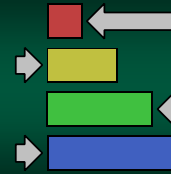




## $O(n \log n)$ Sorting

Section 2.2 – 2.3

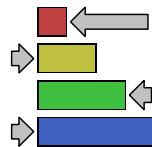


## Merging Arrays

Quite easy... and quite common

## Merging Arrays

- It is a common task in Computer Science to combine two different arrays into one
- If both arrays are unsorted...
  - the task is fairly simple  $O(n)$
  - just add one onto the end of the other



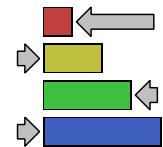
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3

## Merging Arrays

- However, often two sorted arrays are combined
- ...and the resulting array must be sorted



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4

## Merging Arrays

- The algorithm for merging two sorted arrays is very simple
- The resulting time complexity is  $O(n)$
- However, it requires auxiliary storage of  $O(n)$

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5

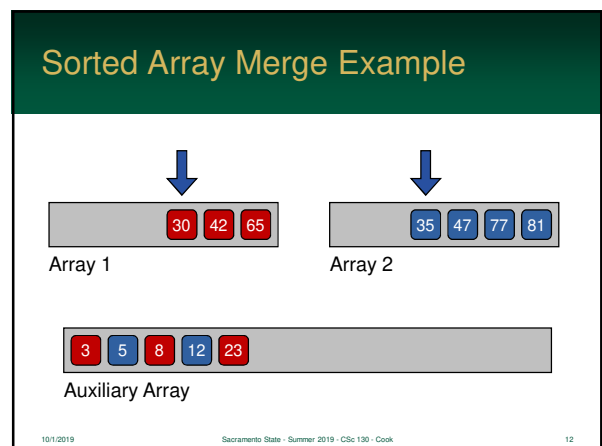
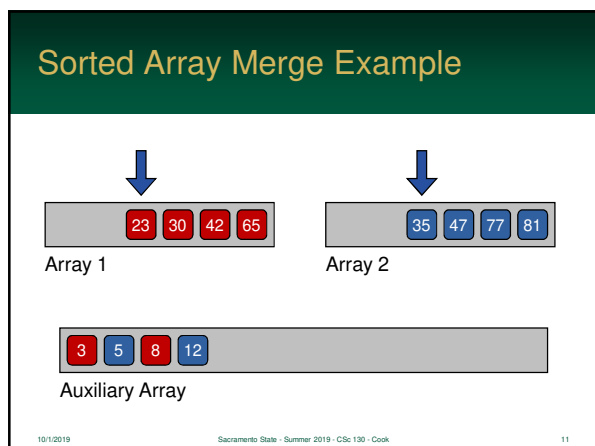
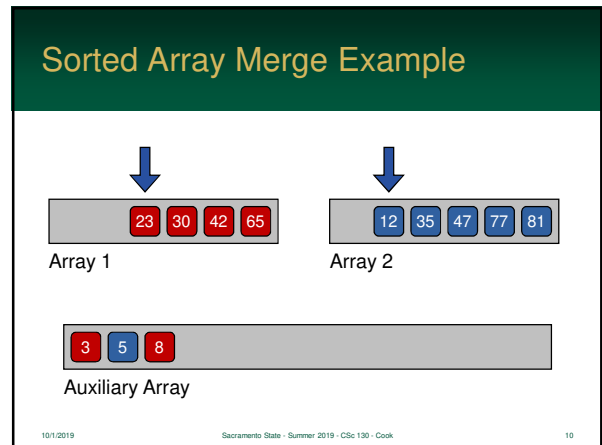
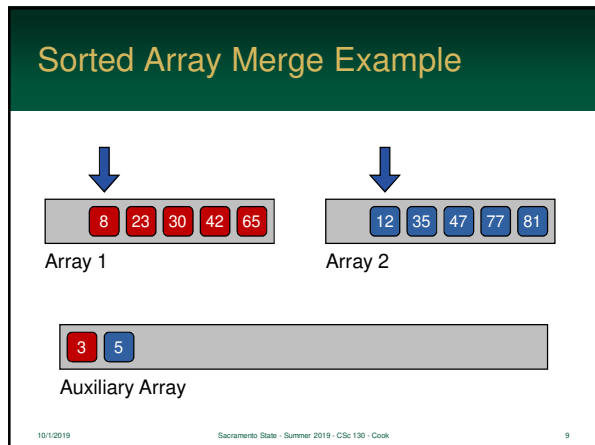
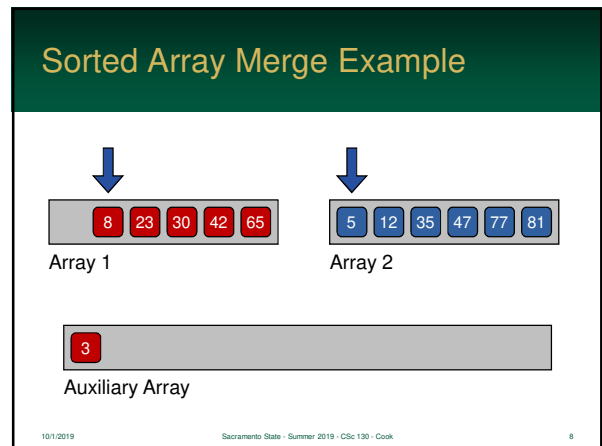
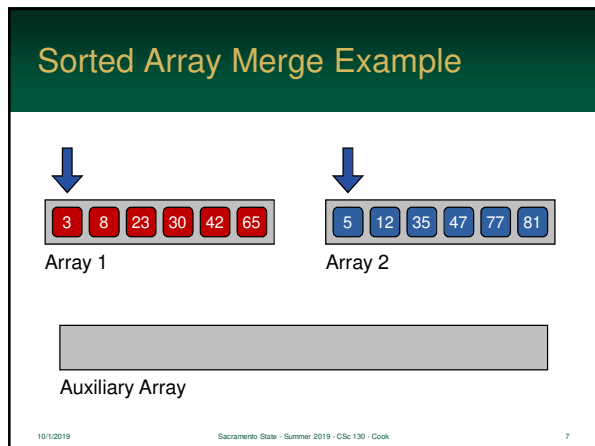
## Merge Algorithm

- Keep two counters – one for each array
- Loop while both arrays have data
  - take the smaller element and put it in the auxiliary array
  - increment the array's counter (which just lost an element)
- After the loop
  - one array will still have elements
  - append them to the auxiliary array

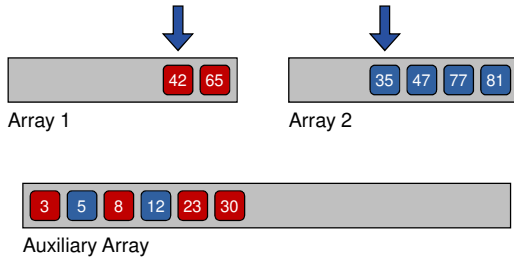
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6



## Sorted Array Merge Example

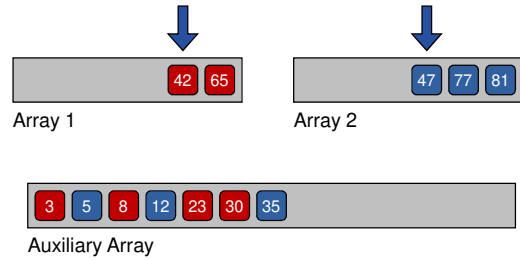


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13

## Sorted Array Merge Example

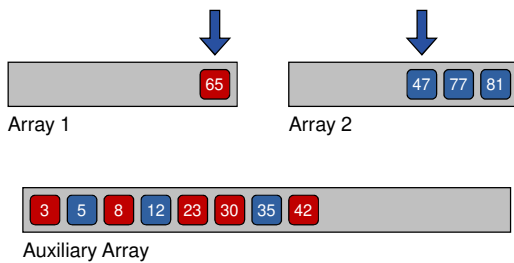


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14

## Sorted Array Merge Example

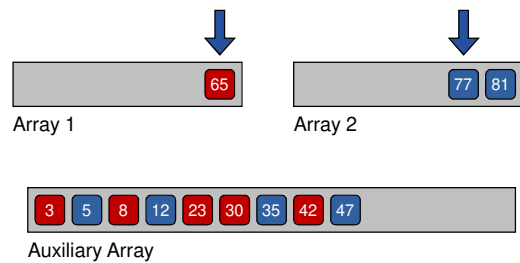


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15

## Sorted Array Merge Example

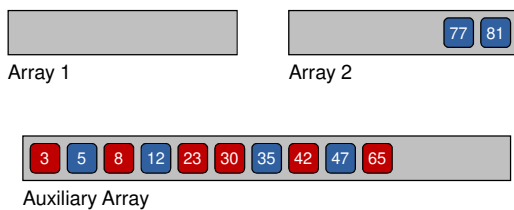


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16

## Dump the Rest of the Array

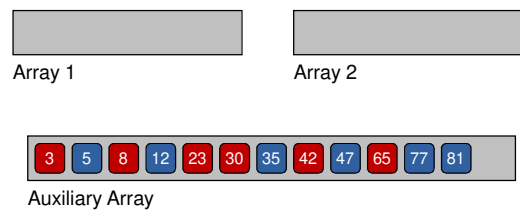


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17

## Dump the Rest of the Array

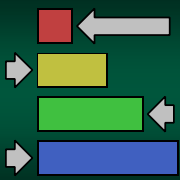


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18

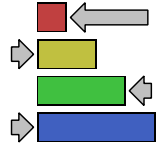
## Merge Sort



Divide and conquer!

## Merge Sort

- *Merge Sort* is a divide-and-conquer approach to sorting arrays
- It is based on the idea of cutting the array into smaller and smaller sublists until sorting them is arbitrary
- This approach ultimately results in  $O(n \log n)$



20

## Merge Sort

- Because Merge-Sort defines a dividing the list into a list into smaller instances of itself, it naturally is solved using recursion
- Each recursive step cuts the lists into 2 until the list is either 1 element – which is, well, obviously sorted

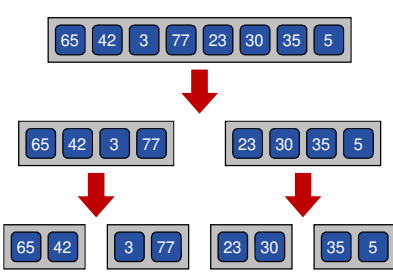
21

## Merge Sort

- As the recursion bubbles up, each sub list is merged using the algorithm we just discussed
- Since an auxiliary array is required for the merge process, Merge-Sort, while fast, has  $O(n)$  auxiliary storage requirements

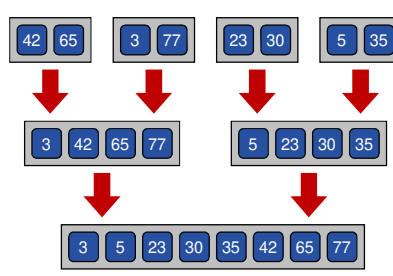
22

## Merge Sort Example: Recurse down



23

## Merge Sort Example: Merge Up



24

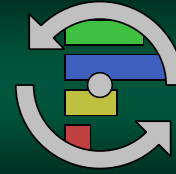
## Merge Sort Summary

Merge Sort	
Time Average	$O(n \log n)$
Time Best	$O(n \log n)$
Time Worst	$O(n \log n)$
Auxiliary space	$O(n)$
Stable	Yes – Equal element order preserved
Online?	Yes – New data → new sublist

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25

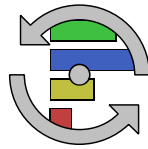


## Quick Sort

Oh, I am getting dizzy....

## Quick Sort

- *Quick-Sort* is a divide-and-conquer algorithm that rotates values around a *pivot*
- Invented by C. A. R. Hoare in 1959
- Even faster than both Merge Sort and Heap Sort
- ... but does a weaknesses



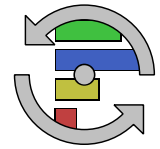
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27

## How it Works

- Like Merge-Sort, the array is broken down into smaller and smaller sub-lists
- However, before recursion
  - an value  $p$  is chosen in the sub-list as the *pivot* value
  - smaller items are moved before it
  - larger items are moved after it



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28

## Choosing a Pivot

- The pivot can be any element in the sub-list – we just need one real value to compare
- This value is used to *partition* the values
- Different versions use different pivots
  - first item in the sub-list
  - end item in the sub-list
  - the midpoint of the sub-list
  - random value in the sub-list

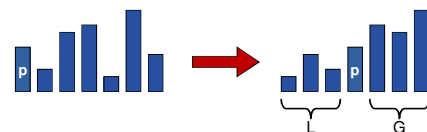
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29

## Partitioning the Values

- After the pivot is selected, all elements are moved
- Two loops move through the elements swapping elements less than/greater than the pivot



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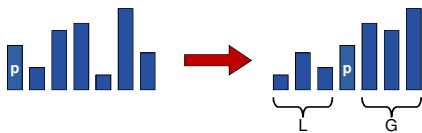
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30

## Partitioning the Values

The result is...

- sub-list **L** that contains items less than P and
- sub-list **G** that contains items greater than P
- The sub-lists are stored in the original data array



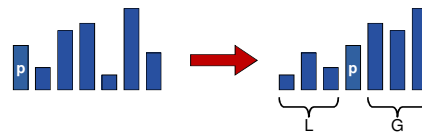
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31

## Partitioning the Values

- **Note:** neither L or G is sorted yet
- These will be called **recursively** by Quick-Sort
- Moving the elements, in-place, can look a tad ugly code-wise, but the logic is straight forward



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32

## Partition Algorithm

- The algorithm maintains two pointers
  - first moves left to right and keeps track of the values that are **too big**
  - second moves right to left and keeps track of the values that are **too little**
- Each moves independently

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33

## Partition Algorithm

- First move the **Too Big** pointer until a value is found that is bigger than the pivot
- Then move the **Too Little** pointer until a value is found that is smaller than Pivot
- Then, these values are swapped
- When the two pointers collide, we are done

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34

## Example Partition

- In this example, we pivot at the **start** of the array
- **Any** value can be used...
  - but it will have to be swapped to the start before the algorithm runs
  - this "saves" the pivot for later



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35

## Quick Sort Algorithm

```
while (tooBig < tooSmall)
{
    while (array[tooBig] <= array[pivot])
    {
        tooBig++;
    }

    while (array[tooSmall] > array[pivot])
    {
        tooSmall--;
    }

    if (tooBig < tooSmall)
    {
        //swap array[tooBig] and array[tooSmall]
    }

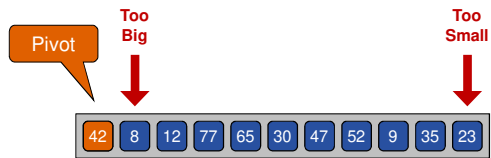
    //swap array[tooSmall] and array[pivot]
    //Recurse QuickSort on both L and G
}
```

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36

## Example: Pivot is First

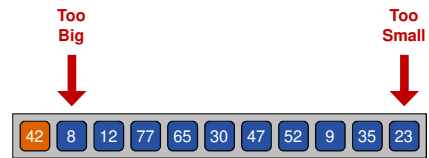


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37

## Move Too Big

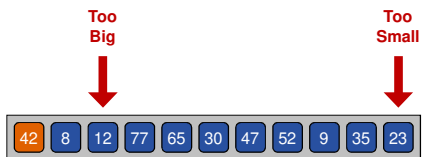


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38

## Move Too Big



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39

## Move Too Big: Found!

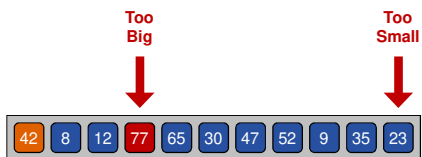


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40

## Now, Move Too Small



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41

## Move Too Small: Found!



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42

## Swap these two

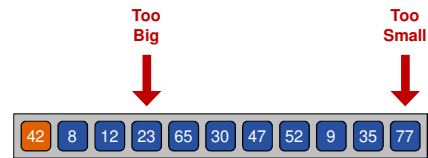


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43

## Keep going... Move Too Big

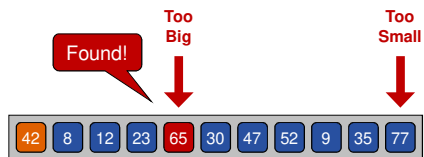


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44

## Move Too Big: Found

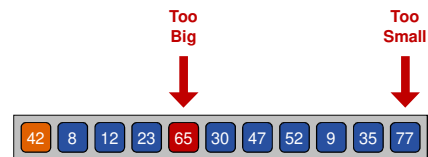


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45

## Move Too Small

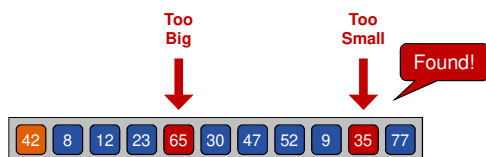


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46

## Move Too Small: Found

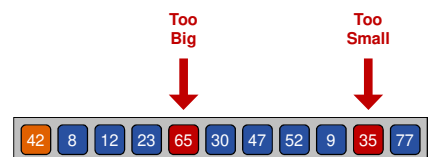


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47

## Swap



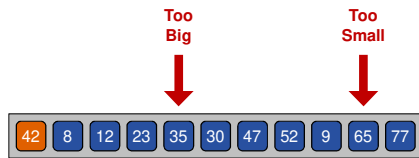
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48



## Still going... Move Too Big

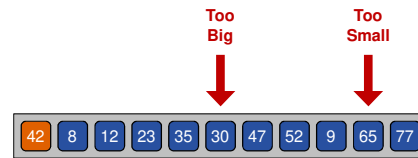


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49

## Move Too Big

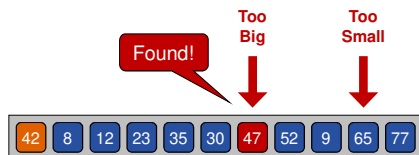


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50

## Move Too Big: Found

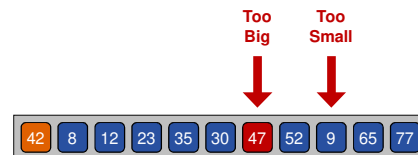


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51

## Move Too Small

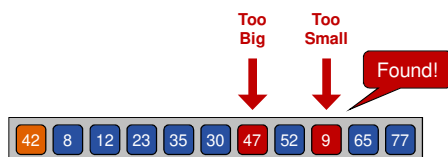


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52

## Move Too Small: Found

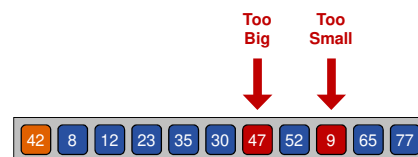


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53

## Swap

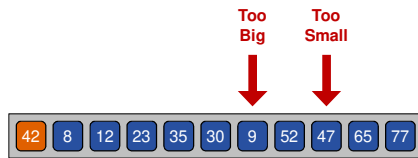


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54

## And again... Move Too Big

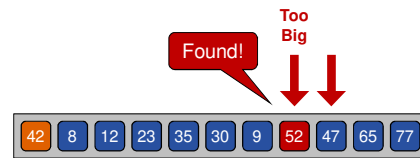


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55

## Move Too Big: Found

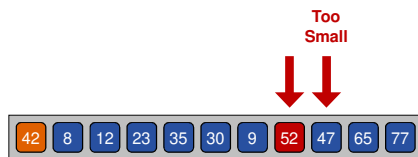


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56

## Move Too Small

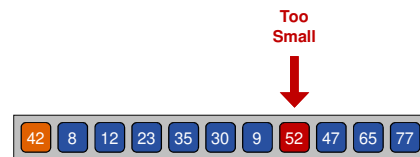


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57

## Move Too Small

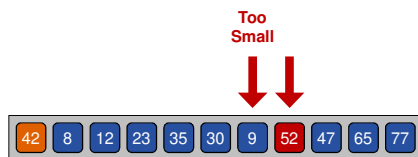


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58

## Pointers Passed Each Other!

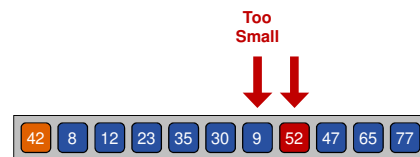


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59

## Finally, Swap Pivot and Too Small



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60

## Done (with this pass)



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61

## Recursion Time!

- Notice: all the items **before** the pivot are **smaller** and all the items **after** are a **larger**
- Now, we can recurse both sides
- The end result is a sorted array

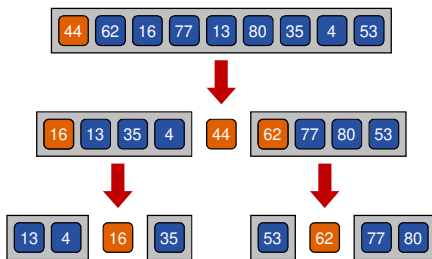


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62

## Quick Sort Example

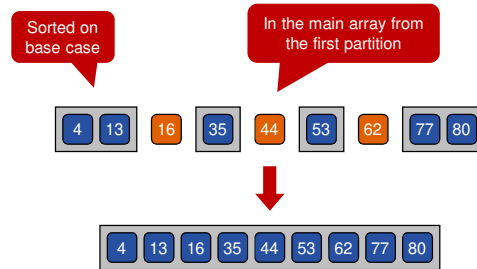


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63

## Quick Sort Example



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64

## Quick Sort: Worst Case



- Assume we get array that is already sorted
- This can cause huge problems!
- Shockingly, the efficiency of this sort can degenerate if we are not careful

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65

## Quick Sort: Worst Case

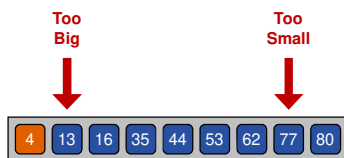
- If the first item is the pivot
  - a reverse sorted list will cause both the pointers will pass simply pass each other
  - one sublist will be empty, the second will contains **ALL** the elements – 1
- If the last item is the pivot
  - a sorted array will have the same effect

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66

## Quick Sort: Worst Case

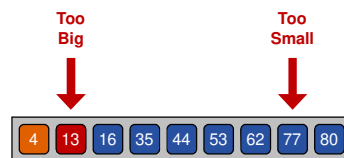


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67

## Quick Sort: Worst Case

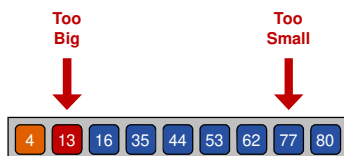


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68

## Quick Sort: Worst Case

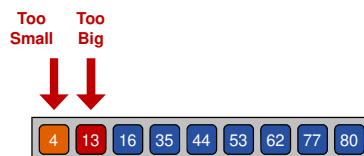


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69

## Quick Sort: Worst Case

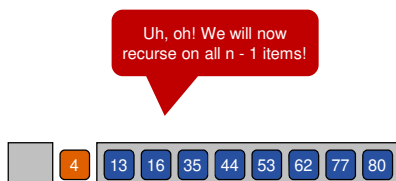


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70

## Quick Sort: Worst Case



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71

## Quick Sort Analysis

- So, in the worst case, Quick Sort is  $O(n^2)$
- ... and, given all the work it has to do with the pointers, it gets beat by Bubble Sort



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72

## How Can We Avoid This?

- If you don't know if the array is randomized, *manually randomize the values*
- $O(n)$  – run  $i$  from first to last element and swap  $\text{array}[i]$  and  $\text{array}[\text{random}]$



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73

## Quick Sort Summary

Quick Sort	
Time Average	$O(n \log n)$
Time Best	$O(n \log n)$
Time Worst	$O(n^2)$
Auxiliary space	$O(1)$
Stable	No – Equal element order not preserved
Online?	No

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74