Week 1 Exercise Solutions

Gov January Linear Algebra Review 2021-01-04

1. (Strang 1.1.4) From the vectors, $v=\begin{bmatrix}2\\1\end{bmatrix}$ and $w=\begin{bmatrix}1\\2\end{bmatrix}$, find the components of 3v+w and cv+dw.

3v + w = (7,5) and cv + dw = (2c + d, c + 2d).

2. (Strang 1.2.1) Calculate the dot products $u \cdot v$ and $u \cdot w$ and $u \cdot (v + w)$ and $w \cdot v$:

$$u = \begin{bmatrix} -0.6 \\ 0.8 \end{bmatrix}$$
 $v = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$ $w = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

 $u \cdot v = -2.4 + 2.4 = 0,$

$$u \cdot w = -.6 + 1.6 = 1$$
,

$$u \cdot (v+w) = u \cdot v + u \cdot w = 0+1,$$

$$w \cdot v = 4 - 6 = -2 = v \cdot w.$$

3. (Strang 1.2.2) Compute the lengths $\|u\|$, $\|v\|$, and $\|w\|$ of the vectors in the last problem. Check the Schwarz inequalities $|u \cdot v| \leq \|u\| \|v\|$ and $|v \cdot w| \leq \|v\| \|w\|$.

||u||=1 and ||v||=5 and $||w||=\sqrt{5}$. Then $|u\cdot v|=0<(1)(5)$ and $|v\cdot w|=10<5\sqrt{5}$, confirming the Schwarz inequality.

4. (Strang 1.2.19 and 1.2.21) There are two equivalent ways to write the triangle inequality:

$$\|\boldsymbol{v} + \boldsymbol{w}\|^2 \le (\|\boldsymbol{v}\| + \|\boldsymbol{w}\|)^2 \qquad \Longleftrightarrow \qquad \|\boldsymbol{v} + \boldsymbol{w}\| \le \|\boldsymbol{v}\| + \|\boldsymbol{w}\|$$

Use the Schwarz inequality to prove the first of these two inequalities. Hint: use these facts about dot products: $m{v}\cdot m{w} = m{w}\cdot m{v}$ and $m{u}\cdot (m{v}+m{w}) = m{u}\cdot m{v} + m{u}\cdot m{w}$.

First, recall that $||a||^2 = (a \cdot a)^2$.

Let's look at $||v+w||^2 = ((v+w)\cdot(v+w))$. Note that the following equality holds if we use the given rules in the right way (1.2.19):

$$(v+w)\cdot(v+w) = (v+w)\cdot v + (v+w)\cdot w \tag{fact 2}$$

$$= v \cdot (v+w) + w \cdot (v+w) \tag{fact 1}$$

$$= v \cdot v + v \cdot w + w \cdot v + w \cdot w \tag{fact 1}$$

$$= v \cdot v + 2v \cdot w + w \cdot w \tag{fact 2}$$

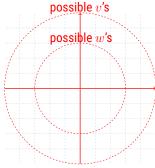
$$= ||v||^2 + 2v \cdot w + ||w||^2$$
 (definition of length)

Now, let's take for given the Triangle inequality which says that $2v \cdot w \leq$ $2||v|| \cdot ||w||$ (technically there's an absolute value on the left, but if it's negative, the inequality definitely holds true!). We can apply this to the middle term in the right hand side of the above equality to get the answer:

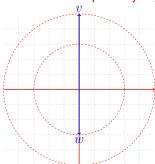
$$\begin{split} ||v+w||^2 &= (v+w)\cdot (v+w) \\ &= ||v||^2 + 2v\cdot w + ||w||^2 \\ &\leq ||v||^2 + 2(||v||\cdot ||w||) + ||w||^2 \\ &= (||v|| + ||w||)^2 \end{aligned} \qquad \text{(Triangle Ineq.)}$$

5. (Strang 1.2.29) If $\|\mathbf{v}\| = 5$ and $\|\mathbf{w}\| = 3$, what are the smallest and largest possible values of $\| {m v} - {m w} \|$? What are the smallest and largest possible values of $v \cdot w$?

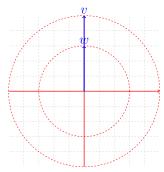
Part 1: If $v, w \in \mathbb{R}^2$, then geometrically we know the following:



The farthest v and w could be away from each other is 8: we could achieve this if v and w were perfectly negatively aligned, say, at (0,5) and (0,-3):



Incidentally, the Triangle inequality also gives us this bound. The closest would be if they were perfectly positive aligned, say, at (0,5) and (0,3):



Part 2: Using the **cosine of angle** rule on p. 18, we know that $\cos \theta = \frac{v \cdot w}{(||v|| \cdot ||w||)} =$ $\frac{v \cdot w}{15}$. The cosine of θ (the angle between v and w) is at most 1 (when they are perfectly positively aligned) and at least -1 (when they are perfectly negatively aligned). So the bounds for $v \cdot w$ are 15 (which we also know from the **Schwarz Inequality**) and -15.

6. (Strang 2.1.9) Compute each Ax by dot products of the rows with the column vector:

(a)
$$\begin{bmatrix} 1 & 2 & 4 \\ -2 & 3 & 1 \\ -4 & 1 & 2 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 3 \end{bmatrix}$$

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$$\begin{bmatrix} 1 & 2 & 4 \\ -2 & 3 & 1 \\ -4 & 1 & 2 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 3 \end{bmatrix}$$
 (b)
$$\begin{bmatrix} 2 & 1 & 0 & 0 \\ 1 & 2 & 1 & 0 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 2 \end{bmatrix}$$

(a)
$$Ax = (18, 5, 0)$$

(b)
$$Ax = (3, 4, 5, 5)$$

7. (Strang 2.1.10) Compute each Ax from the previous question as a combination of the columns of A.

Multiplying as linear combinations of the columns gives the same Ax =(18,5,0) and (3,4,5,5). By rows or by columns: 9 separate multiplications when A is 3 by 3.

8. (Strang 2.2.1-2) Use elimination to solve the following system of linear equations:

$$2x + 3y = 1,$$

$$10x + 9y = 11.$$

If the right side changed to (4, 44) what would the answer be?

Multiply row 1 by 5 and subtract from row 2 to get row 1 of the augmented matrix as [1 | 6]. The pivots to circle are 2 and -6. And the solution is (2, -1). Multiplying the RHS by 4 would multiply the solution also by 4 to produce (8, -4).

9. (Strang 2.3.24) Apply elimination to the 2 by 3 augmented matrix $[A \ b]$. What is the triangular system Ux = c? What is the solution x?

$$A\boldsymbol{x} = \begin{bmatrix} 2 & 3 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 17 \end{bmatrix}.$$

The upper triangular matrix is

$$\begin{bmatrix} 2 & 3 & | & 1 \\ 0 & -5 & | & 15 \end{bmatrix}$$

We can either further reduce or perform back substition to get $x_1\,=\,5$ and $x_2 = -3$.

10. (Strang 2.4.1) Let A be 3 by 5, B be 5 by 3, C be 5 by 1, and D be 3 by 1. All entries of all of these matrices are 1. Which of the following matrix operations are allowed, and what are the results?

$$BA$$
 AB ABD DC $A(B+C)$

BA is 5×5 . AB is 3×3 . ABD is 3×1 . DC and A(B+C) are not defined.

11. (Strang 2.5.12) If the product C = AB is invertible (A and B are square), then A itself is invertible. Find a formula for A^{-1} that involves C^{-1} and B.

$$A^{-1} = BC^{-1}$$
 (see review slides for steps).

12. (Strang 2.5.13) If the product M = ABC of three square matrices is invertible, then B is invertible. (So are A and C.) Find a formula for B^{-1} that involves M^{-1} and A and C.

 $M^{-1} = C^{-1}B^{-1}A^{-1}$ so multiply the left by C and the right by A. We get

- 13. (Strang 2.7.39, Challenge) Suppose Q^T equals Q^{-1} (transpose equals inverse, so $Q^TQ = I$).
- (a) Show that the columns q_1, \ldots, q_n are the unit vectors: $||q_i||^2 = 1$.
- (b) Show that every two different columns of Q are perpendicular: $\mathbf{q}_1^T \mathbf{q}_2 = 0$.

$$\text{Start from } Q^TQ = I \text{ as in } \begin{bmatrix} q_1^T \\ q_2^T \end{bmatrix} \cdot \begin{bmatrix} q_1 & q_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

- (a) The diagonal entries give $q_1^T q_1 = 1$ and $q_2^T q_2 = 1$ (unit vectors).
- (b) The off-diagonal entry is $q_1^T q_2 = 0$ (and in general $q_i^T q_i = 0$)
- (c) The leading example for Q is the rotation matrix $\begin{vmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{vmatrix}$.