

Week 1 Exercise Solutions

Gov January Linear Algebra Review

2021-01-04

1. (Strang 1.1.4) From the vectors, $v = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ and $w = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$, find the components of $3v + w$ and $cv + dw$.

$$3v + w = (7, 5) \text{ and } cv + dw = (2c + d, c + 2d).$$

2. (Strang 1.2.1) Calculate the dot products $u \cdot v$ and $u \cdot w$ and $u \cdot (v + w)$ and $w \cdot v$:

$$u = \begin{bmatrix} -0.6 \\ 0.8 \end{bmatrix} \quad v = \begin{bmatrix} 4 \\ 3 \end{bmatrix} \quad w = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$u \cdot v = -2.4 + 2.4 = 0,$$

$$u \cdot w = -.6 + 1.6 = 1,$$

$$u \cdot (v + w) = u \cdot v + u \cdot w = 0 + 1,$$

$$w \cdot v = 4 - 6 = -2 = v \cdot w.$$

3. (Strang 1.2.2) Compute the lengths $\|u\|$, $\|v\|$, and $\|w\|$ of the vectors in the last problem. Check the Schwarz inequalities $|u \cdot v| \leq \|u\|\|v\|$ and $|v \cdot w| \leq \|v\|\|w\|$.

$\|u\| = 1$ and $\|v\| = 5$ and $\|w\| = \sqrt{5}$. Then $|u \cdot v| = 0 < (1)(5)$ and $|v \cdot w| = 10 < 5\sqrt{5}$, confirming the Schwarz inequality.

4. (Strang 1.2.19 and 1.2.21) There are two equivalent ways to write the triangle inequality:

$$\|v + w\|^2 \leq (\|v\| + \|w\|)^2 \quad \Longleftrightarrow \quad \|v + w\| \leq \|v\| + \|w\|$$

Use the Schwarz inequality to prove the first of these two inequalities. Hint: use these facts about dot products: $v \cdot w = w \cdot v$ and $u \cdot (v + w) = u \cdot v + u \cdot w$.

First, recall that $\|a\|^2 = (a \cdot a)^2$.

Let's look at $\|v + w\|^2 = ((v + w) \cdot (v + w))$. Note that the following equality holds if we use the given rules in the right way (1.2.19):

$$\begin{aligned} (v + w) \cdot (v + w) &= (v + w) \cdot v + (v + w) \cdot w && \text{(fact 2)} \\ &= v \cdot (v + w) + w \cdot (v + w) && \text{(fact 1)} \\ &= v \cdot v + v \cdot w + w \cdot v + w \cdot w && \text{(fact 1)} \\ &= v \cdot v + 2v \cdot w + w \cdot w && \text{(fact 2)} \\ &= \|v\|^2 + 2v \cdot w + \|w\|^2 && \text{(definition of length)} \end{aligned}$$

Now, let's take for given the Triangle inequality which says that $2v \cdot w \leq 2||v|| \cdot ||w||$ (technically there's an absolute value on the left, but if it's negative, the inequality *definitely* holds true!). We can apply this to the middle term in the right hand side of the above equality to get the answer:

$$\begin{aligned} ||v + w||^2 &= (v + w) \cdot (v + w) \\ &= ||v||^2 + 2v \cdot w + ||w||^2 \\ &\leq ||v||^2 + 2(||v|| \cdot ||w||) + ||w||^2 && \text{(Triangle Ineq.)} \\ &= (||v|| + ||w||)^2 && \text{(quadratic factorization)} \end{aligned}$$

5. (Strang 1.2.29) If $||v|| = 5$ and $||w|| = 3$, what are the smallest and largest possible values of $||v - w||$? What are the smallest and largest possible values of $v \cdot w$?

For a specific example, pick $v = (1, 2, -3)$ and then $w = (-3, 1, 2)$. In this example, using the **cosine of angle** rule on p. 18, $\cos \theta = v \cdot w / (||v|| \cdot ||w||) = -7 / \sqrt{14}\sqrt{14} = -1/2$ and $\theta = 120^\circ$. This always happens when $x + y + z = 0$:

$$v \cdot w = xz + xy + yz = \frac{1}{2}(x + y + z)^2 - \frac{1}{2}(x^2 + y^2 + z^2)$$

This is the same as $v \cdot w = 0 - \frac{1}{2}||v|| \cdot ||w||$. Then $\cos \theta = \frac{1}{2}$.

6. (Strang 2.1.9) Compute each Ax by dot products of the rows with the column vector:

$$\text{(a)} \begin{bmatrix} 1 & 2 & 4 \\ -2 & 3 & 1 \\ -4 & 1 & 2 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 3 \end{bmatrix} \quad \text{(b)} \begin{bmatrix} 2 & 1 & 0 & 0 \\ 1 & 2 & 1 & 0 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 2 \end{bmatrix}$$

(a) $Ax = (18, 5, 0)$

(b) $Ax = (3, 4, 5, 5)$

7. (Strang 2.1.10) Compute each Ax from the previous question as a combination of the columns of A .

Multiplying as linear combinations of the columns gives the same $Ax = (18, 5, 0)$ and $(3, 4, 5, 5)$. By rows or by columns: 9 separate multiplications when A is 3 by 3.

8. (Strang 2.2.1-2) Use elimination to solve the following system of linear equations:

$$\begin{aligned} 2x + 3y &= 1, \\ 10x + 9y &= 11. \end{aligned}$$

If the right side changed to $(4, 44)$ what would the answer be?

Multiply row 1 by 5 and subtract from row 2 to get row 1 of the augmented matrix as $[1 \mid 6]$. The pivots to circle are 2 and -6. And the solution is $(2, -1)$.

Multiplying the RHS by 4 would multiply the solution also by 4 to produce $(8, -4)$.

9. (Strang 2.3.24) Apply elimination to the 2 by 3 augmented matrix $[A \mid b]$. What is the triangular system $Ux = c$? What is the solution x ?

$$Ax = \begin{bmatrix} 2 & 3 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 17 \end{bmatrix}.$$

The upper triangular matrix is

$$\left[\begin{array}{cc|c} 2 & 3 & 1 \\ 0 & -5 & 15 \end{array} \right]$$

We can either further reduce or perform back substitution to get $x_1 = 5$ and $x_2 = -3$.

10. (Strang 2.4.1) Let A be 3 by 5, B be 5 by 3, C be 5 by 1, and D be 3 by 1. All entries of all of these matrices are 1. Which of the following matrix operations are allowed, and what are the results?

$$BA \quad AB \quad ABD \quad DC \quad A(B + C)$$

BA is 5×5 . AB is 3×3 . ABD is 3×1 . DC and $A(B + C)$ are not defined.

11. (Strang 2.5.12) If the product $C = AB$ is invertible (A and B are square), then A itself is invertible. Find a formula for A^{-1} that involves C^{-1} and B .

$A^{-1} = BC^{-1}$ (see review slides for steps).

12. (Strang 2.5.13) If the product $M = ABC$ of three square matrices is invertible, then B is invertible. (So are A and C .) Find a formula for B^{-1} that involves M^{-1} and A and C .

$M^{-1} = C^{-1}B^{-1}A^{-1}$ so multiply the left by C and the right by A . We get $B^{-1} = CM^{-1}A$.

13. (Strang 2.7.39, Challenge) Suppose Q^T equals Q^{-1} (transpose equals inverse, so $Q^T Q = I$).

- (a) Show that the columns q_1, \dots, q_n are the unit vectors: $\|q_i\|^2 = 1$.
 (b) Show that every two different columns of Q are perpendicular: $q_1^T q_2 = 0$.

Start from $Q^T Q = I$ as in $\begin{bmatrix} q_1^T \\ q_2^T \end{bmatrix} \cdot \begin{bmatrix} q_1 & q_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$.

- (a) The diagonal entries give $q_1^T q_1 = 1$ and $q_2^T q_2 = 1$ (unit vectors).

(b) The off-diagonal entry is $q_1^T q_2 = 0$ (and in general $q_i^T q_j = 0$)

(c) The leading example for Q is the rotation matrix $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$.