# Invasive mesopredator release

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# 9 Abstract

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- 1. This is the abstract.
- 2. It consists of two paragraphs.
- 3. It consists of two paragraphs.
- 4. Synthesis and applications. It consists of two paragraphs.
- 14 Key words: Camera trap; Felis catus; invasive predator; interspecific competition;
- mesopredator release; population density; spatial capture-recapture; spatial
- mark-resight; species interactions; Vulpes vulpes.

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# 7 1. INTRODUCTION

Understanding species interactions is critical for effective invasive species manage-18 ment (Zavaleta et al., 2001). When several invasive species co-occur, management actions that suppress the dominant invasive species may inadvertently benefit subordinate 20 invasive species (Jackson, 2015; Kuebbing & Nuñez, 2015). Subordinate invasive species 21 may be released from direct top-down pressure following a decline in the dominant preda-22 tor or benefit indirectly from an increase in availability of shared resources (often referred to as mesopredator or competitor release - Crooks & Soulé, 1999; Doherty & Ritchie, 2017; Ruscoe et al., 2011). The release of a subordinate invasive species, particularly 25 predators, can have serious negative implications for native taxa and ecosystem function 26 (Ballari et al., 2016; Courchamp et al., 1999). However, integrated predator manage-27 ment is often far more costly and less feasible than single species control, and so it is important to identify the extra cost if justified (Bode et al., 2015).

Most knowledge of predator interactions stems from unreplicated "natural experiments" (e.g. range contractions - Crooks & Soulé, 1999) or ad-hoc management interventions (e.g. invasive species eradications - Rayner et al., 2007). However, the occurrence, nature (positive or negative, direct or indirect) and strength of species interactions can vary among species assemblages, predation risk, environmental productivity, management regimes, and other landscape contexts (Alston et al., 2019; Finke & Denno, 2004; Hastings, 2001). Replicating management programs in an experimental framework is logistically challenging, but important for understanding these complexities, discriminating between plausible hypotheses and producing generalisable results in order to inform effective pest management (Christie et al., 2019; Glen & Dickman, 2005; Smith et al., 2020).

Unbiased estimates of invasive predator density are vital for inferring native prey impacts on and for setting meaningful control targets (Moseby et al., 2019). However,

controversy around the mesopredator release hypothesis has stemmed from the inability of traditional survey approaches to separate behavioural and numerical population processes (Hayward et al., 2015; Stephens et al., 2015). These nonspatial approaches arbitrarily divide continuous landscapes into discrete spatial sampling units, but highly mobile predators can easily break model assumptions by crossing these (Efford & Dawson, 2012). Additionally, the suppression of an apex predator may change the behaviour 48 and density of a mesopredator, both of which impact detection rates (Broadley et al., 2019; Rogan et al., 2019). And so, even with experimental designs, it is difficult to 50 interpret changes in unidentified counts or presence-absences records of mesopredators 51 in relation to apex predators. While spatially explicit capture-recapture methods have 52 been developed to robustly estimate predator density by separating out behavioural and 53 observational processes from population density, they have seldom been used experimentally or to investigate multispecies interactions (although, see Forsyth et al., 2019).

Predation by two invasive species, the red fox Vulpes vulpes and feral cat Felis catus, 56 has played a major role in Australia's high rates of mammalian extinction (Woinarski et al. 2019). Integrated invasive predator management programs are rare. Introduced 58 red foxes (hereafter foxes) are far more commonly controlled than feral cats, as they are more susceptible to poison-baiting, have greater direct economic impacts and fewer legal impediments to their control (McLeod & Saunders, 2014; Reddiex et al., 2007). Nonetheless, feral cats are one of the most widespread and damaging vertebrate species 62 (Doherty & Ritchie, 2017; Legge et al., 2020; Medina et al., 2011). As foxes are larger-63 bodied (~2 kg difference) and have high dietary overlap with feral cats (Catling, 1988; Glen et al., 2011; Short et al., 1999), the mesopredator release hypothesis predicts that feral cat impacts will increase as fox populations are managed (Soulé et al., 1988). This is alarming because feral cats are extremely difficult to manage in open populations (Fisher et al., 2015; Lazenby et al., 2015).

Evidence that foxes suppress feral cats is inconclusive (Hunter et al., 2018). In parts

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of Australia where the native apex mammalian predator (the dingo *Canis familiaris*) is functionally extinct and introduced red foxes are the largest terrestrial mammalian predator, four studies have observed an increase in feral cat detections following fox control (Marlow et al., 2015; Risbey et al., 2000; Stobo-Wilson et al., 2020). However, two other studies in similar systems did not see any change (Molsher et al., 2017; Towerton et al., 2011). One study with spatial replication detected an increase at one site but not another (Davey et al., 2006), and one study observed a decrease in feral cat activity (Claridge et al., 2010). No previous study has directly estimated feral cat density in response to fox control.

In this study, we experimentally investigated the role of introduced foxes in top-down 79 suppression of feral cat density in two regions of south-eastern Australia. Foxes and 80 feral are the only functional terrestrial mammalian predators in these regions, and each 81 region included at least one area in which foxes were subject to continuous lethal poisonbaiting (hereafter "impact landscape"), and a paired area were foxes were not controlled 83 (hereafter "non-impact landscape"). This allowed a sharp focus on the interactions between the two invasive predators, across a gradient of apex predator (fox) occupancy and vegetation types. We tested for a direct effect of fox control on feral cat density using traditional experimental approaches: a replicated Control-Impact design in the region with long-term fox control, and a Before-After Control-Impact Paired Series (BACIPS) design in the region with newly implemented fox control. Additionally, we tested for fine-scale associations between spatial fox occupancy (derived using generalised additive 90 models) and feral cat density in each region. In accordance with the mesopredator release hypothesis, we predicted that (1) fox control would increase feral cat density, and (2) feral cat density would be negatively correlated with spatial fox occupancy. We based inference on spatial mark-resight models of feral cat density and information criteria methods.

# 96 2. MATERIALS AND METHODS

#### 97 2.1. Study area

We conducted our study across two regions of south-west Victoria, Australia (Fig. 1).

The native temperate forests in both regions are fragmented to varying degrees, primarily
by livestock farming and tree plantations. Although once widespread, dingoes are now
absent throughout, and a native mesopredator, the tiger quoll *Dasyurus maculatus*, is
long absent from the Glenelg region and recently absent in the Otway Ranges (last
sighted in 2014 despite extensive camera-trapping). The terrestrial mammalian predator
guild is therefore depauperate, with the introduced fox and feral cat being the primary
functional mammalian terrestrial predators; birds of prey and snakes are the only other
predators present.

Our study landscapes in the Glenelg region, Gunditjmara country, are primarily lowland forest (with an overstorey of *Eucalyptus obliqua* and *E. ovata*, a sparse midstorey and a fern-rich understorey) and heathy woodland (with an overstorey of *E. baxteri s.l.* and *E. willisii*, a sparse midstorey and a diverse understorey of narrow or ericoid-leaved shrubs). It has gently undulating terrain and frequently experiences prescribed burns and wildfires, creating a mosaic of fire histories and vegetation complexity. The area receives an average annual rainfall of 700 mm, with average minimum temperatures of 8.1°C and maximum of 17.6°C (Meteorology, 2021).

Our study landscapes in the Otway region were in the western section of the Otway
Ranges, Gadubanud country. Here, the vegetation is a mosaic of shrubby wet forest
and cool temperate rainforest, with an overstorey of tall eucalyptus species (primarily E. regnans), Acacia melanoxylon and Nothofagus cunninghamii. The midstorey is
dominated by tree ferns, Acacia verticillata, Pomaderris aspera and Olearia argophylla.
The understorey predominantly comprises a dense layer of ferns and graminoids but can

be relatively sparse in steep rainforest gullies. Maximum daily temperatures average 19.3°C in summer and 9.5°C in winter; annual rainfall averages 1955 mm (Meteorology, 2021). This region rarely experiences fire and is nearly ten times more rugged (based on the terrain ruggedness index (Riley et al., 1999) averaged within a 10 m radius of each camera-trap site).

# 2.2. Lethal fox control

Across broad sections of each region, government land managers conduct ongoing 127 fox control for biodiversity conservation. Manufactured poison baits (FoxOff, Animal 128 Control Technologies, Somerton) containing 3 mg of sodium mono-fluroacetate (1080) are buried at a depth of 10 cm at 1-km intervals along accessible forest tracks and 130 roads (Fig. 1). Different road densities across the two regions therefore result in variable poison-bait densities. In the Glenelg region, fox control in the impact landscapes has been 132 ongoing since October 2005, with baits checked and replaced fortnightly (Robley et al., 133 2014). In the Otway region, baiting commenced in the impact landscape in November 134 2017. Poison baits were replaced weekly for six weeks until December 2017, before 135 changing to monthly bait replacement until July 2018. The fox control program then 136 lapsed for approximately six months until December 2018 due to logistical constraints, 137 when monthly bait replacement recommenced for the duration of our study (Fig. S1).

# 39 2.3. Study design and camera-trapping

We designed experiments around the implementation of fox poison-baiting in each region. We simultaneously surveyed one impact and one non-impact landscape at a time using camera-traps. Each landscape pair was chosen based on similarity in landscape context, namely vegetation groups, with the aim of maintaining spatial independence with respect to predator range movements.

In the Glenelg region, we used a replicated control-impact design to test for differences 145 in areas that have been poison-baited for foxes for more than 13 years compared with 146 unbaited areas. We deployed a pair of camera-trapping grids in Cobboboonee National 147 Park (impact) and Annya State Forest (non-impact) in January – April 2018, then moved 148 these cameras to Mt Clay State Forest/Narrawong Flora Reserve (hereafter "Mt Clay"; 149 impact) and Hotspur State Forest (non-impact) in April – June 2018 (Fig. S3). Each 150 grid was separated by at least 8 km, a distance very unlikely to be traversed regularly 151 by these invasive predators (Hradsky et al., 2017). 152

In the Otway region, we undertook a BACIPS study to assess changes related to the 153 introduction of the fox control program. We deployed camera-trap grids in an impact 154 non-impact pair of landscapes in June – September from 2017 to 2019, in the Great 155 Otway National Park and Otway Forest Park (Fig. S1). Our first survey occurred 156 approximately three months before fox-baiting began. The second survey was conducted 157 six months post-commencement of fox-baiting, however poison bait replacement lapsed 158 at the beginning of the survey until nearly three months afterwards (Fig. S1). Foxbaiting recommenced six months prior to the start of the final survey (Fig. S1). The 160 impact and non-impact landscapes were at least 4.2 km apart, a distance unlikely to be 161 traversed by these invasive predators, although possible (Hradsky et al., 2017). In this 162 study, and a concurrent study which identified individual foxes through genetic sampling 163 (M. Le Pla, in review), we found no evidence of either species of predator moving between 164 these landscapes. 165

In each of the six survey landscapes, we deployed a grid of camera-traps (67 – 110 cameras; mean = 94), with sites spaced on average 448 m apart (range: 194 – 770 m; Fig. 1). At each site, we deployed a single Reconyx trail camera (Reconyx, Holmen, Wisconsin) with an infrared flash and temperature-in-motion detector on a tree, facing a lure of oil-absorbing cloth doused in tuna oil (Fig. S2). More information on the camera-trapping methods is provided in Section 1.2 of the Supporting Information. Overall, we

deployed 938 functional camera-traps, which operated for an average of 68 days (range: 12 – 93 days), totalling 62,415 trap nights (Table S1) across a total study duration of five months and three years in the Glenelg and Otways regions respectively (Fig. S1).

#### 2.4. Individual feral cat identification

We added a species metadata tag for each camera-trap image, compiled species record 176 tables and extracted feral cat photos for individual identification using the "camtrapR" 177 R package (Niedballa et al., 2016). We sorted the cats into five categories based on 178 their coat type: black, spotty tabby, swirly tabby, ginger and other (cats with multiple 179 colour blends or other distinctive coats; Fig. S3). We did not attempt to identify any black cats, even the few with white splotches on their underside, as these markings could 181 not always be seen. Within the other four coat categories, multiple observers identified 182 individual cats based on their unique coat patterns where possible. Detailed information 183 on this process is provided in Section 2 of the Supporting Information. 184

# 2.5. Spatial fox occupancy

Spatial mark-resight models require density covariate values for each grid cell density 186 is estimated across (or a single value for the entire session - each camera-trap grid deploy-187 ment in our case), and so we could not directly use the fox data from the camera-trap 188 sites as independent variables. We therefore used the presence-absence data for each camera-trap site to generate a spatially-interpolated layer of fox occupancy probability 190 using binomial generalised additive models (Wood, 2017). We did so using the "mgcv" R package (version 1.3.1; Wood, 2011). We modelled fox presences and absences (re-192 sponse variable) across space (explanatory variable) separately for each region, with a duchon spline spatial smooth as these provide better predictions at the edge of surveyed 194 space than other splines (Miller & Wood, 2014). In the Otway region, we included a 195 random intercept for each camera-trap site to account for repeat sampling and did not

share spatial information across the years (using a "by variable" smooth with year as a factor). Differences in camera-trap deployment lengths were accounted for using a model offset. We did not use occupancy-detection models because factors which impact fox detectability on camera-traps may also impact fox detectability to feral cats - which is more important than predictive performance in this context. We predicted GAM estimates into the respective spatial mark-resight habitat mask and trapfile (detailed below).

#### 203 2.6. Spatial mark-resight models of feral cat density

We used a spatial capture-recapture approach to estimate feral cat density (Borchers 204 & Efford, 2008). These models consider counts of detections and non-detections of individual animals at trap locations (accounting for trap-specific survey effort) to estimate 206 the location of each individual's activity centre. These models generally assume that individuals have approximately circular home ranges and spend the majority of time 208 in the centre of which ("activity centre"). The probability of observing an individual therefore decreases with distance from the activity centre. Two detectability parameters 210 govern this process: g0, the probability of detecting an individual per occasion in their 211 activity centre and sigma: a spatial scale parameter which is relative to the home range 212 size. Multiple candidate shapes for this decline in detectability with distance from the 213 activity centre ("detection function") can be modelled.

Spatial capture-recapture models have been extended to consider situations where
not all individuals in a population are identifiable (i.e. marked) (Chandler & Royle
2013). These spatial mark-resight models typically assume unmarked individuals to
be a random sample of the population, sharing the same detection process as marked
individuals, and so allow density to be estimated for the entire population. Spatial markresight models have four categories of sightings: (1) marked individuals - detections with
known identities identified to the individual level at least once each session, (2) marked
but unidentifiable individuals - detections of individuals with known identities, but for

which the individual could not be determined in a given session (we had no detections in this category), (3) unmarked individuals - unidentified detections which definitely do not belong to the first two categories (in our study, this category comprised black cats) and (4) mark status uncertain - detections in which individuals cannot be identified and it is not clear whether the individual is of the marked or unmarked category.

We used closed population, sighting-only, spatial mark-resight models to estimate 228 feral cat density using the maximum likelihood "secr" R package (Efford, 2021). Open 229 populations spatial mark-resight models have not yet been developed. Detections of the 230 "mark status uncertain" category cannot be handled in the "secr" R package, we therefore 231 added them to the unmarked detections rather than discard them (Moseby et al. 2020). 232 We condensed detection histories of each mark category to a binary presence-absense 233 record per each camera-trap for a 24-hour length duration ("occasion"), beginning at 234 midday. We treated each camera-trap grid deployment as a separate "session", created a 4000 metre buffer zone around each camera-trap location to estimate feral cat density 236 across, with a grid cell resolution of 200 metres. These habitat mask specifications were based on initial models and our knowledge of feral cats in these area - ensuring density 238 is estimated over a large enough area to encompass the activity centres of all feral cats exposed to our camera-traps, at a fine enough scale to minimise bias in density estimates. 240 We tested the half-normal and exponential detection functions in each region, carrying forward the function with the lowest Akaike's Information Criterion score adjusted for 242 small sample size (AICc) for all subsequent model fitting (Burnham & Anderson, 2004). 243

We expected that foxes would impact both detectability parameters for feral cats concurrently, and so, always specified g0 and sigma consistently (Efford & Mowat, 2014).



Figure 1: Locations of our six study landscapes in south-west Victoria, Australia. The grids of cameratraps are denoted by white dots, the locations of fox poison-bait stations are denoted by smaller black dots. The Glenelg region is to the west and Otway region to the east. Native vegetation is indicated by dark green, with hill shading. Map tiles by Stamen Design, under CC BY 3.0, map data by Open-StreetMap, under CC BY SA.

# **3. RESULTS**

# 4. DISCUSSION

# 5. CONCLUSIONS

# 6. ACKNOWLEDGEMENTS

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# 7. AUTHORS' CONTRIBUTIONS

M.W.R, B.H, J.H.P, B.A.W and A.R conceived the ideas and designed methodology;
M.W.R, J.H.P, M.LP, E.K.B and B.H collected the data; M.W.R analysed the data;

 $_{274}$  M.W.R led the writing of the manuscript. All authors contributed critically to the

 $_{\rm 275}$   $\,$  drafts and gave final approval for publication.

# 276 8. OPEN RESEARCH

Raw data and code are on Github link xx.

Data will be deposited on the Dryad Digital Repository after acceptance.

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