pseudo-code, we can determine the complexity of fast Fourier transform. We begin by noting that we iterate through the outer loop precisely  $\lg n$  times and the inner loop n times. Therefore our com-

plexity is  $T_1 = \Theta(n \lg n)$ .

#### 1.3 Parallelization

For our parallelization, we use a simplified version of the binary exchange algorithm, a parallelization of the Cooley Tukey algorithm designed for use on a hypercube. Since our implementation runs on a single GPU, any thread can access any memory location via a pointer. However, this also complicates the matter by introducing a potential for data races. We solve this by modifying the algorithm to work as follows.

```
1: function PAR-FFT(\mathbf{X}, \mathbf{Y}, n)
 2:
          t := \lg n, BLK := n/p
          \mathbf{R} = \mathbf{X}
 3:
          S = 0
 4:
          for m=0 to t-1 do
 5:
              Swap pointers \mathbf{R} and \mathbf{S}
 6:
 7:
              spawn process for l = 0 to BLK - 1 do
                   for c = l \cdot BLK, to l \cdot (BLK + 1) do
 8:
                        Let (b_0b_1 \dots b_{t-1}) be the binary ex-
    pansion of c
                        j := (b_0 \dots b_{m-1} 0 b_{m+1} \dots b_{t-1})
10:
                        k := (b_0 \dots b_{m-1} 1 b_{m+1} \dots b_{t-1})
r_i := s_j + s_k \omega^{(b_m b_{m-1} \dots b_0 0 \dots 0)}
11:
12:
                   end for
13:
              end spawn
14:
              sync
15:
          end for
16:
          Y := R
17:
18: end function
```

In each iteration, we only write to  $\mathbf{R}$  and only read from  $\mathbf{S}$ . Since we wait until each thread is complete before moving on to the next iteration, we avoid the potential to use old or incorrect data.

If we inspect the parallelization, we see that the outer loop runs  $\lg n$  times. However, the inner loop is ran on p processes, each of which handle n/p iterations. Therefore, the computation cost is  $\Theta(n/p\lg n)$ . Moreover, for communication we simply do two reads from VRAM on each iteration of the inner loop, however some values will be in cache so we may get better performance than that. Ergo, the communication cost  $O(n/p\lg n)$ . Thus, the parallel runtime will be  $T_p = O(n/p\lg n)$  and is cost optimal if and only if  $p \le n$ .

# 2 Experimental Design

The goal of the experiment is to empirically determine the effect of parallelization on the runtime of

the Cooley Tukey algorithm. To this end we want to measure the runtime of fast Fourier transform using differing sizes of n, the dimension of our Complex valued vector, and t, the number of threads. Let  $\mathcal N$  be the set of vector dimensions we will test and let  $\mathcal T$  be the set of thread counts we will test. Furthermore, we specify that each  $n \in \mathcal N$  and each  $t \in \mathcal T$  be powers of two.

For t=1, we will run the Cooley Tukey algorithm on random Complex valued vectors of dimension n for each  $n \in \mathcal{N}$ . Otherwise, we run our parallelization of the Cooley Tukey algorithm on Complex valued vectors of dimension n for each  $n \in \mathcal{N}$ . Moreover, before and after each run, we copy the input to the GPU and the output from the GPU. We do not check the output for correctness during the test in order to save time, but instead checked the correctness of the algorithm beforehand.

## 3 Test Environment

### 3.1 Test System

The machine used to run the test has an Intel i7 4770k running at 4.2GHz, 16GB of RAM, and a Nvidia GTX 970 with a core clock of 1342MHz and memory clock of 7000MHz. The computer was running Arch Linux on Linux kernel 4.2.5 with Nvidia driver version 358.16 and CUDA 7.5.

#### 3.2 Test Program

Firstly, all code can be located at https://github.com/matt-mccarthy/fast-fourier-transform in the fast-fourier folder. We also include a version of the code in the Appendix.

All code was compiled with CUDA toolkit 7.5 and GCC 5.2.0 with the command nvcc -std=c++11-rdc=true -arch=compute\_52 -code=sm\_52 -03. The library source file is src/fast-fourier.cu, and the sequential and parallel main functions are located in sequential-fft.cu and parallel-fft.cu respectively.

- 4 Results
- 4.1 Linear Speedup
- 5 Conclusion

Appendix