12. Algebra of Least Squares

Spring 2023

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Gov 2002 (Harvard)

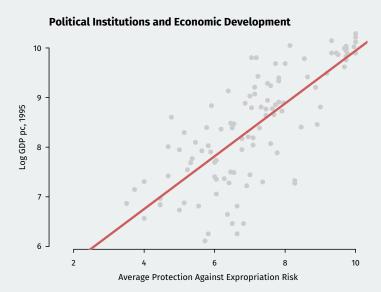
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- How can we estimate the parameters of the linear projection or CEF?
- Now: least squares estimator and its algebraic properties.
- After that: the statistical properties of least squares.

Acemoglu, Johnson, and Robinson (2001)



1/ Deriving the OLS estimator

Assumption

The variables $\{(Y_1, \mathbf{X}_1), \dots, (Y_i, \mathbf{X}_i), \dots, (Y_n, \mathbf{X}_n)\}$ are i.i.d. draws from a common distribution F.

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- Violations include time-series data and clustered sampling.
 - Weakening i.i.d. usually complicates notation but can be done.

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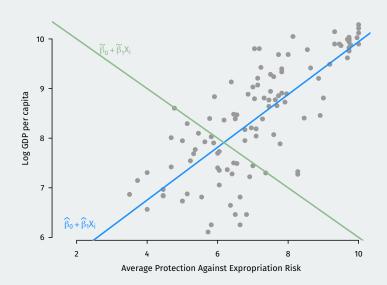
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• How do we estimate β ?

Which line is better?



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- We can use these residuals to get a sample average prediction error:

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• $\hat{S}(\mathbf{b})$ is an estimator of the expected squared error, $S(\mathbf{b})$.

• Ordinary least squares estimator minimizes \hat{S} in place of S.

$$\begin{split} \boldsymbol{\beta} &= \underset{\mathbf{b} \in \mathbb{R}^k}{\operatorname{arg\,min}} \, \mathbb{E}\left[\left(Y - \mathbf{X}' \mathbf{b} \right)^2 \right] \\ \hat{\boldsymbol{\beta}} &= \underset{\mathbf{b} \in \mathbb{R}^k}{\operatorname{arg\,min}} \, \frac{1}{n} \sum_{i=1}^n \left(Y_i - \mathbf{X}_i' \mathbf{b} \right)^2 \end{split}$$

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Bivariate regressions

• **Bivariate regression** is the linear projection model with $\mathbf{X} = (1, X)$:

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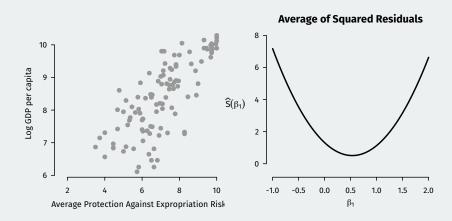
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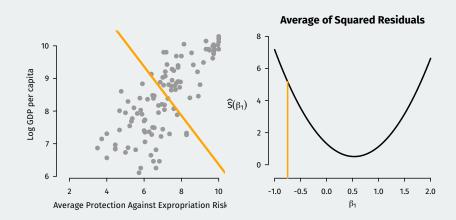
• We can show the OLS estimator of the slope is:

$$\hat{\beta}_1 = \frac{\sum_{i=1}^n (Y_i - \overline{Y})(X_i - \overline{X})}{\sum_{i=1}^n (X_i - \overline{X})^2} = \frac{\widehat{\mathsf{Cov}}(X, Y)}{\widehat{\mathbb{V}}[X]}$$

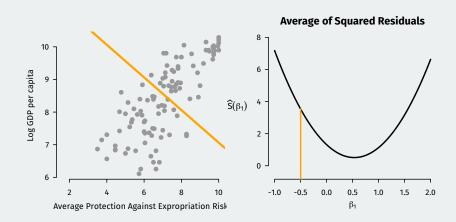
Visualizing OLS

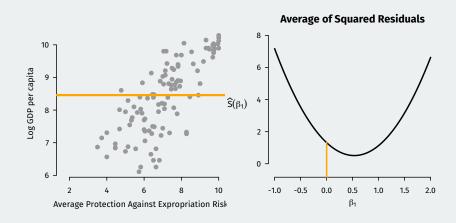


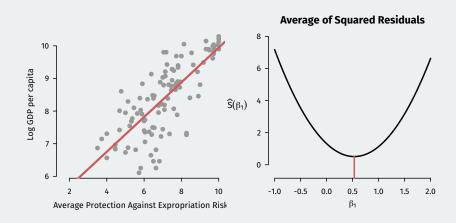
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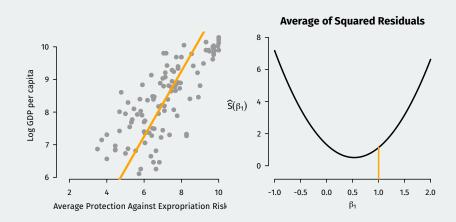


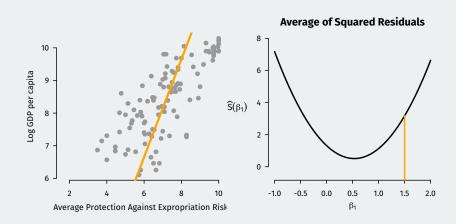
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2/ Model fit

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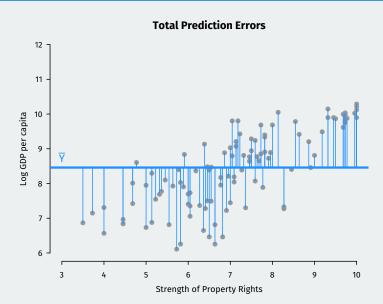
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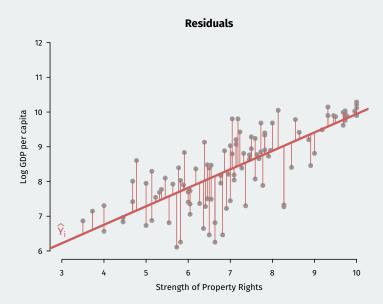
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- Mechanically increases with additional covariates (better fit measures exist)

3/ Geometry of OLS

Linear model in matrix form

• Linear model is a system of n linear equations:

$$Y_1 = \mathbf{X}_1' \boldsymbol{\beta} + e_1$$

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· We can write this more compactly using matrices and vectors:

$$\mathbf{Y} = \begin{pmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{pmatrix}, \quad \mathbb{X} = \begin{pmatrix} \mathbf{X}_1' \\ \mathbf{X}_2' \\ \vdots \\ \mathbf{X}_n' \end{pmatrix} = \begin{pmatrix} 1 & X_{11} & X_{12} & \cdots & X_{1k} \\ 1 & X_{21} & X_{22} & \cdots & X_{2k} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & X_{n1} & X_{n2} & \cdots & X_{nk} \end{pmatrix}, \quad \mathbf{e} = \begin{pmatrix} e_1 \\ e_2 \\ \vdots \\ e_n \end{pmatrix}$$

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· Model is now just:

$$\mathbf{Y} = \mathbb{X}\boldsymbol{\beta} + \mathbf{e}$$

OLS estimator in matrix form

• Key relationship: sample sums can be written in matrix notation:

$$\sum_{i=1}^{n} \mathbf{X}_{i} \mathbf{X}'_{i} = \mathbb{X}' \mathbb{X}$$

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· Implies we can write the OLS estimator as

$$\hat{\pmb{\beta}} = \left(\mathbb{X}'\mathbb{X}\right)^{-1}\mathbb{X}'\mathbf{Y}$$

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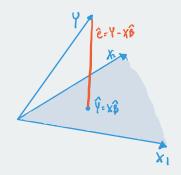
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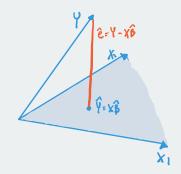
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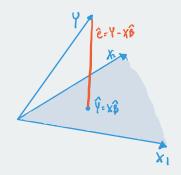
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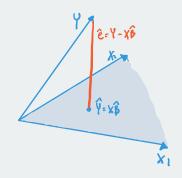
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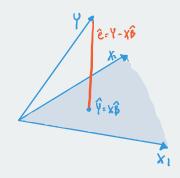
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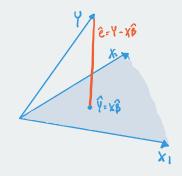
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 - Use OLS to regress $\tilde{\mathbf{e}}_2$ on $\widetilde{\mathbb{X}}_1$

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• Suppose we add an **orthogonal covariate** $\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\boldsymbol{\gamma} + \mathbf{e}$ with $\langle \mathbf{X}, \mathbf{Z} \rangle = 0$.

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- · Only holds in balanced, designed experiments.

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 - 1. Regress Z on $\widetilde{\mathbf{X}} = \mathbf{X} \overline{X}\mathbf{1}$ on and obtain coefficient $\langle \mathbf{Z}, \widetilde{\mathbf{X}} \rangle / \langle \widetilde{\mathbf{X}}, \widetilde{\mathbf{X}} \rangle$

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 - 2. Regress \mathbf{Y} on residual from

Visualizing orthogonalization

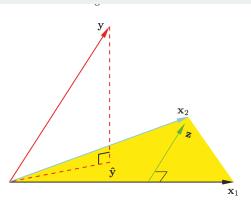


FIGURE 3.4. Least squares regression by orthogonalization of the inputs. The vector \mathbf{x}_2 is regressed on the vector \mathbf{x}_1 , leaving the residual vector \mathbf{z} . The regression of \mathbf{y} on \mathbf{z} gives the multiple regression coefficient of \mathbf{x}_2 . Adding together the projections of \mathbf{y} on each of \mathbf{x}_1 and \mathbf{z} gives the least squares fit $\hat{\mathbf{y}}$.

• We can find $\hat{\pmb{\beta}}_1$ by nested minimization:

$$\hat{\pmb{\beta}}_1 = \operatorname*{arg\,min}_{\pmb{\beta}_1} \left(\operatorname*{min}_{\pmb{\beta}_2} \lVert \mathbf{Y} - \mathbb{X}_1 \pmb{\beta}_1 - \mathbb{X}_2 \pmb{\beta}_2 \rVert^2 \right)$$

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Residual regression

· Define two sets of residuals:

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- Then remembering that M₁ is symmetric and idempotent:

$$\begin{split} \hat{\pmb{\beta}}_2 &= \left(\mathbb{X}_2' \mathbf{M}_1 \mathbb{X}_2\right)^{-1} \left(\mathbb{X}_2' \mathbf{M}_1 \mathbf{Y}\right) \\ &= \left(\mathbb{X}_2' \mathbf{M}_1 \mathbf{M}_1 \mathbb{X}_2\right)^{-1} \left(\mathbb{X}_2' \mathbf{M}_1 \mathbf{M}_1 \mathbf{Y}\right) \\ &= \left(\widetilde{\mathbb{X}}_2' \widetilde{\mathbb{X}}_2\right)^{-1} \left(\widetilde{\mathbb{X}}_2' \widetilde{\mathbf{e}}_1\right) \end{split}$$

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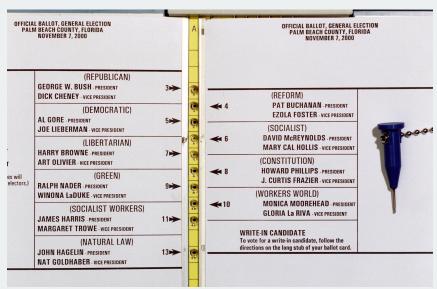
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 - 1. **Leverage point**: extreme in one *X* direction
 - 2. Outlier: extreme in the Y direction

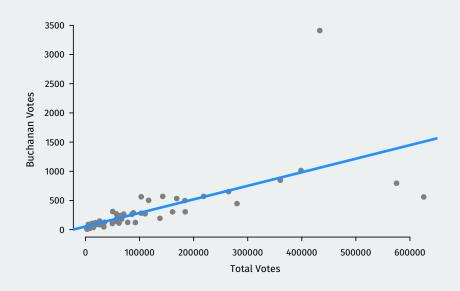
- · Least square heavily penalizes large residuals.
- Implies a just a few unusual observations can be extremely influential.
 - Dropping them leads to large changes in the estimated $\hat{\beta}$.
 - Not all "unusual" observations have the same effect, though.
- · Useful to categorize:
 - 1. **Leverage point**: extreme in one *X* direction
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 - 3. **Influence point**: extreme in both directions

Example: Buchanan votes in Florida, 2000

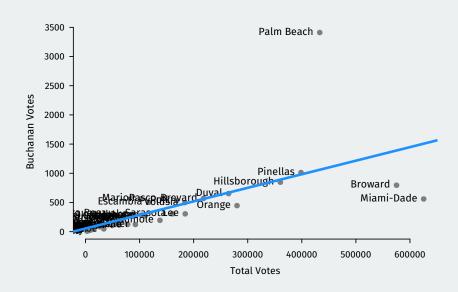
2000 Presidential election in FL (Wand et al., 2001, APSR)



Example: Buchanan votes in Florida, 2000



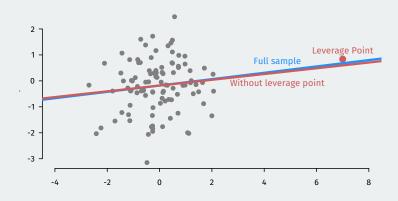
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Example: Buchanan votes

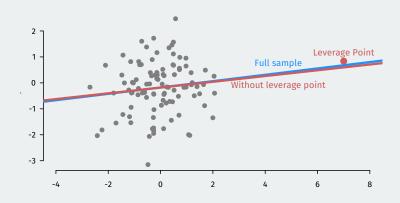
```
mod <- lm(edaybuchanan ~ edaytotal, data = flvote)
summary(mod)</pre>
```

Leverage point definition



• Values that are extreme in the X dimension

Leverage point definition



- Values that are extreme in the X dimension
- That is, values far from the center of the covariate distribution

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$$\widehat{\mathbf{Y}} = \mathbf{PY}$$
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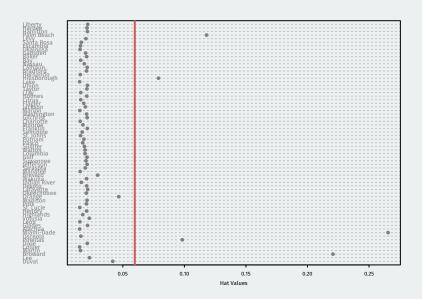
- \rightsquigarrow how far *i* is from the center of the *X* distribution
- **Rule of thumb:** examine hat values greater than 2(k+1)/n

Buchanan hats

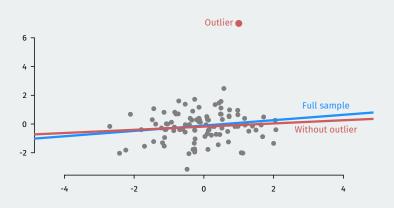
```
head(hatvalues(mod), 5)
```

```
## 1 2 3 4 5
## 0.0418 0.0228 0.2207 0.0156 0.0149
```

Buchanan hats



Outlier definition



• An **outlier** is far away from the center of the *Y* distribution.

Outlier definition



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- Intuitively: a point that would be poorly predicted by the regression.

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- · Simple closed-form expressions:

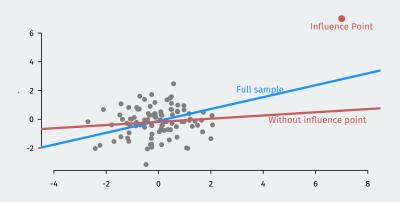
$$\hat{\boldsymbol{\beta}}_{(-i)} = \hat{\boldsymbol{\beta}} - (\mathbb{X}'\mathbb{X})^{-1} \mathbf{X}_i \tilde{e}_i \qquad \tilde{e}_i = \frac{\hat{e}_i}{1 - h_{ii}}$$

Influence points



• An **influence point** is one that is both an outlier and a leverage point.

Influence points



- An **influence point** is one that is both an outlier and a leverage point.
- Extreme in both the X and Y dimensions

$$\widehat{Y}_i - \widetilde{Y}_i = h_{ii}\widetilde{e}_i$$

• Influence of *i* can be measured by change in predictions:

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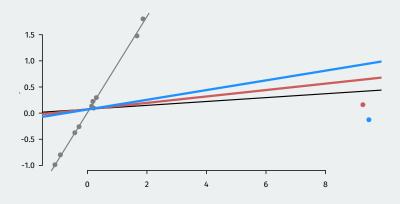
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- · Lots of diagnostics exist, but are mostly heuristic.

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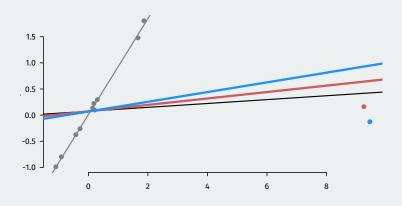
- How much does excluding i from the regression change its predicted value?
- Equal to "leverage × outlier-ness"
- · Lots of diagnostics exist, but are mostly heuristic.
 - · Does removing the point change a coefficient by a lot?

Limitations of the standard tools



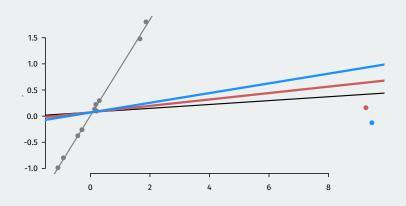
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Limitations of the standard tools



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Limitations of the standard tools



- · What happens when there are two influence points?
- · Red line drops the red influence point
- · Blue line drops the blue influence point

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 - Transform the dependent variable (log(y))
 - Use a method that is robust to outliers (robust regression, least absolute deviations)