Interval-Vector Polytopes

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July 28, 2012

Abstract

An interval vector is a (0,1)-vector where all the ones appear consecutively. Polytopes whose vertices are among these vectors have some astonishing properties that are highlighted in this paper. We present a number of interval-vector polytopes, including one class whose volumes are the Catalan numbers and another class whose face numbers mirror Pascal's triangle.

1 Introduction

In this paper, we will be analyzing the properties of certain groups of *convex polytopes* which are formed by taking the convex hull of finitely many points in \mathbb{R}^d . The *convex hull* of a set $A = \{v_1, v_2, \ldots, v_n\} \subset \mathbb{R}^d$, denoted $\operatorname{conv}(A)$, is defined as

$$\left\{\lambda_1 v_1 + \lambda_2 v_2 + \dots \lambda_n v_n | \lambda_1, \lambda_2, \dots \lambda_n \in \mathbb{R}_{\geq 0} \text{ and } \sum_{i=1}^n \lambda_i = 1\right\}.$$
 (1)

The polytope $\operatorname{conv}(A)$ is contained in the the affine hull of A, or $\operatorname{aff}(A)$, whose definition is the same as (1) but without the restriction that $\lambda_1, \lambda_2, \ldots, \lambda_n \geq 0$. We call a set of points affinely independent if each point is not in the affine hull of the rest. The vertex set of a polytope is the minimal convexly independent set of points whose convex hull form the polytope. These points are called the vertices. The affine space of a polytope is the affine hull of its vertices. A polytope is d-dimensional if the dimension of the affine hull of its vertices is d. Denote the dimension of the polytope \mathcal{P} as $\dim(\mathcal{P})$. We call a d-dimensional polytope a d-simplex if it has d+1 vertices.

A lattice point is a point with integral coordinates. A lattice polytope is a polytope whose vertices are lattice points[1]. A lattice basis of a d-dimensional affine space is a set of d integral vectors where, fixing a lattice point on the affine space v, any lattice point inside the affine space can be written as v plus an integral linear combination of these vectors. If we take a unimodular simplex formed by the vectors of the lattice

basis of the affine hull of \mathcal{P} and assign it volume 1, then the *normalized volume* of a polytope \mathcal{P} , denoted vol(\mathcal{P}), is the volume with respect to this simplex. We will refer to the normalized volume of a polytope as its *volume*.

A t-dilate of a polytope \mathcal{P} is

$$t\mathcal{P} := \{tv \mid v \in \mathcal{P}\}.$$

The Ehrhart polynomial of a lattice polytope \mathcal{P} , denoted $L_{\mathcal{P}}(t)$, is the number of lattice points in the t^{th} dilate of the polytope. Here t is considered a positive integer variable. It is known(see, e.g., [1]) that the constant term of any Ehrhart polynomial is 1, and that the degree of this polynomial is the dimension d of \mathcal{P} . The leading coefficient of the Ehrhart polynomial is the normalized volume of the polytope times $\frac{1}{d!}$.

A hyperplane is of the form

$$H := \{ x \in \mathbb{R}^n | a_1 x_1 + \dots + a_n x_n = b \},$$

where not all a_j 's are 0. The half-spaces defined by this hyperplane are formed by the two weak inequalities corresponding to the equation defining the hyperplane. The half-space description of a polytope is the smallest finite set of closed half-spaces whose intersection is the polytope. A face of \mathcal{P} is the intersection of a hyperplane and \mathcal{P} such that \mathcal{P} lies completely in one half-space of the hyperplane. This face is a polytope called a k-face if its dimension is k. A vertex is a 0-face and an edge is a 1-face. Given a d-dimensional polytope \mathcal{P} with f_k k-dimensional faces, the f-vector of \mathcal{P} is written as $f(\mathcal{P}) := (f_0, f_1, \ldots, f_{d-1})[4]$. E.g., a triangle Δ which is 2-dimensional polytope with 3 vertices and 3 edges has f-vector $f(\Delta) = (3,3)$. As we look at the following polytopes we will see interesting patterns in these properties.

2 Complete Interval-Vector Polytopes

In [2] Dahl introduces a class of polytopes based on interval vectors. An interval vector is a (0,1)-vector $x \in \mathbb{R}^n$ such that, if $x_i = x_k = 1$ for i < k, then $x_j = 1$ for every $i \le j \le k$. Let $\alpha_{i,j} := e_i + e_{i+1} + \cdots + e_j$ for $i \le j$ where e_i is the i^{th} standard unit vector. The interval length of α_{ij} is j - i + 1. If \mathcal{I} is a set of interval vectors then we define the polytope $P_{\mathcal{I}} := \operatorname{conv}(\mathcal{I})$. We are interested in a number of polytopes that arise when we consider various such sets \mathcal{I} . In [2] Dahl provides a method for determining the dimension of these polytopes which we will use throughout this paper.

Denote $\{1, \dots, n\}$ by [n]. Let $\mathcal{I}_n = \{\alpha_{i,j} : i, j \in [n], i \leq j\}$. The complete intervalvector polytope is defined as $\mathcal{P}_{\mathcal{I}_n} := \text{conv}(\mathcal{I}_n)$. Computing the Ehrhart polynomials and volumes of small-dimensional polytopes with the aid of a computer, we notice an astounding connection. We computed the volume of the first 9 complete interval vector polytopes, and found that in each case

$$vol(\mathcal{P}_{\mathcal{I}_n}) = C_n$$

where $C_n := \frac{1}{n+1} \binom{2n}{n}$ is the n^{th} Catalan number. We will prove that this is the case for any n.

In [5], Postnikov defines the complete root polytope $Q_n \subset \mathbb{R}^n$ as the convex hull of 0 and $e_i - e_j$ for all i < j. It is shown that the volume of Q_n is C_{n-1} , the same as expected for $\mathcal{P}_{\mathcal{I}_{n-1}}$. In fact, we prove, in a discrete-geometric sense, that the two polytopes are interchangeable, that is, the two polytopes have the same Ehrhart polynomial.

Theorem 1. $L_{Q_n}(t) = L_{\mathcal{P}_{\mathcal{I}_{n-1}}}(t)$.

Proof. Each of the vertices of Q_n are vectors with entries that sum to zero, so any linear combination (and specifically any convex combination) of these vertices also has entries who sum to zero:

$$\sum_{i} x_i = \sum_{j} y_j = 0 \Longrightarrow \sum_{i} ax_i + \sum_{j} by_j = a \sum_{i} x_i + b \sum_{j} y_j = 0.$$

Define $B := \{x \in \mathbb{R}^n | \sum_{i=1}^n x_i = 0\}$; then $Q_n \subset B$. B is an (n-1)-dimensional affine subspace of \mathbb{R}^n .

Consider the linear transformation T given by the $n \times n$ lower triangular (0, 1)matrix where $t_{ij} = 1$ if $i \geq j$ and $t_{ij} = 0$ otherwise. Then the image

$$T(B) \subset A = \{x \in \mathbb{R}^n | x_n = 0\}.$$

Since T has determinant 1, it is injective when restricting the domain to B. For the same reason, we know that for any $y \in A$, there exists $x \in \mathbb{R}^n$ such that y = T(x). But since $y_n = \sum_{i=1}^n x_i = 0$, then $x \in B$, so that $T|_B : B \to A$ is surjective, and therefore a linear bijection.

Now consider the projection $\Pi: A \to \mathbb{R}^{n-1}$ given by

$$\Pi((x_1,\ldots,x_{n-1},0)) = (x_1,\ldots,x_{n-1}).$$

The transformation is clearly linear, and has the inverse

$$\Pi^{-1}((x_1,\ldots,x_{n-1}))=(x_1,\ldots,x_{n-1},0),$$

so that Π is a bijection.

Now we show that the linear bijection $\Pi \circ T|_B : B \to \mathbb{R}^{n-1}$ is a lattice-preserving map. First we find a lattice basis for B. Consider

$$C = \{e_{i,n} = e_i - e_n | i < n\}.$$

We notice that any integer point of B

$$\left(a_1, \dots, a_{n-1}, -\sum_{i=1}^{n-1} a_i\right) = \sum_{i=1}^{n-1} a_i e_{i,n}.$$

Any integer point is an integer combination elements of C, so C is a lattice basis. Note that $\Pi \circ T(e_{i,n}) = e_i + \cdots + e_{n-1} =: u_i$. Therefore

$$\Pi \circ T(C) = \{u_i | i \le n - 1\} =: U.$$

We notice that $e_{n-1} = u_{n-1}$ and $e_i = u_i - u_{i+1}$, so that each of the standard unit vectors e_i of \mathbb{R}^{n-1} is an integral combination of the vectors in U. Since the standard basis is a lattice basis, so is F, thus $\Pi \circ T|_B$ is a lattice-preserving map. Since our bijection is linear and lattice-preserving, all we have left to show is that the vertices of Q_n map to those of $P_{\mathcal{I}_{n-1}}$. By linearity, $\Pi \circ T(0) = 0$, and given any vertex $\alpha_{i,j}$ for $P_{\mathcal{I}_{n-1}}$, we know that $\Pi \circ T(e_{i,j+1}) = \alpha_{i,j}$ where $i < j+1 \le n$ so that $\Pi \circ T|_B$ is surjective.

The volume of $\mathcal{P}_{\mathcal{I}_n}$ now follows directly from this theorem, since the leading coefficient of the Ehrhart polynomial of $\mathcal{P}_{\mathcal{I}_n}$ is the volume of $\mathcal{P}_{\mathcal{I}_n}$ times $\frac{1}{n!}$.

Corollary 1. $\operatorname{vol}(\mathcal{P}_{\mathcal{I}_n}) = C_n$.

3 Fixed Interval Vector Polytopes

The following construction is due to [2]. Let $e_{i,j} := e_i - e_j$ for i < j. We define the set of elementary vectors as containing all such $e_{i,j}$, each unit vector e_i , and the zero vector. Let T be the lower triangular (0,1)-matrix, as in the proof of Theorem 1. We notice that $T(e_i) = \alpha_{i,n}$ and $T(e_{i,j}) = \alpha_{i,j-1}$. So the image of an elementary vector is an interval vector. Since T is invertible, for any set of interval vectors \mathcal{I} , there is a unique set \mathcal{E} of elementary vectors such that $T(\mathcal{E}) = \mathcal{I}$, namely $T^{-1}(\mathcal{I}) = \mathcal{E}$.

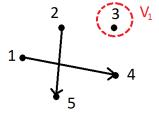
Thus for any interval polytope $\mathcal{P}_{\mathcal{I}} \subset \mathbb{R}^n$, we can construct the corresponding flow-dimension graph $G_{\mathcal{I}} = (V, E)$ as follows. Let $\mathcal{E} = T^{-1}(\mathcal{I})$. We let the vertex set V = [n], specify a subset $V_1 = \{j \in V \mid e_j \in \mathcal{E}\}$, and define the edge set $E = \{(i, j) \mid e_{i,j} \in \mathcal{E}\}$. Also we let k_0 denote the number of connected components \mathcal{C} of the graph G (ignoring direction) so that $\mathcal{C} \cap V_1 = \emptyset$.

Given an interval length i and a dimension n we define the fixed interval vector polytope $\mathcal{Q}_{n,i}$ as the convex hull of all vectors in \mathbb{R}^n with interval length i.

Example 3.1. The fixed interval-vector polytope with n = 5, i = 3 is

$$\mathcal{Q}_{5,3} = \operatorname{conv} \big((1,1,1,0,0) \,,\, (0,1,1,1,0) \,,\, (0,0,1,1,1) \big).$$

Flow-dimension graph of $Q_{5,3}$:



Theorem 2 (Dahl, [2]). If $0 \in \text{aff}(\mathcal{I})$, then the dimension of $P_{\mathcal{I}}$ is $n - k_0$. Else, if $0 \notin \text{aff}(\mathcal{I})$ then the dimension of $P_{\mathcal{I}}$ is $n - k_0 - 1$.

For $Q_{n,i}$, we have $\mathcal{I} = \{\alpha_{j,j+i-1} \mid j \leq n-i+1\}$ which translates to the elementary vector set $\mathcal{E} = \{e_{k,k+i} \mid k \leq n-i\} \cup \{e_{n-i+1}\}$. We can define the corresponding flow-dimension graph $G_{Q_{n,i}} = (V, E)$ where $V = \{1, \ldots, n\}$ and $E = \{(k, k+i) \mid k \in [n-i]\}$ corresponding to each $e_{i,j} \in \mathcal{E}$. Then $V_1 := \{n-i+1\}$ corresponds to $e_{n-i+1} \in \mathcal{E}$.

Two nodes a, b in a graph G = (V, E) are said to be *connected* if there exists a path from a to b, that is there exist $q_0, \ldots, q_s \in V$ such that $(a, q_0), (q_0, q_1), \ldots, (q_s, b) \in E$.

Lemma 1. Let a, b be nodes in the flow-dimension graph $G_{\mathcal{Q}_{n,i}}(V, E)$. Then a and b are connected iff $a \equiv b \mod i$.

Proof. Assume without loss of generality $a \leq b$. Suppose a and b are connected by the path $q_0, \ldots, q_s \in V$. Therefore by definition of E, we have

$$q_0 = a + i$$

 $q_1 = q_0 + i = a + 2i$
 \vdots
 $q_s = q_{s-1} + i = a + (s+1)i$
 $b = q_s + i = a + (s+2)i$

Thus $a \equiv b \mod i$ by definition.

Now suppose that $a \equiv b \mod i$ where $a \leq b$, then there exists $m \in \mathbb{N}$ such that

$$b = a + mi$$
$$= a + (m - 1)i + i.$$

Since b and a + (m-1)i differ by i, then by definition of E, there is an edge between these nodes. Call this edge $(q_t, b) \in E$. Similarly, we have

$$a + (m-1)i = a + (m-2)i + i \qquad \Rightarrow (q_t, q_{t-1}) \in E$$

$$a + (m-2)i = a + (m-3)i + i \qquad \Rightarrow (q_{t-1}, q_{t-2}) \in E$$

$$\vdots$$

$$a + 2i = (a+i) + i \qquad \Rightarrow (q_1, q_0) \in E$$

$$a + i = a + i \qquad \Rightarrow (q_0, a) \in E.$$

Hence $q_0, q_1, \ldots, q_t \in V$, define a path from a to b, so a and b are connected.

Theorem 3. $Q_{n,i}$ is an (n-i)-dimensional simplex.

Proof. For a given dimension and interval length, an interval vector is uniquely determined by the location of the first 1, hence we can determine the number of vertices of $Q_{n,i}$ by counting all possible placements of the first 1 in an interval of i 1's. Since the string must have length i, the number of spaces before the first 1 must not exceed n-i and so there are n-i+1 possible locations for the first 1 in the interval to be placed. Thus, $Q_{n,i}$ has n-i+1 vertices.

By Lemma 1 we know there are i connected components in the flow-dimension graph $G_{\mathcal{Q}_{n,i}}$ and since V_1 has only one element, $k_0 = i - 1$. Thus by Theorem 2 the dimension of $\mathcal{Q}_{n,i}$ is n - i. Therefore $\mathcal{Q}_{n,i}$ is an (n - i)-dimensional simplex by definition.

Theorem 4. $Q_{n,i}$ is an (n-i)-dimensional unimodular simplex.

Proof. Consider the affine space where the sum over every i^{th} coordinate is 1,

$$A = \left\{ \mathbf{x} \in \mathbb{R}^n \,\middle|\, \sum_{j \equiv k \, \text{mod} \, i} x_j = 1, \, \forall \, k \in [i] \right\}.$$

Since the vertices of $\mathcal{Q}_{n,i}$ have interval length i, they are in A. Thus $\mathcal{Q}_{n,i} \subset A$. We want to show that the $w_1, w_2, \ldots, w_{n-i}$ of $\mathcal{Q}_{n,i}$ form a lattice basis for A where

$$\begin{array}{rcl} w_1 & = & \alpha_{1,i} - \alpha_{n-i+1,n} \\ w_2 & = & \alpha_{2,i+1} - \alpha_{n-i+1,n} \\ & \vdots & & & \\ w_{n-i} & = & \alpha_{n-i,n-1} - \alpha_{n-i+1,n} \end{array}$$

We will do this by showing that any integer point $p \in A$ can be expressed as a integral linear combination of the proposed lattice basis, that is, there exist integer coefficients C_1, \ldots, C_{n-i} so that $C_1w_1 + \ldots + C_{n-i}w_{n-i} + \alpha_{n-i+1,n} = p$.

We first notice that p can be expressed as

$$\left(p_1, p_2, \dots, p_{n-i}, \sum_{\substack{j \le n-i \\ j \equiv t-i+1 \bmod i}} (-p_j) + 1, \sum_{\substack{j \le n-i \\ j \equiv t-i+2 \bmod i}} (-p_j) + 1, \dots, \sum_{\substack{j \le n-i \\ j \equiv n = \bmod i}} (-p_j) + 1\right)$$

by solving for the last term in each of the equations defining A. Let

$$C_{t} = \begin{cases} p_{1} & t = 1\\ p_{t} - p_{t-1} & 1 < t \leq i\\ p_{t} - C_{t-i} & i < t \leq n - i \end{cases}$$

Then each C_t is an integer since it is a sum of integers. We claim that

$$C_1w_1 + \cdots + C_{n-i}w_{n-i} + \alpha_{n-i+1,n} = p.$$

Clearly the first coordinate is p_1 since w_1 is the only vector with an element in the first coordinate. Next consider the t^{th} coordinate of this linear combination for $1 < t \le i$, by summing the coefficients of all the vectors who have a 1 in the t^{th} position:

$$C_t + C_{t-1} + C_{t-2} + \dots + C_1 = p_t - p_{t-1} + p_{t-1} - p_{t-2} + \dots + p_2 - p_1 + p_1 = p_t$$

We next consider the t^{th} coordinate of the combination for $i < t \le n - i$ by summing the coefficients of the vectors who have a 1 in the t^{th} position.

$$C_t + C_{t-1} + \dots + C_{t-i+1} = (p_t - C_{t-1} - \dots - C_{t-i+1}) + C_{t-1} + \dots + C_{t-i+1} = p_t$$

Finally, we consider the t^{th} coordinate of the combination for $n-i < t \le n$, noticing that each coordinate from w_1 to w_t has a -1 in the $(t-i)^{\text{th}}$ position and $\alpha_{n-i+1,n}$ has a 1 in this position. Thus we get:

$$-(C_1+C_2+\cdots+C_{t-i})+1.$$

Applying the two relations we have defined between coordinates, and calling $\langle t \rangle$ the least residue of $t \mod i$, we see:

$$-(C_{1} + C_{2} + \dots + C_{t-i}) + 1 = -(C_{1} + C_{2} + \dots + C_{t-2i} + p_{t-i}) + 1$$

$$= -(C_{1} + C_{2} + \dots + C_{t-3i} + p_{t-2i} + p_{t-i}) + 1$$

$$= -\left(C_{1} + C_{2} + \dots + C_{\langle t \rangle} + \sum_{\substack{i < j \le n-i \\ j \equiv t \bmod i}} p_{j}\right) + 1$$

$$= -\left(\sum_{\substack{j \le n-i \\ i \equiv t \bmod i}} p_{j}\right) + 1.$$

Thus $p = C_1 w_1 + C_2 w_2 + \cdots + C_{n-i} w_{n-i} + \alpha_{n-i+1,n}$ and so w_1, \ldots, w_{n-i} form a lattice basis of A.

By the definition of normalized volume, a simplex defined by a lattice basis has volume 1, so $Q_{n,i}$ has volume 1 and is a unimodular simplex.

4 Another Interesting Polytope

Given a dimension n and an interval length i define $\mathcal{P}_{n,i}$ to be the convex hull of all vectors in \mathbb{R}^n with interval length 1 or n-i.

Example 4.1. For n = 4, i = 1,

$$\mathcal{P}_{4,1} = \operatorname{conv}\left(\left(1,0,0,0\right),\,\left(0,1,0,0\right),\,\left(0,1,0,0\right),\,\left(0,0,1,0\right),\,\left(0,0,0,1\right),\,\left(1,1,1,0\right),\,\left(0,1,1,1\right)\right).$$

Proposition 1. The dimension of $\mathcal{P}_{n,1}$ is n.

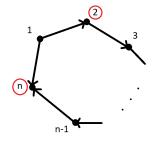


Figure 1: $G_{\mathcal{P}_{n,1}}$

Proof. For $n \geq 3$, the vertices of $\mathcal{P}_{n,1}$ form the set

$$\mathcal{I} = \begin{cases}
e_1 &= (1, 0, \dots, 0, 0) \\
e_2 &= (0, 1, \dots, 0, 0) \\
\vdots & \\
e_n &= (0, 0, \dots, 0, 1) \\
\alpha_{1,n-1} &= (1, 1, \dots, 1, 0) \\
\alpha_{2,n} &= (0, 1, \dots, 1, 1)
\end{cases}.$$

We convert the interval vectors to the corresponding elementary vector set

$$\mathcal{E} = \{e_{1,2}, e_{2,3}, \dots, e_{n-1,n}, e_{1,n}, e_2, e_n\}.$$

From this we construct the flow-dimension graph $G_{\mathcal{P}_{n,1}} = (V, E)$ as seen in Figure 1, where V = [n] and

$$E = \{(k, k+1) | k \in [n-1]\} \cup \{(1, n)\}$$

corresponding to each $e_{i,j}$ in \mathcal{E} . The subset of vertices $V_1 = \{2, n\}$ (circled in Figure 1) corresponds to each e_i in \mathcal{E} . Since the underlying graph is connected, we know

 $k_0 = \#\{\text{connected components } C \text{ in } G_{\mathcal{P}_{n,1}} \text{ such that } C \cap V_1 = \emptyset\} = 0.$

Next we notice that

$$\frac{1}{n-2}e_1 + \frac{1}{n-2}e_2 + \dots + \frac{1}{n-2}e_{n-1} - \frac{1}{n-2}\alpha_{1,n-1} = \mathbf{0}$$

where the sum of the coefficients is

$$\frac{n-1}{n-2} - \frac{1}{n-1} = \frac{n-2}{n-2} = 1$$

So $\mathbf{0} \in \mathrm{aff}(\mathcal{I})$ and by Theorem 2, $\dim(P_{n,1}) = n - k_0 = n$.

4.1 f-Vectors of $\mathcal{P}_{n,i}$

Recall that the f-vector of a polytope tells us the number of faces a polytope has of each dimension. We will see that the f-vector of $\mathcal{P}_{n,1}$ with $n \geq 3$, is precisely the n^{th} row of the Pascal 3-triangle without 1's. The Pascal 3-triangle is an analogue of Pascal's Triangle, where the third row, instead of being 1 2 1, is replaced with 1 3 1, and then the same addition pattern is followed as in Pascal's triangle.

$$n = 1$$
: 3
 $n = 2$: 4 4
 $n = 3$: 5 8 5
 $n = 4$: 6 13 13 6
 $n = 5$: 7 19 26 19 7
 $n = 6$: 8 26 45 45 26 8

The proof of this correspondence requires a few preliminary results.

Lemma 2. Let $\mathcal{P}_{n,1} = \operatorname{conv}(\mathcal{I})$ where $\mathcal{I} := \{e_1, e_2, \dots, e_n, \alpha_{1,n-1}, \alpha_{2,n}\}$ with $n \geq 3$. Then $\mathcal{B} = \operatorname{conv}(e_1, e_n, \alpha_{1,n-1}, \alpha_{2,n})$ is a 2-dimensional face of $\mathcal{P}_{n,1}$.

Proof. We first consider $\mathcal{A} = \text{conv}(e_n, \alpha_{1,n-1}, \alpha_{2,n})$. The corresponding elementary vectors of the vertex set are $\{e_{1,n}, e_2, e_n\}$. So we build the flow-dimension graph as seen in Figure 2, $G_{\mathcal{A}} = (V, E)$ where V = [n], $E = \{(1, n)\}$ corresponding to $e_{1,n}$. The subset $V_1 = \{2, n\}$ (circled in Figure 2) corresponds to e_2 and e_n . This graph has n-1 connected components, two of which contain elements of V_1 so that $V_2 = v_1 - v_2$.

If we let $\lambda_1 e_n + \lambda_2 \alpha_{1,n-1} + \lambda_3 \alpha_{2,n} = \mathbf{0}$, we first notice that $\lambda_2 = 0$ since $\alpha_{1,n-1}$ is the only vector with a nonzero first coordinate. But this implies that $\lambda_1 = \lambda_3 = 0$. Since the coefficients cannot sum to 1, we conclude that $\mathbf{0} \notin \operatorname{aff}(e_n, \alpha_{1,n-1}, \alpha_{2,n})$.

So now by Theorem 2,

$$\dim(\operatorname{conv}(e_n, \alpha_{1,n-1}, \alpha_{2,n})) = n - k_0 - 1 = n - (n-3) - 1 = 2.$$

Finally $e_1 = (1)\alpha_{1,n-1} + (-1)\alpha_{2,n} + (1)e_n$ is in the affine hull of \mathcal{A} and does not add a dimension. Thus we conclude that $\dim(\mathcal{B}) = 2$.

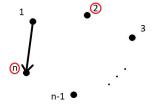


Figure 2: G_A

Corollary 2. Let \mathcal{I} be as in Lemma 2. Then each e_i for $2 \leq i \leq n-1$ adds a dimension to $\mathcal{P}_{n,1}$, that is $e_i \notin \operatorname{aff}(\mathcal{I} \setminus \{e_i\})$.

Proof. This follows from Theorem 1 and Lemma 2. Since \mathcal{B} has dimension 2 and $\mathcal{P}_{n,1}$ has dimension n, then the n-2 remaining vertices must add the remaining n-2 dimensions. Clearly none can add more than one, so each must add precisely one dimension.

Lemma 3. Let \mathcal{B} as in Lemma 2. Then \mathcal{B} has f-vector (4,4).

Proof. Since \mathcal{B} has dimension 2, $f_1 = f_0$. We know that $\{e_n, \alpha_{1,n-1}, \alpha_{2,n}\}$ are three vertices of \mathcal{B} since they form a 2-dimensional object. If $e_1 \in \text{conv}(e_n, \alpha_{1,n-1}, \alpha_{2,n})$ then

$$e_1 = \lambda_1 e_n + \lambda_2 \alpha_{1,n-1} + \lambda_3 \alpha_{2,n} \tag{3}$$

where the coefficients sum to 1. Since $\alpha_{1,n-1}$ is the only vector with a nonzero coordinate in the first position, that implies $\lambda_2 = 1$. This in turn implies that $\lambda_1 = \lambda_3 = 0$, contradicting (3). So $e_1 \notin \text{conv}(e_n, \alpha_{1,n-1}, \alpha_{2,n})$ and therefore forms a fourth vertex. Thus $f_0 = 4 = f_1$ completing the proof.

We can tie all this together with the following theorem. First we define a d-pyramid P^d as the convex hull of the union of a (d-1)-dimensional polytope K^{d-1} (the basis of P^d) and a point $A \notin \text{aff}(K^{d-1})$) (the apex of P^d).

Theorem 5 (see, e.g., [4]). If P^d is a d-pyramid with (d-1)-dimensional basis K^{d-1} then

$$f_0(P^d) = f_0(K^{d-1}) + 1$$

$$f_k(P^d) = f_k(K^{d-1}) + f_{k-1}(K^{d-1}) \quad \text{for } 1 \le k \le d-2$$

$$f_{d-1}(P^d) = 1 + f_{d-2}(K^{d-1}).$$

We notice that the rows of Pascal's 3-triangle act in the same manner and we claim the face numbers for $\mathcal{P}_{n,1}$ can be derived from Pascal's 3-triangle.

Theorem 6. The f-vector for $\mathcal{P}_{n,1}$ for $n \geq 3$ is the n^{th} row of the Pascal 3-triangle.

Proof. Let $\mathcal{I} = \{e_1, e_2, \dots, e_n, \alpha_{1,n-1}, \alpha_{2,n}\}$ be the vertex set for $\mathcal{P}_{n,1}$ with $n \geq 3$, and call $\mathcal{R}_k = \operatorname{conv}(\mathcal{I} \setminus \{e_k, e_{k+1}, \dots, e_{n-1}\})$ for $1 \leq k < n$. Then it is clear that $\mathcal{P}_{n,1}$ is the convex hull of the union of the (n-1)-dimensional polytope \mathcal{R}_{n-1} and $e_{n-1} \notin \operatorname{aff}(\mathcal{R}_{n-1})$ (by Corollary 2), and thus is a pyramid and its face numbers can be computed as in Theorem 5 from the face numbers of \mathcal{R}_{n-1} .

Notice next that \mathcal{R}_{n-1} is the convex hull of the union of the (n-2)-dimensional polytope \mathcal{R}_{n-2} and $e_{n-2} \notin \operatorname{aff}(\mathcal{R}_{n-2})$ (again by Corollary 2), so we can compute the face numbers of \mathcal{R}_{n-1} from those of \mathcal{R}_{n-2} as in Theorem 5.

We can continue this process until we get that \mathcal{R}_3 is the convex hull of \mathcal{R}_2 and $e_2 \notin \operatorname{aff}(\mathcal{R}_2)$. But we notice that $\mathcal{R}_2 = \mathcal{B}$, so by Lemma 3, $f_0(\mathcal{R}_2) = f_1(\mathcal{R}_2) = 4$. From here we can build using f-vectors of $\mathcal{P}_{n,1}$ from Theorem 5 which are exactly those of the Pascal 3-triangle. We do this n-1 times to reach $\mathcal{P}_{n,1}$, and since (4,4) is the second row of the triangle, then the f-vector of $\mathcal{P}_{n,1}$ is the nth row of the Pascal 3-triangle, as desired.

Corollary 3. For $n \geq 3$, $\mathcal{P}_{n,1}$ is self dual.

We can rewrite (2) as

which is Pascal's triangle added to a shifted Pascal's triangle. Thus we can derive a closed formula for the number of k-faces for $\mathcal{P}_{n,1}$:

Corollary 4. For
$$n \geq 3$$
, $f_k(\mathcal{P}_{n,1}) = \binom{n-1}{k} + \binom{n+1}{k+1}$.

5 Volume of $\mathcal{P}_{n,1}$

Lemma 4. The determinant of the $n \times n$ -matrix

$$\begin{bmatrix} 0 & 1 & 1 & \cdots & 1 \\ 1 & 0 & 1 & \cdots & 1 \\ & & \ddots & & \\ 1 & \cdots & 1 & 0 & 1 \\ 1 & 1 & \cdots & 1 & 0 \end{bmatrix}$$

is
$$(-1)^{n-1}(n-1)$$
.

Proof. Let A_n be the $n \times n$ matrix whose diagonal entries are 0, and all entries off the diagonal are 1. E.g.,

$$A_2 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

and so $\det(A_2) = -1$. Assume $\det(A_k) = (-1)^{k-1}(k-1)$. A_{k+1} is the $(k+1) \times (k+1)$ -matrix of the form

$$A_{k+1} = \begin{bmatrix} 0 & 1 & \cdots & 1 & 1 \\ 1 & 0 & 1 & \cdots & 1 \\ & & \ddots & & \\ 1 & 1 & \cdots & 0 & 1 \\ 1 & 1 & \cdots & 1 & 0 \end{bmatrix}.$$

Subtracting the second row from the first, which does not change the value of the determinant, will give us the matrix

$$\begin{bmatrix} -1 & 1 & 0 & \cdots & 0 \\ 1 & 0 & 1 & \cdots & 1 \\ & & \ddots & & \\ 1 & 1 & \cdots & 0 & 1 \\ 1 & 1 & \cdots & 1 & 0 \end{bmatrix}.$$

Now the determinant of A_{k+1} is the sum of two determinants by cofactor expansion. Specifically it is $(-1) \det(A_k)$ minus the determinant of the matrix obtained by taking out the first row and second column. We know that $(-1) \det(A_k) = (-1)^k (k-1)$ by the inductive hypothesis. So what we have left to compute is the determinant of the $(k \times k)$ -matrix

$$\begin{bmatrix} 1 & 1 & \cdots & 1 & 1 \\ 1 & 0 & 1 & \cdots & 1 \\ & & \ddots & & \\ 1 & 1 & \cdots & 0 & 1 \\ 1 & 1 & \cdots & 1 & 0 \end{bmatrix}.$$

We will subtract the first row from each of the rows below it, also not changing the determinant, to give us the upper triangular matrix

$$\begin{bmatrix} 1 & 1 & \cdots & 1 & 1 & 1 \\ 0 & -1 & 0 & \cdots & 0 & 0 \\ 0 & 0 & -1 & 0 & \cdots & 0 \\ & & & \ddots & & \\ 0 & 0 & \cdots & 0 & -1 & 0 \\ 0 & 0 & \cdots & 0 & 0 & -1 \end{bmatrix}$$

whose determinant is $(-1)^{k-1}$. Furthermore,

$$\det(A_{k+1}) = (-1)\det(A_k) - (-1)^{k-1}$$
$$= (-1)^k (k-1) + (-1)^k$$
$$= (-1)^k k.$$

Therefore, by induction, $\det(A_n) = (-1)^{n-1}(n-1)$, for all $n \in \mathbb{Z}_{\geq 2}$.

Theorem 7. vol $(\mathcal{P}_{n,1}) = 2(n-2)$ for $n \geq 3$

Proof. In order to calculate the volume of $\mathcal{P}_{n,1}$ we will first triangulate the 2-dimensional base of the pyramid from Lemma 2

$$\triangle_1 = \operatorname{conv}(e_1 e_n \alpha_{1,n-1}) \text{ and } \triangle_2 = \operatorname{conv}(e_n \alpha_{1,n-1} \alpha_{2,n}).$$

Let x be a point in the base, then for some $\lambda_i \geq 0$, where $\sum_{i=1}^4 \lambda_i = 1$,

$$x = \lambda_{1}e_{1} + \lambda_{2}e_{n} + \lambda_{3}\alpha_{1,n-1} + \lambda_{4}\alpha_{2,n}$$

$$= (\lambda_{1} + \lambda_{3}, \lambda_{3} + \lambda_{4}, \cdots, \lambda_{3} + \lambda_{4}, \lambda_{2} + \lambda_{4})$$

$$= (\lambda_{1} - \lambda_{4})e_{1} + (\lambda_{2} + \lambda_{4})e_{n} + (\lambda_{3} + \lambda_{4})\alpha_{1,n-1}$$

$$= (\lambda_{1} + \lambda_{2})e_{n} + (\lambda_{1} + \lambda_{3})\alpha_{1,n-1} + (\lambda_{4} - \lambda_{1})\alpha_{2,n}.$$

So x is a point in \triangle_1 if $\lambda_1 \ge \lambda_4$ and x is a point in \triangle_2 if $\lambda_4 \ge \lambda_1$. Thus \triangle_1 and \triangle_2 is a triangulation of the 2-dimensional base of the pyramid.

By Corollary 2, each e_2, \dots, e_{n-1} adds a dimension so that the convex hull of these points and Δ_1 is an n-dimensional simplex. The same can be said of Δ_2 . Call these simplices S_1 and S_2 respectively. Thus S_1 and S_2 triangulate $\mathcal{P}_{n,1}$. Therefore the sum of their volumes is equal to the volume of $\mathcal{P}_{n,1}$. In order to calculate the volume of S_1 and S_2 , we will use the Cayley Menger determinant [3] once again. Consider S_1 , whose volume is the determinant of the matrix

$$\begin{bmatrix} e_1 - \alpha_{1,n-1} & e_2 - \alpha_{1,n-1} & \dots & e_n - \alpha_{1,n-1} \end{bmatrix} = \begin{bmatrix} 0 & -1 & -1 & \dots & -1 & -1 \\ -1 & 0 & -1 & \dots & -1 & -1 \\ -1 & -1 & 0 & -1 & \dots & -1 \\ & & & \ddots & & \\ -1 & -1 & \dots & -1 & 0 & -1 \\ 0 & 0 & 0 & \dots & 0 & 1 \end{bmatrix}.$$

Cofactor expansion on the last row will leave us with the determinant, up to a sign, of the $(n-1) \times (n-1)$ matrix

$$\begin{bmatrix} 0 & -1 & -1 & \cdots & -1 \\ -1 & 0 & -1 & \cdots & -1 \\ & & \ddots & & \\ -1 & \cdots & -1 & 0 & -1 \\ -1 & -1 & \cdots & -1 & 0 \end{bmatrix},$$
 (5)

which when ignoring sign by Lemma 4 is n-2. Therefore the volume of S_1 is n-2. Now consider the Cayley Menger determinant of S_2 , the determinant of

$$\left[\alpha_{1,n-1} - \alpha_{2,n} \quad e_2 - \alpha_{2,n} \quad e_3 - \alpha_{2,n} \quad \cdots \quad e_n - \alpha_{2,n}\right] = \begin{bmatrix} 1 & 0 & 0 & 0 & \cdots & 0 \\ 0 & 0 & -1 & -1 & \cdots & -1 \\ 0 & -1 & 0 & -1 & \dots & -1 \\ & & & \ddots & & \\ 0 & -1 & -1 & \cdots & 0 & -1 \\ -1 & -1 & -1 & \cdots & -1 & 0 \end{bmatrix}.$$

By cofactor expansion on the first row we are left with the positive determinant of the matrix (5) which is n-2. Therefore the volume of S_2 is n-2 and so the volume of $\mathcal{P}_{n,1}$ is 2(n-2), as desired.

6 Conclusion

We have looked at several interval-vector polytopes, including complete intervalvector polytopes, fixed interval-vector polytopes, and $\mathcal{P}_{n,1}$. The volume of the ndimensional complete interval-vector polytope is the nth Catalan number. We also formed a bijection between the complete interval-vector polytope and Postnikov's complete root polytope. We proved that the fixed interval-vector polytope with interval length i is an (n-i)-dimensional unimodular simplex. Finally, $\mathcal{P}_{n,1}$ is a pyramid and its f-vector is the nth row of the Pascal 3-triangle. Also, the volume of $\mathcal{P}_{n,1}$ is 2(n-2).

Because of these properties of $\mathcal{P}_{n,1}$, we studied the related polytopes

$$\mathcal{P}_{n,i} := \operatorname{conv}(e_1, \dots, e_n, \alpha_{1,n-i}, \alpha_{2,n-i+1}, \dots, \alpha_{i+1,n}).$$

We observed that the f-vectors of $\mathcal{P}_{n,i}$ correspond to the sum of multiple shifted Pascal triangles. Also, we conjecture that the volume of $\mathcal{P}_{n,i}$ is equal to $2^i(n-(i+1))$. Our future work entails proving this volume conjecture and establishing a more concrete conjecture regarding the f-vectors of $\mathcal{P}_{n,i}$.

Acknowledgements

This work was conducted during the 2012 Mathematical Sciences Research Institute Undergraduate Program (MSRI-UP) in Berkeley, CA. MSRI-UP is supported by the National Science Foundation grant No. DMS-1156499 and the National Security Agency grant No. H98230-11-1-0213. We would like to thank Dr. Matthias Beck, Dr. Ricardo Cortez, Dr. Michael Young, Ana Berrizbeitia, and Amanda Ruiz. We also thank the entire MSRI staff for their continued support throughout our program.

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