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Constants

```
G = [1 1 1; 0 1 1; 0 0 1];

G_down = G' * G;

G_up = G * G';
```

1. Consider G

a. What is the eigen decomposition of G?

```
[V, D] = eig(G)
% Is it significant?
% Assuming significance means nonzero, distinct eigenvalues, then no,
as all eigenvalues are the same.

V =

1.0000 -1.0000 1.0000
0 0.00000

D =

1 0 0
0 1 0
```

0 0 1

b. Show:

```
[V, Gamma, U] = svd(G)
% G = V * Gamma * U
disp("G = V * Gamma * U")
V * Gamma * U'
G_down = G' * G
disp("G_down = G' * G")
G_down
G' * G
% V is the eigen-matrix of G_up
disp("V is the eigen-matrix of G_up")
[temp_v, temp_d] = eig(G_up);
temp_v
% U is the eigen-matrix of G_down
disp("U is the eigen-matrix of G_down")
[temp_v, temp_d] = eig(G_down);
temp_v
% Gamma's nonzero values are equal to the square root of the
 eigenvalues of
% G_up and G_down
disp("Gamma's nonzero values are equal to the square root of the
 eigenvalues of G_up and G_down")
eig_G_up = eig(G_up);
eig_G_down = eig(G_down);
Gamma
sqrt(eig_G_down)
sqrt(eig_G_up)
% G_up = G*G'
disp("G_up = G*G'")
G_up
G*G'
V =
    0.7370
             0.5910
                       0.3280
    0.5910
            -0.3280
                     -0.7370
    0.3280
             -0.7370
                        0.5910
```

Gamma =

U =

G = V * Gamma * U

G =

1 1 1 0 1 1 0 0 1

ans =

1.0000	1.0000	1.0000
0.0000	1.0000	1.0000
0.0000	-0.0000	1.0000

 $G_down = G' * G$

 $G_down =$

1 1 1 1 2 2 1 2 3

ans =

1 1 1 1 2 2 1 2 3

V is the eigen-matrix of G_up

V =

 $temp_v =$

```
-0.3280 -0.5910 0.7370
           0.3280 0.5910
   0.7370
  -0.5910
           0.7370 0.3280
U is the eigen-matrix of G_down
U =
   0.3280 0.7370 0.5910
0.5910 0.3280 -0.7370
   0.7370 -0.5910 0.3280
temp_v =
   0.5910
           0.7370 0.3280
                   0.5910
  -0.7370
           0.3280
   0.3280 -0.5910
                   0.7370
Gamma's nonzero values are equal to the square root of the eigenvalues
of G_up and G_down
Gamma =
   2.2470 0
        0 0.8019
        0
            0 0.5550
ans =
   0.5550
   0.8019
   2.2470
ans =
   0.5550
   0.8019
   2.2470
G_{up} = G*G'
G_up =
    3
        2
             1
    2
        2
              1
         1
    1
               1
```

ans =

3 2 1

```
2 2 1
1 1 1
```

2. What is null of a matrix if the matrix has distinct, non-zero eigenvalues?

% The null of the matrix would be just the O vector.

3. Show null(G' . G) = null(G), R(G' . G) = R(G'), null(G.G') = null(G'), and R(G.G') = R(G)

```
Important definitions:
colspace : range(A)
kernel : null(A)
coimage : range(A')
cokernel : null(A')
For a matrix A = V * Gamma * U' with rank r :
range(A) = first r columns of V
null(A) = last n-r columns of U'
range(A') = first r columns of U'
null(A') = last m-r columns of V
% Important matrices:
G_prime_G = G' * G;
G_G_prime = G*G';
% null(G' . G) = null(G)
disp("null(G' . G) = null(G)")
[m1, n1] = size(G prime G);
r1 = rank(G_prime_G);
[m2, n2] = size(G);
r2 = rank(G);
[v1, g1, u1] = svd(G_prime_G);
u1 = u1';
[v2, v2, u2] = svd(G);
u2 = u2';
if (n1 - r1) == 0 \&\& (n2 - r2) == 0
    disp('Rank of both null spaces is 0 -> same null space');
    disp("These span the same space")
    b1 = u1(:, (n1-r1):end)
    b2 = u2(:, (n2-r2):end)
end
```

```
R(G' . G) = R(G')
disp("R(G' . G) = R(G')")
[m1, n1] = size(G_prime_G);
r1 = rank(G_prime_G);
[m2, n2] = size(G');
r2 = rank(G');
[v1, g1, u1] = svd(G_prime_G);
u1 = u1';
[v2, v2, u2] = svd(G');
u2 = u2';
if r1 == 0 && r2 == 0
    disp('Rank of both ranges is 0 -> same range space');
else
    disp("These span the same space")
    b1 = v1(:, 1:r1)
    b2 = v2(:, 1:r2)
end
% null(G.G') = null(G')
disp("null(G.G') = null(G')")
[m1, n1] = size(G_G_prime);
r1 = rank(G_G_prime);
[m2, n2] = size(G');
r2 = rank(G');
[v1, g1, u1] = svd(G_G_prime);
u1 = u1';
[v2, v2, u2] = svd(G');
u2 = u2';
if (n1 - r1) == 0 \&\& (n2 - r2) == 0
    disp('Rank of both null spaces is 0 -> same null space');
else
    disp("These span the same space")
    b1 = u1(:, (n1-r1):end)
    b2 = u2(:, (n2-r2):end)
end
% R(G.G') = R(G)
disp("R(G.G') = R(G)")
[m1, n1] = size(G_G_prime);
r1 = rank(G_G_prime);
```

```
[m2, n2] = size(G);
r2 = rank(G);
[v1, g1, u1] = svd(G_G_prime);
u1 = u1';
[v2, v2, u2] = svd(G);
u2 = u2';
if r1 == 0 && r2 == 0
   disp('Rank of both ranges is 0 -> same range space');
else
   disp("These span the same space")
   b1 = v1(:, 1:r1)
   b2 = v2(:, 1:r2)
end
null(G' . G) = null(G)
Rank of both null spaces is 0 -> same null space
R(G' \cdot G) = R(G')
These span the same space
b1 =
  -0.3280
            0.7370
                       0.5910
  -0.5910
            0.3280
                     -0.7370
  -0.7370 -0.5910
                      0.3280
b2 =
   2.2470
             0
                           0
        0
            0.8019
                            0
                  0
                       0.5550
null(G.G') = null(G')
Rank of both null spaces is 0 -> same null space
R(G.G') = R(G)
These span the same space
b1 =
  -0.7370
            0.5910
                       0.3280
  -0.5910
            -0.3280
                     -0.7370
  -0.3280
            -0.7370
                     0.5910
b2 =
   2.2470
                 0
                            0
            0.8019
        0
        0
                       0.5550
                  0
```

4. Show the minimum error inverse solution satisfies v* orthogonal to null(G)

```
% Since we solve for a vector which when multiplied by G gives us u.
% If v_bar is in the null space of G, then it will always give 0
  instead of
% u. So v_bar cannot be in the null space of G.
```

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