ENGR-E 399/599: Embedded Systems Reverse Engineering

Indiana University

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Assigned: January 20, 2022

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Assignment 1: Arm disassembly

Due date: February 11, 2022

This assignment is all about analyzing Arm assembly language, primarily focusing on the contents of the binary_water_balloon_arm Linux ELF. Two additional sections of the assignment focus on the identification of standard library functions.

Since binary_water_balloon_arm is compiled for Arm, you will not be able to execute it natively on an x86 system or x86 virtual machine. Instead, you will need to emulate the Arm instruction set architecture. Once you have installed the qemu-user package, you can execute the binary with:

qemu-arm ./binary_water_balloon_arm

In the resources directory of this assignment you can find a copy of the Arm v7A-R architecture reference manual. To allow easy access from Ghidra's "Processor Manual" command, copy the reference manual PDF to the Ghidra/Processors/ARM/data/manuals/ directory of your Ghidra installation.

0.1 Program interaction

There are six independent stages to the binary water balloon, each of which requires a different input to pass. You can type in each of these inputs manually each time the program executes. Or you can pass a filename as an argument when you run the program. The program will read each line from that file as an input for a separate stage. If you have fewer than six lines in your file, the program will request input for later stages on standard input.

If you want to skip a stage in order to attempt a solution on a later stage, you can provide the following input for the phase that you wish to skip:

PASS

0.2 General program flow

The program fetches a line of input before each stage. It passes a pointer to the input string as the sole argument to the function for each stage (phase_1(), phase_2(), phase_3(), etc.) Invalid inputs will result in balloon_splat() being called within the relevant stage's function. You won't need to reverse-engineer any of the details of main() or its supporting functions to complete the assignment, though you are free to do so if you wish.

0.3 Saving Ghidra program for export

To share your marked-up Ghidra program, select "File→Export Program" from the Code-Browser menu. Choose "Ghidra Zip File" as the export format. Submit this file along with your write-up, and include your name in the filename that you choose.

0.4 Dynamic analysis

You may find it helpful to use dynamic analysis techniques to improve your understanding of specific points of the program. To do this, you will want to install the gdb-multiarch package in Ubuntu. You can have QEMU launch a GDB server by specifying a port number with the -g command line switch, for example:

```
qemu-arm -g 1234 ./binary_water_balloon_arm
```

In a different terminal, you can then run

gdb-multiarch binary_water_balloon_arm

and connect to the server with the command

(gdb) target remote localhost:1234

From there, you can interact with the program using standard GDB commands. It is strongly recommended that you use dynamic analysis techniques judiciously. They are very powerful, but it would be very time consuming to step through an entire program instruction-by-instruction.

0.5 References

Azeria Labs ARM assembly overview

Maria Markstedter

https://azeria-labs.com/writing-arm-assembly-part-1/

Practical Reverse Engineering: x86, x64, ARM, Windows Kernel, Reversing Tools, and Obfuscation

Chapter 2: ARM

Bruce Dang, Alexandre Gazet, Elias Bachaalany, and Sébastian Josse

John Wiley & Sons

ISBN-13: 978-1-118-78731-1

https://iu.skillport.com/skillportfe/main.action?assetid=62680

1 Binary water balloon general program information (1 point)

First, document some general information about the binary. From the output of the file command:

- What is the target architecture of the binary?
- Is the binary statically or dynamically linked?
- Are symbols stripped?

Install the **binutils** package for Ubuntu and run the **strings** command on the binary. Do you see some strings that look relevant to your interaction with the program?

Note some general details about this architecture:

- What is the register size of this architecture?
- What is the endianness of this architecture?
- How are arguments passed to functions? (We discussed this in class, but you can also see the Procedure Call Standard for the Arm Architecture for offical documentation. This document is included in the resources directory.)
- How is an integer return value from a function passed back to the calling function?

2 Binary water balloon analysis (2 points/stage; 12 points total)

Now load the program into Ghidra. The default analysis settings will be sufficient. Analyze the functions phase_1() through phase_6(). Within the assembly listing, add comments noting:

- Information about how arguments are passed to each function called from the function that you are analyzing: (contents, types, and storage location of arguments)
- Information about values returned from each of those function calls (contents, types, and storage location of returned values)
- The conditions associated with branch points

You can expect to have one comment for every 4-5 instructions in your assembly listing. The resources/demo directory contains a Ghidra file where the evaluate_input() file has been commented as a demonstration. Note that this documentation is the most important part of this assignment. The goal is to develop a systematic approach to understanding how information flows through the program and for how control flow decisions are made. Even if you have difficulty putting the pieces together to generate a valid input for a stage, having good documentation of these details will earn you partial credit for that stage.

In your write-up for each stage, document the set of valid inputs that would pass each stage. For some stages, there is a single unique input. For others, there is a family of inputs that have some relationship that you should describe.

3 Standard library function identification #1 (1 point)

Below you will find the Arm assembly listing for a single C standard library function. For this function list:

- How many arguments does this function take?
- What are the types of the arguments? (Pointer, integer, etc.)
- What is the type of the returned value?
- Describe what the function does. If you recognize this standard library function, you can simply list the name. If you do not, describe the functionality as best you can.

00000000	02	20	80	e0	add	r2,r0,r2
					LAB_00000004	
00000004	02	00	50	e1	cmp	r0,r2
8000000	05	00	00	0a	beq	LAB_00000024
000000c	01	30	d0	e4	ldrb	r3,[r0],#0x1
00000010	01	c0	d1	e4	ldrb	r12,[r1],#0x1
00000014	0c	30	53	e0	subs	r3,r3,r12
0000018	f9	ff	ff	0a	beq	LAB_00000004
					LAB_000001c	
000001c	03	00	a0	e1	сру	r0,r3
00000020	1e	ff	2f	e1	bx	lr
					LAB_00000024	
00000024	00	30	a0	еЗ	mov	r3,#0x0
00000028	fb	ff	ff	ea	b	LAB_000001c

4 Standard library function identification #2 (1 point)

Below you will find the Arm assembly listing for a single C standard library function. For this function list:

- How many arguments does this function take?
- What are the types of the arguments? (Pointer, integer, etc.)
- What is the type of the returned value?
- Describe what the function does. If you recognize this standard library function, you can simply list the name. If you do not, describe the functionality as best you can.

00000000	00	30	a0	e1	сру	r3,r0
00000004	02	20	80	e0	add	r2,r0,r2
					LAB_00000008	
8000000	02	00	53	e1	cmp	r3,r2
000000c	1e	ff	2f	01	bxeq	lr
0000010	00	c0	d1	e5	ldrb	r12,[r1,#0x0]
0000014	01	c0	сЗ	e4	strb	r12,[r3],#0x1
0000018	00	00	5c	еЗ	cmp	r12,#0x0
000001c	01	10	81	12	addne	r1,r1,#0x1
00000020	f8	ff	ff	ea	b	LAB_0000008