

CS 411 - Artificial Intelligence I

Fall 2019

Assignment 1

Department of Computer Science, University of Illinois at Chicago

Total Points: 25

1. Explain why the “Part-Picking robot” environment is characterized with following properties - partially observable, single-agent, stochastic, episodic, dynamic and continuous . [6*1]

Also give PEAS description of the Part-Picking robot environment. [2*4]

2. Define rational agent and autonomous agent in your own words [4]
3. You have the agent program for simple reflex agent as shown below

```
function REFLEX-VACUUM-AGENT([location,status]) returns an action
  if status = Dirty then return Suck
  else if location = A then return Right
  else if location = B then return Left
```

Figure 2.8 The agent program for a simple reflex agent in the two-state vacuum environment. This program implements the agent function tabulated in Figure 2.3.

Now suppose you can use one more action “NoOp” which does nothing.

- a. Would it be desirable to use this action in this agent program to prevent vacuum cleaner from moving after all squares are cleaned? If yes, modify the simple reflex agent program adding “NoOp” action and if not give an argument that despite the option of “NoOp” the agent is bound to keep moving. [4]
- b. If you have a choice of using other type of agents, which one would you choose and how would it prevent vacuum from moving after all squares are cleaned? [3]

Use the assumptions listed below

- The performance measure awards one point for each clean square at each time step, over a “lifetime” of 1000 time steps.
- The “geography” of the environment is known *a priori* (Figure 2.2) but the dirt distribution and the initial location of the agent are not. Clean squares stay clean and sucking cleans the current square. The *Left* and *Right* actions move the agent left and right except when this would take the agent outside the environment, in which case the agent remains where it is.
- The only available actions are *Left*, *Right*, and *Suck*.
- The agent correctly perceives its location and whether that location contains dirt.