

## • Stationarity

$$\forall \bar{t} : W_m(t, \tau_1, \dots, \tau_m; x_0) = W_m(t + \bar{t}, \tau_1 + \bar{t}, \dots, \tau_m + \bar{t}; x_0)$$

## • Factorization

$$W_1(t, \tau_1, t_0; x_0) = W_{11}(t - \tau_1)$$

$$W_2(t, \tau_1, \tau_2, t_0; x_0) = W_{21}(t - \tau_1) W_{22}(\tau_1 - \tau_2)$$

⋮

$$W_m(t, \tau_1, \dots, \tau_m, t_0; x_0) = W_{m1}(t - \tau_1) \dots W_{mm}(\tau_{m-1} - \tau_m)$$

## • Separability

Stationarity and factorization implies separability of linear representation:

∃ matrices of functions  $Q(\cdot)$  and  $P(\cdot)$  such that

$$\begin{aligned} W_1(t - \tau_1) &= Q(t) P(\tau_1) \quad t \geq \tau_1 \\ &= C e^{(t - \tau_1)} \cdot B \end{aligned}$$

⋮

$$W_{ij}(\tau_{j-1} - \tau_j) = Q_{ij}(\tau_{j-1}) P_{ij}(\tau_j) = C_{ij} e^{(\tau_{j-1} - \tau_j)} A_{ij} B_{ij}$$