# Matteo Bettini

# Curriculum Vitae

### Education

2021- PhD in Computer Science, University of Cambridge

Mar 2025 Researching heterogeneity and resilience in learning for multi-robot/agent systems

2020-2021 MPhil in Advanced Computer Science, University of Cambridge

Distinction GPA: 87.09/100

Thesis on transport network design for multi-agent routing

2017–2020 BEng in Computer Engineering, Politecnico di Milano

110 Cum Laude/110 (Honors)

GPA: 29.16/30

## Experience

Work

Jun-Oct 2023 Meta, PyTorch, Machine Learning Engineer Intern (PhD), London

Worked in the TorchRL team.

- Integrated multi-agent support in TorchRL
- O Developed BenchMARL, a facebook research multi-agent reinforcement learning library

Jun-Sep 2021 Amazon Web Services (AWS), Software Development Engineer Intern, Cambridge

Worked in the EC2 team using the Rust programming language to implement an interactive serial console for Xen-based EC2 instances.

- $\,\circ\,$  Developed a deep knowledge of the Rust programming language
- Used cryptographic and asynchronous programming libraries

#### Teaching

2021-present University of Cambridge, Teaching Assistant and Supervisor, Cambridge

- Teaching assistant, demonstrator, and robot fleet manager for the "Introduction to Robotics" undergraduate and postgraduate course
- MPhil thesis supervisor
- Supervisor for undergraduate courses

# Awards and Recognition

2021 Graduated with Distinction from the University of Cambdrige

2017-2020 Achieved 30 Cum Laude/30 (Honors) for 13 of 25 exams at Politecnico di Milano and graduated Cum Laude

2017-2020 Merit-based scholarship at Politecnico di Milano - 50% tuition reduction

2017 Best Freshmen of Politecnico di Milano Award - 1500€

Skills

Programming Python, Java, Rust, C, JavaScript Deep learning PyTorch, scikit-learn, NumPy, SciPy, Ianguages TorchRL, TorchGeometric

## **Interests**

- Multi-Robot Systems
- Reinforcement Learning
- Multi-Agent Learning
- Graph Neural Networks

# Selected projects

- BenchMARL: created the facebook research BenchMARL project for standardized benchmarking of multi-agent reinforcement learning [5] (Fig. 1a). Link
- TorchRL: second contributor of the official PyTorch reinforcement learning library [1].
  Link
- Heterogeneous robot learning: crystallized the role of heterogeneity in multi-robot reinforcement learning through simulations and real-world experiments [2] (Fig. 1b). Link
- **Vectorized multi-agent simulator**: designed and implemented a batched multi-agent simulator in PyTorch for multi-agent reinforcement learning [4] (Fig. 1c). *Link*



- (a) BenchMARL library.
- (b) Heterogeneous robot learning.
- (c) Vectorized multi-agent simulator.

Figure 1: Project media

#### **Publications**

- [1] Albert Bou, Matteo Bettini, Sebastian Dittert, Vikash Kumar, Shagun Sodhani, Xiaomeng Yang, Gianni De Fabritiis, and Vincent Moens. TorchRL: A data-driven decision-making library for PyTorch. In *International Conference on Learning Representations (ICLR) Spotlight (top 5%)*, 2024.
- [2] Matteo Bettini, Ajay Shankar, and Amanda Prorok. Heterogeneous Multi-Robot Reinforcement Learning. In *Autonomous Agents and Multiagent Systems (AAMAS)*, 2023.
- [3] Steven Morad, Ryan Kortvelesy, **Matteo Bettini**, Stephan Liwicki, and Amanda Prorok. POPGym: Benchmarking Partially Observable Reinforcement Learning. In *International Conference on Learning Representations (ICLR)*, 2023.
- [4] **Matteo Bettini**, Ryan Kortvelesy, Jan Blumenkamp, and Amanda Prorok. VMAS: A Vectorized Multi-Agent Simulator for Collective Robot Learning. In *Distributed Autonomous Robotic Systems (DARS)*, 2022.
- [5] **Matteo Bettini**, Amanda Prorok, and Vincent Moens. BenchMARL: Benchmarking Multi-Agent Reinforcement Learning. *arXiv preprint arXiv:2312.01472*, 2023.
- [6] **Matteo Bettini**, Ajay Shankar, and Amanda Prorok. System Neural Diversity: Measuring Behavioral Heterogeneity in Multi-Agent Learning. *arXiv preprint arXiv:2305.02128*, 2023.
- [7] Jan Blumenkamp, Ajay Shankar, **Matteo Bettini**, Joshua Bird, and Amanda Prorok. The cambridge robomaster: An agile multi-robot research platform. *arXiv preprint arXiv:2405.02198*, 2024.

[8] Matteo Bettini and Amanda Prorok. On the properties of path additions for traffic routing. IEEE International Conference on Intelligent Transportation Systems (ITSC) Workshop on Co-Design and Coordination of Future Mobility Systems, 2022.

# Languages

English Full proficiency Certifications: TOEFL IBT 112/120 (Sept 2019)

Italian Native

#### Invited talks

#### BenchMARL: Benchmarking Multi-Agent Reinforcement Learning

- 2024 O Distributed and Collaborative Intelligent Systems and Technology (DCIST) Collaborative Research Alliance (CRA)
- 2023 O InstaDeep knowledge sharing session InstaDeep

#### Multi-Agent Simulation and Learning in TorchRL

- 2023 O Artificial Intelligence Research Group Talks (Computer Laboratory) University of Cambridge Video link
- 2023 O Multi-agent Reinforcement Learning Reading Group University of Maryland, College Park

#### Heterogeneous Multi-Robot Reinforcement Learning

2022 O Distributed and Collaborative Intelligent Systems and Technology (DCIST) Collaborative Research Alliance (CRA)

## Courses taught

- 2021-22, Introduction to Robotics, MPhil, Part III, Part II in Computer Science, University of
- 2022-23 Cambridge

Teaching assistant, grader, demonstrator, mini-project supervisor, and robot fleet manager

- 2021-22, Concepts in Programming Languages, Part IB in Computer Science, University of
- 2022-23 Cambridge

Creation & grading of personalized supervision sessions for 5 groups of 2 undergraduate students

#### Thesis supervision

- 2023 Alex Shaw, MPhil in Machine Learning and Machine Intelligence, University of Cambridge
- 2023 Sepand Dyanatkar, MPhil in Advanced Computer Science, University of Cambridge

#### Academic service

#### Organization

#### 2023 ICRA 2023 Workshop on Multi-Robot Learning, Contributions Committee

#### Reviewer duty

- o ICRA o RA-L
- O The International Journal of Robotics Research
- Encyclopedia of Robotics

Outreach

2023, 2024 Computer Science Open Day, Volunteer, University of Cambridge

Explained and demonstrated multi-agent reinforcement learning to kids of all ages.