

6.5 Least Squares

When $A\bar{x} = \bar{b}$ is inconsistent we want a process for finding best possible approximate solution
 $[A | \bar{b}]$ least squares solution

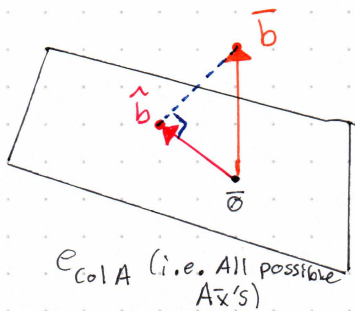
- Handout 20 was provided

Studying $A\bar{x} = \bar{b}$

How do we find a least squares solution?

Idea:

- We can solve $A\bar{x} = \bar{b}$ precisely when \bar{b} is in column A (column space A).
- If \bar{b} is not in Column A (column space of A) then the closest vector to \bar{b} that is in $\text{Col } A$ is $\text{proj}_{\text{Col } A} \bar{b}$.



\bar{b} is in $\text{Col } A \iff A\bar{x} = \bar{b}$

has a solution

Notice $\bar{b} - \hat{b}$ is orthogonal to $\text{Col } A$, so $\bar{b} - \hat{b}$ is orthogonal to every column of A .
 write $A = [\bar{a}_1 \ \bar{a}_2 \ \dots \ \bar{a}_n]$

then

$$\bar{a}_1 \cdot (\bar{b} - \hat{b}) = 0 \iff \bar{a}_1^T \cdot (\bar{b} - \hat{b}) = 0$$

\vdots

\vdots

$$\bar{a}_n \cdot (\bar{b} - \hat{b}) = 0 \iff \bar{a}_n^T \cdot (\bar{b} - \hat{b}) = 0$$

Thus,

$$A^T(\bar{b} - \hat{b}) = \bar{0}$$

$$A^T\bar{b} - A^T\hat{b} = \bar{0}$$

$$A^T\bar{b} = A^T\hat{b}$$

$$\uparrow A\hat{x} = \hat{b}$$

$$A^T\bar{b} = A^TA\hat{x}$$

Theorem

\hat{x} is a least squares solution to $A\bar{x} = \bar{b} \iff \hat{x}$ is an actual solution to

$$\underbrace{A^TA}_{\text{new } A} \bar{x} = \underbrace{A^T\bar{b}}_{\text{new } b}$$

Last Time:

Theorem
 \hat{x} is a best possible approximation solution to $A\hat{x} \approx \bar{b}$ \iff \hat{x} is a least squares solution to $A\hat{x} = \bar{b}$
 $[A \mid \bar{b}]$

\hat{x} is a (actual) solution to $A^T A \hat{x} = A^T \bar{b}$
 $\text{new } A \quad \text{new } \bar{b}$

Review
#11proj_W(\bar{v})

$$\bar{v} = \begin{bmatrix} -19 \\ -14 \\ -14 \end{bmatrix}$$

$$W = \text{Span} \left(\underbrace{\begin{bmatrix} -2 \\ 6 \\ -2 \end{bmatrix}}_{W_1}, \underbrace{\begin{bmatrix} 6 \\ 6 \\ 12 \end{bmatrix}}_{W_2} \right)$$

$$\text{proj}_W(\bar{v}) = \text{proj}_{W_1}(\bar{v}) + \text{proj}_{W_2}(\bar{v})$$

$$= \frac{\bar{v} \cdot \bar{w}_1}{\bar{w}_1 \cdot \bar{w}_1} \bar{w}_1 + \frac{\bar{v} \cdot \bar{w}_2}{\bar{w}_2 \cdot \bar{w}_2} \bar{w}_2$$

$$= \frac{-18}{44} \begin{bmatrix} -2 \\ 6 \\ -2 \end{bmatrix} + \frac{-366}{216} \begin{bmatrix} 6 \\ 6 \\ 12 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{36}{44} \\ \frac{-108}{44} \\ \frac{36}{44} \end{bmatrix} + \begin{bmatrix} -2196/216 \\ -2196/216 \\ -4392/216 \end{bmatrix} = \begin{bmatrix} \frac{36}{44} - 2196/216 \\ \frac{-108}{44} - 2196/216 \\ \frac{36}{44} - 4392/216 \end{bmatrix}$$

$$= \begin{bmatrix} 36/44 - 2196/216 \\ -108/44 - 2196/216 \\ 36/44 - 4392/216 \end{bmatrix}$$

Sidework

$$\bar{v} \cdot \bar{w}_1 = 19 \cdot 2 - 14 \cdot 6 + 14 \cdot 2 = -18$$

$$\bar{w}_1 \cdot \bar{w}_1 = (-2)^2 + (6)^2 + (-2)^2 = 44$$

$$\bar{v} \cdot \bar{w}_2 = -19 \cdot 6 - 14 \cdot 6 - 14 \cdot 12 = -366$$

$$\bar{w}_2 \cdot \bar{w}_2 = 6^2 + 6^2 + (12)^2 = 216$$

HW12, Q4

$$A = \begin{bmatrix} 49 & 24 \\ -112 & -55 \end{bmatrix}$$

$$P = [\bar{v}_1 \quad \bar{v}_2]$$

$$D = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \rightarrow \begin{bmatrix} 7 & 0 \\ 0 & -1 \end{bmatrix}$$

↑ ↑ corresponding eigenvalues

$$A = P D P^{-1}$$

eigenvalues

$$P(\lambda) = \det(A - \lambda I)$$

$$= \det \left(\begin{bmatrix} 49 - \lambda & 24 \\ -112 & -55 - \lambda \end{bmatrix} \right)$$

$$= (49 - \lambda)(-55 - \lambda) - 24(-112)$$

$$= \lambda^2 - 6\lambda - 2695 + 2688$$

$$= \lambda^2 - 6\lambda - 7$$

$$P(\lambda) = 0$$

$$\lambda^2 - 6\lambda - 7 = 0$$

$$(\lambda + 7)(\lambda - 1) = 0$$

$$\boxed{\lambda = -7, 1}$$