

ELEC-7500

September 18, 2013

- general solution of state equations
- other approaches to find e^{At}
- Cayley-Hamilton Theorem

Laplace transform approach to solutions $x(t), t > 0$
of the state equation (continued)

$$\dot{x} = Ax + Bu, \quad x(0) \text{ - initial condition}$$

(Previously we got this): Solution in transform domain

$$X(s) = [sI - A]^{-1} x(0) + [sI - A]^{-1} B U(s)$$

\downarrow inverse Laplace transform \downarrow "temptation"

$$x(t) = e^{At} x(0) + \underbrace{e^{At} B u(t)}$$

\nearrow
matrix exponential

$$\text{Laplace transform of } e^{At} \Rightarrow [sI - A]^{-1}$$

$$\text{or } e^{At} = \underbrace{\mathcal{L}^{-1}}_{\text{inverse Laplace transform}} \left\{ \underbrace{[sI - A]^{-1}}_{\text{matrix inverse}} \right\}$$

(1)

But temptations are usually not good.

$$[sI - A]^{-1} B U(s) \xrightarrow{\mathcal{L}^{-1}} \cancel{e^{At} B u(t)}$$

Recall from transform theory:

$$\text{If: } \begin{aligned} x(t) &\rightarrow X(s) \\ y(t) &\rightarrow Y(s) \end{aligned}$$

$$\text{Then } \underbrace{X(s) Y(s)}_{\substack{\text{multiplication} \\ \text{in transform domain}}} \xrightarrow{\mathcal{L}^{-1}} \underbrace{\int_0^t x(t-\tau) y(\tau) d\tau}_{\substack{\text{convolution in} \\ \text{time domain}}}$$

So, the correct answer:

$$\begin{aligned} X(s) &= [sI - A]^{-1} x(0) + [sI - A]^{-1} B U(s) \\ \downarrow \\ x(t) &= e^{At} x(0) + \int_0^t e^{A(t-\tau)} B u(\tau) d\tau \end{aligned}$$

General solution of $\dot{x} = Ax + Bu$, $x(0)$ given

$$x(t) = \boxed{e^{At} x(0)} + \boxed{\int_0^t e^{A(t-\tau)} Bu(\tau) d\tau}$$

- response to initial condition
 - "homogeneous solution"
 - completely characterized by matrix A .
 - "zero input response"
- response to an input
 - "particular solution"
 - will depend on $u(t)$
 - "zero state response"
 ↑
 initial state

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Summary of recent days:

e^{At} ~ matrix exponential

① ~ can be found by coordinate change
involves eigenvectors of A

$$e^{At} = M e^{St} M^{-1}$$

↑
matrix of eigenvectors

S ~ matrix of eigenvalues of A

② ~ can also use $e^{At} = \mathcal{L}^{-1} \{ [sI - A]^{-1} \}$

$$x(t) = e^{At} x(0) + \underbrace{\int_0^t e^{A(t-\tau)} B u(\tau) d\tau}_{\text{convolution integral.}}$$

④

Today: Another approach to find e^{At} ?
(there are many!)

Infinite series? $e^t \sim$ scalar function

$$e^x \approx e^t = 1 + t + \frac{t^2}{2!} + \frac{t^3}{3!} + \dots$$

$$e^{at} = 1 + at + \frac{(at)^2}{2!} + \dots$$

Matrix: $e^{At} = \underset{\substack{\uparrow \\ \text{identity matrix}}}{I_{n \times n}} + At + A^2 \left(\frac{t^2}{2!} \right) + A^3 \left(\frac{t^3}{3!} \right) + \dots$
power series in t

An approximation can be found by
ending the series (truncate).

Q: Does there exist a finite series
that is not an approximation?

⑤

$$e^{At} = \sum_{k=0}^{\infty} A^k \left(\frac{t^k}{k!} \right)$$

power series in t

$$e^{At} \stackrel{?}{=} \sum_{k=0}^P A^k \left(\beta_k(t) \right)$$

some other functions?

Something from linear algebra:

"Cayley-Hamilton Theorem"
 A matrix A satisfies its own characteristic equation.

Example $A = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix}$

Characteristic equation is $|\lambda I - A| = 0$

$$\begin{vmatrix} \lambda & -1 \\ 2 & \lambda + 3 \end{vmatrix} = 0 \leadsto \lambda^2 + 3\lambda + 2 = 0$$

⑥

$$A = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \rightarrow |\lambda I - A| = 0$$

$$\lambda^2 + 3\lambda + 2 = 0$$

Cayley-Hamilton theorem says:

$$A^2 + 3A + 2I_{2 \times 2} = O_{2 \times 2}$$

$$A^2 = -2I - 3A$$

In the general case A is $n \times n$

A^n = a linear combination of
 $I, A, A^2, \dots, A^{n-1}$ ⑦

How can we use C-H theorem?

Power series

$$e^{At} = \sum_{k=0}^{\infty} A^k \left(\frac{t^k}{k!} \right)$$

Claim: A^k for $k=n, n+1, \dots$
can be replaced by combinations
of $I, A, A^2, \dots, A^{n-1}$.

Next meeting: The finite series
solution for e^{At} . \square

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