# **Matthew Hong**

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#### **EDUCATION**

University of Southern California, Los Angeles, California

# **USC Viterbi School of Engineering**

# Bachelor of Science in Mechanical Engineering, Minor in Computer Science

Aug 2020 - May 2024

- Relevant Major Coursework: Introduction to Matlab, Statics, Fundamentals of Thermodynamics, Strength of
  Materials, Dynamics, Dynamic Systems, Mechoptronics (In progress), Dynamics of Fluids (In progress),
  Computer-Aided Analyses for Aero-Mechanical Design (In Progress)
- Relevant Minor Coursework: Introduction to Programming, Discrete Methods in Computer Science, Data Structures and Object Oriented Design (In Progress)

#### WORK EXPERIENCE

## Research Assistant in the Realization of Robotic Systems Lab (RROS), USC, Los Angeles, CA Jan 2022 - present

• Conducting research on rapidly reconfigurable, deployable robotics and automation technologies with an emphasis on robots that can perform household tasks

### Engineering Intern, Mixel Inc, San Jose, CA

Jun 2019 - Jul 2019

- Responsible for performing Conformance suite tests(CTS) on MIPI PHYs.
- Wrote Python scripts allowing the automatic sweeping of electrical parameters to dramatically reduce the overall testing and automatically generate CTS reports.
- Ported the Mentor DxDesigner schematic database of MIPI PLL IP to Pyxis database and ran Calibre SVS to verify the equivalence of the schematic databases.

## Local Poke, Pleasanton, CA

Aug 2020 - Aug 2021

- Part-time job working 8-10 hours on the weekends
- Prepared food, served customers, managed kitchen, and trained new hirees

## ACADEMIC/PERSONAL PROJECTS

#### **Robotic Pruning**

- Utilized ROS libraries to create the trajectory of bimanual arms and motion planning of Baxter robot
- Iterative design of end effectors (gripper and shears) using SolidWorks with servo motors integrated and controlled through Arduino
- Used OpenCV and image processing techniques to detect patterns for leaves to prune in real-time
- Successfully found four different orientations and created a trajectory of two arms to prune leaves in those orientations

#### **Coffee Shop Mapper**

- Developed a website using NodeJS that allows users to search for coffee shops based on certain filters such as location, hours of operation, and popular drinks
- Primarily worked as project manager with the responsibility of scheduling meetings, forming deadlines, and ensuring project goals were well articulated

# **3D Truss Bridge**

• Collaborated with a team of engineering students to design, test, and produce a truss bridge made out of Polylactic Acid (PLA) using Finite Element Analysis and 3D modeling features in Solidworks

#### **SKILLS**

- Languages: C++, Java, Python, SQL, JavaScript/HTML/CSS, MATLAB
- Frameworks and Libraries: ROS, NodeJS
- CAD: Solidworks, NX, Fusion 360, AutoCAD
- Tools: Git, Docker, Linux, Excel