

EDUCATION

Brown University Ph.D. in Computer Science, GPA: 4.00/4.00 Advisors: George Konidaris and Stefanie Tellex	Providence, RI 2017–Present
Northeastern University M.S. in Computer Science, GPA: 3.96/4.00, Advisor: Robert Platt	Boston, MA 2015–2017
Rensselaer Polytechnic Institute B.S. in Electrical Engineering, GPA: 3.98/4.00	Troy, NY 2012–2015

PUBLICATIONS

- [1] **M. Corsaro**, S. Tellex, and G. D. Konidaris, “Learning to Detect Multi-Modal Grasps for Dexterous Grasping in Dense Clutter”, in *2020 (In Submission)*.
- [2] T. Nguyen, N. Gopalan, R. Patel, **M. Corsaro**, E. Pavlick, and S. Tellex, “Robot Object Retrieval with Contextual Natural Language Queries”, in *Robotics: Science and Systems 2020*.

RESEARCH EXPERIENCE

Brown University Research Assistant @ George Konidaris’s Intelligent Robot Lab	Providence, RI 2017–Present
<ul style="list-style-type: none">– Grasp Detection for Intelligent Manipulation– Ongoing dissertation research on robot grasping and abstraction for intelligent manipulation.– Completed course projects involving <i>Action-Conditional Video Prediction using Deep Networks in Atari Games</i> and integrating deep learning into <i>Skill Discovery in Continuous Reinforcement Learning Domains using Skill Chaining</i>.	
Northeastern University Research Assistant @ Robert Platt’s The Helping Hands Lab	Boston, MA 2015–2017
<ul style="list-style-type: none">– Grasp Pose Detection in Dense Clutter with a UR5– Ported the system described in <i>High Precision Grasp Pose Detection in Dense Clutter</i> to a UR5 robot and helped to improve the grasp success rate.	
Harvard University Summer Research Intern @ Robert Howe’s Harvard Biorobotics Lab	Cambridge, MA Summer 2014
<ul style="list-style-type: none">– Grasp Point Recognition from Geometric Cues– Integrated a computer vision algorithm to detect and execute grasps with a real robot.	

WORK EXPERIENCE

Locus Robotics

Robot Software Engineering Intern

Wilmington, MA

Summer 2017

- Depth Estimation from 2D Images
- Computer vision project to extract point clouds from monocular camera feed on mobile robot.

Locus Robotics

Robot Software Engineering Intern

Wilmington, MA

Summer 2016

- 3D Vision for Mobile Robots
- Integrated 3D depth sensor with mobile robot platform, improved 3D data processing pipeline.

Vecna Technologies

Robot Software Engineering Intern

Cambridge, MA

Summer 2015

- Navigation for Mobile Robots
- Worked on mobile robot navigation stack to execute predictable motion paths.

The Boeing Company

Rensselaer Multidisciplinary Capstone Design Project

Troy, NY

Spring 2015

- Robot Arms for Airplane Assembly
- Led multidisciplinary group of students in designing and simulating robotic arms for automated airplane wing maintenance and assembly.
- Held weekly conference calls with Boeing engineer, presented results to group of Boeing employees.

SKILLS

- **Programming:** C++, Python
- **Simulation:** Drake
- **Deep Learning:** TensorFlow
- **Some additional experience with:** PyTorch, PyBullet, MATLAB
- **Robot Software:** ROS, PCL

AWARDS

- Andries van Dam Graduate Fellowship 2017–2018
- RPI Wynatt James William Prize 2015
- Boeing Scholarship 2015
- RPI Medal 2012

TEACHING

- **Grad Teaching Assistant** at Brown University Spring 2018
Topics in Collaborative Robotics (CSCI 2951K)
- **Teaching Assistant** at Northeastern University Spring 2017
Foundations of Artificial Intelligence (CS 5100)
- **Head Teaching Assistant** at Northeastern University Fall 2016
Foundations of Artificial Intelligence (CS 5100)

MENTORSHIP

- Bingjie Tang, Brown University, M.S. 2020 2018–2020
Now Ph.D. Student at University of Southern California
Project: Learning Combined Planar Pushing and 6 DoF Grasping Policies
- Anthony Cruz, Brown University, Sc.B. 2018 2017–2018
Now Software Engineer at Google
- Four high school students from the MET High School 2018–2019
Mentored four students through Brown’s CSCI 1951R: *Intro to Robotics* curriculum.

OUTREACH & SERVICE

- Outreach Coordinator for the Intelligent Robot Lab and Humans to Robots Lab 2018–Present
Schedule lab tours and presentations for elementary, middle, and high school student groups, scout groups, visiting university officials, professional groups, alumni, and staff. Traveled to local schools and the Rhode Island Robot Block Party to teach the community about robotics.
- Brown University Graduate Student Council 2018–2019
One of the computer science department’s representatives to the grad student council.

SELECTED COURSEWORK

Brown University

CSCI 2470 Deep Learning
CSCI 2951X Reintegrating AI
CSCI 2951F Learning and
Sequential Decision Making

Northeastern University

CS 5335 Robotic Science
and Systems
CS 6140 Machine Learning
CS 5100 Foundations of
Artificial Intelligence
CS 7800 Advanced Algorithms
CS 7600 Intensive Computer
Systems
CS 7400 Intensive Principles of
Programming Languages

RPI

ESCE 4480 Robotics I
ESCE 4510 Digital Control
Systems
CSCI 1200 Data Structures
ECSE 4790 Microprocessor
Systems
MATH 4100 Linear Algebra