Fundamental sets of solutions for systems *

Here we answer the question: Is there a notion of a fundamental set of solutions, and what constitutes a fundamental set of solutions and a general solution?

There is a notion of a fundamental set of solutions! Though we restrict our attention to systems of *n*-many linear differential equations with *n*-many unknowns.

Theorem

If we have **n**-many differential equations in a system with **n**-many unknowns, then **n**-many linearly independent solutions form a fundamental set of solutions for the system.

However, this begs another question. How do we know if a set of solutions (which are vectors) is linearly independent?

To answer this, we only look at the case of systems of 2 linear differential equations with 2 unknowns. To determine if two solutions of such a system are linearly independent, we use the following theorem.

Theorem

Suppose $y_1=egin{pmatrix} a_1 \ b_1 \end{pmatrix}$ and $y_2=egin{pmatrix} a_2 \ b_2 \end{pmatrix}$ are solutions to a 2×2 system of linear differential equations on an interval I. Then y_1 and y_2 are linearly independent if and only if

$$W\left(y_{1},y_{2}
ight)=\det\left(\left(egin{matrix}a_{1}&a_{2}\b_{1}&b_{2}\end{matrix}
ight)
ight)
eq0$$

on all of *I*.

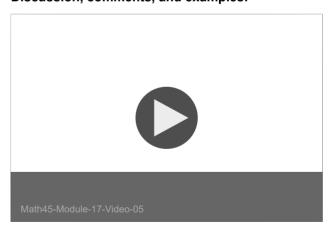
Note: The W above is again called the **Wronskian**, but here there are no derivatives.

Finally, we note that again, if y_1 and y_2 form a fundamental set of solutions for the system of homogeneous linear differential equations is given by

$$y=c_1y_1+c_2y_2,$$

just as before. (And a general solution for a nonhomogeneous system also follows the framework from before, though we omit that discussion here.)

Discussion, comments, and examples:



WeBWorK module 17 exercises:

• Problems 8, 9

Relevant Wikipedia articles:

• See Theorems 10.3.1 and 10.3.2 in the textbook (https://digitalcommons.trinity.edu/mono/8/)