

1. (1 point) Evaluate the following matrix-vector product.

$$\begin{bmatrix} 5 & -2 \\ 3 & -4 \end{bmatrix} \begin{bmatrix} 9 \\ -3 \end{bmatrix} = \begin{bmatrix} ______ \\ ______ \end{bmatrix}$$

Correct Answers:

- $\begin{bmatrix} 51 \\ 39 \end{bmatrix}$

2. (1 point) Perform the following matrix operation:

$$\begin{bmatrix} -6 \\ 5 \\ -9 \end{bmatrix} - \begin{bmatrix} -9 \\ -8 \\ 7 \end{bmatrix} = \begin{bmatrix} ______ \\ ______ \\ ______ \end{bmatrix}$$

Correct Answers:

- $\begin{bmatrix} 3 \\ 13 \\ -16 \end{bmatrix}$

3. (1 point) Perform the following matrix operation:

$$\begin{bmatrix} -5 & -9 \\ 1 & -2 \\ 5 & 1 \end{bmatrix} - \begin{bmatrix} -3 & -5 \\ -6 & -9 \\ -6 & 3 \end{bmatrix} = \begin{bmatrix} ______ & ______ \\ ______ & ______ \\ ______ & ______ \end{bmatrix}$$

Correct Answers:

- $\begin{bmatrix} -2 & -4 \\ 7 & 7 \\ 11 & -2 \end{bmatrix}$

4. (1 point)

If

$$A = \begin{bmatrix} -8 \\ -5 \\ -4 \end{bmatrix}$$

then

$$5A = \begin{bmatrix} ______ \\ ______ \\ ______ \end{bmatrix}$$

Correct Answers:

- -40
- -25
- -20

Consider the system of differential equations

$$\begin{aligned} \frac{dx}{dt} &= 7x + 2y + e^{8t} \\ \frac{dy}{dt} &= 5x + 7y + \sin(7t). \end{aligned}$$

Which of the following expressions is the matrix form of this system of DEs?

- A. $\mathbf{X}' = \begin{pmatrix} 7 & 2 \\ 5 & 7 \end{pmatrix} \mathbf{X} + \begin{pmatrix} \sin(7t) \\ e^{8t} \end{pmatrix}$
- B. $\mathbf{X}' = \begin{pmatrix} 7 & 2 \\ 5 & 7 \end{pmatrix} \mathbf{X} + \begin{pmatrix} e^{8t} \\ \sin(7t) \end{pmatrix}$
- C. $\mathbf{X}' = \begin{pmatrix} 7 & 2 \\ 4 & 7 \end{pmatrix} \mathbf{X} + \begin{pmatrix} e^{8t} \\ \sin(7t) \end{pmatrix}$
- D. $\mathbf{X}' = \begin{pmatrix} 7 & 2 \\ 5 & 7 \end{pmatrix} \mathbf{X}$

Solution:

SOLUTION:

The correct answer is B.

Correct Answers:

- B

6. (1 point) This is the first part of a four-part problem.

Let

$$P = \begin{bmatrix} 9 & -4 \\ 15 & -7 \end{bmatrix},$$

$$\vec{y}_1(t) = \begin{bmatrix} 2e^{3t} + 8e^{-t} \\ 3e^{3t} + 20e^{-t} \end{bmatrix}, \quad \vec{y}_2(t) = \begin{bmatrix} -4e^{3t} + 2e^{-t} \\ -6e^{3t} + 5e^{-t} \end{bmatrix}.$$

(1) Show that $\vec{y}_1(t)$ is a solution to the system $\vec{y}' = P\vec{y}$ by evaluating derivatives and the matrix product

$$\vec{y}_1'(t) = \begin{bmatrix} 9 & -4 \\ 15 & -7 \end{bmatrix} \vec{y}_1(t)$$

Enter your answers in terms of the variable t .

$$\begin{bmatrix} ______ \\ ______ \end{bmatrix} = \begin{bmatrix} ______ \\ ______ \end{bmatrix}$$

- (2) Show that $\vec{y}_2(t)$ is a solution to the system $\vec{y}' = P\vec{y}$ by evaluating derivatives and the matrix product

$$\vec{y}_2'(t) = \begin{bmatrix} 9 & -4 \\ 15 & -7 \end{bmatrix} \vec{y}_2(t)$$

Enter your answers in terms of the variable t .

$$\begin{bmatrix} \underline{\hspace{2cm}} \\ \underline{\hspace{2cm}} \end{bmatrix} = \begin{bmatrix} \underline{\hspace{2cm}} \\ \underline{\hspace{2cm}} \end{bmatrix}$$

Correct Answers:

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7. (1 point) Select all of system of linear differential equation IVPs which are guaranteed the existence of a unique solution on the interval $I = (0, \infty)$.

- A. $\mathbf{X}' = \begin{pmatrix} 4 & 6 \\ 4 & 6 \end{pmatrix} \mathbf{X}$
- B. $\mathbf{X}' = \begin{pmatrix} 4 & 6 \\ 4 & 6 \end{pmatrix} \mathbf{X} + \begin{pmatrix} 1 \\ (t-4)^6 \\ t^3 \end{pmatrix}$
- C. $\mathbf{X}' = \begin{pmatrix} 4 & 6 \\ 4 & 6 \end{pmatrix} \mathbf{X} + \begin{pmatrix} e^{1t} \\ \sin(3t) \end{pmatrix}$
- D. $\mathbf{X}' = \begin{pmatrix} 6 & 4 \\ 6 & 6 \end{pmatrix} \mathbf{X} + \begin{pmatrix} 0 \\ 3t \end{pmatrix}$
- E. $\mathbf{X}' = \begin{pmatrix} 4 & 6 \\ 4 & 6 \end{pmatrix} \mathbf{X} + \begin{pmatrix} \sqrt{t} \\ 1 \\ t \end{pmatrix}$
- F. $\mathbf{X}' = \begin{pmatrix} 4 & 6 \\ 4 & 6 \end{pmatrix} \mathbf{X} + \begin{pmatrix} \sqrt{t-1} \\ t^3 \end{pmatrix}$
- G. $\mathbf{X}' = \begin{pmatrix} 4 & 6 \\ 4 & 6 \end{pmatrix} \mathbf{X} + \begin{pmatrix} e^{1t} \\ 1 \\ t-3 \end{pmatrix}$
- H. None of the above

Solution:

SOLUTION:

The correct answer is ACDE.

Correct Answers:

- ACDE

8. (1 point)

Suppose $y_1 = \begin{pmatrix} 8e^{6t} \\ 9e^{6t} \end{pmatrix}$ and $y_2 = \begin{pmatrix} 2e^{5t} \\ 7e^{5t} \end{pmatrix}$. Compute the Wronskian $W(y_1, y_2)$.

(Note: your answer should be a function of t .)

$W(y_1, y_2) = \det \begin{pmatrix} 8e^{6t} & 2e^{5t} \\ 9e^{6t} & 7e^{5t} \end{pmatrix} = 56e^{11t} - 18e^{11t} = 38e^{11t}$

Solution:

SOLUTION:

The answer is $38e^{11t}$.

Correct Answers:

- $(8*7-2*9)*e^{(6+5)*t}$

Solution:

9. (1 point) Consider the vector functions $y_1(t) = \begin{pmatrix} f_1(t) \\ g_1(t) \end{pmatrix}$ and $y_2(t) = \begin{pmatrix} f_2(t) \\ g_2(t) \end{pmatrix}$. Mark all of the following which must be true if $y = c_1y_1 + c_2y_2$ is a general solution to the system of linear equations $\mathbf{X}' = A\mathbf{X}$, where A is a matrix.

- A. y_1, y_2 are solutions to the system of differential equation.
- B. The system is nonhomogeneous.
- C. The system consists of two equations with two unknown functions.
- D. y_1, y_2 are linearly dependent.
- E. y_1, y_2 are linearly independent.
- F. y_1, y_2 are linear combinations.
- G. None of the above

Solution:

SOLUTION:

The correct answer is ACE.

Correct Answers:

- ACE

10. (1 point) Suppose that the matrix A has the following eigenvalues and eigenvectors:

$$\lambda_1 = 3 \text{ with } \vec{v}_1 = \begin{bmatrix} -2 \\ 2 \end{bmatrix}.$$

and

$$\lambda_2 = 4 \text{ with } \vec{v}_2 = \begin{bmatrix} -2 \\ 3 \end{bmatrix}.$$

Write the solution to the linear system $\mathbf{X}' = A\mathbf{X}$ in the following forms.

A. In eigenvalue/eigenvector form:

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} \quad \\ \quad \end{bmatrix} e^{\quad t} + c_2 \begin{bmatrix} \quad \\ \quad \end{bmatrix} e^{\quad t}$$

B. As two equations: (write " c_1 " and " c_2 " for c_1 and c_2)

$$x(t) = \underline{\hspace{2cm}}$$

$$y(t) = \underline{\hspace{2cm}}$$

Hint: For part B, you can multiply out part A and solve for $x(t)$ and $y(t)$.

Note: Both forms of writing the solution above are correct and acceptable.

Correct Answers:

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| $(c_1 \begin{bmatrix} -2 \\ 2 \end{bmatrix} e^{3t} + c_2 \begin{bmatrix} -2 \\ 3 \end{bmatrix} e^{4t})$ |
|---|
- | |
|--|
| $x(t) = (c_1(-2)e^{3t} + c_2(-2)e^{4t})$
$y(t) = (c_1(2)e^{3t} + c_2(3)e^{4t})$ |
|--|