## **Doctors of Intelligence & Technology**

### Installation for TS300 (SR10)



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### Introduction

This user manual is used for the installation of TS100 generated by SZdoit, together with the motor connection with the development board. Specially, the installation is very similar to the other T series tank chassis from SZdoit, excluding the shock suspension. Therefore, the installation is very convenient.

# 1. Installation for Driving wheel (two wheels for one TS300)

- a) Material for one driving wheel:
  - 1) Wheel piece: 2pcs
  - 2) Aluminum alloy coupling: 1pcs (with 3 types for the different motors:  $\Phi 4$ ,  $\Phi 5$ ,  $\Phi 6$ mm, the default size is  $\Phi 4$ mm)
  - 3) 17mm copper pillar: 3pcs
  - 4) M3\*8 screw: 6pcs
  - 5) M4\*10: 1pcs
  - 6) Jackscrew: 2pcs

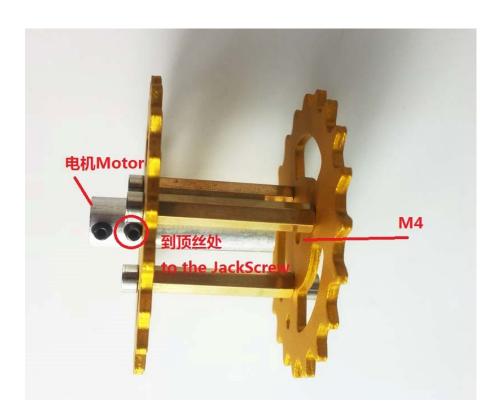


b) Firstly, put jackscrew to aluminum alloy coupling, and let copper pillar to wheel pieces





**c**) After install the two wheel pieces together, and then let the coupling pu through the wheel piece with big hole firstly. Note: (1) let the location hole align with each other; (2) the wheel piece with small hole is connected to M4 screw, and the other is connected to motor.





# 2. Installation for bearing wheel (one TS300 needs 10pcs bearing wheel)

a) material for one bearing wheel:

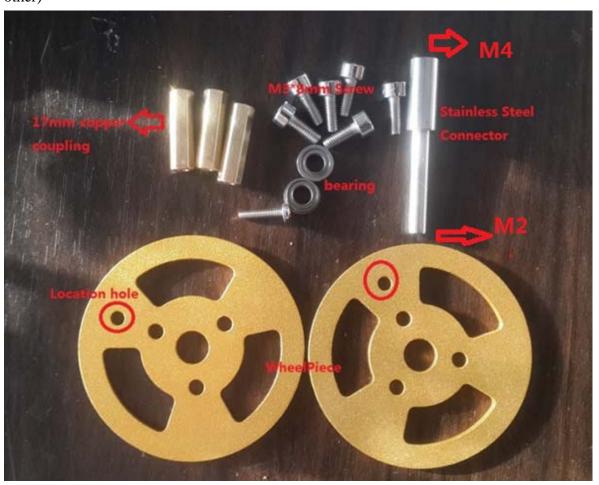
1) 17mm copper pillar: 3pcs

2) M3\*8 screw: 6pcs

3) stainless steel connector: 1pcs

4) M2 screw: 1pcs5) cup bearing: 2pcs

6) wheel piece: 2pcs (note: when install the wheel, please let the location hole is aligned with each other)



d) Install the copper pillar to the 2pcs wheel pieces Firstly, install 3pcs copper pillar to one wheel piece



e) Then, let another pcs wheel piece to install the pillar to it. Note that, please let the location is aligned with each other.



f) Let one cup bearing through the stainless steel



g) Then install one wheel piece to install the stainless steel with cup bearing, and later install another wheel piece. Use a M2 screw to fix the outside wheel piece.



Some notation when install the bearing wheel

- 1) Align the wheel pieces;
- 2) After installation the bearing wheel. Let the bearing wheel turn to test whether it is smooth. If not, then loose the M2 screw.

## 3. Install the shock suspension (the total is 8pcs, including left and right 4pcs)

a) Materials when install a shock suspension:

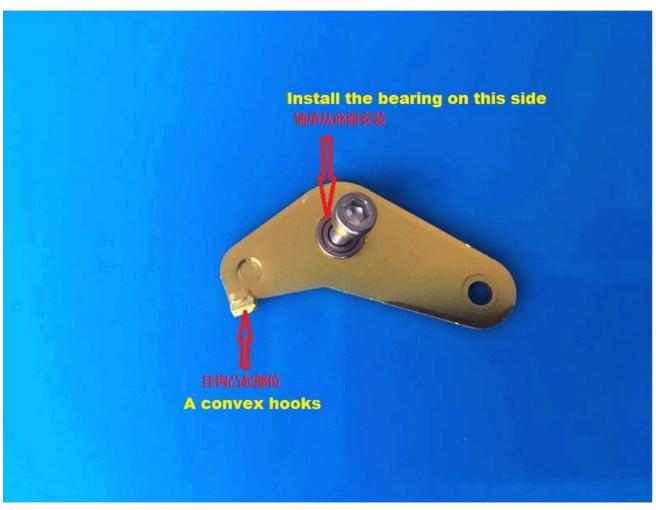
installed bearing wheel: 1pcs
shock suspension bracket: 1pcs

3) cup bearing: 1pcs4) M4\*8 screw: 2pcs5) M4 screw nut: 1pcs

6) spring: 1pcs



b) Firstly, put the cup bearing into the centre hole of the shock suspension bracket. Importantly, the hook must on the top surface.

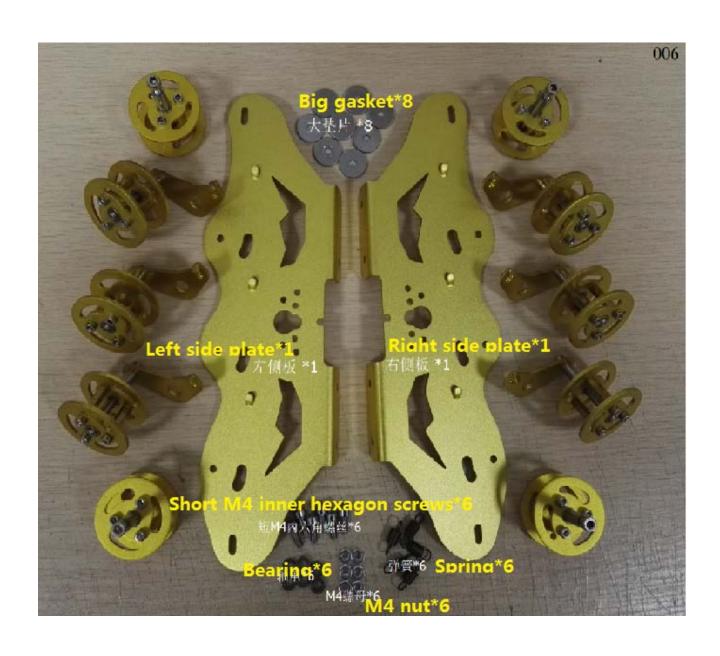


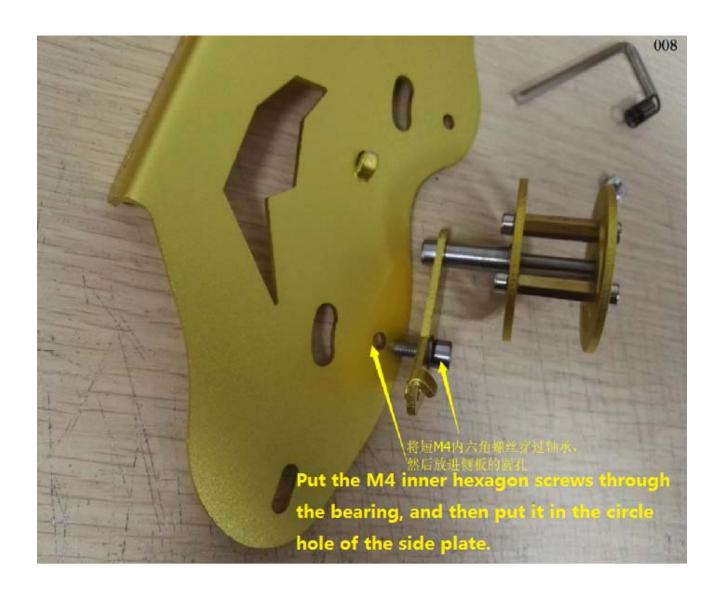
c) Use M4\*8 screw to connect the bearing wheel and the shock suspension bracket.



d) Then, use M4\*8 screw and nut to fix on the side plate, shown in the following picture

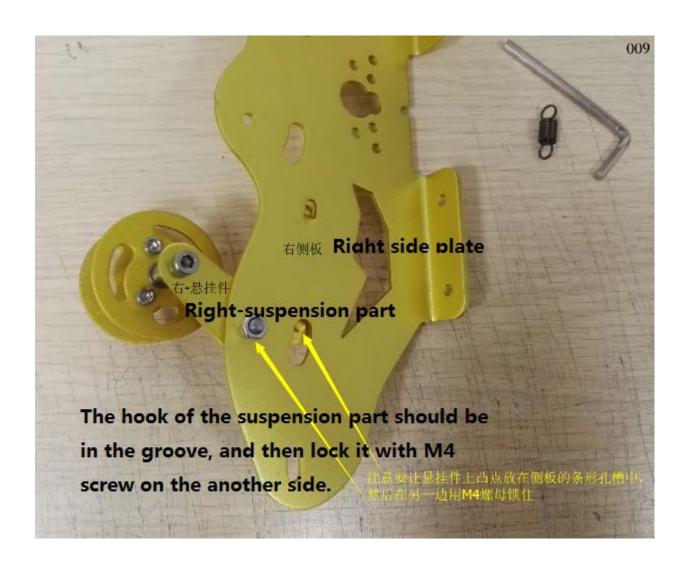


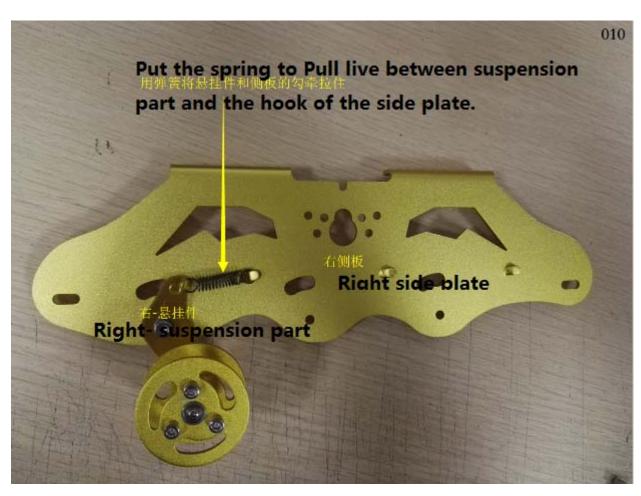






Importantly, you must the direction of the bearing wheels are the same, shown in the following picture



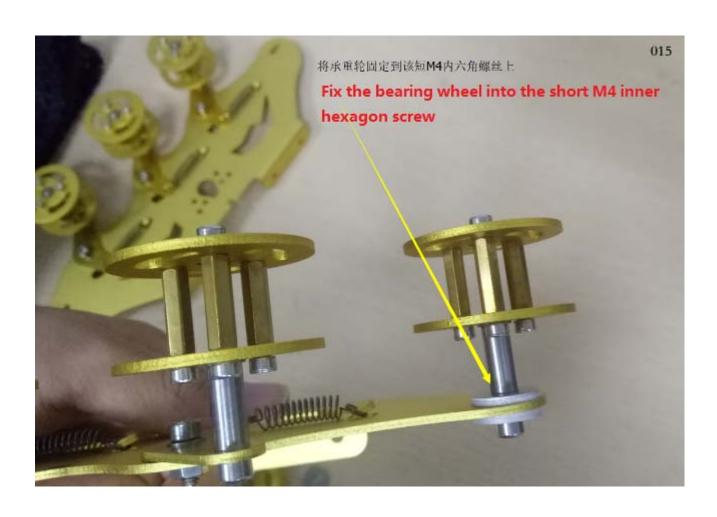




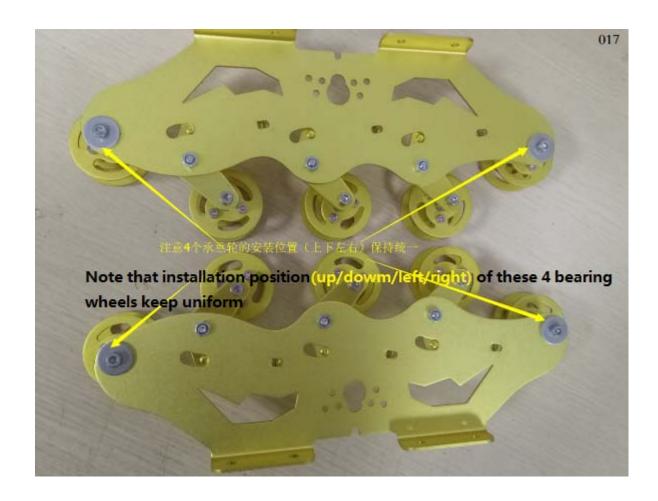












# 4. Installation a bearing wheel to the side plate (left and right)

The wheel can adjust the length of track.

a) Material when install a bearing wheel

bearing wheel: 1pcs
16mm gasket: 2pcs
M4 screw: 1pcs

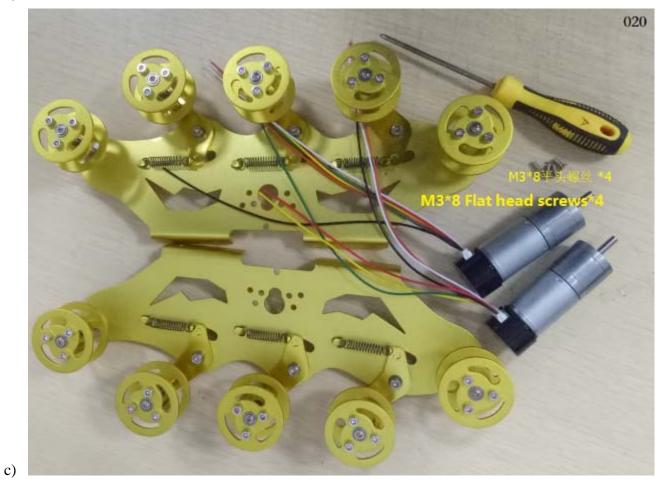
b) Leave enough space to adjust the track when install this bearing wheel to the side plate

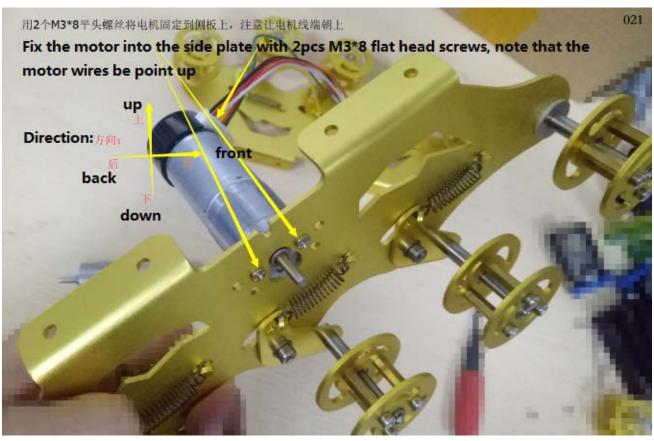


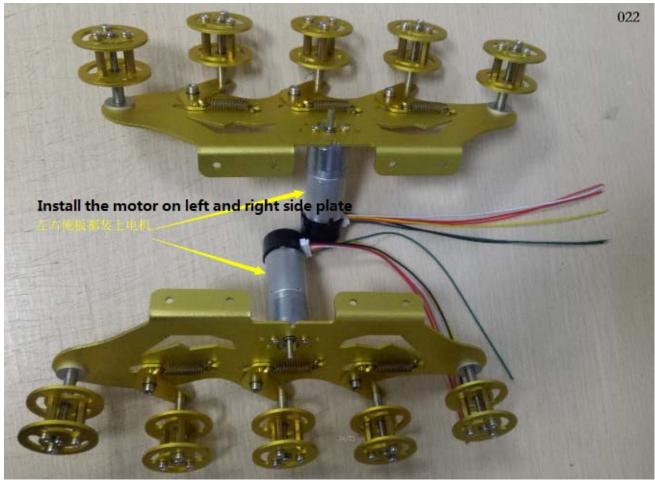
## 5. Summary

- a) materials
  - 1) metal panel: 1pcs
  - 2) left and right installed side plate with bearing wheel
  - 3) installed driving wheel: 2pcs
  - 4) motor: 2pcs
  - 5) track: 2pcs
  - 6) M3\*12 screw: 8pcs
  - 7) M3 nut: 8pcs
  - 8) M3\*10 screw: 4pcs

### b) Install the motor with m3\*10 screw.

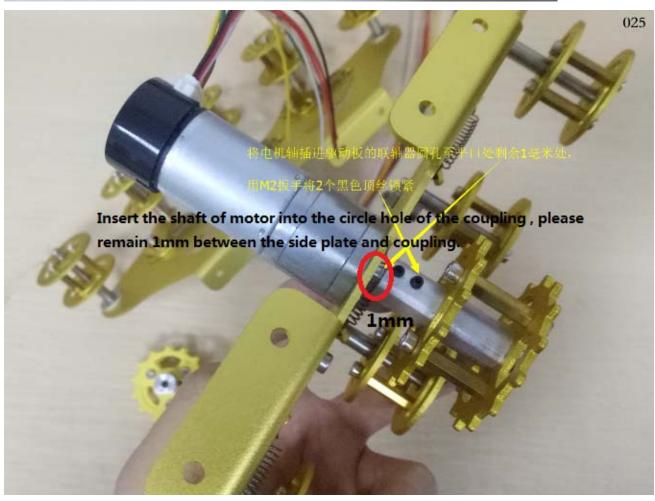






### d) Install the driving wheel and connect the motor



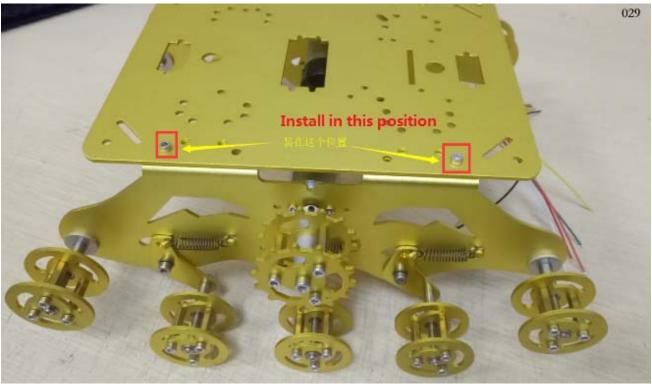


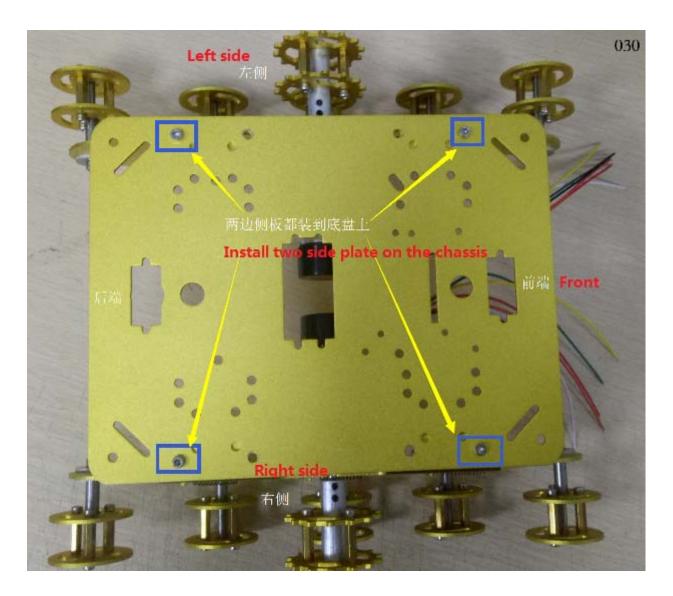


### e) Install the metal panel

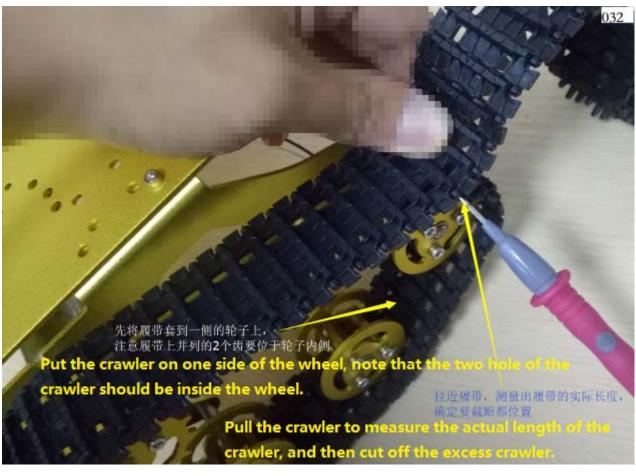


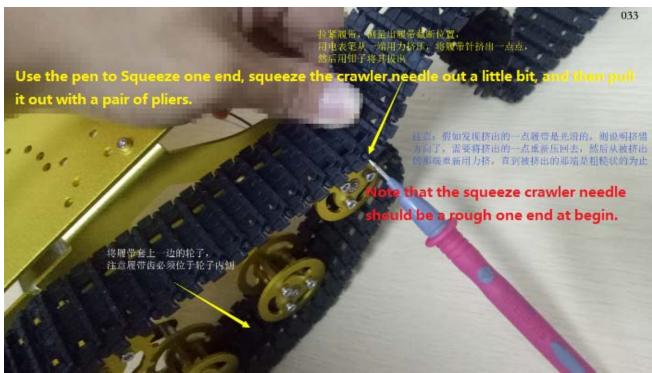






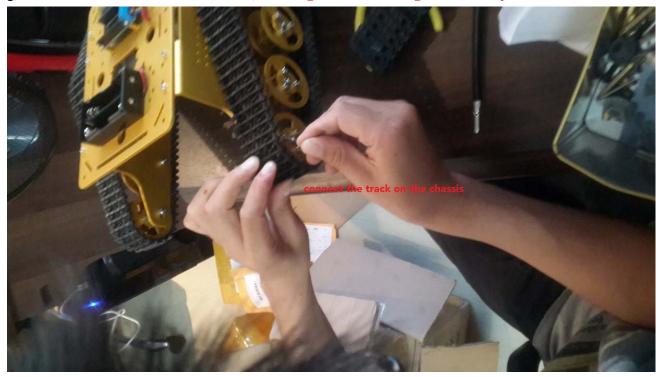
f) Adjust the length of the track and install it to the car chassis. Note, the track can be changed at random length.



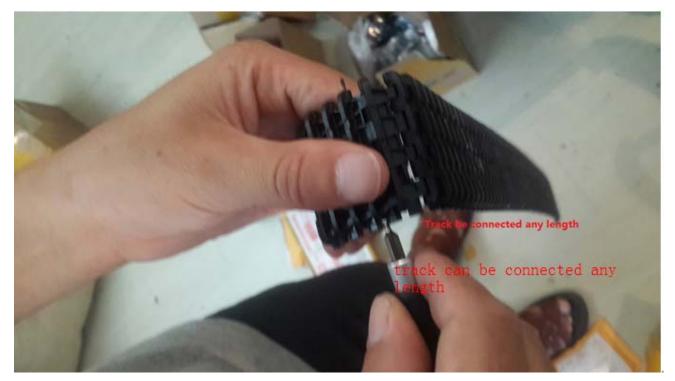




g) Install the track to the wheel. Note, the length can be changed randomly.



### h) The complete TS100 after installation







#### **Some notations**

- 1) Align the location hole when install the wheels;
- 2) Track can be changed randomly;
- 3) Note the screw models when installs the car;
- 4) M2 doesn't fix to tight when install the bearing wheel;
- 5) by adjust the location of the end of bearing wheel, can adjust the track;
- 6) the same direction is necessary when install the shock suspension;

### 6. Connection for the motor



This motor has Hall sensor, which can be used to measure the speed. If we face the shaft of the motor, the interface is VM (power for motor), GM( GND for motor); V(power for Hall sensor), G (GND for Hall sensor); S1(signal from the first sensor), S2 (signal from the  $2^{nd}$  sensor).



VM, GM is the motor wiring, V, G is the sensor power supply line, S1, S2 is the sensor signal output line.

## 其中,VM、GM为电机接线,V、G为传感器供电线,S1,S2为传感器信号输出线。



G-GND for Hall Sensor— S1-Singal from the 1st Hall Sensor S2-Singal from the 2nd Hall Sensor

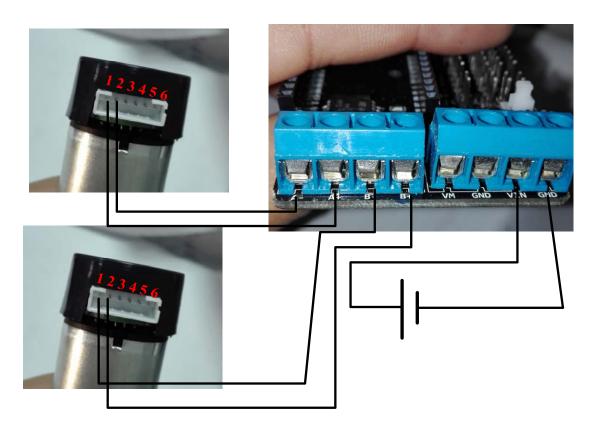
#### C. Product Parameters:

72.5		Conditions)	
_	性使用条件 (Standard Operation	照 (Specification)	检验方法 (Test Method)
10.	項目(Item)		电压表 ( Multimeter )
1.1	翻译明任 ( Rated Voltage )	DC 9.0V	etica ( Muniment )
1.2	速比 ( Gear Ratio)	1/75	季盛 (Handle)
1.3	马达转向(Rotation)	CW	手感 (Handle)
1.4	委员(Motor Position)	检查时水平 (All position in horizontal)	温度计 ( Thermometer )
1.5	检测时时温度范围 Temperature	0 Degree - 30 Degree Celsius	
1.6	检测时时指度范围 Humidity	30% ~ 95%	沮疫计 ( Hygroscope )
2. 电柱	几性能 (Performance Of Moto	ors)	
NO.	In EN (Item)	规格(Specification)	检验方法 (Test Method)
2.1	空程转速 ( No-load Speed )	11500±10%rpm	转速表 (Flash Speed Indicator)
22	空载电流 (No-load Current )	180mA(Max)	电流表 (DC Power Supply)
23	送转电流 (Stall Current)	4500mA(Max)	电流表 (DC Power Supply)
2.4	指转力矩 (Stall Torque)	160g.cm	扭力计 (Torque Measure)
	机性能(Performance of Gea	ar motors)	
NO.	项目(Item)	规格(Specification)	检验方法 (Test Method)
	輸出转速 (Output Speed)	150±10%rpm	转速表 (Flash Speed Indicator)
3.1	空程电流 (No-load Current)	200mA(Max)	电流表 (DC Power Supply)
3.2		4500mA(Max)	电流表 (DC Power Supply)
3.3	通转电流 (Stall Current)	9.5kg.cm	祖力计 (Torque Measure)
3.4	地勢力矩 (Stall Torque)	3000g.cm	組力計 (Torque Measure)
3.5	负载力矩(Rated Torque) 负载电流(Rated Current)	1200mA(Max)	电流表 (DC Power Supply)
3.6	负载电流(Rated Current) 负载转速(Rated Speed)	100±10%rpm	转速表 (Flash Speed Indicator)
3.7	负载转速 ( Kated Speed ) 聯音 30CM ( Noise )	S6dB	分贝仪(Digital Sound Levd Meter
3.8			
4. 基	本尺寸 (The Dimension )	规格 ( Specification)	检验方法 (Test Method)
NO.	项目(Item)		根尺 (Vernier Calipers)
4.1	結伸尺寸 (The Outside Shaft Length)		治具 (Frock)
4.2	轴向间旋 (Shaft End Play)	0.05-0.50mm	治異 (Frock)
4.3	想孔 (Screw Size )	M3.0	· 表尺 (Vernier Calipers)
4.4	出驗查径 (Dia.of shaft)	Ф4mm D3.5	
4,5	外形安装尺寸 (Outline Mounting Dimension)	Refer to the Outline Drawing	治典和卡尺 Calipe

If you use our controller kit, you can get it from the smartarduino.com, and the connection is shown in the following.



NodeMCU kit



Connection

