

- This is our current setup, and it works relatively well. The problem with it however is that it can only take data in from the VAO.
- We want more than just the VAO to determine how a model is rendered. For example light, fog, glows, particles, etc. Also moving and rotating the model cannot be done with just a VAO.
- Our solution is uniform variables.



## Uniform Variables:

- Variables that are in the shader code that can be set by our java code at any time.
- This means we can send data into either shader at any time to change how the models are rendered.
- we will calculate things such as light/brightness, fog density, etc. and then send that data into the shaders through uniform variables.

### to-Do:

- We need to know the location of our uniform variables when load our models so we can access them.
- The first use of our uniform variables will be to move and resize our models.
- The definitions for these uses are on the next page.



Translation:  $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$  Moving a model

from one position to another.  
- Shown with an  $(x, y, z)$  coordinate.

Rotation:  $(r_x, r_y, r_z)$  Rotating a model in a direction.

- Shown with rotation angles for each axis. (these are called euler rotations)

Scale:  $S$  Scaling a model

bigger or smaller. (changing its size)  
- Shown with a single scale value  $S$ . (One(1) is the normal model size)

• These three ways to alter an object are known together as an object's Transformation.

- Each object in our code will have its own transformation.

- Transformations are stored as a  $4 \times 4$  Matrix. (A transformation matrix)



- Transformation Matrices are actually a very mathematically involved subject. So I will not go into any details. All we ~~we~~ need to know how to do is turn our three factors (translation, scale, and rotation) into a single transformation matrix.

Entity: An entity is an object containing a model, a position, a rotation, and a scale. This way we can have multiple models at different sizes and positions in our screen.

- If we want to render 100 trees, instead of editing our models 100 times, causing mass lag, we can use instead an entity's values to directly change the model INSIDE our ~~vector~~ shader code. This way we can change the model without changing its VAO.
- 1 VAO, 100 trees. Because of uniform variables.



- The way our transformation Matrix can alter our vertex coordinates inside our shader code is simply by multiplying them!

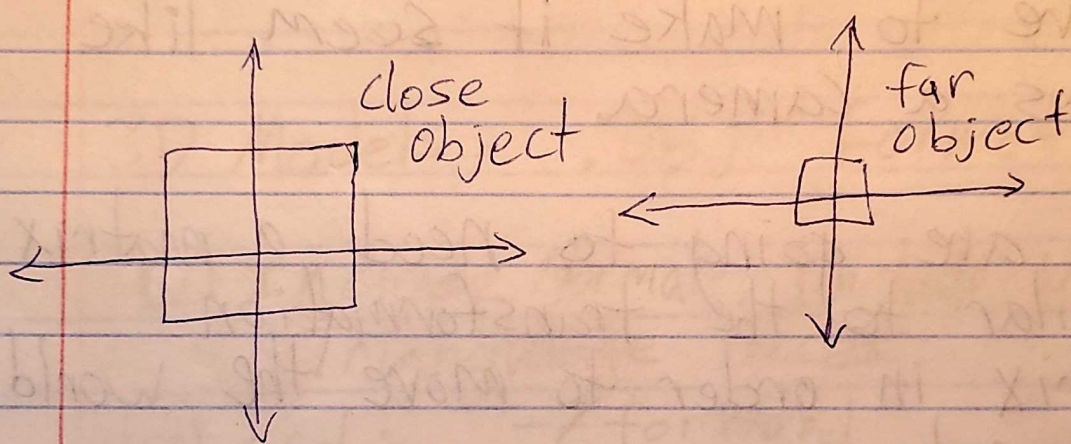
$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} x \\ y \\ z \\ 1.0 \end{bmatrix} = \begin{bmatrix} x_t \\ y_t \\ z_t \\ w_t \end{bmatrix}$$

transformation matrix      vertex matrix      transformed vertex

- The vertex Shader Code does this for every vertex in our model.

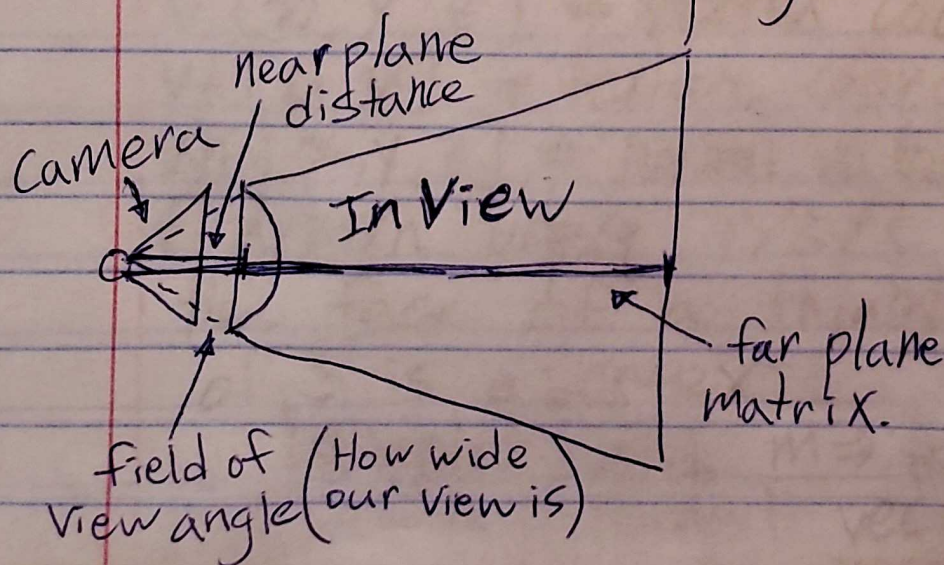


- When you look at the screen, you can only see the  $x$  and  $y$  because the  $z$  goes towards you. In order to make our models 3D we can scale them up and down to make them appear to have dimension.



- We can use a matrix similar to the transformation matrix that scales the model based on  $z$  values

- This is called a projection Matrix



- This matrix makes our scene look like the diagram. It copies real life.



- A projection Matrix uses a lot of matrix math to achieve a realistic view of our scene.
- In OpenGL, there is no actual camera that moves around. Instead all the world's objects move to make it seem like there's a camera.
- We are going to need a matrix similar to the transformation matrix in order to move the world around.

View Matrix: The transformation matrix used to move all objects.

- It will move when ~~at~~ our camera is moved. (once every frame)



Camera: this is our view of the world. It has a position, yaw, pitch, and roll.

pitch =

yaw =

roll =

3D Models: .Obj format (wavefront)

☒ Include Normals, Include UVs, and Triangulate faces.

Forward: -Z forward

Up: y up

\* All seams must be "EdgeSplit"  
\* Entire model use "Smooth" shading

• put them in the res folder.

.Obj files:

$V[x, y, z] \Rightarrow$  vertex coordinates

$VT[u, v] \Rightarrow$  texture coordinates.

$VN[x, y, z] \Rightarrow$  normal vectors

$f\ l/m/n\ o/p/q\ r/s/t \Rightarrow f$  represents the face of a triangle and each block of 3 is a vertex

$l \Rightarrow$  vertex coord.  $m \Rightarrow$  texture coord.

$n \Rightarrow$  normal vector.