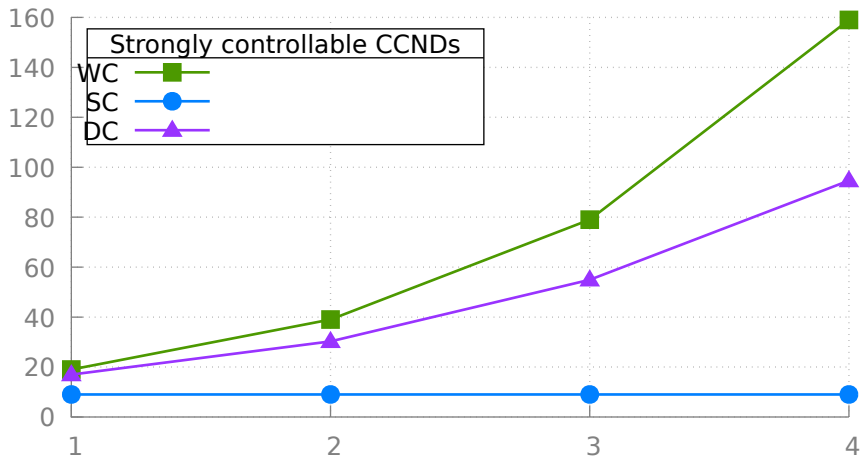


SPACE (# of nodes)



Number of pairs observation-decision points