

Last Time

- Intro to determinants ^{ants} via cofactor expansion
- We saw

$$\det \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & 0 & a_{nn} \end{pmatrix} = a_{11} a_{22} \dots a_{nn}$$

Product of entries

Section 3.2 Properties of Determinants

We'll first study how row operations affect determinants.
Let's investigate 2×2 case

$$\text{Let } A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}. \det A = ad - bc$$

Interchange Rows

$$\text{Consider } B = \begin{bmatrix} c & d \\ a & b \end{bmatrix}$$

$$\begin{aligned} \det B &= cb - da \\ &= bc - ad \\ &= -ad + bc \\ &= -(ad - bc) \\ &= -\det A \end{aligned}$$

$$\text{Thus } A \xrightarrow{r_1 \leftrightarrow r_2} B \text{ then } -\det A = \det B$$

Scaling a Row

$$\text{Consider } B = \begin{bmatrix} ka & kb \\ c & d \end{bmatrix}$$

$$\begin{aligned} \det B &= ka \cdot d - kb \cdot c \\ &= k(ad - bc) \\ &= k \cdot \det A \end{aligned}$$

Thus,

$$A \xrightarrow{kr_1 \rightarrow r_1} B \Rightarrow k \det A = \det B$$

Replacement

$$\text{Consider } B = \begin{bmatrix} a & b \\ ka+c & kb+d \end{bmatrix}$$

$$\begin{aligned} \det B &= a(kb+d) - b(ka+c) \\ &= akb + ad - bka - bc \\ &= ad - bc \\ &= \det A \end{aligned}$$

Thus,

$$A \xrightarrow{kr_1 + r_2 \rightarrow r_2} B \Rightarrow \det A = \det B$$

Theorem: Let A be $n \times n$

① Replacement: If B is the result of performing a replacement row operation on A , then $A \xrightarrow{kr_i + r_j \rightarrow r_i} B \Rightarrow \det A = \det B$

② Interchange: If B is the result of interchanging 2 rows of A then, $A \xrightarrow{r_i \leftrightarrow r_j} B \Rightarrow -\det A = \det B$

③ Scaling: If B is the result of scaling one row of A by k , then

$$A \xrightarrow{kr_i \rightarrow r_i} B \Rightarrow k \det A = \det B$$

$$\begin{aligned} & \text{purple} \quad (\det A = \frac{1}{k} \det B) \\ & \text{if } k \neq 0 \end{aligned}$$

Reduction to triangular form

20290102 Page 2

* $\begin{vmatrix} x & y & z \\ x & y & z \\ x & y & z \end{vmatrix} \leftarrow$ straight lines mean determinants

Example A Compute

$$\begin{vmatrix} 1 & -4 & 2 \\ -2 & 8 & -9 \\ -1 & 7 & 0 \end{vmatrix} \xrightarrow{S_0} \begin{vmatrix} 1 & -4 & 2 \\ -2 & 8 & -9 \\ -1 & 7 & 0 \end{vmatrix} \xrightarrow{\substack{2r_1 + r_2 \rightarrow r_2 \\ r_1 + r_3 \rightarrow r_3 \\ \text{Replacement} \\ \text{So determinants are equal}}} \begin{vmatrix} 1 & -4 & 2 \\ 0 & 0 & -5 \\ 0 & 3 & 2 \end{vmatrix} \xrightarrow{r_2 \leftrightarrow r_3} \begin{vmatrix} 1 & -4 & 2 \\ 0 & 3 & 2 \\ 0 & 0 & -5 \end{vmatrix} \xrightarrow{= - (1 \cdot 3 \cdot (-5))} = \boxed{15}$$

$\det \begin{pmatrix} 1 & -4 & 2 \\ -2 & 8 & -9 \\ -1 & 7 & 0 \end{pmatrix}$

Example B

$$\begin{vmatrix} 2 & -8 & 6 & 8 \\ 3 & -9 & 5 & 10 \\ -1 & 4 & -3 & -6 \\ -3 & 0 & 1 & -2 \end{vmatrix} \xrightarrow{\substack{\frac{1}{2}r_1 \rightarrow r_1 \\ \text{Scale}}} \begin{vmatrix} 2 & -8 & 6 & 8 \\ 3 & -9 & 5 & 10 \\ -1 & 4 & -3 & -6 \\ -3 & 0 & 1 & -2 \end{vmatrix} \xrightarrow{S_0} \begin{vmatrix} 2 & -8 & 6 & 8 \\ 3 & -9 & 5 & 10 \\ -1 & 4 & -3 & -6 \\ -3 & 0 & 1 & -2 \end{vmatrix} \xrightarrow{\substack{-3r_1 + r_2 \rightarrow r_2 \\ r_1 + r_3 \rightarrow r_3 \\ 3r_1 + r_4 \rightarrow r_4 \\ \text{Replacement}}} = 2 \begin{vmatrix} 1 & -4 & 3 & 4 \\ 0 & 3 & -4 & -2 \\ 0 & 0 & 0 & -2 \\ 0 & -12 & 10 & 10 \end{vmatrix} \xrightarrow{\substack{4r_2 + 6r_4 \rightarrow r_4 \\ \text{Replace}}} = \begin{vmatrix} 1 & -4 & 3 & 4 \\ 0 & 3 & -4 & -2 \\ 0 & 0 & 0 & -2 \\ 0 & 0 & 0 & -2 \end{vmatrix} \xrightarrow{r_3 \leftrightarrow r_4} \begin{vmatrix} 1 & -4 & 3 & 4 \\ 0 & 3 & -4 & -2 \\ 0 & 0 & -6 & 2 \\ 0 & 0 & 0 & -2 \end{vmatrix} \xrightarrow{= -2(1 \cdot 3 \cdot (-6) \cdot (-2))} = \boxed{-72}$$

* Note $A \xrightarrow{kr_i \rightarrow r_i} B$
 $k \det A = \det B$
 $\det A = \frac{1}{k} \det B$

Section 3.2: Properties of Determinants - Invertability & Determinants

Recall: A^{-1} exists $\Leftrightarrow A \sim I$

Assume A^{-1} exists. What can we say about $\det A$.

$$A^{-1} \text{ exists} \Rightarrow A \sim A_1 \sim A_2 \sim \dots \sim A_k = I$$

$$\Rightarrow \det A = c_1 \det A_1 = c_1 c_2 \det A_2 = \dots = c_1 c_2 \dots c_k \det I$$

for some c_1, c_2, \dots, c_k

Note: $\det I = 1$

and none of c_1, c_2, \dots, c_k are equal to zero

Recap: A^{-1} exists $\Rightarrow \det A = c_1 c_2 \dots c_k$ where c_1, \dots, c_k are not zero

$$\Rightarrow \det A \neq 0$$

Similar idea shows $\det A \neq 0 \Rightarrow A^{-1}$ exists

* Theorem A is invertable $\Leftrightarrow \det A \neq 0$
 A^{-1} exists

Other Properties of the determinantTheoremTranspose: for 2×2

$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \det \begin{pmatrix} a & c \\ b & d \end{pmatrix}$$

$$\bullet \det(A^T) = \det A$$

Important

$$\bullet \det(A \cdot B) = (\det A)(\det B)$$

$$\bullet \text{ for } k=1, 2, 3, \dots; \det(A^k) = (\det A)^k$$

Note: Typically $\det(A+B) \neq \det A + \det B$

$$\bullet \text{ if } \det A \neq 0, \text{ then } \det(A^{-1}) = \frac{1}{\det A} = (\det A)^{-1}$$

Example Suppose you know $\det A = 7$, $\det B = \frac{1}{2}$

Compute

$$\left. \begin{array}{l} \text{(a) } \det(BA) \\ \text{(b) } \det(B^3) \\ \text{(c) } \det(A^{-1}) \end{array} \right\} \begin{array}{l} \text{(a) } \det(BA) = \det B \cdot \det A \\ \quad = \frac{1}{2} \cdot 7 \\ \text{(b) } \det(B^3) = \frac{1}{8} \\ \text{(c) Since } \det A \neq 0, A^{-1} \text{ exists} \end{array}$$

$$A \cdot A^{-1} = I$$

$$\det(A \cdot A^{-1}) = \det I$$

$$(\det A) \cdot (\det A^{-1}) = 1$$

$$\det A^{-1} = \frac{1}{\det A} = \boxed{\frac{1}{7}}$$