# 6. Multivariate Distributions

Spring 2023

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Gov 2002 (Harvard)

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- Distributions of one variable: how to describe and summarize uncertainty about one variable.
- Today: distributions of multiple variables to describe relationships between variables.
- Later: use data to **learn** about probability distributions.

# Why multiple random variables?

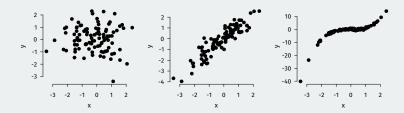
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# Why multiple random variables?

- 1. How to measure the relationship between two variables X and Y?
- 2. What if we have many observations of the same variable,  $X_1, X_2, \dots, X_n$ ?

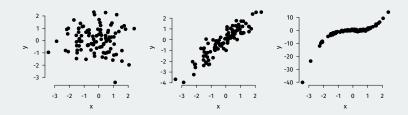
# **1/** Distributions of Multiple Random Variables

# **Joint distributions**



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#### **Joint distributions**



- The joint distribution of two r.v.s, X and Y, describes what pairs of observations, (x, y) are more likely than others.
- Shape of the joint distribution  $\leadsto$  the relationship between X and Y

#### Definition

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#### Definition

The **joint probability mass function (p.m.f.)** of a pair of discrete r.v.s, (X, Y) describes the probability of any pair of values:

$$f_{X,Y}(x,y) = \mathbb{P}(X=x,Y=y)$$

• Properties of a joint p.m.f.:

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  - $\sum_{x}$  is shorthand for sum over all possible values of X

	Support Gay	Oppose Gay
	Marriage	Marriage
	Y=1	Y = 0
Female $X = 1$	0.32	0.19
Male $X = 0$	0.29	0.20

• Joint p.m.f. can be summarized in a cross-tab:

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$$p_{X,Y}(1,1) = \mathbb{P}(X=1,Y=1) = 0.32$$

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  - Works because values of X are disjoint.

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$$\mathbb{P}(Y=1)$$

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Marginal	0.32 + 0.29		

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#### **Conditional p.m.f.**

#### Definition

The **conditional probability mass function** or conditional p.m.f. of Y conditional on X is

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for all values x s.t.  $\mathbb{P}(X = x) > 0$ .

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$$P(Y = y \mid X = x) \ge 0$$
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• 
$$P(Y = y \mid X = x) \ge 0$$
 and  $\sum_{y} \mathbb{P}(Y = y \mid X = x) = 1$ 

• Can define the **conditional expectation** of this p.m.f.:

$$E[Y \mid X = x] = \sum_{y} y \mathbb{P}(Y = y \mid X = x)$$

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$$\mathbb{P}(Y=1\mid X=0)$$

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Probability of favoring gay marriage conditional on male?

$$\mathbb{P}(Y = 1 \mid X = 0) = \frac{\mathbb{P}(X = 0, Y = 1)}{\mathbb{P}(X = 0)}$$

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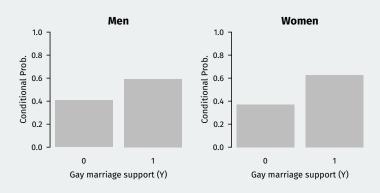
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$$\mathbb{P}(Y=1 \mid X=0) = \frac{\mathbb{P}(X=0, Y=1)}{\mathbb{P}(X=0)} = \frac{0.29}{0.29 + 0.20}$$

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$$\mathbb{P}(Y=1 \mid X=0) = \frac{\mathbb{P}(X=0, Y=1)}{\mathbb{P}(X=0)} = \frac{0.29}{0.29 + 0.20} = 0.592$$



• Two values of  $X \rightsquigarrow$  two **univariate** conditional distributions of Y

## **Bayes and LTP**

· Bayes' rule for r.v.s:

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$$\mathbb{P}(Y = y \mid X = x) = \frac{\mathbb{P}(X = x \mid Y = y)\mathbb{P}(Y = y)}{\mathbb{P}(X = x)}$$

· Law of total probability for r.v.s:

$$\mathbb{P}(X = x) = \sum_{y} \mathbb{P}(X = x \mid Y = y) \mathbb{P}(Y = y)$$

## Joint c.d.f.s

### Definition

For two r.v.s X and Y, the **joint cumulative distribution function** or joint c.d.f.  $F_{X,Y}(x,y)$  is a function such that for finite values x and y,

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- Well-defined for discrete and continuous X and Y.
- · For discrete we simply have:

$$F_{X,Y}(x,y) = \sum_{i \le x} \sum_{j \le y} \mathbb{P}(X = i, Y = j)$$

## **Continuous r.v.s**

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 Two continuous r.v.s: probability of being in some subset of the 2-dimensional plane.



## Continuous joint p.d.f.

#### Definition

If two continuous r.v.s X and Y with joint c.d.f.  $F_{X,Y}$ , their **joint p.d.f.**  $f_{X,Y}(x,y)$  is the derivative of  $F_{X,Y}$  with respect to x and y,

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$$\mathbb{P}((X,Y)\in A)=\iint_{(x,y)\in A}f_{X,Y}(x,y)dxdy.$$

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• Integrate over both dimensions to get the probability of a region:

$$\mathbb{P}((X,Y) \in A) = \iint_{(x,y) \in A} f_{X,Y}(x,y) dx dy.$$

•  $\{(x,y): f_{X,Y}(x,y) > 0\}$  is called the **support** of the distribution.

• Joint p.d.f. must meet the following conditions:

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1.  $f_{X,Y}(x,y) \ge 0$  for all values of (x,y),

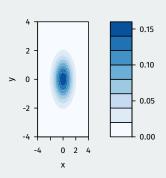
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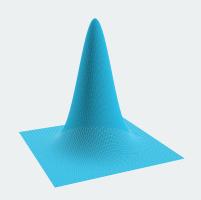
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- $\mathbb{P}(X = x, Y = y) = 0$  for similar reasons as with single r.v.s.

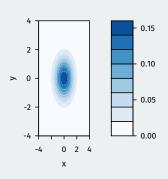
# **Joint densities are 3D**

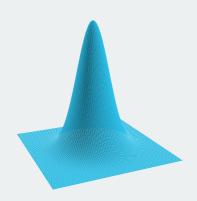




• X and Y axes are on the "floor," height is the value of  $f_{X,Y}(x,y)$ .

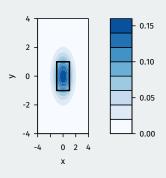
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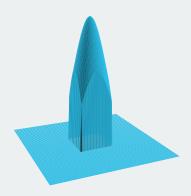




- X and Y axes are on the "floor," height is the value of  $f_{X,Y}(x,y)$ .
- Remember  $f_{X,Y}(x,y) \neq \mathbb{P}(X=x,Y=y)$ .

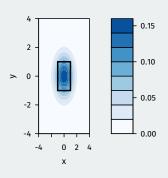
# Probability = volume

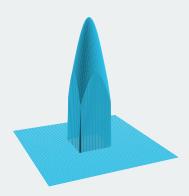




• 
$$\mathbb{P}((X,Y) \in A) = \iint_{(x,y)\in A} f_{X,Y}(x,y) dx dy$$

# **Probability = volume**





- $\mathbb{P}((X,Y) \in A) = \iint_{(X,Y) \in A} f_{X,Y}(x,y) dx dy$
- Probability = volume above a specific region.

## **Continuous marginal distributions**

 We can recover the marginal PDF of one of the variables by integrating over the distribution of the other variable:

$$f_{Y}(y) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dx$$

## **Continuous marginal distributions**

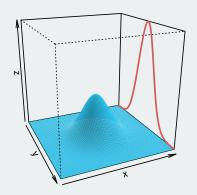
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· Works for either variable:

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dy$$

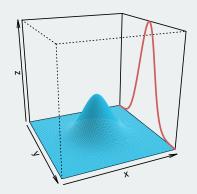
## Visualizing continuous marginals



• Marginal integrates (sums, basically) over other r.v.:

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Marginal integrates (sums, basically) over other r.v.:

$$f_{Y}(y) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dx$$

• Pile up/flatten all of the joint density onto a single dimension.

### **Continuous conditional distributions**

### Definition

The conditional p.d.f. of a continuous random variable is

$$f_{Y|X}(y|x) = \frac{f_{X,Y}(x,y)}{f_X(x)}$$

for all values x s.t.  $f_X(x) > 0$ .

Implies

$$\mathbb{P}(a < Y < b | X = x) = \int_a^b f_{Y|X}(y|x) dy$$

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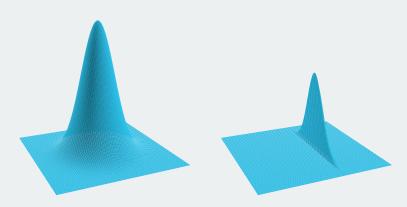
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 Based on the definition of the conditional p.m.f./p.d.f., we have the following factorization:

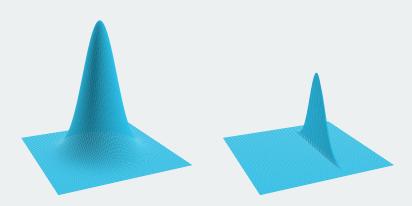
$$f_{X,Y}(x,y) = f_{Y|X}(y|x)f_X(x)$$

# **Conditional distributions as slices**



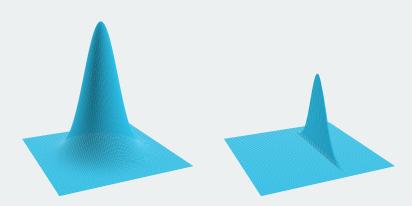
+  $f_{Y|X}(y|x_0)$  is the conditional p.d.f. of Y when  $X=x_0$ 

### **Conditional distributions as slices**



- $f_{Y|X}(y|x_0)$  is the conditional p.d.f. of Y when  $X=x_0$
- +  $f_{Y|X}(y|x_0)$  is proportional to joint p.d.f. along  $x_0$ :  $f_{X,Y}(y,x_0)$

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- $f_{Y|X}(y|x_0)$  is the conditional p.d.f. of Y when  $X=x_0$
- $f_{Y|X}(y|x_0)$  is proportional to joint p.d.f. along  $x_0$ :  $f_{X,Y}(y,x_0)$
- Normalize by dividing by  $f_X(x_0)$  to ensure proper p.d.f.

#### Independence

Two r.v.s Y and X are **independent** (which we write  $X \perp \!\!\! \perp Y$ ) if for all sets A and B:

$$\mathbb{P}(X \in A, Y \in B) = \mathbb{P}(X \in A)\mathbb{P}(Y \in B)$$

• Knowing the value of *X* gives us no information about the value of *Y*.

#### Independence

Two r.v.s Y and X are **independent** (which we write  $X \perp \!\!\! \perp Y$ ) if for all sets A and B:

$$\mathbb{P}(X \in A, Y \in B) = \mathbb{P}(X \in A)\mathbb{P}(Y \in B)$$

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- Conditional independence implies similar to conditional distributions:

$$\mathbb{P}(X \in A, Y \in B \mid Z) = \mathbb{P}(X \in A \mid Z)\mathbb{P}(Y \in B \mid Z)$$

# 2/ Expectations of Joint Distributions

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· Marginal expectations:

$$\mathbb{E}[Y] = \sum_{x} \sum_{y} y \ f_{X,Y}(x,y)$$

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## **3/** Covariance and Correlation

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The **covariance** between two r.v.s, *X* and *Y* is defined as:

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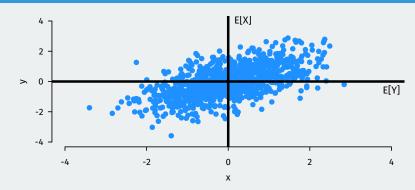
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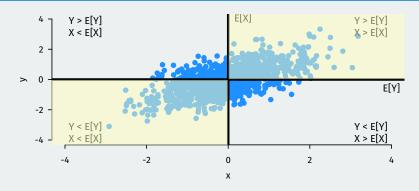
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- · Properties of covariances:
  - $Cov[X, Y] = \mathbb{E}[XY] \mathbb{E}[X]\mathbb{E}[Y]$
  - If  $X \perp \!\!\! \perp Y$ , then Cov[X, Y] = 0

## **Covariance intuition**

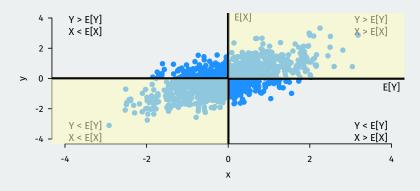


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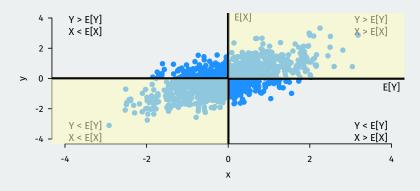


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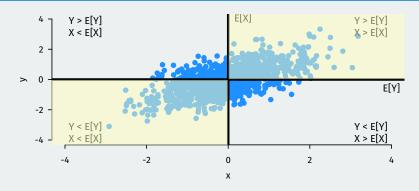
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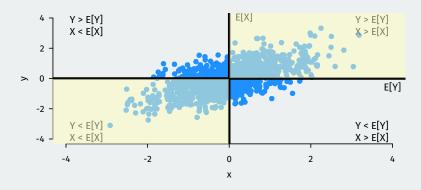
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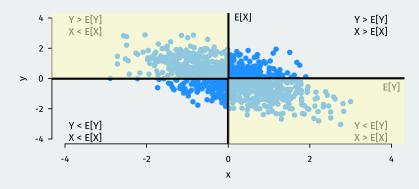
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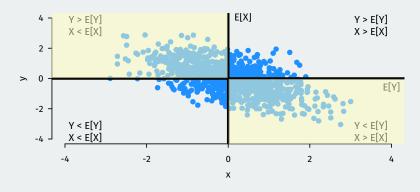
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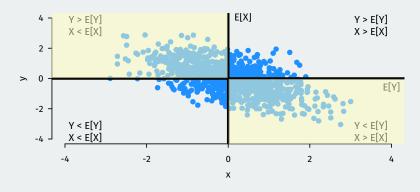
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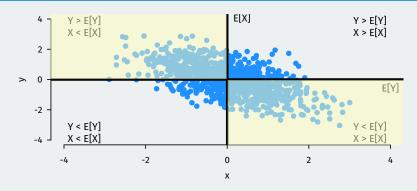
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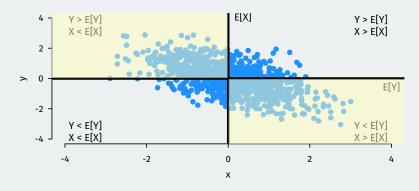
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  - 5. Cov[X + Y, Z] = Cov[X, Z] + Cov[Y, Z]
  - $\mathbf{6.} \ \, \mathsf{Cov}[X+Y,Z+W] = \mathsf{Cov}[X,Z] + \mathsf{Cov}[Y,Z] + \mathsf{Cov}[X,W] + \mathsf{Cov}[Y,W]$

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  - Beware: V[X Y] = V[X] + V[Y] as well.

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- Covariance is a measure of linear dependence, so it can miss non-linear dependence.

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$$\rho = \rho(X, Y) = \frac{\mathsf{Cov}[X, Y]}{\sqrt{\mathbb{V}[X]\mathbb{V}[Y]}} = \mathsf{Cov}\left(\frac{X - \mathbb{E}[X]}{SD[X]}, \frac{Y - \mathbb{E}[Y]}{SD[Y]}\right)$$

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  - $-1 \le \rho \le 1$
  - $|\rho(X, Y)| = 1$  if and only if X and Y are perfectly correlated with a deterministic linear relationship: Y = a + bX.

4/ Random vectors

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- More generally, if  $\mathbf{X} \sim \mathcal{N}(\pmb{\mu}, \pmb{\Sigma})$  then  $\mathbf{Y} = \mathbf{a} + \mathbf{B} \mathbf{X} \sim \mathcal{N}(\mathbf{a} + \mathbf{B} \pmb{\mu}, \mathbf{B} \pmb{\Sigma} \mathbf{B}')$

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