# Matteo Bettini

## Curriculum Vitae

### Education

2021- PhD in Computer Science, University of Cambridge

Jun 2025(Est) Researching heterogeneity and resilience in learning for multi-robot/agent systems

2020–2021 MPhil in Advanced Computer Science, University of Cambridge

Distinction GPA: 87.09/100

Thesis on transport network design for multi-agent routing

2017–2020 BEng in Computer Engineering, Politecnico di Milano

110 Cum Laude/110 (Honors)

GPA: 29.16/30

## Experience

#### Work

Jun-Oct 2023 Machine Learning Engineer Intern (PhD), Meta - PyTorch, London

Worked in the TorchRL team.

- Integrated multi-agent in TorchRL
- Developed BenchMARL, a facebook research multi-agent reinforcement learning benchmarking library

Jun-Sept Software Development Engineer Intern, Amazon Web Services (AWS), Cambridge

2021 Worked in the EC2 team using the Rust programming language to implement an interactive serial console for Xen-based EC2 instances.

- O Developed a deep knowledge of the Rust programming language
- Used cryptographic and asynchronous programming libraries

#### **Teaching**

2021-present Teaching Assistant and Supervisor, University of Cambridge, Cambridge

- Teaching assistant, demonstrator, and robot fleet manager for the "Introduction to Robotics" undergraduate and postgraduate course
- MPhil Thesis Supervisor
- O Supervisor for the "Concepts in Programming Languages" undergraduate course

## Awards and Recognition

2017-2020 Merit-based scholarship at Politecnico di Milano - 50% tuition reduction

2017-2020 Achieved 30 Cum Laude/30 (Honors) for 13 of 25 exams at Politecnico di Milano

2017 Best Freshmen of Politecnico di Milano Award - 1500€

## Skills

Programming Python, Java, Rust, C, JavaScript Deep learning PyTorch, scikit-learn, NumPy, RLlib, SciPy

Systems Linux, ROS, Networking, Bash Others HTML, CSS, Java Servlets, SQL, RDF, OWL, XML, VHDL, LATEX

# Languages

English Full proficiency Certifications: TOEFL IBT 112/120 (Sept 2019)

Italian Native

# Publications

- [1] **Matteo Bettini**, Ajay Shankar, and Amanda Prorok. Heterogeneous multi-robot reinforcement learning. AAMAS '23. International Foundation for Autonomous Agents and Multiagent Systems, 2023.
- [2] Steven Morad, Ryan Kortvelesy, **Matteo Bettini**, Stephan Liwicki, and Amanda Prorok. Popgym: Benchmarking partially observable reinforcement learning. In *International Conference on Learning Representations*, 2023.
- [3] **Matteo Bettini**, Ryan Kortvelesy, Jan Blumenkamp, and Amanda Prorok. Vmas: A vectorized multi-agent simulator for collective robot learning. *The 16th International Symposium on Distributed Autonomous Robotic Systems*, 2022.
- [4] Matteo Bettini and Amanda Prorok. On the properties of path additions for traffic routing. IEEE International Conference on Intelligent Transportation Systems (ITSC) Workshop on Co-Design and Coordination of Future Mobility Systems, 2022.

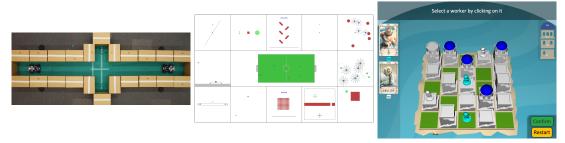
#### Interests

Multi-Robot Systems

- Heterogeneous Multi-Agent Learning
- Reinforcement Learning
- Graph Neural Networks

## Selected projects

- Heterogeneous robot learning: crystallized the role of heterogeneity in multi-robot reinforcement learning through simulations and real-world experiments [1] (Fig. 1a). Link
- Vectorized multi-agent simulator: designed and implemented a batched multi-agent simulator in PyTorch for multi-agent reinforcement learning [3] (Fig. 1b). Link
- Santorini videogame: reinvented the table game "Santorini" as a Java multiplayer online game with 3D graphics and many new features (Fig. 1c). *Link*



(a) Heterogeneous robot learning

(b) Vectorized multi-agent simulator

(c) Santorini videogame

Figure 1: Project media