# 7. Conditional Expectation

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Gov 2002 (Harvard)

#### Where are we? Where are we going?

- · Covered most aspects of multivariate distributions.
- Time to preview a feature of these distributions we'll care a lot a bout: conditional expectations.
- At its core: how the average of one variable varies with others.

# **Defining condition expectations**

#### Definition

The **conditional expectation** of Y conditional on X = x is:

$$\mu(\mathbf{x}) = \mathbb{E}[Y \mid \mathbf{X} = \mathbf{x}] = \begin{cases} \sum_{y} y \ \mathbb{P}(Y = y \mid \mathbf{X} = \mathbf{x}) & \text{discrete } Y \\ \int_{-\infty}^{\infty} y \ f_{Y \mid \mathbf{X}}(y \mid \mathbf{x}) dy & \text{continuous } Y \end{cases}$$

- Expected value of the conditional distribution of Y given X = x.
  - $\mathbf{X} = (X_1, X_2, \dots, X_k)$  is a random vector (k = 1) just an r.v.)
- Viewed as a function of x, it is the conditional expectation function (CEF)
  - How does the average value of Y change given different levels of X?

#### **Conditional expectation example**

	Support Gay	Oppose Gay	
	Marriage	Marriage	
	Y = 1	Y = 0	
Female $X = 1$	0.30	0.21	
Male $X = 0$	0.22	0.27	

• Conditional expectation of gay marriage support Y among men X=0?

$$\mathbb{E}[Y \mid X = 0] = \sum_{y} y \, \mathbb{P}(Y = y \mid X = 0)$$

$$= 0 \times \mathbb{P}(Y = 0 \mid X = 0) + 1 \times \mathbb{P}(Y = 1 \mid X = 0)$$

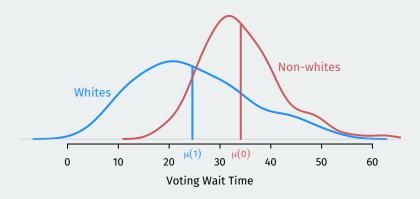
$$= 1 \times \frac{0.22}{0.22 + 0.27} = 0.45$$

## **CEF for binary covariates**

- · Example:
  - Y<sub>i</sub> is the time respondent i waited in line to vote.
  - $X_i = 1$  for whites,  $X_i = 0$  for non-whites.
- Then the mean in each group is just a conditional expectation:

$$\mu(\text{white}) = E[Y_i|X_i = \text{white}]$$
  
 $\mu(\text{non-white}) = E[Y_i|X_i = \text{non-white}]$ 

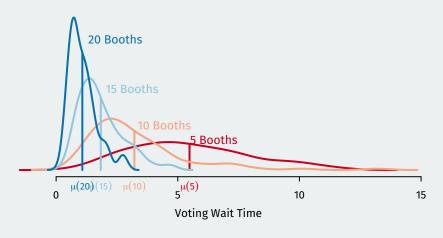
# Why is the CEF useful?



- The CEF encodes relationships between variables.
- If  $\mu$ (white)  $< \mu$ (non-white), so that waiting times for whites are shorter on average than for non-whites.
- Indicates a relationship **in the population** between race and wait times.

#### **CEF for discrete covariates**

- New covariate:  $X_i$  is the # of polling booths at citizen i's polling station.
- $\mu(x)$  is the mean of  $Y_i$  changes as  $X_i$  changes:



#### **CEF with multiple covariates**

• We can also CEF conditioning on multiple variables  $\mu(\mathbf{x})$ :

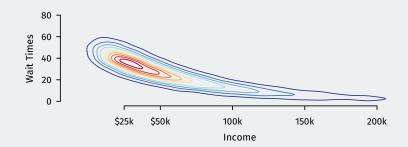
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\begin{split} \mu(\text{white}, \text{man}) &= \mathbb{E}[Y_i | X_i = \text{white}, Z_i = \text{man}] \\ \mu(\text{white}, \text{woman}) &= \mathbb{E}[Y_i | X_i = \text{white}, Z_i = \text{woman}] \\ \mu(\text{non-white}, \text{man}) &= \mathbb{E}[Y_i | X_i = \text{non-white}, Z_i = \text{man}] \\ \mu(\text{non-white}, \text{woman}) &= \mathbb{E}[Y_i | X_i = \text{non-white}, Z_i = \text{woman}] \end{split}
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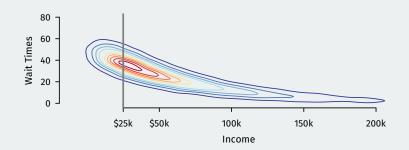
- Why? Allows more credible all else equal comparisons (ceteris paribus).
- Ex: average difference in wait times between white and non-white citizens of the same gender:

$$\mu(\text{white}, \text{man}) - \mu(\text{non-white}, \text{man})$$

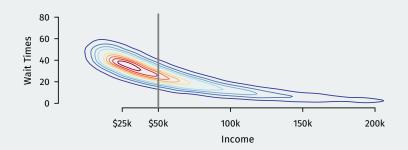
#### **CEF for continuous covariates**

- What if our independent variable,  $X_i$  is income?
- Many possible values of  $X_i \rightsquigarrow \text{many possible values of } \mathbb{E}[Y_i | X_i = x].$ 
  - Writing out each value of the CEF no longer feasible.
- Now we will think about  $\mu(x) = \mathbb{E}[Y_i | X_i = x]$  as function. What does this function look like:
  - Linear:  $\mu(x) = \alpha + \beta x$
  - Quadratic:  $\mu(x) = \alpha + \beta x + \gamma x^2$
  - Crazy, nonlinear:  $\mu(x) = \alpha/(\beta + x)$
- These are **unknown functions in the population**! This is going to make producing an estimator  $\hat{\mu}(x)$  very difficult!

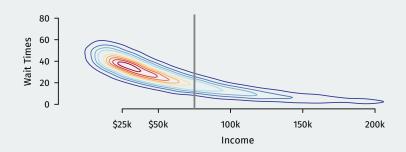


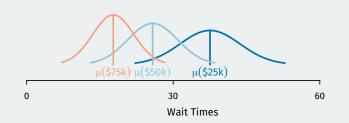


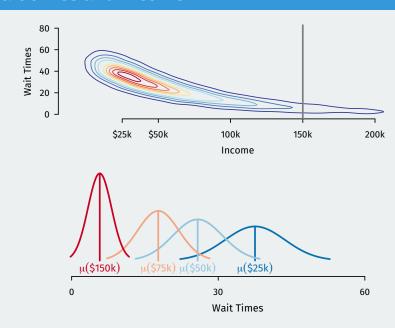












## **Conditional expectations as random variables**

- The conditional expectation is a function of **x**:  $\mu(\mathbf{x}) = \mathbb{E}[Y \mid \mathbf{X} = \mathbf{x}].$ 
  - Not random: for a particular x,  $\mu(x)$  is a number.
  - · Conditional expectation given an event.
- What about the conditional expectation given an r.v.,  $\mathbb{E}[Y \mid X]$ ?
  - Why? Best prediction about Y given we get to know X.
- Obtained by plugging r.v. into the CEF:  $\mathbb{E}[Y \mid X] = \mu(X)$
- This is itself a random variable! For binary X:

$$\mathbb{E}[Y \mid X] = \begin{cases} \mu(0) & \text{with prob. } \mathbb{P}(X = 0) \\ \mu(1) & \text{with prob. } \mathbb{P}(X = 1) \end{cases}$$

• Has an expectation,  $\mathbb{E}[\mathbb{E}[Y \mid X]]$ , and a variance,  $\mathbb{V}[\mathbb{E}[Y \mid X]]$ .

## Law of iterated expectations

#### Simple Law of Iterated Expectations

If  $\mathbb{E}[Y] < \infty$ , for any random vector **X**,  $\mathbb{E}\{\mathbb{E}[Y \mid \mathbf{X}]\} = E[Y]$ .

- Expectation of the conditional expectation is the marginal expectation.
  - Discrete version:  $\mathbb{E}\left[\mathbb{E}[Y\mid X]\right] = \sum_{x} \mathbb{E}[Y\mid X=x]\mathbb{P}(X=x) = \mathbb{E}[Y]$
  - Continuous version:  $\mathbb{E}\left[\mathbb{E}[Y\mid X]\right] = \int_{X} \mathbb{E}[Y\mid X=x]f_X(x)dx = \mathbb{E}[Y]$
- General version allows for two conditioning sets:

#### Law of Iterated Expectations

If  $\mathbb{E}|Y|<\infty$  , for any random vectors  $\mathbf{X}_1$  and  $\mathbf{X}_2$  ,

$$\mathbb{E}\left\{\mathbb{E}[Y\mid \mathbf{X}_1,\mathbf{X}_2]\mid \mathbf{X}_1\right\}=E[Y\mid \mathbf{X}_1].$$

• "Averaging" over what is not constant  $(\mathbf{X}_2)$ .

#### **Example: law of iterated expectations**

	Support Gay	Oppose Gay	
	Marriage	Marriage	Marginal
	Y = 1	Y = 0	
Female $X = 1$	0.30	0.21	0.51
Male $X = 0$	0.22	0.27	0.49
Marginal	0.52	0.48	

- $\mathbb{E}[Y \mid X = 1] = 0.59$  and  $\mathbb{E}[Y \mid X = 0] = 0.45$ .
- $\mathbb{P}(X = 1) = 0.51$  (females) and  $\mathbb{P}(X = 0) = 0.49$  (males).
- · Plug into the iterated expectations:

$$\mathbb{E}[\mathbb{E}[Y \mid X]] = \mathbb{E}[Y \mid X = 0]\mathbb{P}(X = 0) + \mathbb{E}[Y \mid X = 1]\mathbb{P}(X = 1)$$
$$= 0.45 \times 0.49 + 0.59 \times 0.51 = 0.52 = \mathbb{E}[Y]$$

## **Properties of conditional expectations**

- 1.  $\mathbb{E}[c(X)Y \mid X] = c(X)\mathbb{E}[Y \mid X]$  for any function c(X).
  - Example:  $\mathbb{E}[X^2Y\mid X]=X^2\mathbb{E}[Y\mid X]$  (If we know X, then we also know  $X^2$ )
- 2. If X and Y are independent r.v.s, then

$$\mathbb{E}[Y \mid X = x] = \mathbb{E}[Y].$$

3. If  $X \perp \!\!\!\perp Y \mid Z$ , then

$$\mathbb{E}[Y \mid X = x, Z = z] = \mathbb{E}[Y \mid Z = z]$$

4. Linearity:  $\mathbb{E}[Y + X \mid Z] = \mathbb{E}[Y \mid Z] + E[X \mid Z]$ 

#### **CEF errors and projection**

- CEF error:  $e = Y \mathbb{E}[Y \mid \mathbf{X}]$
- Properties of the CEF error:
  - 1.  $\mathbb{E}[e \mid \mathbf{X}] = 0$
  - 2.  $\mathbb{E}[e] = 0$
  - 3. If  $\mathbb{E}[|Y|^r] < \infty$  for  $r \ge 1$ , then  $\mathbb{E}[|e|^r] < \infty$
  - 4. For any function  $h(\mathbf{X})$ ,  $h(\mathbf{X})$  is uncorrelated with e:  $\mathbb{E}[h(\mathbf{X})e] = 0$
- Last property: CEF errors are orthogonal to the space of functions of X.
  - $\mathbb{E}[Y \mid X]$  is the **projection** of Y on the space of all functions of X.
  - Closest point in that space to Y.
- These properties are definitional, not assumptions.

## **Conditional Expectation as Best Predictor**

- Suppose we want to predict Y based on random vector X.
  - We can use any function  $g(\mathbf{X})$  as our predictor.
- · Mean squared error of our predictions:

$$\mathbb{E}\left[\left(Y-g(\mathbf{X})\right)^2\right]$$

- What function will minimize this error? The CEF,  $\mu(\mathbf{x})!$
- If  $E[Y^2] < \infty$ , then for any predictor  $g(\mathbf{X})$ ,

$$\mathbb{E}\left[\left(Y - g(\mathbf{X})\right)^{2}\right] \geq \mathbb{E}\left[\left(Y - \mu(\mathbf{X})\right)^{2}\right]$$

#### **Conditional Variance**

#### Definition

The **conditional variance** of a Y given X =is defined as:

$$\sigma^2(\mathbf{x}) = \mathbb{V}[\mathbf{Y} \mid \mathbf{X} = \mathbf{x}] = \mathbb{E}\left[(\mathbf{Y} - \boldsymbol{\mu}(\mathbf{x}))^2 \mid \mathbf{X} = \mathbf{x}\right]$$

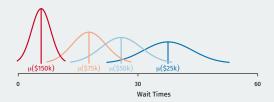
- · Spread of the conditional distribution around its expectation.
- · By definition, same as the variance of the CEF errors:

$$\mathbb{V}[Y \mid \mathbf{X} = \mathbf{x}] = \mathbb{V}[e \mid \mathbf{X} = \mathbf{x}] = \mathbb{E}[e^2 \mid \mathbf{X} = \mathbf{x}]$$

· Can re-express in the usual way:

$$\mathbb{V}[Y \mid \mathbf{X} = \mathbf{x}] = \mathbb{E}\left[Y^2 \mid \mathbf{X} = \mathbf{x}\right] - \left(\mathbb{E}[Y \mid \mathbf{X} = \mathbf{x}]\right)^2$$

## **Skedasticity**



- The error is **homoskedastic** if  $\sigma^2(\mathbf{x}) = \sigma^2$  does not depend on  $\mathbf{x}$ .
  - Homoskedasticity greatly simplifies math, but often strong and implausible.
- The error is **heteroskedastic** if  $\sigma^2(\mathbf{x})$  does depend on  $\mathbf{x}$ 
  - Hetero = different, skedastic = scatter
- Default assumption should be the less restrictive one: heteroskedastic

#### **Conditional variance as a random variable**

- Conditional variance is just a function of  $\mathbf{x}$ :  $\sigma^2(\mathbf{x}) = \mathbb{V}[Y \mid \mathbf{X} = \mathbf{x}]$
- $\sigma^2(\mathbf{X}) = \mathbb{V}[Y \mid \mathbf{X}]$  is an r.v. and a function of  $\mathbf{X}$ , just like  $\mathbb{E}[Y \mid \mathbf{X}]$ .
- With a binary X:

$$\mathbb{V}[Y \mid X] = \begin{cases} \sigma^2(0) & \text{with prob. } \mathbb{P}(X = 0) \\ \sigma^2(1) & \text{with prob. } \mathbb{P}(X = 1) \end{cases}$$

Theorem (Law of Total Variance/EVE's law):

$$\mathbb{V}[Y] = \mathbb{E}[\mathbb{V}[Y \mid \mathbf{X}]] + \mathbb{V}[\mathbb{E}[Y \mid \mathbf{X}]]$$

- The total variance can be decomposed into:
  - 1. the average of the within group variance ( $\mathbb{E}[V[Y \mid X]]$ ) and
  - 2. how much the average varies between groups ( $V[\mathbb{E}[Y \mid \mathbf{X}]]$ ).