

Matt McDade  
System Simulation  
HW #3

$$A) \frac{V_{out}(s)}{V_{in}(s)} = H(s) = \frac{4/3 \cdot 10^7}{s^2 + 250s + 3.33 \cdot 10^7} = \frac{4/3 \cdot 10^7}{s(s + 250) + 3.33 \cdot 10^7}$$

$$\frac{1}{s} \Leftrightarrow \frac{Tz}{z-1} \quad s \Leftrightarrow \frac{z-1}{Tz}$$

~~$$\frac{4/3 \cdot 10^7 \cdot Tz}{(z-1)(1+250T) + 3.33 \cdot 10^7} = \frac{4/3 \cdot 10^7 \cdot Tz}{(z-1)(1+250T) + 3.33 \cdot 10^7}$$~~

$$\frac{4/3 \cdot 10^7 \cdot Tz}{\frac{z-1}{Tz} \left( \frac{z-1}{Tz} + 250 \right) + 3.33 \cdot 10^7} = \frac{(z-1)^2}{Tz^2} + \frac{250(z-1)}{Tz} + 3.33 \cdot 10^7$$

$$= \frac{4/3 \cdot 10^7 \cdot Tz^2}{z^2 - 2z + 1 + 250Tz^2 - 250Tz + 3.33 \cdot 10^7 Tz^2}$$

$$= \frac{4/3 \cdot 10^7 \cdot Tz^2}{z^2(1 + 250T + 3.33 \cdot 10^7 T^2) + z(-2 - 250T) + 1}$$

$$b_2 = \frac{4}{3} \cdot 10^7 \cdot T^2$$

$$b_1 = 0$$

$$b_0 = 0$$

$$a_1 = -2 - 250T$$

~~$$a_2 = 1 + 250T + 3.33 \cdot 10^7 T^2$$~~

$$a_0 = 1$$

$$\star y(k+2) = (2 + 250T) y(k+1) - y(k) + \left( \frac{4}{3} \cdot 10^7 \cdot T^2 \right) u(k+2)$$

$$B) \frac{V_{out}(s)}{S(s)} = \frac{4 \cdot 10^8}{s^2 + 250s + 3.33 \cdot 10^7}$$

$$s \Leftrightarrow \frac{z-1}{Tz}$$

$$4 \cdot 10^8 T^2 z^2$$

$$\frac{(z-1)^2}{Tz^2} + 250 \left( \frac{z-1}{Tz} \right) + 3.33 \cdot 10^7 = \frac{z^2 - 2z + 1 + 250Tz^2 - 250Tz + 3.33 \cdot 10^7 T^2 z^2}{z^2}$$

$$4 \cdot 10^8 T^2 z^2$$

$$z^2(1 + 250T + 3.33 \cdot 10^7 T^2) + z(-2 - 250T) + 1$$

$$a_1 = -2 - 250T$$

$$b_2 = 4 \cdot 10^8 T^2$$

$$a_0 = 1$$

$$b_1 = 0$$

$$b_0 = 0$$

$$\star y(k+2) = (2 + 250T) y(k+1) - y(k) + (4 \cdot 10^8 T^2) u(k+2)$$



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% Matt McDade
% System Simulation HW 3
% Graphs are certainly wrong but I think I'm close
close all;

T = 0.001;
x = 0:T:100;
N = length(x);

step = ones(1, N);
u_a = 12 * step;
u_b = 0.4 * step;

y_a = zeros(1, N);
y_b = zeros(1, N);

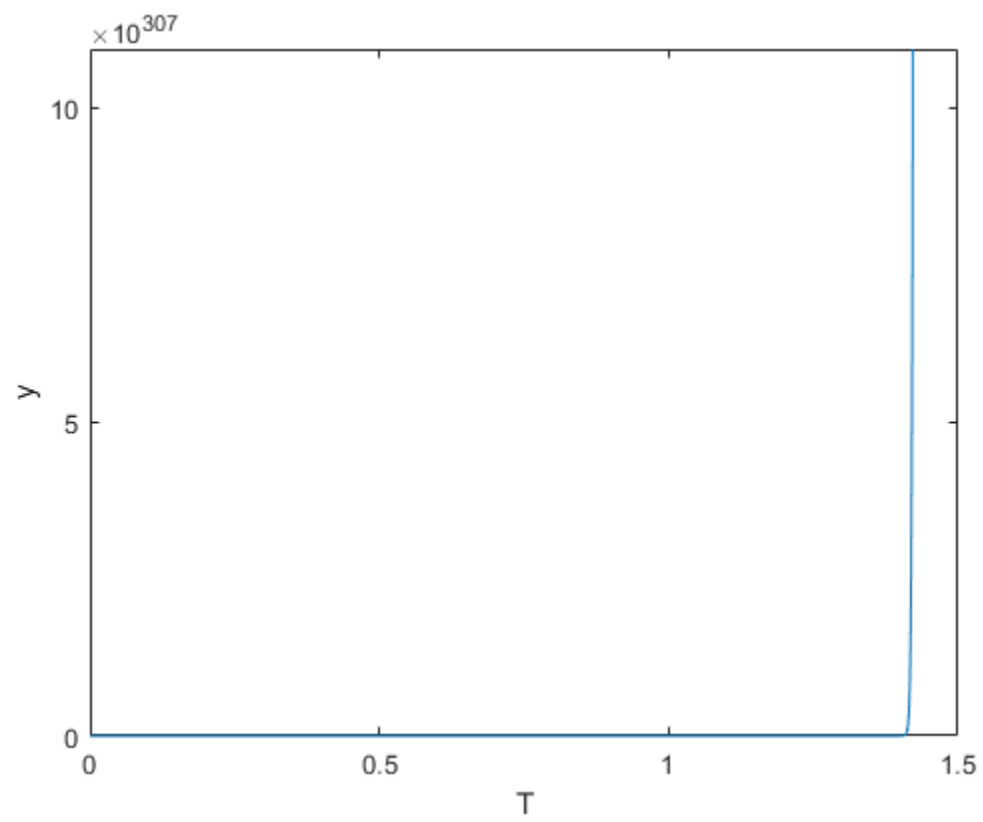
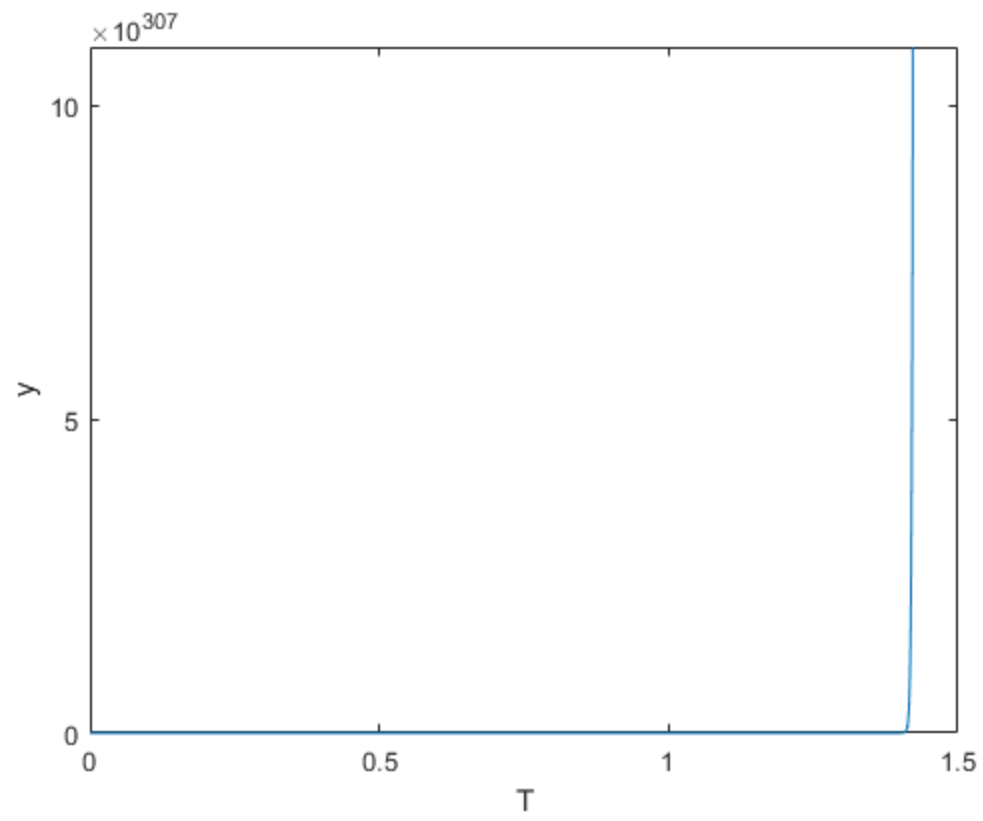
b2_a = (4/3) * 10^7 * T^2;
a1_a = -2-250*T;
a0_a = 1;

b2_b = 4 * 10^8 * T^2;
a1_b = -2-250*T;
a0_b = 1;

for k = 3:N
    y_a(k) = -a1_a * y_a(k-1) - a0_a * y_a(k-2) + b2_a * u_a(k);
    y_b(k) = -a1_b * y_b(k-1) - a0_b * y_b(k-2) + b2_b * u_b(k);
end

figure(); plot(x, y_a)
xlabel('T'); ylabel('Y')

figure(); plot(x, y_b)
xlabel('T'); ylabel('Y')
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