

Servo Control From Python

EGR 445/545: PA 2

Due: 05/23/19

Overview

In this assignment, you are essentially combining HW 2 and PA 1 and demonstrating that you can command one servo over its entire range of motion from Python.

Python Requirements

Demonstrate to the instructor that you can enter values between 1000 and 2000 in Python and move the servo through out its entire 180 degree range of motion. Command the servo to move from 0 to 180 degrees in several increments with a pause between each one using a for loop.