Consider or typical classification problem 4: X-0 Y \$: X → Y

· b: probodsitity distribution over X

S: Somple of n inctorces drawn from X (occording to distribution D) and for which we know f(x)

Performance evolution in classification; s based on Accuracy of ERROR RATE.

Let's define two errors:

· the TRUE ERROR of hypothesis h wrt torgor funding of ord distribution Dis the probability that I will miss classify on instace drown of rondon occording to bi

errors (h) = Pr [f(x) fh(x)] Hoke of confine

· The SAMPLE GRROR of the writ toget fundion and sample S is the proportion of examples In miss dossifies:

error (en) = $\frac{1}{5} \sum_{x \in S} S(f(x) \neq h(x))$ computed from the dotosets

 $\left\{ \left(\frac{f(x)}{h(x)} \right) = \begin{cases} 1 & \text{if } f(x)/h(x) = 1 \\ 0 & \text{otherwise} \end{cases}$

the true error is more important, is what we word to evolute, becouse we ere interested in classify a new instance.

The TRUE GRROR cond be computed since for a new instance we do not know f(x). Note: the good of a learning system is to be occurred in how tx & S. ACCURACY(h)= 1-ERROR(h) IF ACEURACY (h) is very high and ACEURACY (h) is very low, then our system would not be useful. We now understand how to compute the semple error. Let's understand the following: X S, to how errors, (h) pererte a dotaset by the set & and compute a selvion In for which we conjoure the error is LIKE ROLLING A DICE, because we close a porticular set of ROLL THE SICE AGAIN WE have a new solution and a NEW ERROR. In general, given a rondon veriable the expected volve is detined as the infinite average of possible outcomes BIAS = E [errors (h)] - errors (h)

We won't that the bios is zero and if it is error, (h) = E[error, (h)].
How to compute error, (h):

· fortition the dooset > (5=TUS adTAS=0) (We use a training set to bean a and a set to compute the hypothesis evolution, this is on unbiased estimation

to be UNBIASES the set for which we compute the error should be independent from the ene used to compute the hypothesis.

- · Compute la by size !
- Evolute errors (ei)= $\frac{1}{n} \stackrel{2}{\lesssim} S(g(x) \neq h(x))$

This process should be respected many times twe do not rolling a dice once), in principle you should respect it infinite times.

Confidence intervals

-5 contains in sample

(In increases while percentage increases)

Then with approximately N% possibility, every (h) lies in intenditions (h) (1 - every (ev))every (h) $\pm \sqrt{every (ev) (1 - every (ev))}$

N% 50% 68% 80% --- 99% 22 0.67 1.28 1.64 --- 7.58

Crive two hypothesis we may most to compare then. We have no GUARANTEES that if one has better on S is also better on S.

d= errors (hi) - errors (hz) d= errors (lm) - errors (lnz) d is on un biosed E[d]=d estimos for a iff h, hz, s, and sz ere INSEPENDENT Hypothesis held OVERFITS freining doze if there is from each other or oftendive hypothesis h'elt such that error (h) < error (h) AND error (h) > error (h) EVALUATION of the output of LEARNING ALC. The best way to evaluate the output of a learning deposition is to use a technique collect ke fold cross volidain K-FOLD CROSS VALIDATION e Pertition dooset binto & DISSOINT set Si. Sk (|Sil > 30) · For := 1 ... K solve k luse So as test set, and the remaining data times, as training set Ti earing | T: + { D - 5: } problem | hi & L(Ti) [solution of the learning desithin] S; & error (Cik • Return: error, 5; 1 € 5; , acuracy = 1 - error, 5

We con use it also for comparino two different learning algorithm LA and LB if the value returned size of then LA is better than LB.

Note: He size of the training set K-1/DI (nost of the size)

OTHER PERFORMANCE METRICS

"Is eccured durys a good performace metric!"

Let's suppose to have a binary classification

g: X-P \{-, +\} with training set. D containing

90 % of positive samples.

I have two hypothesis hi and he hi, has accuracy of the 90% and he nos accuracy 85%, which is the best?

Well in general his but his may be a solution that always return t and his a result of a classification algorithm.

In some cases, ecurecy is not enough to assess the performanced of a classification method.

Unbolored do osets de very common in problems reloted to anomaly objection.

(e.e. include oralysis, froud detection, medical texts, etc.

PRESICTES CLASS $\mathcal{N} \mathcal{O}$ TRUE CLASS YES YES TP FN NO FP TN Error rote = | error | / lingonces 2 (FN+FP) (FP+FN+TP+TN) Occuracy = 1- Evarate = TP+TN FP+FN+JP+TN P= TP (FP+FP) R= TP TP+FN & red positive RECALL! dostity pred-Jed of the 5/5 positive to ovoid FN PRECISION: doilty to

F1 - Score = ZPR P+R

Let's consider the system of outeromous cor that detects pedestion and brotes!

- · FP: Here is no person, but the system sees or person
- · FN: Here is a person but the system does not see it.

Folse positive and folse regotive have different relevance, you want ALGH RECALL!

ROC CURVE: you can plot the relation between TPI and FP, very ing some parameter of the algorithm.

TP D ROC Area: Area under the curve

CONFUSION MATRIX:

la e classification problem with many classes, we can compute how many times on instance of Ci is classified as Cj.

MAIN SIAGONAL CONTAINS ACCURACY FOR EACH CLASS.

By CM you can understand which classes ore usually miss classified.