

• Linear systems $\dot{x} = Ax \quad x_0 \in \mathbb{R}^n$

Consider a subspace $V \subseteq \mathbb{R}^n$ and a linear mapping $A: \mathbb{R}^n \rightarrow \mathbb{R}^n$

V is invariant under A if $Av \in V$

(where, of course, v is a vector of V)

$x \in V$ belongs to the state-space

$Ax \in V$ does not belong to the state-space. It belongs to the space of the 1-st derivative: Target space

Trivial subspaces are $\{0\}$, V .

Invariant subspaces \subseteq eigenspaces

• Non linear systems

$$\dot{x} = f(x) \quad x(0) = x_0 \neq 0 \in \mathbb{R}^n$$

$f(\cdot)$ vector field: law which associates a function f to each x

$$x \mapsto f(x) \in \underbrace{T_x \mathbb{R}^n}_{\text{target space}}$$

\rightarrow **Manifold** of \mathbb{R}^n (attached to the point x)

in general:

$x \in M$: M differential manifold \rightarrow the most general surface structure on which I can define a differential equation

An n -dimensional Manifold is a surface in the linear space \mathbb{R}^{n+1}

example: Manifold of dimension 2: $M \subset \mathbb{R}^3$

It's possible to define a differential equation over a Manifold by defining a vector field that represents the target space of M

$f(x) \in T_x M$: $T_x M$ target space of M

Given a manifold and a differential equation we can define the evolution on that manifold.

$f(x)$ is said to be integrable at x_0 if the integral curves doesn't intersect themselves (unique solution)

The integral of a vector field $f(x)$ corresponds to the solution of $\dot{x}(x)$

The integral of a vector field $f(x)$ corresponds to the
potential of $f(x)$