Invasive mesopredator release

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9 Abstract

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- 1. Background.
- Methods.
- 3. Results.
- 4. Synthesis and applications.
- 14 Key words: Camera trap; Felis catus; invasive predator; interspecific competition;
- mesopredator release; population density; spatial capture-recapture; spatial mark-resight;
- species interactions; Vulpes vulpes.

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1. INTRODUCTION

Understanding species interactions is critical for effective invasive species management (Zavaleta et al., 2001). When several invasive species co-occur, management actions that 19 suppress the dominant invasive species may inadvertently benefit subordinate invasive species (Jackson, 2015; Kuebbing & Nuñez, 2015). Subordinate invasive species may be released from 21 direct top-down pressure following a decline in the dominant predator or benefit indirectly from an increase in availability of shared resources (often referred to as mesopredator or competitor 23 release - Crooks & Soulé, 1999; Doherty & Ritchie, 2017; Ruscoe et al., 2011). The release of a subordinate invasive species, particularly predators, can have serious negative implications for 25 native taxa and ecosystem function (Ballari et al., 2016; Courchamp et al., 1999). However, 26 integrated predator management is often far more costly and less feasible than single species control, and so it is important to identify the extra cost if justified (Bode et al., 2015).

Most knowledge of predator interactions stems from unreplicated "natural experiments" (e.g. range contractions - Crooks & Soulé, 1999) or ad-hoc management interventions (e.g. invasive species eradications - Rayner et al., 2007). However, the occurrence, nature (positive or negative, direct or indirect) and strength of species interactions can vary among species assemblages, predation risk, environmental productivity, management regimes, and other landscape contexts (Alston et al., 2019; Finke & Denno, 2004; Hastings, 2001). Replicating management programs in an experimental framework is logistically challenging, but important for understanding these complexities, discriminating between plausible hypotheses and producing generalisable results in order to inform effective pest management (Christie et al., 2019; Glen & Dickman, 2005; Smith et al., 2020).

Unbiased estimates of invasive predator density are vital for inferring native prey impacts on and for setting meaningful control targets (Moseby et al., 2019). However, controversy around the mesopredator release hypothesis has stemmed from the inability of traditional survey approaches to separate behavioural and numerical population processes (Hayward et al., 2015; Stephens et al., 2015). These nonspatial approaches arbitrarily divide continuous landscapes into discrete spatial sampling units, but highly mobile predators can easily break model assumptions by crossing these (Efford & Dawson, 2012). Additionally, the suppression of an apex predator may change the behaviour and density of a mesopredator, both of which impact detection rates (Broadley et al., 2019; Rogan et al., 2019). And so, even with experimental designs, it is difficult to interpret changes in unidentified counts or presence-absence records of mesopredators in relation to apex predators. While spatially explicit capture-recapture methods have been developed to robustly estimate predator density by separating out behavioural and observational processes from population density, they have seldom been used experimentally or to investigate multispecies interactions (although, see Forsyth et al., 2019).

Predation by two invasive species, the red fox *Vulpes vulpes* and feral cat *Felis catus*, has played a major role in Australia's high rates of mammalian extinction (Woinarski et al. 2019). Integrated invasive predator management programs are rare. Introduced red foxes (hereafter foxes) are far more commonly controlled than feral cats, as they are more susceptible to poison-baiting, have greater direct economic impacts and fewer legal impediments to their control (McLeod & Saunders, 2014; Reddiex et al., 2007). Nonetheless, feral cats are one of the most widespread and damaging vertebrate species (Doherty & Ritchie, 2017; Legge et al., 2020; Medina et al., 2011). As foxes are larger-bodied (~2 kg difference) and have high dietary overlap with feral cats (Catling, 1988; Glen et al., 2011; Short et al., 1999), the mesopredator release hypothesis predicts that feral cat impacts will increase as fox populations are managed (Soulé et al., 1988). This is alarming because feral cats are extremely difficult to manage in open populations (Fisher et al., 2015; Lazenby et al., 2015).

Evidence that foxes suppress feral cats is inconclusive (Hunter et al., 2018). In parts of Australia where the native apex mammalian predator (the dingo *Canis familiaris*) is functionally extinct and introduced red foxes are the largest terrestrial mammalian predator, four studies have observed an increase in feral cat detections following fox control (Marlow et al., 2015; Risbey et al., 2000; Stobo-Wilson et al., 2020). However, two other studies in similar systems did not see any change (Molsher et al., 2017; Towerton et al., 2011). One study with spatial replication detected an increase at one site but not another (Davey et al., 2006), and one study observed a decrease in feral cat activity (Claridge et al., 2010). No previous study has directly

estimated feral cat density in response to fox control.

In this study, we experimentally investigated the role of introduced foxes in top-down sup-74 pression of feral cat density in two regions of south-eastern Australia. Foxes and feral cats are the only functional terrestrial mammalian predators in these regions, and each region included 76 at least one area in which foxes were subject to continuous lethal poison-baiting (hereafter 77 "impact landscape"), and a paired area were foxes were not controlled (hereafter "non-impact landscape"). This allowed a sharp focus on the interactions between the two invasive predators, across a gradient of apex predator (fox) occupancy and landscape productivity. We tested for 80 a direct effect of fox control on feral cat density using traditional experimental approaches: a 81 replicated Control-Impact design in the region with long-term fox control, and a Before-After Control-Impact Paired Series (BACIPS) design in the region with newly implemented fox con-83 trol. We also tested for direct associations between feral cat density and spatial fox occupancy (derived using generalised additive models) in each region, as well as investigated the relative 85 importance of fine or broad scale fox measurements. In accordance with the mesopredator release hypothesis, we predicted that (1) fox control would increase feral cat density, and (2) 87 feral cat density would be negatively correlated with spatial fox occupancy. We based inference on spatial mark-resight models of feral cat density and information criteria methods.

2. MATERIALS AND METHODS

2.1. Study area

We conducted our study across two regions of south-west Victoria, Australia (Fig. 1).

The native temperate forests in both regions are fragmented to varying degrees, primarily by livestock farming and tree plantations. Although once widespread, dingoes are now absent throughout, and a native mesopredator, the tiger quoll *Dasyurus maculatus*, is long absent from the Glenelg region and recently absent in the Otway Ranges (last sighted in 2014 despite extensive camera-trapping). The terrestrial mammalian predator guild is therefore depauper-ate, with the introduced fox and feral cat being the primary functional mammalian terrestrial predators; birds of prey and snakes are the only other predators present.

Our study landscapes in the Glenelg region, Gunditjmara country, are primarily lowland 100 forest (with an overstorey of Eucalyptus obliqua and E. ovata, a sparse midstorey and a fern-101 rich understorey) and heathy woodland (with an overstorey of E. baxteri s.l. and E. willisii, a 102 sparse midstorey and a diverse understorey of narrow or ericoid-leaved shrubs). It has gently 103 undulating terrain and frequently experiences prescribed burns and wildfires, creating a mosaic 104 of fire histories and vegetation complexity. The area receives an average annual rainfall of 105 700 mm, with average minimum temperatures of 8.1°C and maximum of 17.6°C (Bureau of 106 Meteorology, 2021). 107

Our study landscapes in the Otway region were in the western section of the Otway Ranges, 108 Gadubanud country. Here, the vegetation is a mosaic of shrubby wet forest and cool tem-109 perate rainforest, with an overstorey of tall eucalyptus species (primarily E. regnans), Acacia 110 melanoxylon and Nothofaqus cunninghamii. The midstorey is dominated by tree ferns, Acacia 111 verticillata, Pomaderris aspera and Olearia argophylla. The understorey predominantly com-112 prises a dense layer of ferns and graminoids but can be relatively sparse in steep rainforest 113 gullies. Maximum daily temperatures average 19.3°C in summer and 9.5°C in winter; annual 114 rainfall averages 1955 mm (Bureau of Meteorology, 2021). This region rarely experiences fire 115 and is nearly ten times more rugged (based on the terrain ruggedness index (Riley et al., 1999) 116

averaged within a 10 m radius of each camera-trap site).

8 2.2. Lethal fox control

Across broad sections of each region, government land managers conduct ongoing fox control 119 for biodiversity conservation. Manufactured poison baits (FoxOff, Animal Control Technologies, 120 Somerton) containing 3 mg of sodium mono-fluroacetate (1080) are buried at a depth of 10 cm 121 at 1-km intervals along accessible forest tracks and roads (Fig. 1). Different road densities 122 across the two regions therefore result in variable poison-bait densities. In the Glenelg region, 123 fox control in the impact landscapes has been ongoing since October 2005, with baits checked 124 and replaced fortnightly (Robley et al., 2014). In the Otway region, baiting commenced in 125 the impact landscape in November 2017. Poison baits were replaced weekly for six weeks until December 2017, before changing to monthly bait replacement until July 2018. The fox 127 control program then lapsed for approximately six months until December 2018 due to logistical 128 constraints, when monthly bait replacement recommended for the duration of our study (Fig. 129 S1). 130

2.3. Study design and camera-trapping

We designed experiments around the implementation of fox poison-baiting in each region.
We simultaneously surveyed one impact and one non-impact landscape at a time using cameratraps. Each landscape pair was chosen based on similarity in landscape context, namely vegetation groups, with the aim of maintaining spatial independence with respect to predator range
movements.

In the Glenelg region, we used a replicated control-impact design to test for differences in areas that have been poison-baited for foxes for more than 13 years compared with unbaited areas. We deployed a pair of camera-trapping grids in Cobboboonee National Park (impact) and Annya State Forest (non-impact) in January – April 2018, then moved these cameras to Mt Clay State Forest/Narrawong Flora Reserve (hereafter "Mt Clay"; impact) and Hotspur

State Forest (non-impact) in April – June 2018 (Fig. S3). Each grid was separated by at least 8 km, a distance very unlikely to be traversed regularly by these invasive predators (Hradsky et al., 2017).

In the Otway region, we undertook a BACIPS study to assess changes related to the intro-145 duction of the fox control program. We deployed camera-trap grids in an impact – non-impact pair of landscapes in June - September from 2017 to 2019, in the Great Otway National Park 147 and Otway Forest Park (Fig. S1). Our first survey occurred approximately three months before fox-baiting began. The second survey was conducted six months post-commencement of 149 fox-baiting, however poison bait replacement lapsed at the beginning of the survey until nearly 150 three months afterwards (Fig. S1). Fox-baiting recommended six months prior to the start of 151 the final survey (Fig. S1). The impact and non-impact landscapes were at least 4.2 km apart, a 152 distance unlikely to be traversed by these invasive predators, although possible (Hradsky et al., 153 2017). In this study, and a concurrent study which identified individual foxes through genetic 154 sampling (M. Le Pla, in review), we found no evidence of either species of predator moving between these landscapes. 156

In each of the six survey landscapes, we deployed a grid of camera-traps (67 – 110 cameras; 157 mean = 94), with sites spaced on average 448 m apart (range: 194 - 770 m; Fig. 1). At each 158 site, we deployed a single Reconyx trail camera (Reconyx, Holmen, Wisconsin) with an infrared 159 flash and temperature-in-motion detector on a tree, facing a lure of oil-absorbing cloth doused 160 in tuna oil (Fig. S2). More information on the camera-trapping methods is provided in Section 161 1.2 of the Supporting Information. Overall, we deployed 938 functional camera-traps, which 162 operated for an average of 68 days (range: 12 – 93 days), totalling 62,415 trap nights (Table 1) 163 across a total study duration of five months and three years in the Glenelg and Otways regions 164 respectively (Fig. S1).

2.4. Individual feral cat identification

We added a species metadata tag for each camera-trap image, compiled species record tables and extracted feral cat photos for individual identification using the "camtrapR" R package (Niedballa et al., 2016). We sorted the cats into five categories based on their coat type:
black, spotty tabby, swirly tabby, ginger and other (cats with multiple colour blends or other
distinctive coats; Fig. S3). We did not attempt to identify any black cats, even the few with
white splotches on their underside, as these markings could not always be seen. Within the
other four coat categories, multiple observers identified individual cats based on their unique
coat patterns where possible. Detailed information on this process is provided in Section 2 of
the Supporting Information.

2.5. Spatial fox occupancy

Spatial mark-resight models require density covariate values for each grid cell density is 177 estimated across (or a single value for the entire session - each camera-trap grid deployment in our case), and so we could not directly use the fox data from the camera-trap sites as 179 independent variables. We therefore used the presence-absence data for each camera-trap site to 180 generate a spatially-interpolated layer of fox occupancy probability using binomial generalised 181 additive models (Wood, 2017). We did so using the "mgcv" R package (version 1.3.1; Wood, 182 2011). We modelled fox presences and absences (response variable) across space (explanatory 183 variable) separately for each region, with a duchon spline spatial smooth as these provide better 184 predictions at the edge of surveyed space than other splines (Miller & Wood, 2014). In the 185 Otway region, we included a random intercept for each camera-trap site to account for repeat 186 sampling and did not share spatial information across the years (using a "by variable" smooth with year as a factor). Differences in camera-trap deployment lengths were accounted for using 188 a model offset. We did not use occupancy-detection models because factors which impact fox detectability on camera-traps may also impact fox detectability to feral cats - which is more 190 important than predictive performance in this context. We predicted GAM estimates into the 191 respective spatial mark-resight habitat mask and trapfile (detailed below). 192

2.6. Spatial mark-resight models of feral cat density

We used a spatial capture-recapture approach to estimate feral cat density (Borchers & 194 Efford, 2008). These models consider counts of detections and non-detections of individual 195 animals at trap locations (accounting for trap-specific survey effort) to estimate the location of 196 each individual's activity centre. These models generally assume that individuals have approx-197 imately circular home ranges and spend the majority of time in the centre of which ("activity 198 centre"). The probability of observing an individual therefore decreases with distance from 199 the activity centre. Two detectability parameters govern this process: g0, the probability of 200 detecting an individual per occasion in their activity centre and sigma: a spatial scale param-201 eter which is relative to the home range size. Multiple candidate shapes for this decline in 202 detectability with distance from the activity centre ("detection function") can be modelled. 203

Spatial capture-recapture models have been extended to consider situations where not all 204 individuals in a population are identifiable (i.e. marked) (Chandler & Royle 2013). These spa-205 tial mark-resight models typically assume unmarked individuals to be a random sample of the 206 population, sharing the same detection process as marked individuals, and so allow density to 207 be estimated for the entire population. Spatial mark-resight models have four categories of 208 sightings: (1) marked individuals - detections with known identified to the individ-209 ual level at least once each session, (2) marked but unidentifiable individuals - detections of individuals with known identities, but for which the individual could not be determined in a 211 given session (we had no detections in this category), (3) unmarked individuals - unidentified 212 detections which definitely do not belong to the first two categories (in our study, this category 213 comprised black cats) and (4) mark status uncertain - detections in which individuals cannot 214 be identified and it is not clear whether the individual is of the marked or unmarked category. 215

We used closed population, sighting-only, spatial mark-resight to estimate feral cat density using the maximum likelihood "secr" R package (Efford, 2021). Detections of the "mark status uncertain" category cannot be handled in the "secr" R package, we therefore added them to the unmarked detections rather than discard them (Moseby et al., 2020). We condensed detection histories of each mark category to a binary presence-absence record per each camera-trap for

a 24-hour length duration ("occasion"), beginning at midday. We ran separate models for each region and treated each camera-trap grid deployment as a "session". We created a 4000 metre buffer zone around each camera-trap location to estimate feral cat density across, with 223 grid cell resolution of 200 metres. These habitat mask specifications were based on initial models and our knowledge of feral cats in these area - ensuring density is estimated over a large 225 enough area to encompass the activity centres of all feral cats exposed to our camera-traps, 226 at a fine enough scale to minimise bias in density estimates. We tested the half-normal and 227 exponential detection functions in each region, carrying forward the function with the lowest 228 Akaike's Information Criterion score adjusted for small sample size (AICc) for all subsequent 229 model fitting (Burnham & Anderson, 2004). 230

For each region, we ran three sets of models: (1) to choose the best "null model" to carry
through into other model sets (2) to experimentally evaluate the effect of fox control on feral cat
density, and (3) test fine-scale association between spatial fox occupancy and feral cat density.
We assessed the relative performance of models in each set using AICc score, with models
within 2 delta AICc of the top-ranked model considered strongly supported compared to the
other candidate models (Burnham & Anderson, 2004).

We compared four candidate "null models" (1) for each region. The first model (1A) was
the simplest - density and detectability parameters were held constant. Model 1B included an
effect of vegetation group on feral cat density (with detectability parameters constant). For
this model, we condensed Ecological Vegetation Class groupings (DELWP, 2020) into three
categories for each region: cleared land, heathy woodlands, lowland forests (Glenelg region
only) and wet forests (Otways region only). Detailed information on this process is provided in
Section X of the Supporting Information. Model 1C included a linear time trend on g0, keeping
density and sigma constant - because the potency of the tuna oil lure likely decreased over the
survey duration (Rees et al., 2019). The fourth model (1D) was a combination of model 1B
and 1C: density ~ vegetation group, g0 ~ T, sigma ~ 1.

We compared two types of experimental models on feral cat density (2) to their respective null model in each region. The first was a standard control-impact or before-after-control impact

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- model specification in the Glenelg and Otways regions respectively with the effect of foxbaiting averaged across space and time replicates. The second experimental models modelled fox-baiting effects separately for each space and time replicate in the Glenelg and Otways regions respectively. We ran these models twice: once where detectability was constant, and another where detectability parameters mirrored the respective density parameter specification.
- In the Glenelg region, we fit a standard control-impact model using a binary impact (fox-baited) or non-impact categorical covariate. In the Otway Ranges, we fit a standard beforeafter-control-impact model with an interaction between landscape (impact or non-impact) and
 time period (before [2017] or after [2018-19] poison-baiting began).
- non-impact session covariate.
- We also fit an interaction model between
- 260 categorical session
- 261 Experimental models
- The first was the simplest model that density and detectability parameters constant, (2)
 density
- We expected that foxes would impact both detectability parameters for feral cats concurrently, and so, always specified g0 and sigma consistently (Efford & Mowat, 2014).

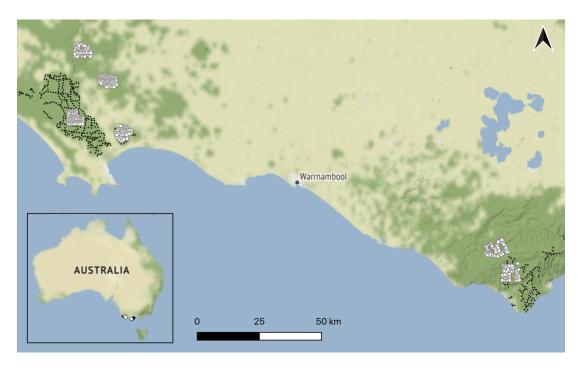


Figure 1: Locations of our six study landscapes in south-west Victoria, Australia. The grids of camera-traps are denoted by white dots, the locations of fox poison-bait stations are denoted by smaller black dots. The Glenelg region is to the west and Otway region to the east. Native vegetation is indicated by dark green, with hill shading. Map tiles by Stamen Design, under CC BY 3.0, map data by OpenStreetMap, under CC BY SA.

266 **3. RESULTS**

Table 1: Camera-trap surveys and feral cat spatial capturerecapture summary statistics.

Land-	Fox	Camera-	Trap	Identified	Identified	Unidentified	Unmarked
scape	control	traps	nights	cats	detections	detections	detections
Annya	no	110	8000	9	23	3	20
Cobbob	yes	110	7752	13	35	9	37
Hotspur	no	99	6085	8	22	3	13
Mt	yes	106	5451	10	33	5	0
Clay							
South	no	73	3565	20	62	8	46
2017							
North	no	67	7099	26	60	4	48
2017							
South	yes	85	7838	24	75	12	62
2018							
North	no	103	4543	30	90	17	59
2018							
South	yes	86	6077	25	133	22	101
2019							
North	no	99	7150	27	90	23	58
2019							

Note: There is a maximum of one detection per each 24-hour occasion.

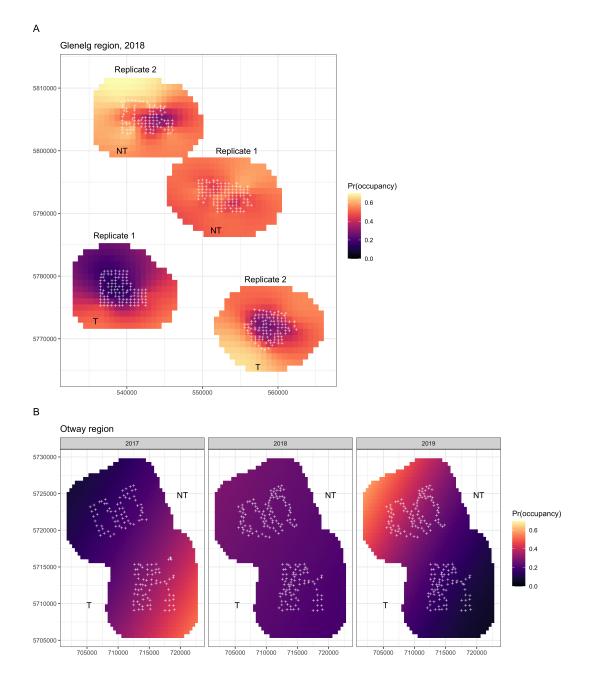


Figure 2: Fox probability of occupancy derived from generalised additive models within each impact (I) and associated non-impact (NI) landscape in the Glenelg (A) and Otways (B) regions. Estimates were used as predictor variables in the feral cat spatial mark-resight models.

268 4. DISCUSSION

5. CONCLUSIONS

6. ACKNOWLEDGEMENTS

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7. AUTHORS' CONTRIBUTIONS

M.W.R, B.H, J.H.P, B.A.W and A.R conceived the ideas and designed methodology; M.W.R, J.H.P, M.LP, E.K.B and B.H collected the data; M.W.R analysed the data; M.W.R led the writing of the manuscript. All authors contributed critically to the drafts and gave final approval for publication.

296 8. OPEN RESEARCH

- Raw data and code are on Github link xx.
- $_{\rm 298}$ $\,$ Data will be deposited on the Dryad Digital Repository after acceptance.

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