



POLITECNICO
MILANO 1863

SCUOLA DI INGEGNERIA INDUSTRIALE
E DELL'INFORMAZIONE

IoT Challenge #1, Exercise sink placement

INTERNET OF THINGS

Authors: **Kevin Zioldi - 10764177**
Matteo Volgari - 10773593

Professors: Alessandro Redondi, Antonio Boiano
Academic Year: 2024-2025
Version: 1.0
Release date: 20-3-2025

Contents

Contents	i
1 Exercise sink placement	1

1 | Exercise sink placement

Data

The data of the exercise is reported here.

- 10 sensors
- $T_{transmission} = 10$ minutes
- $b = 2000$ bit
- $E_b = 5$ mJ
- $E_c = 50$ nJ/bit
- $E_{tx}(d) = k \cdot d^2$ nJ/bit
- $k = 1$ nJ/bit/ m^2

The sensors of the parking lot have fixed positions, reported in the following table.

Sensor	Position
1	(1, 2)
2	(10, 3)
3	(4, 8)
4	(15, 7)
5	(6, 1)
6	(9, 12)
7	(14, 4)
8	(3, 10)
9	(7, 7)
10	(12, 14)

Table 1.1: Sensor position table

The following picture describes the distributions of sensors.

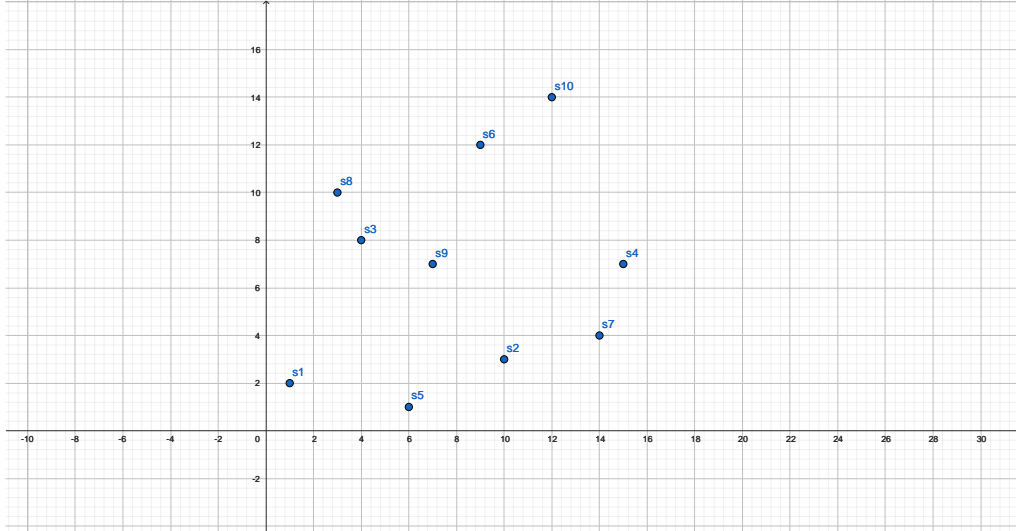


Figure 1.1: Sensor distribution

Lifetime of the system with sink in (20,20)

In order to compute the lifetime of the system when the sink position is $(x_s, y_s) = (20, 20)$, we need to compute the lifetime of the furthest sensor from the sink.

We calculated the distance of every sensor from the sink, the values are reported in the following table.

Sensor	Position	Distance from sink
1	(1, 2)	$\sqrt{685}$ m
2	(10, 3)	$\sqrt{389}$ m
3	(4, 8)	20 m
4	(15, 7)	$\sqrt{194}$ m
5	(6, 1)	$\sqrt{557}$ m
6	(9, 12)	$\sqrt{185}$ m
7	(14, 4)	$2\sqrt{73}$ m
8	(3, 10)	$\sqrt{389}$ m
9	(7, 7)	$13\sqrt{2}$ m
10	(12, 14)	10 m

Table 1.2: Distances from sink

The distance between the sink and the furthest sensor, sensor 1, is:

$$distance_1 = d\{(1, 2), (20, 20)\} = \sqrt{(20 - 1)^2 + (20 - 2)^2} = \sqrt{685}m$$

We compute the energy consumed by sensor 1 as:

$$E_{cycle,1} = E_c \cdot b + E_{tx,1}(d) \cdot b = 50nJ/bit \cdot 2000 \text{ bit} + 1nJ/bit/m^2 \cdot 685m^2 \cdot 2000 \text{ bit} = 1.47mJ$$

The lifetime, measured in number of cycles, is:

$$L_{cycles} = E_b / E_{cycle,1} = 3.401 \text{ cycles}$$

Assuming that each sensor transmits at the beginning of the ten minutes, the system will last for three cycles and during the fourth cycle the furthest sensor will die.

Optimal sink position

In order to maximize the system's lifetime, we need to maximize the lifetime of the sensor node that consumes the most energy. The energy consumption for a transmission is given by:

$$E_{cycle} = E_c \cdot b + E_{tx}(d) \cdot b = E_c \cdot b + k \cdot d^2 \cdot b$$

Since the energy for the circuitry, E_c , is constant, the energy consumption grows with the distance. In order to maximize the lifetime of the system, we need to minimize the maximum distance between the sink and the furthest node. This problem is equivalent to that of finding the smallest circle enclosing all point on the cartesian plane, representing the positions of nodes.

A very efficient algorithm that can be used to solve the smallest enclosing circle problem is Welzl's algorithm, which finds a solution in $O(n)$ time. The algorithm is recursive and uses two sets:

- P: contains all input points;
- R: initially empty, at the end, contains point on the boundary of the minimum enclosing circle;

The base cases are the ones in which the smallest circle encloses three or less points:

- if it doesn't enclose any point, the circle is undefined;
- if it encloses one point, the degenerate circle is the point itself and has radius zero;
- if it encloses two points or three points, there is just one circle passing through

them;

At each step, select a point p from P and find the smallest enclosing circle of the other points:

- if p lies in D , D is the minimum enclosing circle;
- otherwise, p must be part of the boundary, remove p from P and add it to R , recurse on the next element of set P ;

A Python implementation of the algorithm can be found below.

```
import math
import random

# data structures
class Point:
    def __init__(self, x, y):
        self.x = x
        self.y = y

class Circle:
    def __init__(self, c, r):
        self.c = c
        self.r = r

# checks wheter point p is inside circle c
def isInside(c, p):
    return math.dist([c.c.x, c.c.y], [p.x, p.y]) <= c.r

# checks if all points in ps are in c
def isValidCircle(c, ps):
    return all(isInside(c, point) for point in ps)

# helper method to get a circle defined by 3 points
def getCircleCenter(bx, by, cx, cy):
    b = bx * bx + by * by
    c = cx * cx + cy * cy
    d = bx * cy - by * cx
    return Point((cy * b - by * c) / (2 * d), (bx * c - cx * b) / (2 * d))

# returns the circle passing for 2 points (a,b)
def circleFromTwo(a, b):
    c = Point((a.x + b.x) / 2.0, (a.y + b.y) / 2.0)
    return Circle(c, math.dist([a.x, a.y], [b.x, b.y]) / 2.0)
```



```

# returns the circle passing for 3 points (a,b,c)
def circleFromThree(a, b, c):
    i = getCircleCenter(b.x - a.x, b.y - a.y, c.x - a.x, c.y - a.y)
    i.x += a.x
    i.y += a.y
    return Circle(i, math.dist([i.x, i.y], [a.x, a.y]))

# minimum enclosing circle trivial cases
def minCircleTrivial(p):
    assert len(p) <= 3
    if not p:
        return Circle(Point(0, 0), 0)
    elif len(p) == 1:
        return Circle(p[0], 0)
    elif len(p) == 2:
        return circleFromTwo(p[0], p[1])

    for i in range(3):
        for j in range(i + 1, 3):
            c = circleFromTwo(p[i], p[j])
            if isValidCircle(c, p):
                return c
    return circleFromThree(p[0], p[1], p[2])

def welzl(p):
    pCopy = list(p)
    random.shuffle(pCopy)
    return welzlHelper(pCopy, [], len(pCopy))

def welzlHelper(p, r, n):
    if n == 0 or len(r) == 3:
        return minCircleTrivial(r[:])

    idx = random.randint(0, n - 1)
    pnt = p[idx]
    p[idx], p[n - 1] = p[n - 1], p[idx]

    d = welzlHelper(p, r, n - 1)

    if isInside(d, pnt):
        return d

    return welzlHelper(p, r + [pnt], n - 1)

```

```

# run algorithm on nodes positions
nodes_positions = [
    Point(1,2),
    Point(10,3),
    Point(4,8),
    Point(15,7),
    Point(6,1),
    Point(9,12),
    Point(14,4),
    Point(3,10),
    Point(7,7),
    Point(12,14)
]
mec = welzl(nodes_positions)

# print sink position
print("Sink position:", mec.c.x, mec.c.y)
print("Furthest node:", mec.r)

```

Running the algorithm, we get the following result:

Sink position: 6.871681415929204 7.65929203539823

Furthest node: 8.155012507169454

Thus, the optimal position of the sink is approximately (6.87, 7.66) and the maximum distance from the sink to a node is of about 8.16 meters.

We can compute the lifetime of the system when the sink is in position (6.87, 7.66) as follows.

$$E_{cycle, furthest} = E_c \cdot b + E_{tx, furthest}(d) \cdot b = 0.233mJ$$

$$L_{cycles} = E_b / E_{cycle, furthest} = 21.443 \text{ cycles}$$

Under the assumption that each sensor transmits at the beginning of the ten minutes, it will last 21 cycles and die in the next one.

Trade-offs fixed versus dynamic sink position

The ability of the sink to move can optimize the energy efficiency of the network in certain scenarios, but it also introduces complexity and infrastructure challenges.

Pros of a mobile sink:

- If one sensor's battery runs out faster than the others, a static sink may continue to force inefficient transmissions from the remaining sensors. A mobile sink, on the other hand, can dynamically relocate itself to optimize communication distances with the remaining active sensors, thereby extending their operating life and ensuring more balanced energy consumption.
- Sensors can be divided into four or more macro areas, each with a specific transmission interval. By knowing in advance when a macro area is about to transmit, the sink can move closer to it, shortening transmission distances and reducing the power consumption of the sensors in that area. This approach improves battery efficiency and allows sensors to operate longer before requiring maintenance or replacement.

Cons of a mobile sink:

- While moving the sink closer to specific macro-areas improves energy efficiency, it also requires precise synchronization between groups of sensors. Each macro area must coordinate its transmission schedule to ensure that data is sent when the sink is optimally positioned. This synchronization adds complexity to the network communication protocol and may introduce delays or require additional control mechanisms.
- A moving sink requires infrastructure to facilitate movement, such as robotic systems or external guidance mechanisms, which adds cost and maintenance challenges. Alternatively, equipping the sink with an external battery to support mobility creates another tradeoff - once the sink's battery is depleted, the entire system ceases to function. This dependence on the sink's mobility infrastructure can make the system more susceptible to failure and reduce overall reliability.

Conclusions:

Given the premises, a mobile sink, for the sensor configuration we have, definitely brings more advantages than disadvantages in the long term, but also requires initial design efforts to develop an autonomous and intelligent motion system for the sink.