

# Paths

Matteo Paz, Dylan Rupel

February 27th, 2024

**Definition 1** *A path in a topological space  $Y$  is a continuous mapping from  $[0, 1] \rightarrow Y$ .*

Intuitively, a path is just a line or curve in your topological space. We define it to be homeomorphic to the real interval  $[0, 1]$ . If we have two paths  $p_1$  and  $p_2$ , we can also concatenate or merge them naturally, given that the endpoint  $p_1(1) = p_2(0)$ :

$$p_1 * p_2 = \begin{cases} p_1(2t) & \text{if } 0 \leq t \leq \frac{1}{2} \\ p_2(2t) & \text{if } \frac{1}{2} \leq t \leq 1 \end{cases}$$

Using this we can define a natural equivalence relation, in which all points which are path-connected are considered as a group:

**Proposition 1**  *$x_1 \sim x_2$  if there exists a path  $p : [0, 1] \rightarrow X$  with  $p(0) = x_1$  and  $p(1) = x_2$  gives an equivalence relation*

*Proof.*

1. Reflexive: For  $x \in X$ , the path  $p(t) = x$  for all  $t \in [0, 1]$  satisfies.
2. Symmetric: If  $x \sim x'$  then there is a path  $p : x \rightarrow x'$ . If we define  $p'(t) = 1 - p$ , then  $p'(0) = x'$  and  $p'(1) = x$
3. Transitive: If  $x \sim x'$  and  $x' \sim x''$ , then simply concatenate the respective paths with the aforementioned construction so that  $p * p' : x \rightarrow x''$

Thus, path-connectedness is an equivalence relation.