Projects Assignments

Sistemi embedded e real-time

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Standard Assignment

General information and requirements

- 1. Hardware: B-L475E-IOT1A or Qemu platform
- 2. RTOS: FreeRTOS
- 3. Delivery
 - 3.1 Code and short report (max 2 pages)
 - 3.2 Presentation with demo and discussion
 - · On the same date of the written exam
 - · Other appointments to be aggregated and scheduled on demand

Application requirements

Channels: sensors, buttons, UART / LED, GPIO, UART...

- 1. use 1 task per input/output channel
- 2. use \geq 3 input channels
- 3. use \geq 2 sensor devices or 1 sensor device + 1 network device
- 4. use \geq 2 output channels
- 5. use \geq 1 many-to-one task communication

Misc

- Inter-team collaboration is allowed and encouraged only if on the forum and about the following topics
 - · Project definition (ideas about what to do)
 - Publicly available resources (e.g. drivers)
 - Implementation of specific algorithms (e.g. Kalman filter)
- Synergies with other classes' projects is allowed and mildly encouraged Out-of-scope contributions will increase the project evaluation

Additional requirements

Easy

- Git versioning
- Periodic execution (timer-based tasks)
- Task WCET analysis measurement-based (under isolation assumption)
- Tuning
 - Footprint minimisation
 - Task's constraints optimisation (e.g. sensor refresh rate)

Challenging

- MISRA C compliance
- Response time analysis, e.g. w/ Mast
- Task WCET analysis w/ Otawa (implies Arm Cortex M4 modelisation)

See also the challenging Project Assignment

Ideas

- Weather station with remote signalling and real-time actuation
- Microphone-captured voice distortion w/ FFT and bluetooth audio
- Vocal command to operate LEDs blinking
- · NFC card authentication



General information

- Effort is comparable with the standard assignment
- Tasks are research-level, original, challenging (and fun!)
- Access restricted to motivated and independent students
- Collaboration with the RTES research team
- Possible collaboration with industrial companies: Arm, Xilinx, Nvidia; Lynx;
 Ferrari (also GES), Maserati; Tetra Pak, IMA, SACMI

Technical requirements

- · High-performance platforms: Nvidia, Xilinx, NXP, Huawei
- Rich multi-OS layer
 - Jailhouse/Xen hypervisor
 - Erika/FreeRTOS RTOS
 - Linux
- Possible applications: car ECU/gateway, drone flight computer, industrial automation control

Topic list i

- 1. Safety system monitor
 - 1.1 Virtual machine watchdog for Jailhouse: detect failures and take actions
 - 1.2 Hardware watchdog support for Jailhouse on i.MX 8QM
- 2. Automated testing on Linux and Jailhouse
 - 2.1 Automatic test execution routine on Nvidia Xavier AGX (e.g. CUDA tests, DRIVE demo)
 - 2.2 Initial Jailhouse support for Arm Workload Automation

Topic list ii

- 3. Advanced memory management on Jailhouse hypervisor
 - 3.1 Human interface for memory bandwidth throttling: static configuration of VM
 - 3.2 Automatic VM configurator: translate JSON to C configurations
- 4. Jailhouse paravirtualisation support (VM drivers + hypervisor mediation)
 - 4.1 Engineering of UART support for console multiplexing
 - 4.2 Engineering of CAN support for virtual devices

Questions on the Dolly forum, or privately at

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