

34. Jordan canonical form

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$$\dot{x} = Ax \quad A \in \mathbb{R}^{n \times n}$$

$$\exists T : TAT^{-1} = J$$

$$A = T^{-1}JT = T^{-1}e^{Jt}T$$

$$e^{At} = e^{(T^{-1}JT)t} = I + T^{-1}JTt + \frac{t^2}{2!} T^{-1}J^2T + \dots \\ = T^{-1} (I + tJ + \frac{t^2}{2!} J^2 + \dots) T$$

A regular (T can be diagonalized)

$$|\lambda I - A| = 0 \Rightarrow d(\lambda) = a_0 + a_1\lambda + \dots + a_n\lambda^{n-1} + a_n = 0$$

$\rightarrow \lambda_1, \lambda_2, \dots, \lambda_v$ with corresponding algebraic multiplicity m_{α_i} ,
 $m_{\alpha_1}, m_{\alpha_2}, \dots, m_{\alpha_v}, i = 1, \dots, v$

$$\sum_{i=1}^v m_{\alpha_i} = n$$

To be diagonalizable A must satisfy $\forall i = 1, \dots, v$:

$$\text{rank } \{(A - \lambda_i I)\} = n - m_g(\lambda_i)$$

or in other words: $\dim \{\ker(A - \lambda_i I)\} = m_g(\lambda_i)$ that is the geometric multiplicity.

If this condition holds T can find n independent eigenvectors v_i s.t., applying T , A becomes diagonal

$$T^{-1} = [v_1, \dots, v_n] \Rightarrow TAT^{-1} = \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{bmatrix} = \text{diag}\{\lambda_1, \dots, \lambda_n\}$$

complex case

$$T^{-1} = \begin{pmatrix} v & | & va & vb \end{pmatrix}$$

$$TAT^{-1} = \begin{pmatrix} \lambda & | & 0 & \\ 0 & | & \alpha & w \\ 0 & | & -w & \alpha \end{pmatrix} = \Lambda_R \sim \text{real diagonal form of the operator}$$

$$A = T^{-1} \Lambda_R T$$

$$e^{At} = T^{-1} e^{\Lambda_R t} T \rightarrow e^{\Lambda_R t} = \begin{pmatrix} e^{\lambda t} & | & 0 & \\ 0 & | & e^{(\alpha w - \beta)t} & \\ 0 & | & e^{(-\alpha w - \beta)t} & \end{pmatrix}$$

$$e^{At} = T^{-1} e^{A\lambda_1 t} T + \dots + T^{-1} e^{A\lambda_n t} T = \left(\sum_{i=1}^n e^{(\lambda_i + \alpha_i) t} \right)$$

$$e^{(\lambda_i + \alpha_i) t} = e^{\alpha_i t} \begin{pmatrix} \cos \omega_i t & \sin \omega_i t \\ -\sin \omega_i t & \cos \omega_i t \end{pmatrix}$$

A non-regular

Let $\{\lambda_1, \dots, \lambda_v\}$ the set of distinct eigenvalues of A

m_i = algebraic multiplicity of λ_i

μ_i = geometric " "

Suppose that at least for one λ_i is $m_i \neq \mu_i$

I or squared non-singular matrix $T \in \mathbb{C}^{n \times n}$ s.t.

$$\textcircled{*} \quad TAT^{-1} = J = \text{diag} \{ J_1, \dots, J_v \}$$

$$\dim \{ J_i \} = m_i \quad i = 1, \dots, v \quad J_i = \text{Jordan blocks of } A$$

$\underbrace{\quad}_{\text{square}}$

$$\textcircled{*} \quad J_i = \text{diag} \{ J(\lambda_i, d_{i1}), \dots, J(\lambda_i, d_{i\mu_i}) \}$$

λ_i = eigenvalue $i = 1, \dots, v$

d_{ij} = dimension $j = 1, \dots, \mu_i$

$$J(\lambda_i, d_{ij}) = \begin{bmatrix} \lambda_i & & & 0 \\ & \ddots & & \\ & & \ddots & 0 \\ 0 & & & \lambda_i \end{bmatrix}$$

for a given matrix A the Jordan form is unique.

Property

μ_i = number of Jordan blocks of A associated to λ_i

Generalized eigenvectors of A

$$TAT^{-1} = J \Rightarrow AT^{-1} = T^{-1}J \subset T^{-1} \text{diag} \{ J_1, \dots, J_v \}$$

partitioning T^{-1} :

$$A[W_1 | \dots | W_v] = [W_1 | \dots | W_v] \begin{bmatrix} J_1 & & \\ & \ddots & \\ & & J_v \end{bmatrix}$$

$$A W_i = W_i J_i \quad i = 1, \dots, v$$

Partitioning W_i :

$$A[W_{i1}, \dots, W_{ip_i}] = [W_{i1}, \dots, W_{ip_i}] \begin{bmatrix} \mathcal{S}(\lambda_i, d_{i1}) & & \\ 0 & \ddots & \\ & & \mathcal{S}(\lambda_i, d_{iN_i}) \end{bmatrix}$$
$$AW_{ij} = W_{ij} \quad \mathcal{S}(\lambda_i, d_{ij}) \quad i=1 \dots v$$
$$\quad \quad \quad j=1, \dots, N_i$$

Let w_{ijl} , $l=1, \dots, d_{ij}$ be the columns of W_{ij} :

$$A[w_{ij1}, \dots, w_{ijd_{ij}}] = [w_{ij1}, \dots, w_{ijd_{ij}}] \begin{bmatrix} \lambda_i & 1 & 0 \\ 0 & \lambda_i & 1 \\ 0 & 0 & \lambda_i \end{bmatrix}$$

After some computations we obtain the relation

$$\begin{cases} (A - \lambda_i I)^{d_{ij}} w_{ijl} = 0 & l=1, \dots, d_{ij} \\ (A - \lambda_i I)^{d_{ij}-1} w_{ijl} = w_{ij1} \neq 0 & l=2, \dots, d_{ij} \end{cases}$$

