Electrical Engineering HSLU, Semester 2

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Contents

Ι	•••						
1							
	1.1	Current strength or current "I"					
	1.2	Current density "J"					
	1.3	Temperature dependence of the resistance					
	1.4	Object properties					
	1.5	Reciprocal quantities					
		1.5.1 Specific resistance					
		1.5.2 Conductance					
		1.5.3 Specific conductivity					
2	Gra	Gravitational fields					
	2.1	Between bodies					
	2.2	Between particles					
		2.2.1 Coulomb's law					
	2.3	Electric field and force on a charge Q					
		2.3.1 Homogeneous electric fields					
		2.3.2 Force on a point charge					
3	Cap	pacitance and Capacitor					
	3.1	Capacitor					
	3.2	Capacitance					
		3.2.1 Capacitance of a plate capacitor					
		3.2.2 Energy in a capacitor					
	3.3	Capacitors in parallel connection					
	3.4	Capacitors in series connection					
4	Trai	Transient Analysis in RC Circuits					
	4.1	Charging of a Capacitor					
	4.2	Discharging of a Capacitor					
	4.3	Transitional phase					
5	Add	Additional Topics					
	5.1	Energy Stored in a Capacitor					
	5.2	Charge–Voltage Relationship					
6	Elec	Electromagnetic fields					
Ū	6.1	Hans Christian Ørsted Observation					
	6.2	Definitions and formulas					
	0.2	6.2.1 Magnetomotive force					
		6.2.2 Ampère's circuital law					
		6.2.3 Magnetic field in a coil					
		6.2.4 Magnetic flux density					
		U.4.T IVINGHOUL HUA UCHOUV					

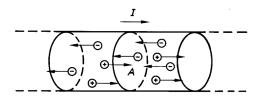
		6.2.5 Magnetic field strength in coil with iron core	0				
		6.2.6 Magnetic relative permeability μ	0				
		6.2.7 Coils with and without iron core	1				
		6.2.8 Law of induction and inductance					
		6.2.9 Inductance and induction	2				
		6.2.10 Inductivity of a very long coil	2				
		6.2.11 Energy stored in an inductor	2				
		6.2.12 Current-voltage relationship of an inductor	3				
		6.2.13 Transient analysis	3				
	6.3	Examples	4				
		6.3.1 Charging an inductor in a RL-network	4				
		6.3.2 Discharging an inductor in a RL-network	5				
_	A 1:	1. (40)	_				
7		Alternating current (AC) 7.1 Generation of alternating current / voltage					
	7.1	0 / 0					
	7.2	Comparison of AC and DC					
		7.2.1 Advantages of AC					
	- 0	7.2.2 Disadvantages of AC					
	7.3	Phasors					
	7.4	Oscillation as a function of the angle					
	7.5	Zero phase angle φ					
	= 0	7.5.1 Phase shift $\Delta \varphi$ between two signals					
	7.6	Power in a sinusoidal signal and effective value					
		7.6.1 Instantaneous power					
		7.6.2 Effective value					
	7.7	Relationship between current and voltage on a capacitor					
	7.8	Capacitive reactance X_c					
	7.9	Relationship between current and voltage on an ideal inductor					
	7.10	Inductive reactance X_L	9				

Part I

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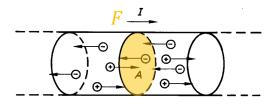
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1.1 Current strength or current "I"



$$I[A] = \frac{\text{el. charge}}{t}$$

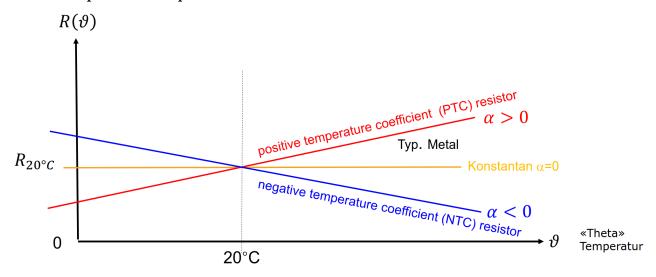
1.2 Current density "J"



The current density indicates how large the current per cross-sectional area (F) is:

$$J\ [\frac{A}{mm^2}] = \frac{I}{F}$$

1.3 Temperature dependence of the resistance



Depending on the material, the resistance can increase, remain the same or decrease with temperature. In ET+L we calculate using the linear approach.

$$R(\vartheta) = R_{20}(1 + \alpha(\vartheta - 20^{\circ}C)) = R_{20}(1 + \alpha\Delta T)$$

1.4 Object properties

The resistance indicates the voltage required for a current. In addition to the material, the cross-sectional area and also the length are decisive factors.

$$R = \frac{U}{I}$$

1.5 Reciprocal quantities

1.5.1 Specific resistance

To describe material properties, the resistance per length and cross-sectional area is specified (precondition: homogeneous conductor, direct current):

$$\rho \; [\frac{\Omega \cdot mm^2}{m}] = R \cdot \frac{A}{l}$$

1.5.2 Conductance

1.5.3 Specific conductivity

2 Gravitational fields

2.1 Between bodies

$$F_1 = F_2 = G \frac{m_1 m_2}{d^2}$$

2.2 Between particles

2.2.1 Coulomb's law

It calculates the amount of force between two electrically charged particles at rest:

$$F = \frac{1}{4\pi\varepsilon_0} \cdot \frac{q_1 q_2}{r^2}$$

where:

- *F*: Force [N];
- q: Charge [As];
- ε_0 : absolute permittivity = $8.8542 \cdot 10^{-12}$ [As/Vm].

2.3 Electric field and force on a charge Q

2.3.1 Homogeneous electric fields

$$E = \frac{U}{d}$$

where:

- E: electric field strength [V/m];
- *U*: voltage [V];
- d: distance of the electrodes [m].

2.3.2 Force on a point charge

$$F = Q \cdot E$$

- E: electric field strength [V/m];
- Q: charge [As];
- *F*: force [N].

3 Capacitance and Capacitor

3.1 Capacitor

A capacitor is a device in which the capacitance is used.

3.2 Capacitance

Capacitance C is the **capability** to store electric charge. It is measured by the charge divided by the applied voltage:

$$C = \frac{Q}{U}$$

where:

- *Q*: charge [As];
- *U*: voltage [V];
- C: capacitance [As/V = F (Farad)].

3.2.1 Capacitance of a plate capacitor

$$C = \varepsilon \cdot \frac{A}{d}$$

where:

- A: plate area (one side) [m^2];
- d: distance between plates [m];
- C: capacitance [F].

Permittivity

$$\varepsilon = \varepsilon_r \cdot \varepsilon_0$$

- ε_r : relative permittivity of the dielectric, relative to the air;
- ε_0 : absolute permittivity [As/Vm].

3.2.2 Energy in a capacitor

If a capacitor is discharged with a constant current, the voltage decreases linearly:

$$\int_0^{t_{\text{empty}}} U(t) \cdot I \, dt = I \cdot U_0 = \frac{I \cdot U_0 \cdot t_{\text{empty}}}{2}$$

Or, simplified:

$$W = \frac{1}{2}C \cdot U_0^2$$

- W: energy [J or Ws];
- U_0 : initial voltage [V];
- C: capacitance [F].

3.3 Capacitors in parallel connection

Capacitances connected in parallel add up:

$$C_{\text{tot}} = \frac{\sum_{n} Q_n}{U} = \sum_{n} C_n$$

or

$$C = \frac{\varepsilon \cdot (\sum_{n} A_n)}{d} = \sum_{n} C_n$$

3.4 Capacitors in series connection

In a series connection, the reciprocal of the total capacitance is the sum of the reciprocals of the individual capacitances:

$$\boxed{\frac{1}{C_{\rm tot}} = \sum_{n} \frac{1}{C_{n}}}$$

where:

- C_{tot} : total capacitance [F];
- C_n : capacitance of the *n*-th capacitor [F].

4 Transient Analysis in RC Circuits

4.1 Charging of a Capacitor

When a capacitor is charged through a resistor, the voltage across it increases exponentially:

$$U_C(t) = U_0 \cdot \left(1 - e^{-t/(R \cdot C)}\right)$$

with the time constant defined as:

$$\tau = R \cdot C$$

where:

- $U_C(t)$: voltage across the capacitor at time t [V];
- U_0 : applied voltage [V];
- R: resistance $[\Omega]$;
- C: capacitance [F];
- τ : time constant [s].

4.2 Discharging of a Capacitor

When a charged capacitor discharges through a resistor, the voltage decays exponentially:

$$U_C(t) = U_0 \cdot e^{-t/(R \cdot C)}$$

and the discharging current is:

$$I(t) = \frac{U_0}{R} \cdot e^{-t/(R \cdot C)}$$

4.3 Transitional phase

$$f(t) = A + \Delta \cdot (1 - e^{t/\tau}) = A + (B - A) \cdot (1 - e^{1/\tau})$$

5 Additional Topics

5.1 Energy Stored in a Capacitor

The energy stored in a capacitor is given by:

$$W = \frac{1}{2}C \cdot U_0^2$$

where:

• W: energy [J];

• C: capacitance [F];

• U_0 : voltage [V].

5.2 Charge-Voltage Relationship

For an ideal capacitor, the relationship between charge and voltage is:

$$\boxed{Q = C \cdot U}$$

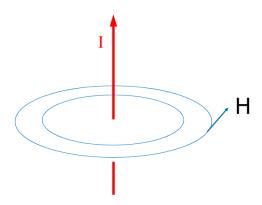
Moreover, the current is the time derivative of the charge:

$$I = \frac{dQ}{dt} = C \cdot \frac{dU}{dt}$$

Note that the voltage across an ideal capacitor cannot change instantaneously.

6 Electromagnetic fields

6.1 Hans Christian Ørsted Observation



- 1. The magnetic field lines encircle the current-carrying conductor;
- 2. The magnetic field lines lie in a plane perpendicular to the current-carrying wire;
- 3. If the direction of the current is reversed, the direction of the magnetic field lines is also reversed;
- 4. The strength of the field is directly proportional to the magnitude of the current;
- 5. The strength of the field at any point is inversely proportional to the distance of the point from the wire.

6.2 Definitions and formulas

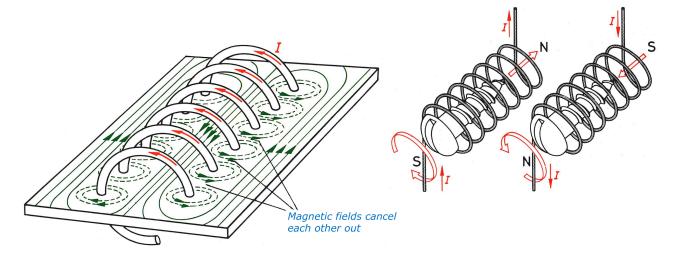
6.2.1 Magnetomotive force

$$\theta = N \cdot I$$

6.2.2 Ampère's circuital law

$$\theta = \oint \overrightarrow{H(s)} \cdot d\vec{s}$$

6.2.3 Magnetic field in a coil



6.2.4 Magnetic flux density

$$B = \frac{\Phi}{A} = \mu \cdot H = \mu_0 \mu_r \cdot H$$

where:

• B: magnetic flux density $[T = Vs/m^2]$;

• Φ: magnetic flux [Wb];

• A: area [m²];

• μ : magnetic permeability [H/m = Vs/Am];

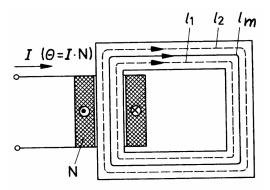
• *H*: magnetic field strength [A/m];

• μ_0 : magnetic constant $[4\pi \cdot 10^{-7} \text{ Vs/Am}]$;

• μ_r : relative permeability.

Note: Φ is the sum of all B-field lines through the cross section A

6.2.5 Magnetic field strength in coil with iron core



$$H = \frac{N \cdot I}{l_m} = \frac{\Theta}{l_m}$$

where:

• *H*: magnetic field strength [A/m];

• N: number of turns;

• *I*: current [A];

• l_m : median field line length [m];

• Θ : magnetomotive force [A].

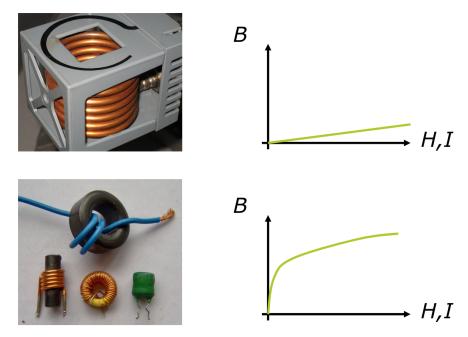
6.2.6 Magnetic relative permeability μ

Permeability is a measure for the ability to conduct magnetic field lines:

Material	$\mu_{\mathbf{r}}$
Air	1
Pure iron	up to 250'000
Electrical steel	$500 \dots 7000$
Steel	$40 \dots 7000$
Water	0.99991

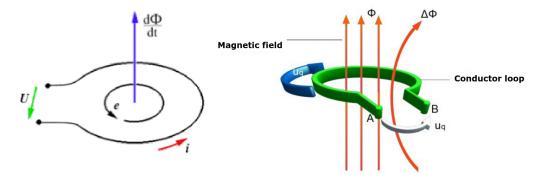
6.2.7 Coils with and without iron core

The magnetization curve of a coil without a core is linear, but there is significantly less flux density B than with an iron core.



6.2.8 Law of induction and inductance

Changing magnetic flux generates a voltage



Phenomenon: a changing magnetic flux Φ induces a voltage in a conductor loop around it:

$$U = -N \cdot \frac{\mathrm{d}\Phi}{\mathrm{d}t}$$

6.2.9 Inductance and induction

Inductance L is the capability to generate a magnetic field. It is measured by the voltage divided by the rate of change of current over time. It is a measure of the magnetic "capacity" of an arrangement of conductors (e.g. coil) and can be compared to the capacity C of a capacitor. It indicates how much magnetic flux per ampere is generated.

$$L = \frac{N \cdot \Phi}{I} = \frac{U}{\frac{\Delta I}{\Delta t}}$$

where:

- L: inductance [H = Vs/A];
- N: number of turns;
- Φ: magnetic flux [Wb];
- *I*: current [A];
- *U*: voltage [V].

6.2.10 Inductivity of a very long coil

The inductance of a very long coil can be calculated approximately with:

$$L = \frac{\mu \cdot N^2 \cdot A}{l}$$

where:

- L: inductance [H = Vs/A];
- μ : magnetic permeability [Vs/Am];
- N: number of turns;
- A: cross-section of the coil [m²];
- *l*: length [m].

6.2.11 Energy stored in an inductor

Since a variable magnetic field induces a voltage in which a current can also flow, the magnetic field must contain energy:

$$W = \frac{1}{2}L \cdot I^2$$

- W: work, energy [J = Ws];
- L: inductance [H = Vs/A];
- I: current [A].

6.2.12 Current-voltage relationship of an inductor

The current-voltage relationship of an inductor is:

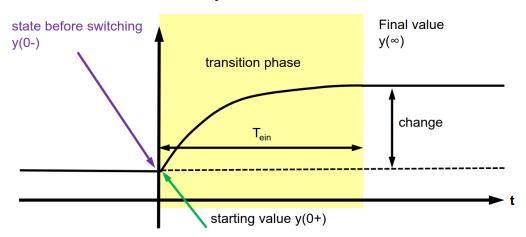
$$U = L \cdot \frac{\mathrm{d}I}{\mathrm{d}t}$$

Special case:

$$0 = L \cdot \frac{\mathrm{d}I}{\mathrm{d}t} \to u_c = 0$$

6.2.13 Transient analysis

state variable y



Switch action at t = 0

Duration of the transition phase: theoratical $T_{ein}=\infty$ practial $T_{ein}=5\cdot \tau$

1. The state variable y(t) is the variable that cannot change instantaneously. For the inductor, this is $i_L(t)$. The state just before the switch action:

$$y(0^-) = i_L(0^-).$$

2. The starting value is the state immediately before the switch action:

$$y(0^+) = i_L(0) = i_L(0^-).$$

That is, the state variable i_L keeps the value from $t = 0^-$.

3. The final value is the value long after the switch action:

$$y(\infty) = i_L(\infty),$$

which is practically reached after 5τ .

4. The transient is described by the function of time:

$$y(t) = \text{final value} + \left(\text{starting value} - \text{final value}\right) \, \exp\left(-\frac{t}{\tau}\right).$$

Hence,

$$i_L(t) = i_L(\infty) + \left(i_L(0+) - i_L(\infty)\right) \, \exp{\left(-\frac{t}{\tau}\right)}.$$

13

Time constant τ for an inductor

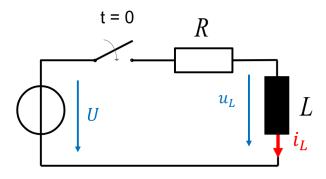
$$\tau = \frac{L}{R}$$

where:

- τ : time constant [s];
- L: inductance [H];
- R: resistance $[\Omega]$.

6.3 Examples

6.3.1 Charging an inductor in a RL-network

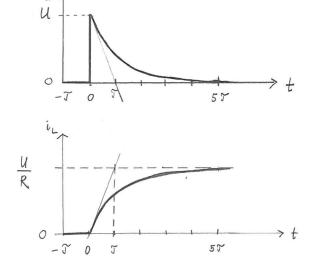


For t<0 stationary state, L discharged

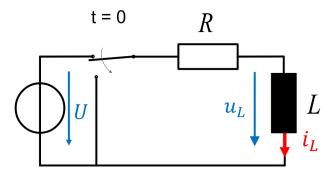
Calculations

$$i_{L} = \frac{U}{R} \cdot \left(1 - \exp\left(-\frac{t}{\tau}\right)\right)$$
$$u_{L} = U \cdot \exp\left(-\frac{t}{\tau}\right)$$

Graphical representation



6.3.2 Discharging an inductor in a RL-network



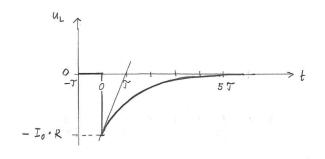
Before t = 0 stationary state: Current in inductor is I_0

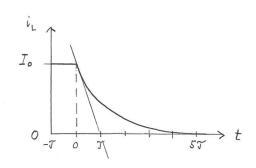
Calculations

$$i_{L} = I_{0} \cdot \exp\left(-\frac{t}{\tau}\right)$$

$$u_{L} = -I_{0} \cdot R \cdot \exp\left(-\frac{t}{\tau}\right)$$

${\bf Graphical\ representation}$





7 Alternating current (AC)

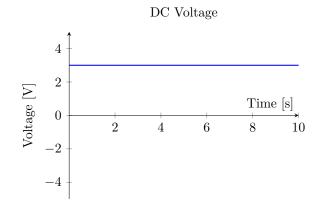
7.1 Generation of alternating current / voltage

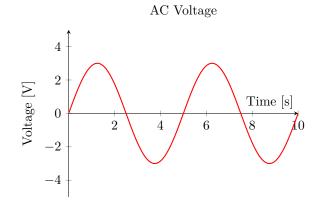
$$U = -N \cdot \frac{\Delta \Phi}{\Delta t}$$

where:

- U: voltage [V];
- N: number of turns;
- Φ : magnetic flux [Wb].

7.2 Comparison of AC and DC





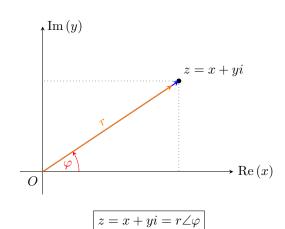
7.2.1 Advantages of AC

- Simple voltage transformation;
- Efficient trransmission;
- Easier generation;
- Compatibility with electric motors.

7.2.2 Disadvantages of AC

- Complexity in storage;
- Higher risk of shock;
- Complex circuits;
- Higher rectification costs.

7.3 Phasors



7.4 Oscillation as a function of the angle

Sinusoidal voltage has an instantaneous value u(t) or u for every time t.

After a period of time T, the curve repeats itself.

$$u(t) = \widehat{U}\sin(\omega \cdot t)$$

7.5 Zero phase angle φ

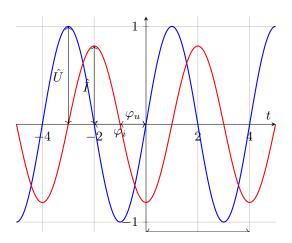
$$u(t) = \widehat{U}\sin(\omega \cdot t + \varphi_u)$$

7.5.1 Phase shift $\Delta \varphi$ between two signals

$$u(t) = \widehat{U}\sin(\omega \cdot t + \varphi_u)$$
$$i(t) = \widehat{I}\sin(\omega \cdot t + \varphi_i)$$

The phase shift between two signals is the difference between the their zero phase signals:

$$\Delta \varphi = \varphi_u - \varphi_i$$



7.6 Power in a sinusoidal signal and effective value

7.6.1 Instantaneous power

The instantaneous power p(t) is the actual power at a specific time t and is the product of the voltage u(t) and the current i(t) at that moment:

$$p(t) = u(t) \cdot i(t) = \frac{u(t)^2}{R} = i(t)^2 \cdot R$$

The active power P corresponds to the mean value of the instantaneous powerr p(t) averaged over a period T:

$$P = \frac{1}{T} \int_{0}^{T} p(t) dt$$

17

7.6.2 Effective value

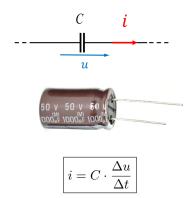
The effective value U_{eff} of a sinusoidal signal is the voltage that would generate the same power in a resistor as the sinusoidal signal:

$$U_{\text{eff}} = \sqrt{\frac{1}{T} \int_{0}^{T} u(t)^{2} dt} = \frac{\widehat{U}}{\sqrt{2}}$$

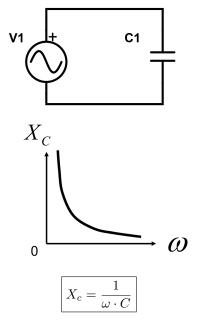
The same can be applied to the effective value $I_{\rm eff}$:

$$I_{\text{eff}} = \frac{\widehat{I}}{\sqrt{2}}$$

7.7 Relationship between current and voltage on a capacitor

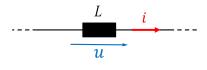


7.8 Capacitive reactance X_c



- X_c : capacitive reactance [Ohm];
- ω : angular frequency [rad/s];
- C: capacitance [F = As/V].

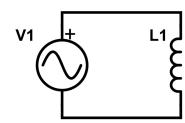
7.9 Relationship between current and voltage on an ideal inductor

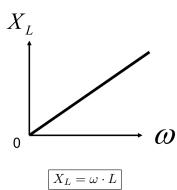




$$u = L \cdot \frac{\Delta i}{\Delta t}$$

7.10 Inductive reactance X_L





- X_L : inductive reactance [Ohm];
- L: inductance [H];
- ω : angular frequency [rad/s];