

### Binary Search Tree Issues

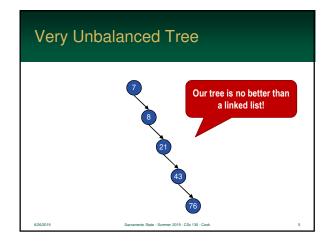
- Binary Search Trees have the ability to find data in O(log n)
- This is incredibly more efficient than a linear search of O(n)
- However, internal nodes never change and have a



huge impact on the tree

### Binary Search Tree Issues

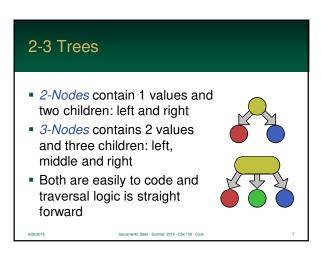
- There are cases where the tree is unbalanced - one particular path contains all the data
- In this case, the time complexity slowly deteriorates to O(n)

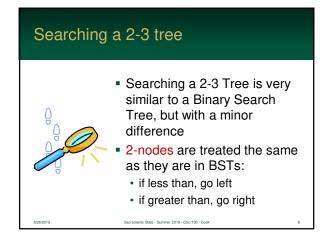


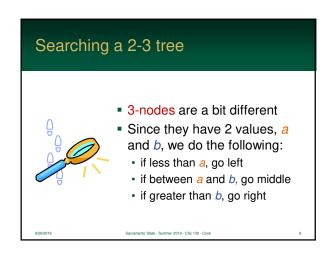
### 2-3 Trees

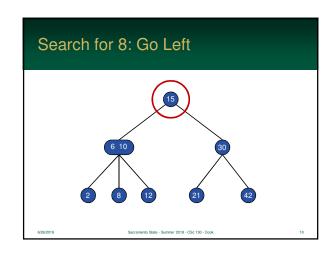
- The 2-3 Tree is a special type of BST invented by John Hopcroft in 1970
- It automatically maintains balance as it grows!
- It does this by using a clever variation of the node that can contain multiple values

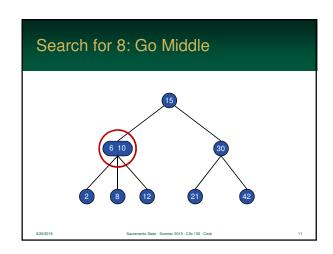


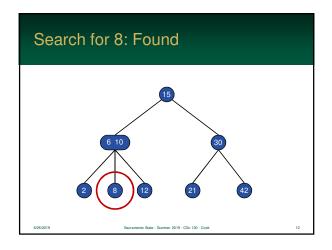


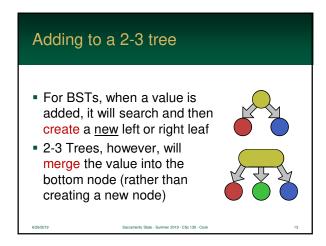


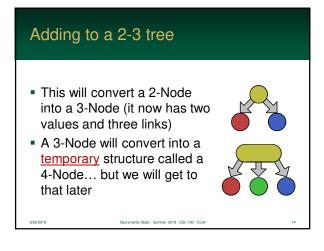


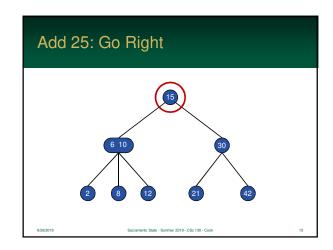


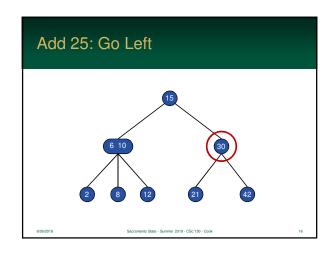


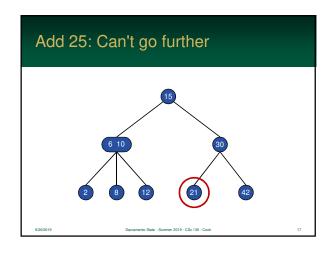


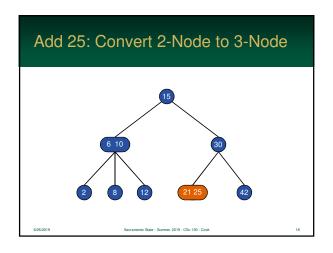












### Adding to a 2-3 tree

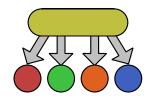


- Notice, when the value was added to the 2-3 Tree, that the height of the tree did not change
- Binary Search Tree would have added another child node and the height would have changed

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### The 4-Node

- So, what happens when we add a value to a 3-node?
- It becomes a 4-Node, which has 3 values and 4 children
- This is temporary, it will be converted



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### The 4-Node

- When a 4-Node is created, the 2-3 Tree algorithm will split it into other nodes
- Given that 4 is a nice even number, we can split equally
- ... and balanced!

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### The Types of Splits

- There are a total of six different splits that can occur in a 2-3 tree
- In each split, the middle value ascends up to the parent node



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### The Types of Splits

- This will change a parent from a 2-Node to 3-Node
- ... or from 3-Node to 4-Node
  - then, the parent will split
  - it continues to bubble up possibly all the way to the root
  - this is O(log n)

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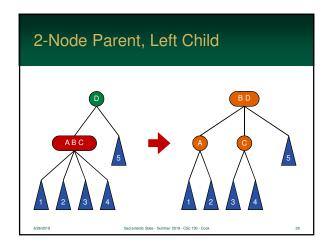
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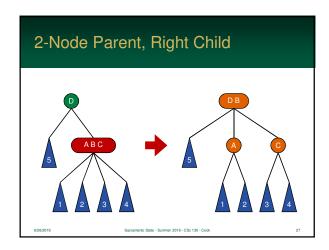


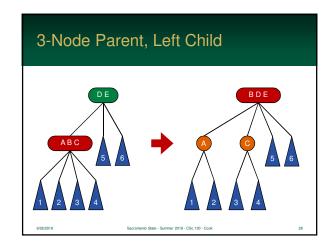
### The Six Splits

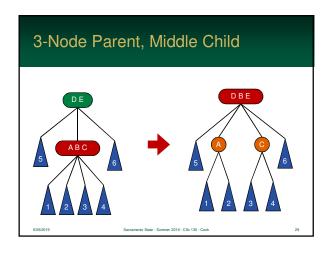
- Parent is 2-Node:
  - node is the left child of the parent (1)
  - node is the right child of the parent (2)
- Parent is 3-Node:
  - node is the left child of the parent (3)
  - node is the middle child of the parent (4)
  - node is the right child of the parent (5)
- Node is the root (6)

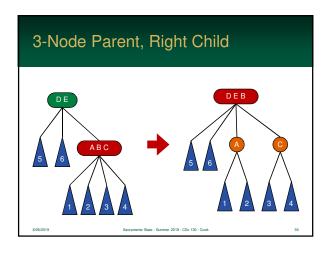
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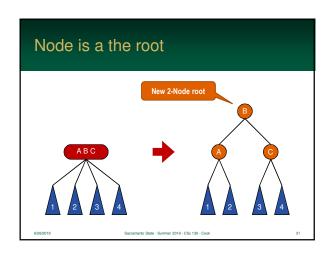


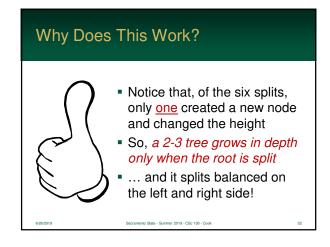


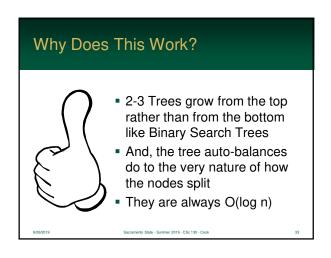


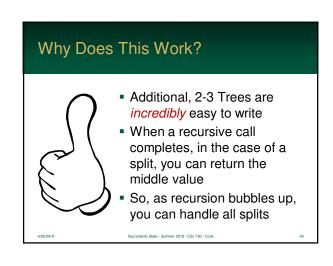


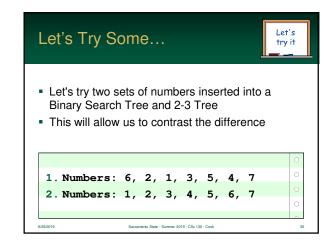


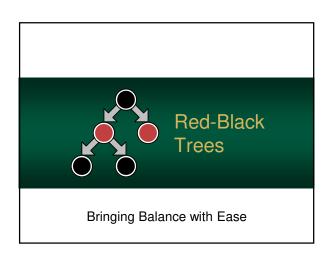












### **Red-Black Trees**

- 2-3 Trees are re-mark-a-ble!
- However, the nodes are a tad complex
- Can we implement the same concept by using the Binary Search Tree's basic 2-Node?





The answer is. yes

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### **Red-Black Trees**

- The Red-Black Tree is ADT that implements a 2-3 tree using strictly 2-nodes
- However, this does add some complexity to our balancing logic... but we will get the same results



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### Red-Black Trees

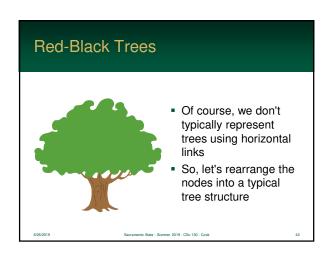


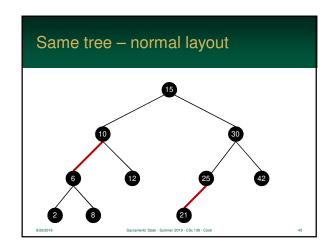
- So, let's look a 2-3 tree and make some modifications
- First, we will convert all of our 3-nodes into a chain of two 2-Nodes
- So we know that they belong together, let's make the branch as red

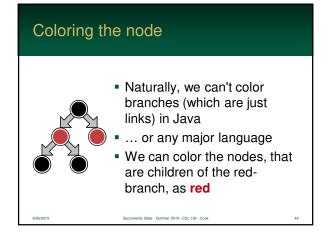
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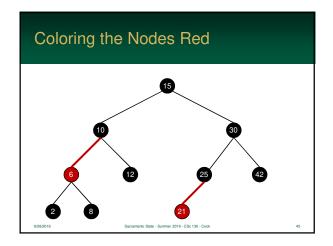
# Basic 2-3 Tree

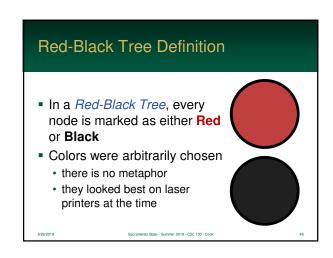
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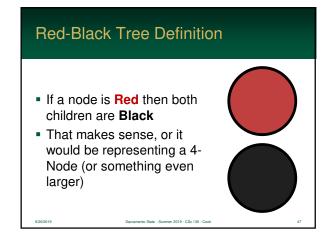


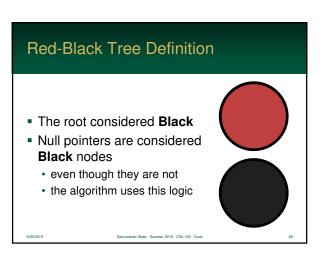










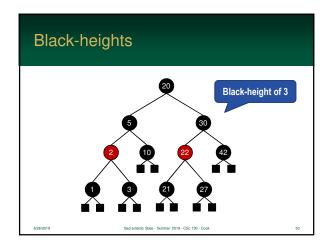


### The Black-Height

- Black-height of a node is the number of Black nodes on any path to a null
- We don't count red nodes since they are represent part of a 3-Node
- We also don't count the root
- Every path from any node to a null contains the same number of Black nodes

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### Balancing the tree

- Balancing the Red-Black tree is done in the same manner as a 2-3 tree
- However, because we use 2-Nodes, we use a series of rotations to get the same effect as splits



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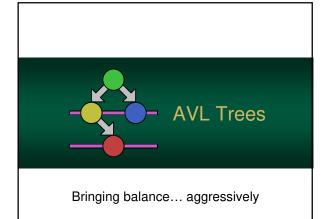
### Balancing the tree

- They are tad more complicated
- Unfortunately, we don't have time to cover them this Summer, but they are cool



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### **AVL Trees**

- AVL Tree is a heightbalanced binary search tree invented by Adelson-Velskii and Landis
- The ADT keeps track of the height of each subtree and reorders the data as needed



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### **AVL Trees**

- AVL Trees <u>aggressively</u> balance the nodes – which ensures the O(log n) search
- So, searching is optimized
- However, these steps require considerable work and hurts efficiency



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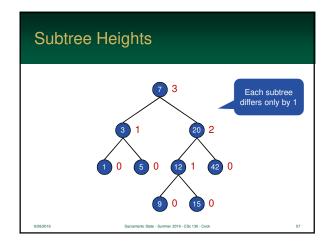
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### **AVL Trees**

- Each subtree has a "height" property
  - it is the maximum between the height of the left and right subtree + 1
  - · leafs have a height of zero
- As long as the right and left branches only differ by 1, the AVL Tree is sufficiently balanced
- If not, they are balanced by "rotating"

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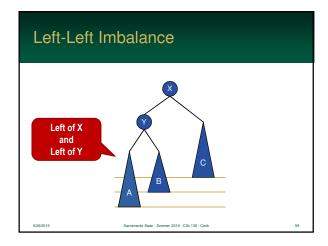


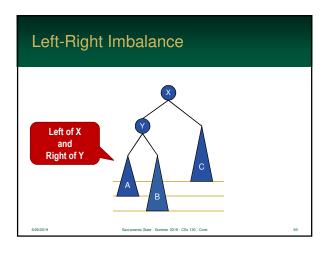
### **Inserting Nodes**

- Unless values are inserted in a very specific order, the tree will, naturally, become unbalanced
- Imbalance falls into two distinct categories
  - 1. Left-Left (or Right-Right) imbalance
  - 2. Left-Right (or Right-Left) imbalance

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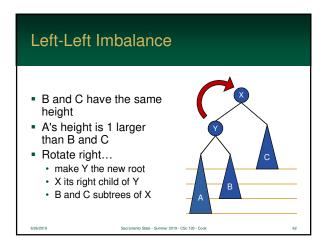




- Only nodes on the path from insertion point to root node have possibly changed in height
- So after the Insert...
  - start balancing starting at the lowest node
  - recurse back up to the root rotating as needed

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## B and C have the same height A's height is 1 larger than B and C Rotate right... make Y the new root X its right child of Y B and C subtrees of X

