

TAGE / JAVA

MouseLook Controller / Custom Cursors

// Demonstrates using a Java "Robot" to recenter the mouse after each
// mouse move, keeping the mouse from ever reaching the screen edge.

(imports go here)

```
public class MyGame extends VariableFrameRateGame
{
    private Robot robot; // these are additional variable declarations
    private float curMouseX, curMouseY, centerX, centerY;
    private float prevMouseX, prevMouseY; // loc of mouse prior to move
    private boolean isRecentering; // indicates the Robot is in action

    // constructor, main(), setupWindow(), and update() same as before
    // code to build ManualObject (pyramid) also the same as before
}
```

```
@Override
Public void initializeGame()
{
    ...
    initMouseMode();
}
```

```
private void initMouseMode()
{
    RenderSystem rs = engine.getRenderSystem();
    Viewport vw = rs.getViewport("MAIN");
    float left = vw.getActualLeft();
    float bottom = vw.getActualBottom();
    float width = vw.getActualWidth();
    float height = vw.getActualHeight();

    centerX = (int) (left + width/2);
    centerY = (int) (bottom - height/2);

    isRecentering = false;

    try // note that some platforms may not support the Robot class
    { robot = new Robot(); } catch (AWTException ex)
    { throw new RuntimeException("Couldn't create Robot!"); }

    recenterMouse();
    prevMouseX = centerX; // 'prevMouse' defines the initial
    prevMouseY = centerY; // mouse position

    // also change the cursor
    Image facelImage = new
        ImageIcon("./assets/textures/face.gif").getImage();
    Cursor faceCursor = Toolkit.getDefaultToolkit().
        createCustomCursor(facelImage, new Point(0,0), "FaceCursor");
    canvas = rs.getCanvas();
    canvas.setCursor(faceCursor);
}
```

```
@Override
public void mouseMoved(MouseEvent e)
{
    // if robot is recentering and the MouseEvent location is in the center,
    // then this event was generated by the robot

    if (isRecentering &&
        centerX == e.getXOnScreen() && centerY == e.getYOnScreen())
    {
        // mouse recentered, recentering complete
        isRecentering = false;
    }
    else
    {
        // event was due to a user mouse-move, and must be processed
        curMouseX = e.getXOnScreen();
        curMouseY = e.getYOnScreen();
        float mouseDeltaX = prevMouseX - curMouseX;
        float mouseDeltaY = prevMouseY - curMouseY;
        yaw(mouseDeltaX);
        pitch(mouseDeltaY);
        prevMouseX = curMouseX;
        prevMouseY = curMouseY;

        // tell robot to put the cursor to the center (since user just moved it)
        recenterMouse();
        prevMouseX = centerX; // reset prev to center
        prevMouseY = centerY;
    }
}
```

```
private void recenterMouse()
{
    // use the robot to move the mouse to the center point.
    // Note that this generates one MouseEvent.

    RenderSystem rs = engine.getRenderSystem();
    Viewport vw = rs.getViewport("MAIN");
    float left = vw.getActualLeft();
    float bottom = vw.getActualBottom();
    float width = vw.getActualWidth();
    float height = vw.getActualHeight();
    int centerX = (int) (left + width/2.0f);
    int centerY = (int) (bottom - height/2.0f);

    isRecentering = true;
    robot.mouseMove((int)centerX, (int)centerY);
}
```

```
public void yaw(float mouseDeltaX)
{
    float tilt;
    Camera c = engine.getRenderSystem()
        .getViewport("MAIN").getCamera();
    Vector3f rightVector = c.getU();
    Vector3f upVector = c.getV();
    Vector3f fwdVector = c.getN();
    if (mouseDeltaX < 0.0) tilt = -1.0f;
    else if (mouseDeltaX > 0.0) tilt = 1.0f;
    else tilt = 0.0f;
    rightVector.rotateAxis(0.01f*tilt, upVector.x(),
        upVector.y(), upVector.z());
    fwdVector.rotateAxis(0.01f*tilt, upVector.x(),
        upVector.y(), upVector.z());

    c.setU(rightVector);
    c.setN(fwdVector);
}
```

```
public void pitch(float mouseDeltaX) { } // not shown here
```