

1. (1 point) Evaluate the following matrix-vector product.

$$\begin{bmatrix} 5 & -2 \\ 3 & -4 \end{bmatrix} \begin{bmatrix} 9 \\ -3 \end{bmatrix} = \begin{bmatrix} \_\_\_\_\_\_ \\ \_\_\_\_\_\_ \end{bmatrix}$$

2. (1 point) Perform the following matrix operation:

$$\begin{bmatrix} -6 \\ 5 \\ -9 \end{bmatrix} - \begin{bmatrix} -9 \\ -8 \\ 7 \end{bmatrix} = \begin{bmatrix} \_\_\_\_\_\_ \\ \_\_\_\_\_\_ \\ \_\_\_\_\_\_ \end{bmatrix}$$

3. (1 point) Perform the following matrix operation:

$$\begin{bmatrix} -5 & -9 \\ 1 & -2 \\ 5 & 1 \end{bmatrix} - \begin{bmatrix} -3 & -5 \\ -6 & -9 \\ -6 & 3 \end{bmatrix} = \begin{bmatrix} \_\_\_\_\_\_ & \_\_\_\_\_\_ \\ \_\_\_\_\_\_ & \_\_\_\_\_\_ \\ \_\_\_\_\_\_ & \_\_\_\_\_\_ \end{bmatrix}$$

4. (1 point)

If

$$A = \begin{bmatrix} -8 \\ -5 \\ -4 \end{bmatrix}$$

then

$$5A = \begin{bmatrix} \_\_\_\_\_\_ \\ \_\_\_\_\_\_ \\ \_\_\_\_\_\_ \end{bmatrix}$$

Consider the system of differential equations

$$\begin{aligned} \frac{dx}{dt} &= 7x + 2y + e^{8t} \\ \frac{dy}{dt} &= 5x + 7y + \sin(7t). \end{aligned}$$

Which of the following expressions is the matrix form of this system of DEs?

- A.  $\mathbf{X}' = \begin{pmatrix} 7 & 2 \\ 5 & 7 \end{pmatrix} \mathbf{X} + \begin{pmatrix} \sin(7t) \\ e^{8t} \end{pmatrix}$
- B.  $\mathbf{X}' = \begin{pmatrix} 7 & 2 \\ 5 & 7 \end{pmatrix} \mathbf{X} + \begin{pmatrix} e^{8t} \\ \sin(7t) \end{pmatrix}$
- C.  $\mathbf{X}' = \begin{pmatrix} 7 & 2 \\ 4 & 7 \end{pmatrix} \mathbf{X} + \begin{pmatrix} e^{8t} \\ \sin(7t) \end{pmatrix}$
- D.  $\mathbf{X}' = \begin{pmatrix} 7 & 2 \\ 5 & 7 \end{pmatrix} \mathbf{X}$

6. (1 point) This is the first part of a four-part problem.

Let

$$P = \begin{bmatrix} 9 & -4 \\ 15 & -7 \end{bmatrix},$$

$$\vec{y}_1(t) = \begin{bmatrix} 2e^{3t} + 8e^{-t} \\ 3e^{3t} + 20e^{-t} \end{bmatrix}, \quad \vec{y}_2(t) = \begin{bmatrix} -4e^{3t} + 2e^{-t} \\ -6e^{3t} + 5e^{-t} \end{bmatrix}.$$

(1) Show that  $\vec{y}_1(t)$  is a solution to the system  $\vec{y}' = P\vec{y}$  by evaluating derivatives and the matrix product

$$\vec{y}_1'(t) = \begin{bmatrix} 9 & -4 \\ 15 & -7 \end{bmatrix} \vec{y}_1(t)$$

Enter your answers in terms of the variable  $t$ .

$$\begin{bmatrix} \_\_\_\_\_\_ \\ \_\_\_\_\_\_ \end{bmatrix} = \begin{bmatrix} \_\_\_\_\_\_ \\ \_\_\_\_\_\_ \end{bmatrix}$$

(2) Show that  $\vec{y}_2(t)$  is a solution to the system  $\vec{y}' = P\vec{y}$  by evaluating derivatives and the matrix product

$$\vec{y}_2'(t) = \begin{bmatrix} 9 & -4 \\ 15 & -7 \end{bmatrix} \vec{y}_2(t)$$

Enter your answers in terms of the variable  $t$ .

$$\begin{bmatrix} \_\_\_\_\_\_ \\ \_\_\_\_\_\_ \end{bmatrix} = \begin{bmatrix} \_\_\_\_\_\_ \\ \_\_\_\_\_\_ \end{bmatrix}$$

7. (1 point) Select all of system of linear differential equation IVPs which are guaranteed the existence of a unique solution on the interval  $I = (0, \infty)$ .

- A.  $\mathbf{X}' = \begin{pmatrix} 4 & 6 \\ 4 & 6 \end{pmatrix} \mathbf{X}$
- B.  $\mathbf{X}' = \begin{pmatrix} 4 & 6 \\ 4 & 6 \end{pmatrix} \mathbf{X} + \begin{pmatrix} 1 \\ (t-4)^6 \\ t^3 \end{pmatrix}$
- C.  $\mathbf{X}' = \begin{pmatrix} 4 & 6 \\ 4 & 6 \end{pmatrix} \mathbf{X} + \begin{pmatrix} e^{1t} \\ \sin(3t) \end{pmatrix}$
- D.  $\mathbf{X}' = \begin{pmatrix} 6 & 4 \\ 6 & 6 \end{pmatrix} \mathbf{X} + \begin{pmatrix} 0 \\ 3t \end{pmatrix}$

- E.  $\mathbf{X}' = \begin{pmatrix} 4 & 6 \\ 4 & 6 \end{pmatrix} \mathbf{X} + \begin{pmatrix} \sqrt{t} \\ \frac{1}{t} \end{pmatrix}$
- F.  $\mathbf{X}' = \begin{pmatrix} 4 & 6 \\ 4 & 6 \end{pmatrix} \mathbf{X} + \begin{pmatrix} \sqrt{t-1} \\ t^3 \end{pmatrix}$
- G.  $\mathbf{X}' = \begin{pmatrix} 4 & 6 \\ 4 & 6 \end{pmatrix} \mathbf{X} + \begin{pmatrix} e^{1t} \\ \frac{1}{t-3} \end{pmatrix}$

- H. None of the above

8. (1 point)

Suppose  $y_1 = \begin{pmatrix} 8e^{6t} \\ 9e^{6t} \end{pmatrix}$  and  $y_2 = \begin{pmatrix} 2e^{5t} \\ 7e^{5t} \end{pmatrix}$ . Compute the Wronskian  $W(y_1, y_2)$ .

(Note: your answer should be a function of  $t$ .)

$W(y_1, y_2) =$  \_\_\_\_\_

9. (1 point) Consider the vector functions  $y_1(t) = \begin{pmatrix} f_1(t) \\ g_1(t) \end{pmatrix}$

and  $y_2(t) = \begin{pmatrix} f_2(t) \\ g_2(t) \end{pmatrix}$ . Mark all of the following which must be true if  $y = c_1 y_1 + c_2 y_2$  is a general solution to the system of linear equations  $\mathbf{X}' = \mathbf{A}\mathbf{X}$ , where  $A$  is a matrix.

- A.  $y_1, y_2$  are solutions to the system of differential equation.
- B. The system is nonhomogeneous.
- C. The system consists of two equations with two unknown functions.

- D.  $y_1, y_2$  are linearly dependent.
- E.  $y_1, y_2$  are linearly independent.
- F.  $y_1, y_2$  are linear combinations.
- G. None of the above

10. (1 point) Suppose that the matrix  $A$  has the following eigenvalues and eigenvectors:

$$\lambda_1 = 3 \text{ with } \vec{v}_1 = \begin{bmatrix} -2 \\ 2 \end{bmatrix}.$$

and

$$\lambda_2 = 4 \text{ with } \vec{v}_2 = \begin{bmatrix} -2 \\ 3 \end{bmatrix}.$$

Write the solution to the linear system  $\mathbf{X}' = \mathbf{A}\mathbf{X}$  in the following forms.

A. In eigenvalue/eigenvector form:

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} \text{---} \\ \text{---} \end{bmatrix} e^{\text{---}t} + c_2 \begin{bmatrix} \text{---} \\ \text{---} \end{bmatrix} e^{\text{---}t}$$

B. As two equations: (write "c1" and "c2" for  $c_1$  and  $c_2$ )

$$x(t) = \text{---}$$

$$y(t) = \text{---}$$

Hint: For part B, you can multiply out part A and solve for  $x(t)$  and  $y(t)$ .

**Note:** Both forms of writing the solution above are correct and acceptable.