## Math Problem Set 6

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July 27, 2018

**Problem 9.1.** Proof. Let L be an unconstrained linear objective function. Suppose that L has a minimizer  $x^*$ . I'll show that L must be constant.

Suppose that L is not constant, i.e, there exists y such that  $Ly \neq Lx^*$ . If  $Ly < Lx^*$ , then  $x^*$  is not a minimizer and we have a contradiction. If  $Ly > Lx^*$ , then  $L(x^* - y) < 0$  and we can consider the point  $x^* + x^* - y$ :

$$L(x^* + x^* - y) = Lx^* + L(x^* - y) < Lx^*$$

so  $x^*$  is not a minimizer and we have a contradiction

**Problem 9.2.** Proof. Minimizing ||Ax - b|| is equivalent to

$$(Ax - b)^{T}(Ax - b) = (x^{T}A^{T} - b^{T})(Ax - b)$$

$$= x^{T}A^{T}Ax - x^{T}A^{T}b - b^{T}Ax + 2b^{T}b$$

$$= x^{T}A^{T}Ax - 2b^{T}Ax + 2b^{T}b$$

Note that  $A^TA$  is positive semidefinite. Taking the FOC of this expression yields:

$$2x^{T}A^{T}A - 2b^{T}A = 0$$

$$\iff x^{T}A^{T}A = b^{T}A$$

$$\iff A^{T}Ax = A^{T}b$$

And because  $A^TA$  is positive definite, the second order-condition

$$2A^TA > 0$$

will always be satisfied.

Problem 9.3. Text explication - Return here

**Problem 9.4.** *Proof.* I'll need to show both directions.

•  $\Leftarrow$  Suppose  $x_0$  is chosen such that  $Df(x_0)^T = Qx_0 - b$  is an eigenvector for Q, i.e,  $Q(Qx_0 - b) = \lambda(Qx_0 - b)$  for some  $\lambda \in \mathbb{R}$ . We see that:

$$x_1 = x_0 - \alpha Q(Qx_0 - b) = x_0 - \alpha \lambda (Qx_0 - b)$$

I choose  $\alpha$  to minimize  $f(x_1)$ . If  $\alpha = \frac{1}{\lambda^2}$ , then

$$Qx_1 = Q(x_0 - \alpha\lambda(Qx_0 - b))$$

$$= Qx_0 - \alpha\lambda^2(Qx_0 - b)$$

$$= Qx_0 - Qx_0 - b$$

$$= b$$

And if  $Qx_1 = b$ , then we know that  $x_1$  is the minimum of the function, so I've chosen the right  $\alpha$ , and the algorithm converges in one step.

•  $\Rightarrow$  Suppose the algorithm converges in one step. Then I know that  $Qx_1 = b$ , and thus that

$$Q(x_0 - \alpha Q(Qx_0 - b)) = b$$

Now consider the kernel of  $I - \alpha Q$ .

$$(I - \alpha Q)(Qx_0 - b) = Qx_0 - b - \alpha Q(Qx_0 - b)$$
$$= Q(x_0 - \alpha Q(x_0 - b)) - b$$
$$= Qx_1 - b$$
$$= 0$$

So  $Qx_1 - b \in \text{Ker}(I - \alpha Q)$ , and therefore it is an eigenvector of Q with eigenvalue  $\alpha$ .

I have two different eigenvalues for the same eigenvectors - one of the directions must be wrong. Anyone see the issue?

**Problem 9.5.** Proof. I will begin by stating without proof a result of vector calculus.

**Fact:** The gradient of a function at a point  $Df^{T}(x)$  is orthogonal to the level set of the function at the point x.

This fact gives some idea about where I'm going with this proof: first I'll show that I can reduce the proposition to the statement that the two gradients  $Df^{T}(x_{k})$  and  $Df^{T}(x_{k+1})$  are orthogonal, and then I'll use the fact to show that this is indeed the case.

Consider  $\langle x_{k+1} - x_k, x_{k+2} - x_{k+1} \rangle$ .

$$\langle x_{k+1} - x_k, x_{k+2} - x_{k+1} \rangle = \langle x_k - \alpha_{k+1} D f^T(x_k) - x_k, x_{k+1} - \alpha_{k+2} D f^T(x_{k+1}) - x_{k+1} \rangle$$
  
=  $\langle -\alpha_{k+1} D f^T(x_k), -\alpha_{k+2} D f^T(x_k + 1) \rangle$ 

And if I want to set this equal to zero, I can pull out the scalars  $-\alpha_{k+1}$ ,  $-\alpha_{k+2}$  and set  $\langle Df^T(x_k), Df^T(x_k+1) \rangle = 0$ . So we see that

$$\langle x_{k+1} - x_k, x_{k+2} - x_{k+1} \rangle = 0 \iff \langle Df^T(x_k), Df^T(x_k+1) \rangle = 0$$

I'll now show that the gradients are orthogonal.

Consider the gradient  $Df^{T}(x_{k})$ .  $-Df^{T}(x_{k})$  is the direction of steepest descent, and  $x_{k+1} = x_{k} - \alpha Df^{T}(x_{k})$ . We choose  $\alpha$  to minimize  $f(x_{k+1})$ . Consider the evaluation of the gradient  $Df(x_{k})$  at the point  $x_{k+1}$ .

Claim:  $Df(x_k)(x_{k+1}) = 0$ 

Proof of Claim: This will be an intuitive argument which follows from the continuity of the derivative (f is  $C^1$ ). Suppose  $-Df(x_k)(x_{k+1}) < 0$ . Then, I can go a bit further along the descent to

$$x^* = x_k - (\alpha + \varepsilon)Df^T(x_k), \varepsilon > 0$$

such that  $f(x^*) < f(x_{k+1})$ . Similarly, if  $-Df(x_k)(x_{k+1}) > 0$ , then I can go a bit less far along the descent to

$$x^* = x_k - (\alpha - \varepsilon)Df^T(x_k), \varepsilon > 0$$

such that  $f(x^*) < f(x_{k+1})$ . So we see that  $Df(x_k)(x_{k+1}) = 0$ , which proves the claim.

Excellent. Now,  $Df(x_k)(x_{k+1}) = 0$ , so the gradient  $Df^T(x_k)$  is tangent to the level set of f at the point  $x_{k+1}$ . We know from our fact that  $Df^T(x_{k+1})$  is orthogonal to the level set of f at  $x_{k+1}$ , so it is orthogonal to  $Df^T(x_k)$  as well, which concludes the proof.

See Figure 1 for some geometric intuition.

Problem 9.6. Jupyter

Problem 9.7. Jupyter

Problem 9.8. Jupyter

Problem 9.9. Jupyter

**Problem 9.10.** Proof. We know that  $x^*$  is the unique minimizer of f iff

$$f'(x) = 0 \iff Qx^* - b = 0 \iff x^* = Q^{-1}b$$

Now let us start Newton's method from an arbitrary initial guess  $x_0$ . Calculate  $x_1$ :

$$x_1 = x_0 - D^2 f(x_0)^{-1} D f(x_0)$$
  
=  $x_0 - Q^{-1} (Qx_0 - b)$   
=  $x_0 - x_0 + Q^{-1} b = Q^{-1} b$ 

which is what was desired.

**Problem 9.12.** Proof. Choose  $\lambda_i$  arbitrarily, and let  $v_i$  be its eigenvector. Then

$$Bv_i = (A + \mu I)v_i = Av_i + \mu Iv_i = \lambda_i v_i + \mu v_i = (\lambda_i + \mu)v_i$$

**Problem 9.15.** I'll multiply the left side by the right:

Proof.

$$(A + BCD)(A^{-1} - A^{-1}B(C^{-1} + DA^{-1}B)^{-1}DA^{-1})$$

$$= AA^{-1} - AA^{-1}B(C^{-1} + DA^{-1}B)^{-1}DA^{-1} + BCDA^{-1} - BCDA^{-1}B(C^{-1} + DA^{-1}B)^{-1}DA^{-1}$$

$$= I - B(C^{-1} + DA^{-1}B)^{-1}DA^{-1} + BCDA^{-1} - BCDA^{-1}B(C^{-1} + DA^{-1}B)^{-1}DA^{-1}$$

$$= I - B(C^{-1} + DA^{-1}B)^{-1}DA^{-1} + BCDA^{-1} - BCDA^{-1}B(C^{-1} + DA^{-1}B)^{-1}DA^{-1}$$

$$= I + BCDA^{-1} - (B(C^{-1} + DA^{-1}B)^{-1} + BCDA^{-1}B(C^{-1} + DA^{-1}B)^{-1})DA^{-1}$$

$$= I + BCDA^{-1} - ((B + BCDA^{-1}B)(C^{-1} + DA^{-1}B)^{-1})DA^{-1}$$

$$= I + BCDA^{-1} - (BC(C^{-1} + DA^{-1}B)(C^{-1} + DA^{-1}B)^{-1})DA^{-1}$$

$$= I + BCDA^{-1} - (BC(C^{-1} + DA^{-1}B)(C^{-1} + DA^{-1}B)^{-1})DA^{-1}$$

$$= I + BCDA^{-1} - BCDA^{-1} = I$$

Problem 9.16. I'm not seeing how to apply the theorem - RETURN HERE

**Problem 9.18.** Proof. I choose  $\alpha_k$  to minimize the function  $\phi_k(\alpha) = f(x_k + \alpha_k d_k)$ , so I need  $\phi'_k(\alpha_k) = 0$ . Because f is a quadratic, I know that

$$\phi'_k(\alpha) = -Df(x_k + \alpha_k d_k) \cdot d_k$$

$$= [(x_k - \alpha_k d_k)^T Q - b^T] d_k$$

$$= [x_k^T Q - b^T] d_k - (\alpha_k d_k)^T Q d_k = r_k^T d_k - \alpha_k (d_k^T Q d_k)$$

And from this last line we see:

$$\alpha_k = \frac{r_k^T d_k}{d_k^T Q d_k}$$

**Problem 9.20.** Proof. I will prove that  $r_i^T r_k = 0$  for all i < 0 by induction on k.

Base Case: k = 1. Recall that in my proof from Problem 9.5, I showed that  $Df^{T}(x_{k})$  was orthogonal to  $Df^{T}(x_{k+1})$ , where  $x_{k+1} = x_{k} - \alpha_{k}Df^{T}(x_{k})$ . In general the conjugate gradient method constructs  $x_{k+1}$  differently, so this theorem does not always apply. But in the first step,  $r_0 = d_0 = -Df(x_0)^T$ , so we see that:

$$x_1 = x_0 + \alpha_0 d_0 = x_0 - \alpha_0 D f^T(x_0)$$
  
 $\implies r_1 = D f(x_1)^T \perp D f(x_0)^T = r_0$ 

which shows the base case.

Inductive Case: Assume that

$$r_i^T r_k' = 0$$
 for all  $i < k'$ 

is true for any k' < k. I will show that the statement is also true for k. There is a bit of preliminary work necessary for my argument. Define the sets  $D_{k-1} = \text{span}\{d_0, ..., d_{k-1}\}$  and  $R_{k-1} = \text{span}\{r_0, ..., r_{k-1}\}$ . I'll state and justify a few facts about these sets.

Fact 1:  $D_{k-1}$  and  $R_{k-1}$  are both bases for subspaces of dimension k-1.

Justification:  $R_{k-1}$  and  $D_{k-1}$  are both orthogonal over some inner product space on  $R^n$ :  $R_{k-1}$  by the inductive assumption, and  $D_{k-1}$  by the property that it is Q-conjugate (and so orthogonal over the inner product space  $\langle \cdot, \cdot \rangle_Q$ . It is a theorem somewhere that orthogonal vectors are linearly independent, which shows the fact.

## Fact 2: $D_{k-1} \subset R_{k-1}$

Justification: If  $d \in D_{k+1}$ , then it is a linear combination of elements  $d_i, i \in \{0, 1, ..., k-1\}$ . Therefore this fact will follow if I show that any element  $d_i \in R_{k-1}$ . And indeed,

$$\begin{aligned} d_i &= r_i - \beta_{i-1} d_{i-1} \\ &= r_i - \beta_{i-1} (r_{i-1} - \beta_{i-2} d_{i-2}) = r_i - \beta_{i-1} r_{i-1} + \beta_{i-1} \beta_{i-2} d_{i-2} \\ &= \dots \\ &= \sum_{j=0}^i \bigg( \prod_{k=j}^{i-1} -\beta_k \bigg) r_j \end{aligned}$$

The actual final expression doesn't matter - what matters is that  $d_i$  is expressed as a linear combination of the  $r_i$ s.

## Fact 3: $D_{k+1} = R_{k+1}$

Justification: This follows from facts 1 and 2: Since the two spaces have the same dimension, one inclusion implies equality.

Now, we'll put this new knowledge to work and prove the inductive step. By Lemma 9.5.3,  $d_i^T r_k = 0$  for any i < j. This means that  $r_k \in D_{k-1}^{\perp} = R_{k-1}^{\perp}$  with the usual inner product, and therefore  $r_i^T r_k = 0$  for all i < k, which was what we wanted to show.

Note: There has to be a simpler way to do this proof. Apologies if this was very roundabout, but it's all I could think of!