

The eigenvectors VI, ..., Vg form a basis for 185. This means

$$\bar{X}_{e} = C_{1}\bar{V}_{1} + C_{2}\bar{V}_{2} + C_{3}\bar{V}_{3} + C_{4}\bar{V}_{4} + C_{5}\bar{V}_{5}$$

for some choice of scalars c1, -, G

$$T^{k}\overline{x}_{0} = T^{k}(C_{1}\overline{v}_{1} + \cdots + C_{g}\overline{v}_{g})$$

$$= C_{1}T^{k}\overline{v}_{1} + \cdots + C_{g}T^{k}v_{g}$$

$$= C_{1}T^{k}\overline{v}_{1} + C_{2}\lambda_{z}^{k}v_{z} + \cdots + C_{g}\lambda_{g}^{k}$$

So:
$$\overline{X}_{\infty} = \lim_{k \to \infty} |k| \overline{X}_{\infty}$$

$$= \lim_{k \to \infty} (c_1 | \overline{Y}_1 + c_2 | \overline{Y}_2 + \cdots + c_n | \overline{Y}_1)$$

$$= c_1 \overline{Y}_1$$

Thus the vector Xoo that we want satisfies

$$\{AND \times \infty \text{ is in } \mathcal{E}_1(T) \}$$

· Xas is a probability vector

> This makes X00 a Steady-State vector for T

Now we'll see that we can find \$00 without doing the full diagonalization process

· Eiganvalues of T

$$\lambda_1, \lambda_2, \lambda_3, \lambda_4, \lambda_5$$

$$\lambda_1 = 1$$

$$|\lambda_2| = |\lambda_3| \times 0.7$$

$$|\lambda_4| = |\lambda_5| \approx 0.3$$

$$\cdot$$
 T = PPP-1

$$\mathfrak{J} = \begin{bmatrix} 1 & & & \\ \lambda_2 & & & \\ & \lambda_3 & & \\ & & \lambda_6 \end{bmatrix}$$

$$P = \begin{bmatrix} \overline{V_1} & \overline{V_2} & \overline{V_3} & \overline{V_4} & \overline{V_5} \end{bmatrix}$$

Thus,
$$\overline{X}_{\infty} = \lim_{K \to \infty} \overline{X}_{K}$$

$$= \lim_{K \to \infty} \overline{X}_{K} \overline{X}_{\infty}$$

$$= \overline{X}_{\infty} - \overline{X}_{\infty}$$

S: D

$$= \rho \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 0 & \vdots \\ 0 & \cdots & 0 & 0 \end{bmatrix} \rho^{-1}$$