# Matteo Bettini

# Researcher in multi-agent learning

Interested and experienced in reinforcement learning, multi-robot systems, and graph neural networks

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2021-Mar PhD in Computer Science, University of Cambridge, UK

2025 Thesis: Neural diversity in multi-agent systems, Supervisor: Prof. Amanda Prorok

- $\circ$  Published 8 research papers [1–8] at top conferences (e.g., ICML, ICLR, AAMAS) and journals (JMLR)
- $\ \, \text{Focus on studying [4], measuring [9], and controlling [1] behavioral diversity in multi-agent reinforcement learning}$
- O Created and maintained VMAS [5] (320+ stars), a vectorized simulator and task collection written in PyTorch
- Deployed and demonstrated research on a fleet of Cambridge Robomaster autonomous mobile ground robots [8] ♂

2020–2021 MPhil in Advanced Computer Science, University of Cambridge, UK

Distinction, GPA: 87.09/100, Supervisor: Prof. Amanda Prorok

Thesis on transport network design for multi-agent routing using genetic algorithms and reinforcement learning 🗅

2017–2020 BEng in Computer Engineering, Politecnico di Milano, Italy

110 Cum Laude/110 (Honors), GPA: 29.16/30

Project on software engineering: reinvented board game "Santorini" in Java with online multiplayer and 3D graphics 🗅

# Experience

#### Work

Jun-Oct 2023 Meta, PyTorch, Machine Learning Engineer Intern (PhD), London, UK

Worked in the TorchRL team on PyTorch and facebook-research open-source projects, leading to 2 publications [2,3]

- $\circ$  Integrated multi-agent in the PyTorch reinforcement learning library TorchRL (2.2k+ stars), becoming  $2^{nd}$  contributor
- O Developed and maintained BenchMARL (250+ stars), a facebook-research multi-agent reinforcement learning library

Jun-Sep 2021 Amazon Web Services (AWS), Software Development Engineer Intern, Cambridge, UK

Worked in the EC2 team using Rust to implement an interactive serial console for Xen-based EC2 instances

- O Learned and used the Rust language with cryptographic and asynchronous programming libraries
- O Implemented an encrypted CoAP client-server and tested on docker rapid development environment

## **Teaching**

2021-present University of Cambridge, Teaching Assistant and Supervisor, Cambridge, UK

- Teaching assistant, demonstrator, and robot manager for "Introduction to Robotics" bachelor and master course ☑
- ${\scriptsize \circ} \ \ \, \textit{Thesis supervisor} \,\, \text{for MPhil students, guiding them in conducting research and producing a master dissertation}$
- O Supervisor and material curator for undergraduate courses, tutoring 19 students in small-sized groups

## Outreach

2024-present The Alan Turing Institute, Organizer, London, UK

- Organized the UK Multi-Agent Systems Symposium, a one-day event in King's College London with 200 attendees ♂

2024-25 **Lead The Future**, *Mentor* 

Mentored 5 high-achieving STEM Italian students and professionals in a non-profit organization focused on Give Back ♂

2023, 2024 Computer Science Open Day, Volunteer, University of Cambridge, UK

Demonstrated multi-robot reinforcement learning to 100+ kids of all ages via live and interactive experiments ♂

2023 ICRA Workshop on Multi-Robot Learning 2 , Contributions Committee, London, UK

# Awards and recognition

- 2024 Hughes Hall College (University of Cambridge) travel grant 500£
- 2021 Graduated with Distinction from the University of Cambridge
- 2017–2020 Achieved 30 Cum Laude/30 (Honors) for 13 of 25 exams at Politecnico di Milano and graduated Cum Laude
- 2017–2020 Merit-based scholarship at Politecnico di Milano 50% tuition reduction
  - 2017 Best Freshmen of Politecnico di Milano Award 1500€

## Skills

Programming Python, Java, Rust, C, JavaScript, VHDL Systems Linux, MacOS, ROS, SLURM, HPC, Docker

Al Libraries PyTorch, scikit-learn, NumPy, SciPy, TorchRL, TorchGeometric, TensorFlow, Pandas, matplotlib

# Selected projects

- o **BenchMARL**: created the facebook-research BenchMARL library (250+ stars, 5k+ downloads) to standardize benchmarking in multi-agent reinforcement learning, published at JMLR and presented at NeurIPS [2] ☑
- Controlling behavioral diversity: introduced the first method able to control behavioral diversity in multi-agent learning, showing the emergence of unprecedented and more efficient diverse strategies [1] ☑
- o **TorchRL**: second contributor of the PyTorch reinforcement learning library (2.2k+ stars, 340k+ downloads), spanning multiple domains of data-driven decision-making (model-based/free, LLM RLHF, POMDPs) [3] ☑
- o **Heterogeneous robot learning**: crystallized the role of heterogeneity in multi-robot reinforcement learning through simulations and real-world experiments, demonstrating the intrinsic resilience of diverse robots [4] ♂
- o **Vectorized multi-agent simulator (VMAS)**: implemented and maintained VMAS (320+ stars, 31k+ downloads), a batched PyTorch multi-agent simulator and task collection for collective learning [5] □
- **Multi-robot navigation**: deployed and demonstrated collective learning in a zero-shot sim-to-real setting on a fleet of custom Cambridge Robomaster holonomic ground robots equipped with NVIDIA Jetsons [8] ☑

# Selected publications

- [1] Matteo Bettini, Ryan Kortvelesy, and Amanda Prorok. Controlling Behavioral Diversity in Multi-Agent Reinforcement Learning 2. In *International Conference on Machine Learning (ICML)*, 2024.
- [2] Matteo Bettini, Amanda Prorok, and Vincent Moens. BenchMARL: Benchmarking Multi-Agent Reinforcement Learning . Journal of Machine Learning Research (JMLR), 25, 2024.
- [3] Albert Bou, **Matteo Bettini**, Sebastian Dittert, Vikash Kumar, Shagun Sodhani, Xiaomeng Yang, Gianni De Fabritiis, and Vincent Moens. TorchRL: A data-driven decision-making library for PyTorch 2. In *International Conference on Learning Representations (ICLR) Spotlight (top 5%)*, 2024.
- [4] **Matteo Bettini**, Ajay Shankar, and Amanda Prorok. Heterogeneous Multi-Robot Reinforcement Learning ... In *Autonomous Agents and Multiagent Systems (AAMAS)*, 2023.
- [5] **Matteo Bettini**, Ryan Kortvelesy, Jan Blumenkamp, and Amanda Prorok. VMAS: A Vectorized Multi-Agent Simulator for Collective Robot Learning 2. In *Distributed Autonomous Robotic Systems (DARS)*, 2022.
- [6] Amanda Prorok and Matteo Bettini. Heterogeneous Teams 2. Encyclopedia of Robotics, 2024.
- [7] Steven Morad, Ryan Kortvelesy, **Matteo Bettini**, Stephan Liwicki, and Amanda Prorok. POPGym: Benchmarking Partially Observable Reinforcement Learning . In *International Conference on Learning Representations* (*ICLR*), 2023.
- [8] Jan Blumenkamp, Ajay Shankar, **Matteo Bettini**, Joshua Bird, and Amanda Prorok. The Cambridge RoboMaster: An Agile Multi-Robot Research Platform 2. In *Distributed Autonomous Robotic Systems* (DARS), 2024.
- [9] **Matteo Bettini**, Ajay Shankar, and Amanda Prorok. System Neural Diversity: Measuring Behavioral Heterogeneity in Multi-Agent Learning 2. arXiv preprint arXiv:2305.02128, 2023.

## Invited talks

## BenchMARL: Benchmarking Multi-Agent Reinforcement Learning

- 2024 O Distributed and Collaborative Intelligent Systems and Technology (DCIST) Collaborative Research Alliance (CRA)
- 2023 O InstaDeep knowledge sharing session InstaDeep

#### Multi-Agent Simulation and Learning in TorchRL

- 2023 O Artificial Intelligence Research Group Talks (Computer Laboratory) 🗈 University of Cambridge 🛂
- 2023 O Multi-agent Reinforcement Learning Reading Group & University of Maryland, College Park

#### Heterogeneous Multi-Robot Reinforcement Learning

2022 O Distributed and Collaborative Intelligent Systems and Technology (DCIST) Collaborative Research Alliance (CRA)

## Courses taught

- 2021-22, Introduction to Robotics of , MPhil, Part III, Part III in Computer Science, University of Cambridge
- 2022-23 Teaching assistant, grader, demonstrator, mini-project supervisor, and robot fleet manager
- 2021-22, Concepts in Programming Languages 2 , Part IB in Computer Science, University of Cambridge
- 2022-23 Creation & grading of personalized supervision sessions for 19 undergraduate students in groups of 2

### Languages

English Full proficiency (TOEFL IBT 112/120)

Italian Native