



### Getting the Shortest Path

- The Kruskal and Prim Algorithms can efficiently create minimum spanning trees
- And these are the "best" trees that span all nodes



2019

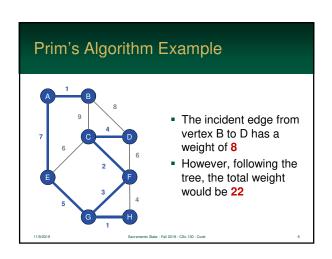
### Getting the Shortest Path

- However, it doesn't necessarily produce the minimum path for each vertex to reach other vertices
- In other words, the shortest path for each might not be reflected in the MST



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## Prim's Algorithm Example This is the spanning tree created by both the Prim and Kruskal Algorithms Let's say we want to get the minimal path from B to D



### Getting the Shortest Path

- We need to compute the best path for <u>each</u> node
- This is known as the distance
- Given 2 vertices u and v ...
  - find a path with the "best" total weight between u and v
  - e.g. the minimum total is the sum of all the edges in the path



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### Some Real World Examples

- Internet packet routing
  - fastest route faster downloads
  - · load distribution
- Driving directions
  - · shortest route in miles
  - fastest route given traffic and speed limit data



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### **Shortest Path Attributes**

- A sub-path of a shortest path
  - · ... is itself a shortest path
  - so, any subset of a optimal solution is optimal
- There is a tree of shortest paths
  - there are multiple solutions from the start vertex to all the other vertices
  - might be multiple equally-optimal solutions

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### Edsger Dijkstra

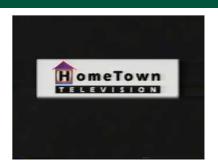
- The algorithm used today to find the optimal path was written by Edsger Dijkstra
- In fact, his algorithm runs the Internet – a self healing, load distributioning network



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### We're riding on the Internet!



### Dijkstra's Algorithm

- Dijkstra's Shortest Path First Algorithm computes the distances of all the vertices from a given start vertex s
- Works on directed and undirected graphs
- However
  - all edges must have nonnegative weight
  - · the graph is connected

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### Dijkstra's Algorithm

- Dijkstra's Algorithm is greedy
  - <u>always</u> takes the <u>best</u> immediate or local solution while finding an answer
  - they find optimal solutions for some optimization problems very efficiently
  - · but may find less-than-optimal solutions
- Greedy algorithms require extra analyzation to determine if they work – Dijkstra's does

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# Each vertex has its own "distance" table The table contains the best weight to each other vertex as well as the best path

## Dijkstra's Algorithm Logic

- 1. Initialize a distance table
  - table represents the best distance (weight) to get to the specific vertices
  - set all to infinity (worst possible)
  - it will be updated as we see more vertices
- 2. Recurse until are settled (visited)
  - · depth-first search the graph
  - · advance on smallest weighted edge

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### Dijkstra's Algorithm Logic

- Given table D, vertex v, edge weight w with target t: D(t) = D(v) + w
- For example:
  - if it takes 12 to get to v
  - ... and an edge of 6 goes to t
  - ... then it will take 12 + 6 total to get to t

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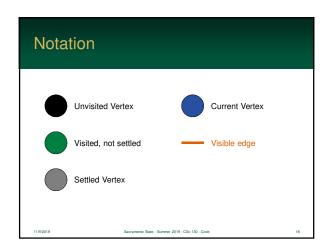
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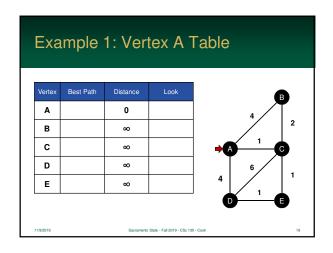
### Dijkstra's Algorithm Logic

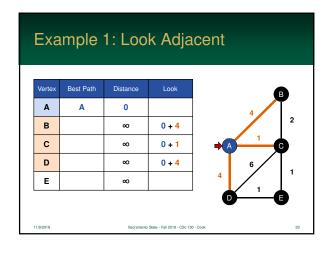
- For each vertex v
  - compute the total distance to get each vertex t that v is adjacent to (v edges point to t)
  - if the value is better than the current table value then update
  - don't update t if will cause a cycle i.e. t is already in the path

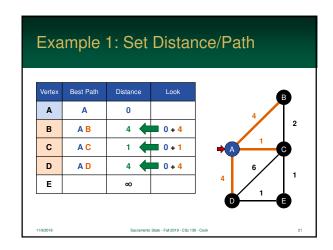
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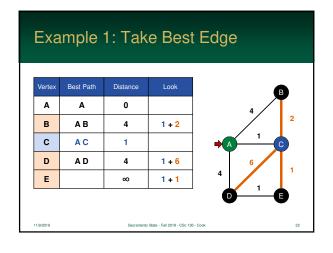
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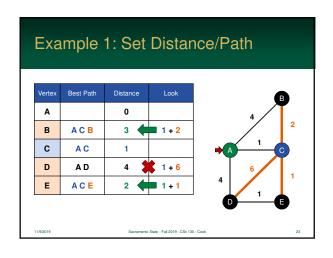


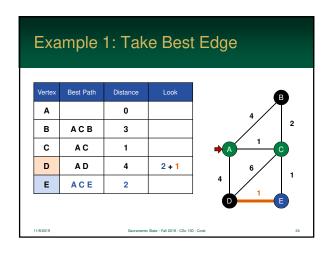


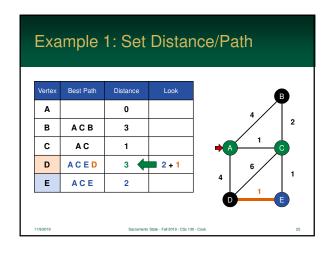


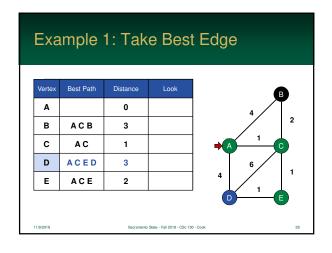


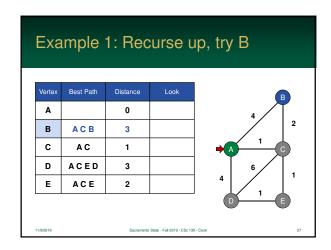


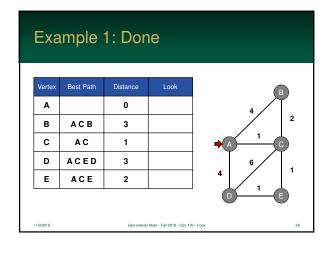


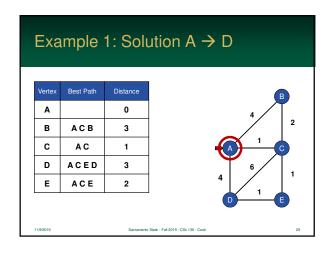


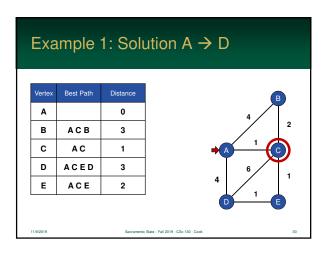


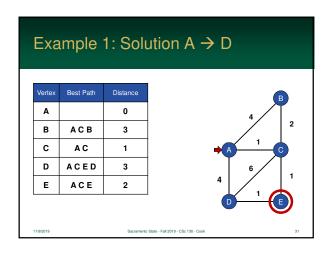


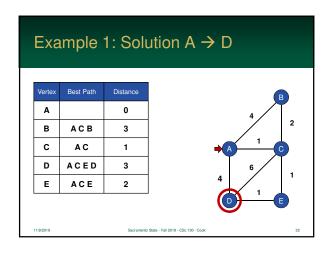


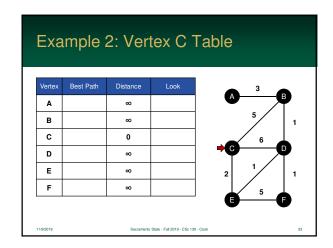


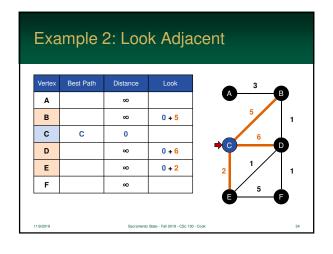


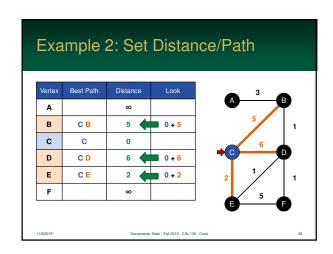


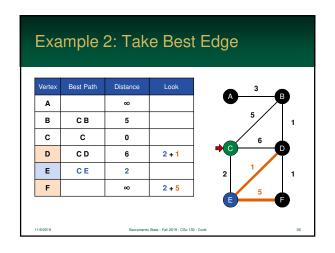


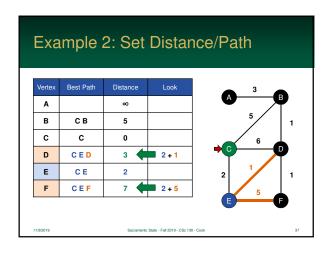


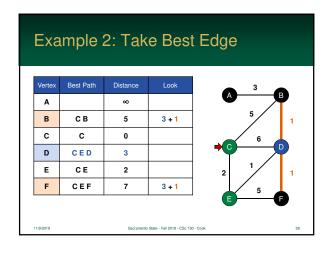


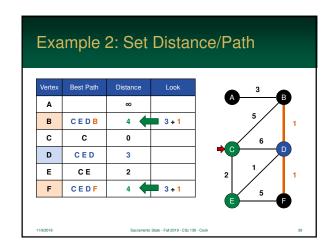


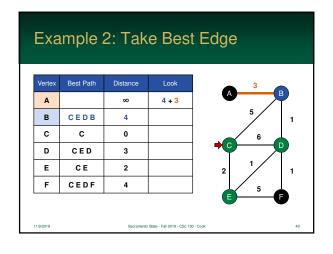


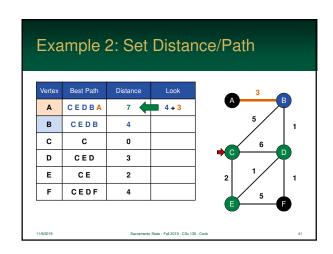


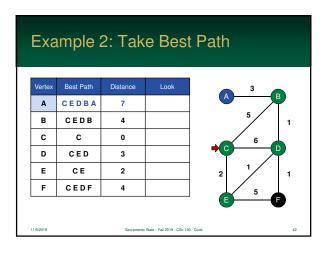


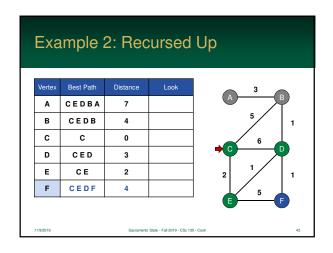


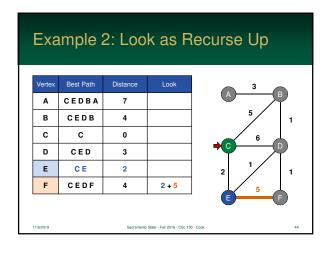


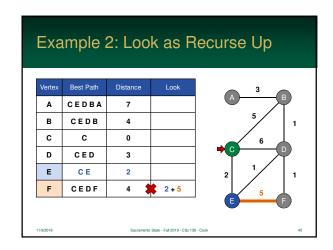


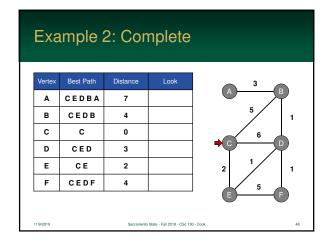


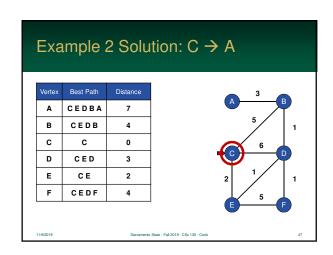


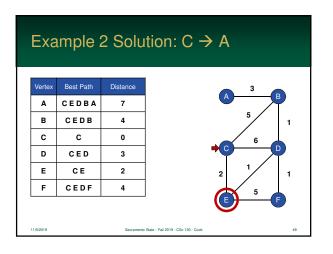


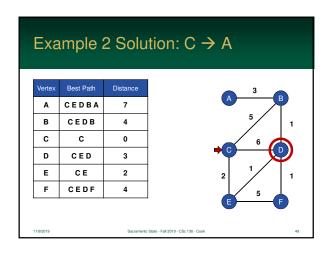


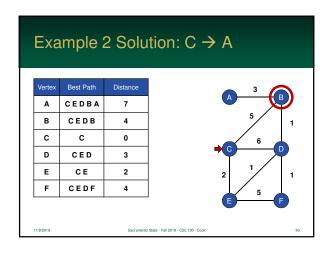


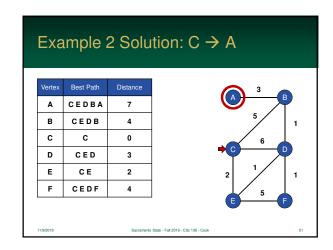


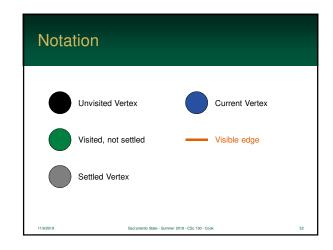


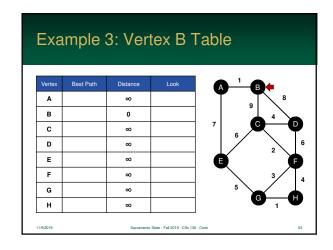


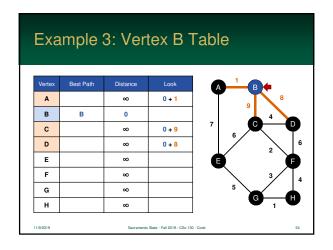


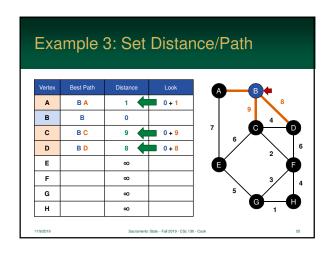


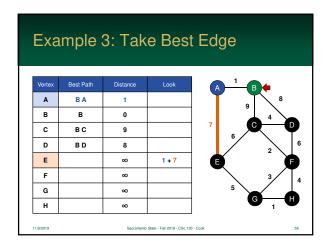


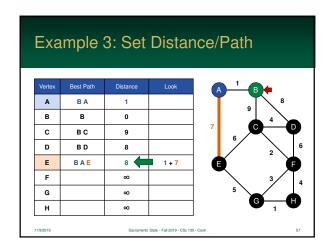


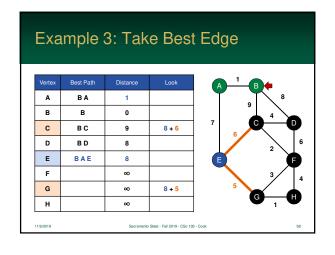


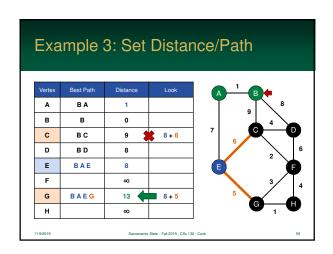


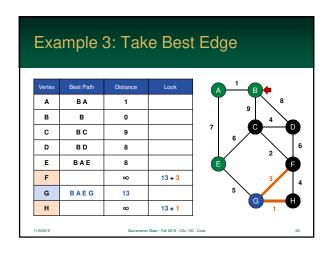


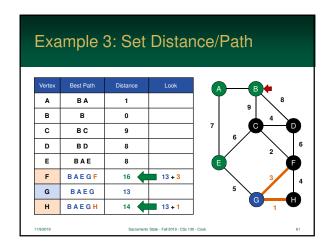


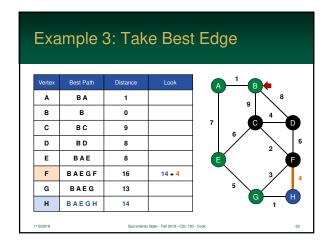


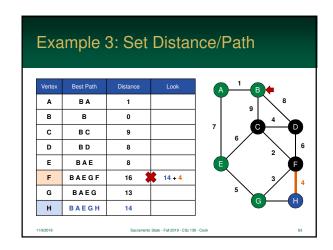


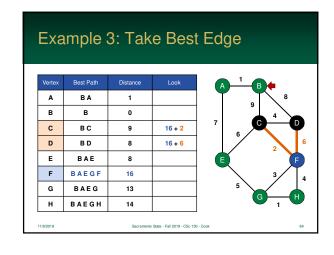


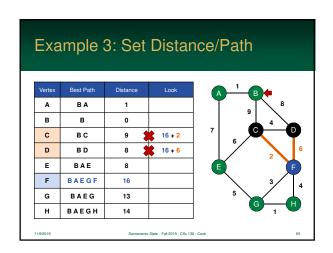


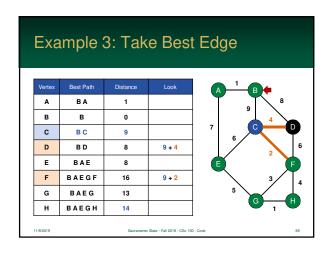


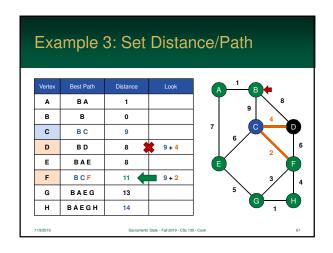


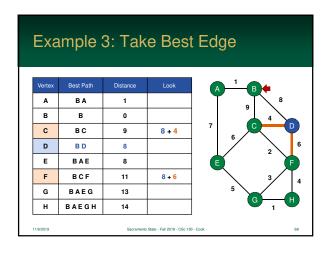


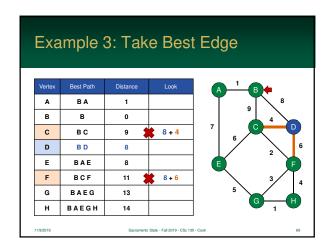


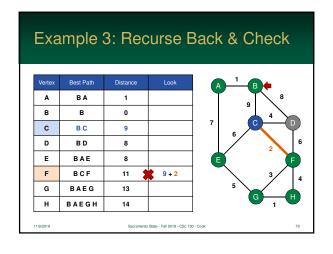


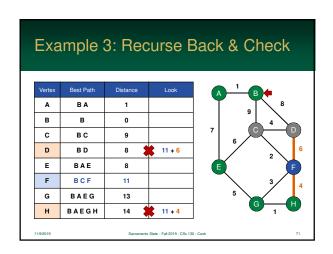


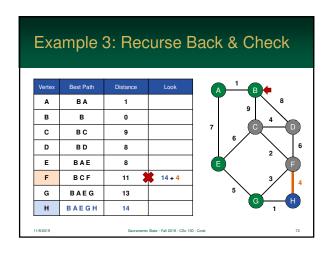


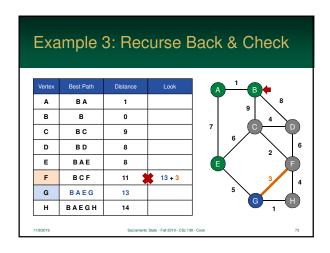


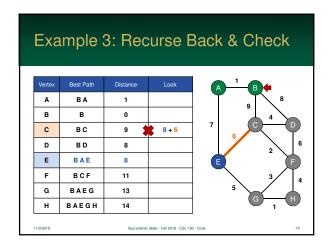


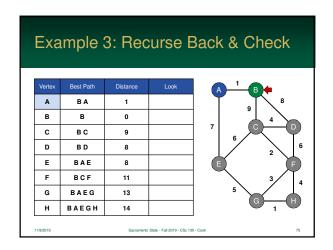


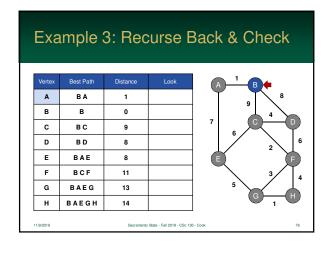


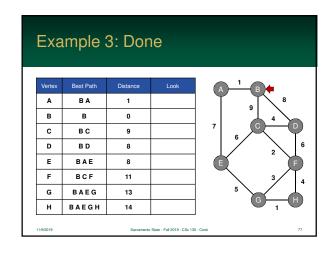




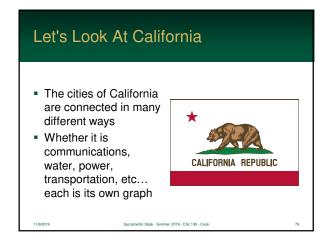








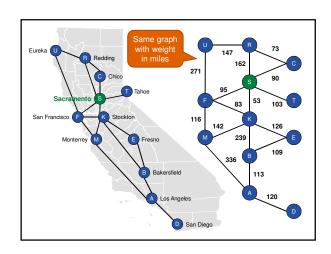


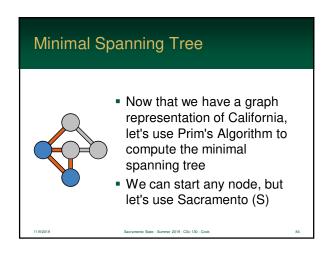


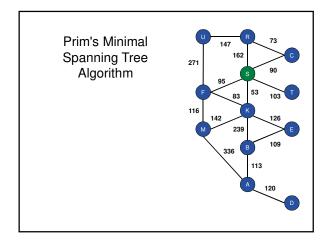


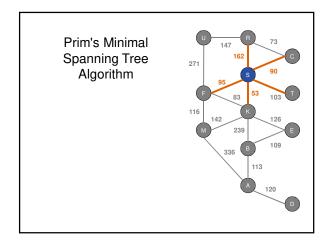


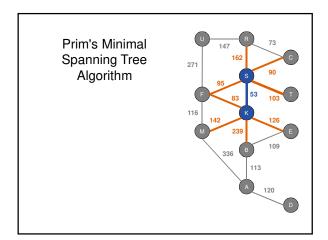


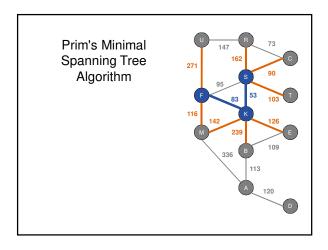


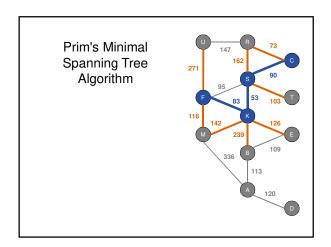


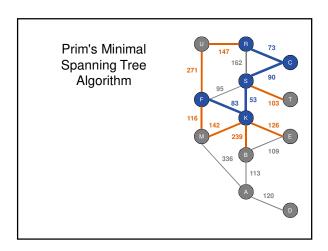


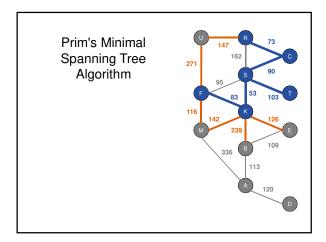


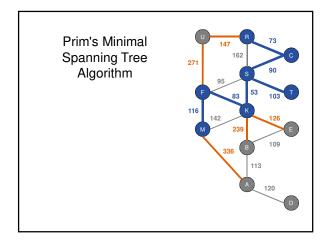


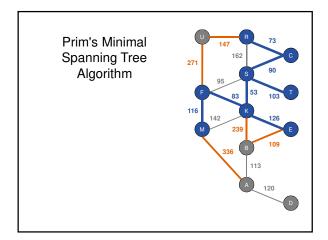


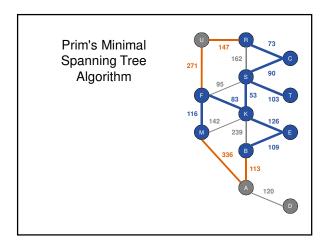


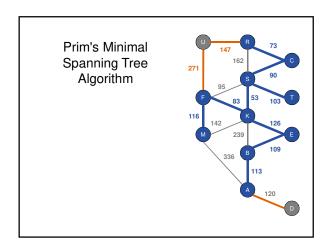


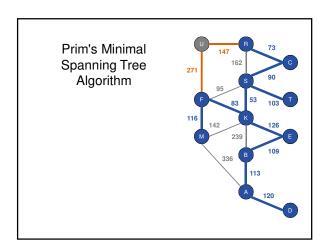


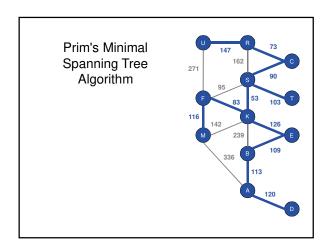


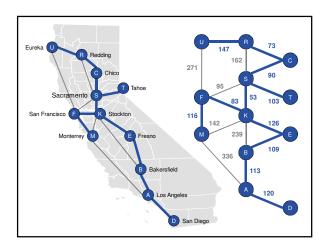


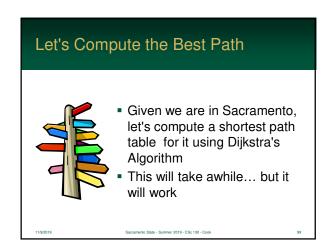


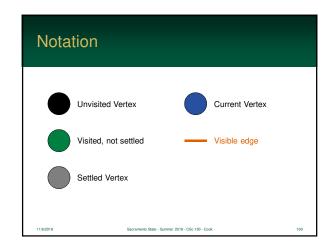


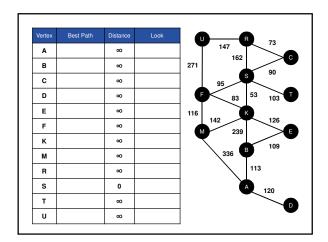


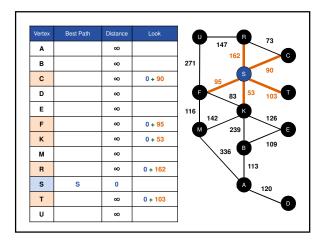


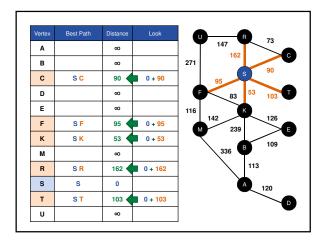




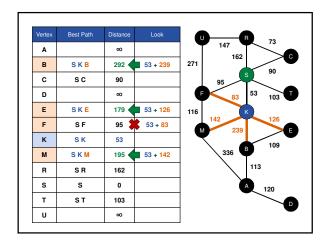


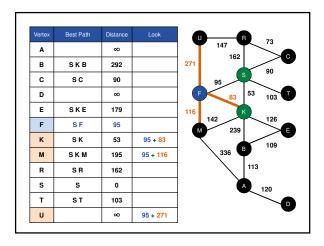


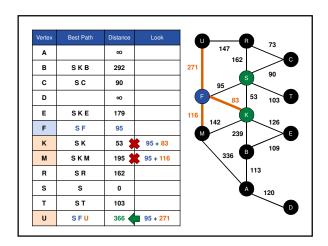


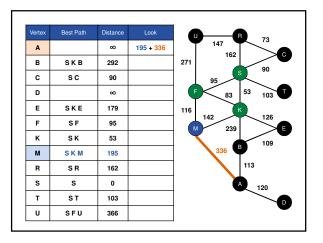


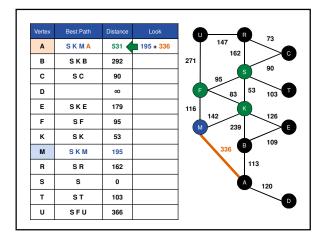
Vertex	Best Path	Distance	Look
Α		∞	
В		∞	53 + 239
С	sc	90	
D		∞	
Е		∞	53 + 126
F	SF	95	53 + 83
К	SK	53	
М		∞	53 + 142
R	SR	162	
S	s	0	
Т	ST	103	
U		∞	



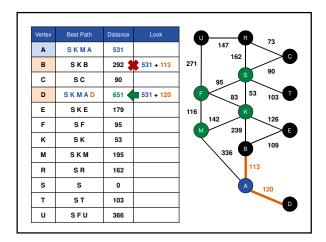


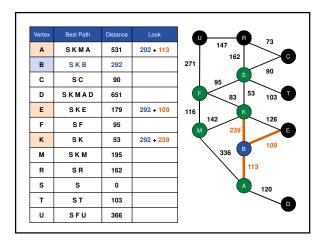


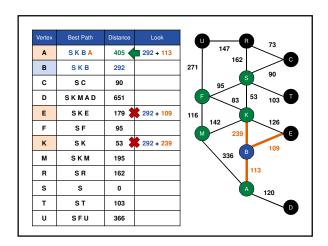


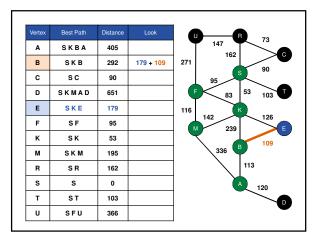


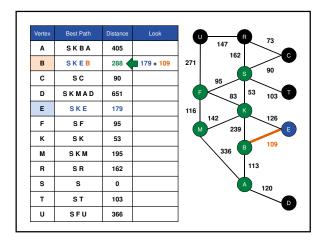
Vertex	Best Path	Distance	Look
Α	SKMA	531	
В	SKB	292	531 + 113
С	sc	90	
D		∞	531 + 120
Е	SKE	179	
F	SF	95	
к	sĸ	53	
М	SKM	195	
R	SR	162	
s	s	0	
т	ST	103	
U	SFU	366	











Vertex	Best Path	Distance	Look
Α	SKBA	405	288 + 113
В	SKEB	288	
С	sc	90	
D	SKMAD	651	
E	SKE	179	
F	SF	95	
к	sĸ	53	
М	SKM	195	
R	SR	162	
s	s	0	
т	ST	103	
U	SFU	366	

