

Augmented

$$\left\{ \begin{array}{ccccc} 1 & 0 & 0 & -7 & 0 \\ 0 & 1 & 0 & -3 & 0 \\ 0 & 0 & 1 & -1 & 0 \end{array} \right\} \begin{array}{l} x_1 + (-7x_4) \\ x_2 + (-3x_4) \\ x_3 + (-1x_4) \\ x_4 \text{ is free} \end{array} \left\{ \begin{array}{l} x_1 = 7x_4 \\ x_2 = 3x_4 \\ x_3 = 1x_4 \\ x_4 \text{ is free} \end{array} \right\}$$

Parametric Vector Form

$$\bar{X} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 7s \\ 3s \\ s \\ s \end{bmatrix} = s \begin{bmatrix} 7 \\ 3 \\ 1 \\ 1 \end{bmatrix}$$

Let $x_4 = s$

Matrix Transpose

\downarrow

$[1 \ 1 \ 1]$

No Solution $-1=0$ is a contradiction \therefore the system is **INCONSISTENT**

∞ solution $0=0$ - The matrix has 1 or more solutions \therefore the system is Consistent

When **NOT** the trivial solution (all zeros) - **Linearly Dependent**; else, independent

No free var

$$\left\{ \begin{array}{ccc} 1 & 0 & 5 \\ 0 & 1 & -3 \\ 0 & 0 & 0 \end{array} \right\} \begin{array}{l} x_1 = -5x_3 - 2x_4 \\ x_2 = 3x_3 - x_4 \\ x_3 \text{ is free} \\ x_4 \text{ is free} \end{array}$$

Let x_3 be s

Let x_4 be t

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = s \begin{bmatrix} -5 \\ 3 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -2 \\ -1 \\ 0 \\ 1 \end{bmatrix}$$

Null space = Param

$\left\{ \begin{bmatrix} -5 \\ 3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ -1 \\ 0 \\ 1 \end{bmatrix} \right\}$

Basis for column space - Matrix A

are your Basis

① Get to RREF ② The pivots Reference original matrix

Basis for $\text{Col}(A) \left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right\}$

Is Basis Check

1. Linear Independence Trivial solution

2. Spanning set - span domain, No Combo

Determinant 2x2

$$\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} \rightarrow ad - bc$$

Finding A^{-1} of 2x2

Linear Transform $A \begin{bmatrix} 8 & -3 & 4 \\ -7 & 5 & 4 \end{bmatrix}, \vec{v} = \begin{bmatrix} a \\ b \\ c \end{bmatrix} \rightarrow \begin{bmatrix} 8a + (-3b) + 4c \\ -7a + 5b + 4c \end{bmatrix}$

$R^3 \rightarrow R^2$

If $\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} \neq 0, \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \frac{1}{\det}$

$\det(A)=4, \det(B)=-9, 3 \times 3$

* $\det(AB) = (4 \cdot -9)$

$\cdot \det(-2A) = (-2)^3 \det A \rightarrow (-2)^3 \cdot 4$

$\cdot \det(AT) = \det(A)$

* $\det(B^{-1}) = \frac{1}{\det B} \rightarrow -\frac{1}{9}$

$\cdot \det(B^2) = -9 \cdot -9 = 81$

Determinant Properties

Matrix A 3×3 Matrix B 3×2 • Pivot in all row "only" Determinant of $n \times n$ $-a_{22}[-a_{22}]$

• Pivot in every col 1:1 $\rightarrow +a_{11} - a_{12} + a_{13}$

Approach 1

Just go across the top

Approach 2

Find col w/ most 0s and go down that

multiply each element in row A by column B

$$\begin{bmatrix} 2 & 1 & 1 \\ 3 & 2 & 2 \\ -1 & 0 & 5 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 5 & -2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} (2 \cdot 1) + (1 \cdot 5) + (1 \cdot 0) & (2 \cdot 1) + (1 \cdot -2) + (1 \cdot 1) \\ (3 \cdot 1) + (2 \cdot 5) + (2 \cdot 0) & (3 \cdot 1) + (2 \cdot -2) + (2 \cdot 1) \\ (-1 \cdot 1) + (0 \cdot 5) + (5 \cdot 0) & (-1 \cdot 1) + (0 \cdot -2) + (5 \cdot 1) \end{bmatrix}$$

$$-a_{21} + a_{22} - a_{23}$$

$$+a_{31} - a_{32} + a_{33}$$

Diagonalization $A = n \times n$; If A has n different eigenvalues; then
 step 1) Find eigenvalues A is diagonalisable

$$A = \begin{bmatrix} 3 & -4 \\ 5 & 6 \end{bmatrix} \det(A - \lambda I) = 0$$

$$\rightarrow \begin{bmatrix} 3-\lambda & -4 \\ 5 & 6-\lambda \end{bmatrix} = 0 \rightarrow [(-3-\lambda)(6-\lambda) - (-20)] = 0$$

$$\rightarrow -18 + 3\lambda + 6\lambda + \lambda^2 + 20 = 0$$

Factor out

$$\rightarrow \lambda^2 - 3\lambda + 2 = 0 \rightarrow (\lambda - 1)(\lambda - 2) = 0$$

eigenvalues are $\lambda = 1$ & $\lambda = 2$

step 1) Find eigenvectors
 Plug-in λ into $(A - \lambda I)\vec{x} = \vec{0}$

$\lambda = 1$

$$\begin{bmatrix} 3 & -4 \\ 5 & 6 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & -4 \\ 5 & 5 \end{bmatrix} \rightarrow \begin{cases} -4x_1 + 4x_2 = 0 \\ 5x_1 + 5x_2 = 0 \end{cases}$$

Now pick easy # to plug in for x_2

* Let $x_2 = 1$ $x_1 = -1$, $x_2 = 1$; $\vec{x}_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

$\lambda = 2$

$$\begin{bmatrix} 3 & -4 \\ 5 & 6 \end{bmatrix} - \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -4 \\ 5 & 4 \end{bmatrix} \rightarrow \begin{cases} -4x_1 + 4x_2 = 0 \\ 5x_1 + 4x_2 = 0 \end{cases}$$

* Choosing x_2 be 1

$x_1 = -4/5(1)$
 $x_2 = 1$

eigenvectors are $\vec{x}_2 = \begin{bmatrix} -4/5 \\ 1 \end{bmatrix}$

Diagonal Matrix \rightarrow made of e-vectors
 made of e-val \rightarrow

$$P = [\vec{v}_1 \dots \vec{v}_n] = \begin{bmatrix} -1 & -4/5 \\ 1 & 1 \end{bmatrix}, D = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

$$P^{-1} = \begin{bmatrix} 1 & -4/5 \\ 1 & 1 \end{bmatrix} \cdot \frac{1}{1/5} \rightarrow \begin{bmatrix} 5 & -4 \\ 5 & 5 \end{bmatrix} \therefore A = PDP^{-1}$$

Find Least Sq

1) Show $A\vec{x} = \vec{b}$ has no soln.

Augment Matrix - row reduce

2) Find $A^T A$ & $A^T \vec{b}$

3) Solve sys. $A^T A \vec{x} = A^T \vec{b}$

Augment Matrix - row reduce

RREF
 Step 3 gives soln $\hat{x} = \begin{bmatrix} \dots \end{bmatrix}$

4) Find Error

$$\|A\vec{x} - \vec{b}\| \rightarrow \sqrt{(b_1 - A_1)^2 + (b_2 - A_2)^2}$$

Dot Product

$$u = \begin{bmatrix} 3 \\ 1 \end{bmatrix}, v = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$$

$$u \cdot v = [3 \cdot 0 + 1 \cdot 2 + 5 \cdot 7]$$

Distance $e(v, w) = \|v - w\|$

$$v = \begin{bmatrix} 1 \\ 1 \end{bmatrix}; w = \begin{bmatrix} 0 \\ 5 \end{bmatrix}$$

$$\sqrt{(1-0)^2 + (3-2)^2 + (2-5)^2}$$

Orthogonality, $u = \begin{bmatrix} 1 \\ 3 \end{bmatrix}, v = \begin{bmatrix} 5 \\ 1 \end{bmatrix}$

step 1) dot product 2 vect

$$[1 \cdot 2 + 3 \cdot (-1) + (-5 \cdot 3)]$$

$= 0$? Yes or No
 orthog? Not orth

step 2) Find θ both vec

$$\vec{v}_1 = \sqrt{a^2 + b^2} \cos \theta$$

$$u \cdot v = \|u\| \cdot \|v\| \cos \theta$$

Row operations change e-val
 but similarity does not

similarity show $\det A = \det B$
 $B = P^{-1} A P$ for some P

$$\det(B) = \det(P^{-1} A P) \Rightarrow \det(P^{-1}) \det(A) \det(P)$$

$$\rightarrow \frac{1}{\det P} \cdot \det A \cdot \det P = \det A$$

Diagonalization

$\lambda = \#$

Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ linear transformation $T(\vec{v}) = \begin{bmatrix} -y \\ y-2x \\ 7x \end{bmatrix}$

a) image of vect $\begin{bmatrix} 2 \\ 5 \end{bmatrix}$

$$T\left(\begin{bmatrix} 2 \\ 5 \end{bmatrix}\right) = \begin{pmatrix} -5 \\ 5-2(2) \\ 7(2) \end{pmatrix} \rightarrow T = \begin{bmatrix} -5 \\ 1 \\ 14 \end{bmatrix}$$

Std Matrix

$$T\left[\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right]$$

$$T\left[\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right]$$