

# Introduction to Embedded Systems – WS 2022/23

## Exercise 8: Architecture Synthesis II

### Task 1: Scheduling with Pipeline Resources

Pipeline-resources process data in time intervals that are smaller than the actual execution time  $w$ . As soon as after the start of a task  $v_1$  the so-called *pipeline-interval*  $PI$  has elapsed, the next task  $v_2$  can be started on the same resource (see Figure 1). Non-pipeline-resources are a special case of pipeline-resources with  $PI = w$ .

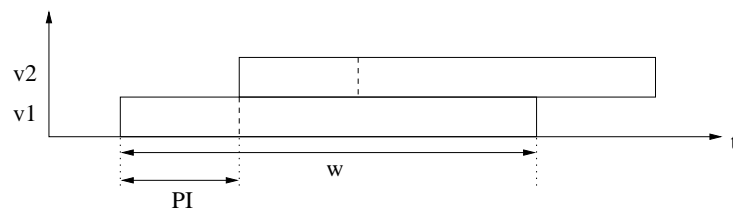


Figure 1: Tasks on pipeline-resource

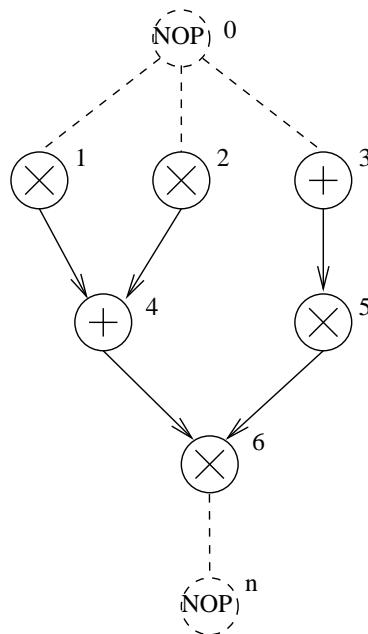


Figure 2: Sequence graph for Pipelining

- Modify the LIST algorithm given in the lecture notes so that pipeline-resources are considered. Which step has to be reformulated and how? (Explain your answer!)
- Perform the scheduling for the sequence graph given in Figure 2 using the modified algorithm. You can use Table 1. The multiplication ( $r_2$ ) lasts 4 time units and the length of the pipeline-interval is 2 time

units. The addition ( $r_1$ ) lasts 2 time units and cannot be executed as pipeline-operation. 1 adder and 1 multiplier are available. Use the number of successor nodes as priority criterion. What is the resulting latency?

## Task 2: Integer Linear Programming

Given the sequence graph  $G_S = (V_S, E_S)$  in Fig. 3.

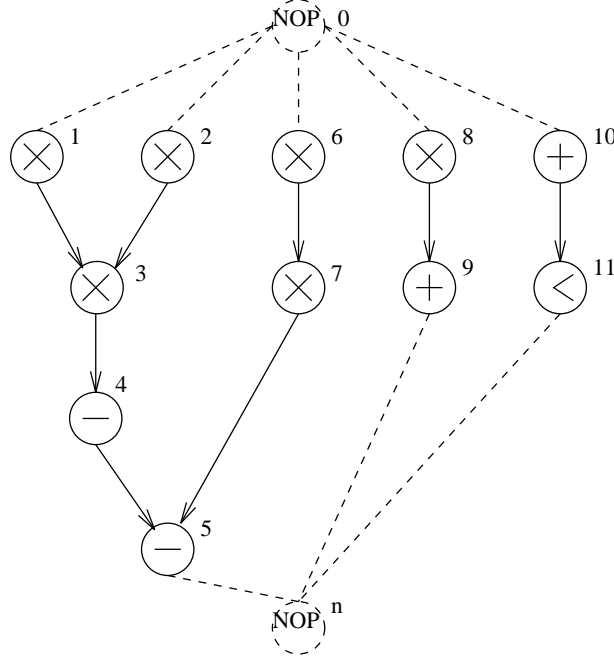


Figure 3: Sequence graph.

For the execution times of the operations assume: A multiplication operation (MULT) takes 2 time units and all other (ALU) operations take 1 time unit each. Two units of the resource type  $r_1$  (multiplier) and two units of the resource type  $r_2$  (ALU) are allocated.

- Apply the ASAP and ALAP algorithms to compute the earliest ( $l_i$ ) and the latest ( $h_i$ ) starting time of all operations  $v_i \in V_S, i \in \{1, \dots, 11\}$ . For ALAP, assume the maximum latency  $\bar{L} = 7$ . Fill in the starting times in Table 2.
- Formulate the problem of latency minimization with restricted resources as an integer linear program (ILP). For this, you should introduce the binary variables  $x_{i,t} \in \{0, 1\} \forall v_i \in V_S$  and  $\forall t \in \{t \in \mathbb{Z} \mid l_i \leq t \leq h_i\}$ .  $\tau(v_i)$  is used to denote the starting time of operation  $v_i \in V_S$  and  $\alpha(r_i)$  with  $r_i \in V_R = \{\text{MULT}, \text{ALU}\}$  denotes the number of allocated resource instances. Given the above notations, write down the following equations/inequations without using the  $\sum$  symbol.
  - Express the objective function of the ILP
  - Define  $\tau(v_i) \forall i \in \{1, \dots, 11\}$  as a function of  $x_{i,t}$ , where  $l_1 \leq t \leq h_1$
  - Express all data dependencies
  - Express all resource limitations
- In an analogous manner try to formulate an ILP that solves the problem of cost minimization with latency limitation. Hint: We assume that the cost of a realization is the sum of the costs  $c$  of the multipliers with  $c(r_1) = 2$  per allocated unit, and of the ALUs with  $c(r_2) = 1$  per allocated unit. For the latency bound, we choose  $\bar{L} = 6$ .

$t$	$k$			
0	$r_1$			
	$r_2$			
1	$r_1$			
	$r_2$			
2	$r_1$			
	$r_2$			
3	$r_1$			
	$r_2$			
4	$r_1$			
	$r_2$			
5	$r_1$			
	$r_2$			
6	$r_1$			
	$r_2$			
7	$r_1$			
	$r_2$			
8	$r_1$			
	$r_2$			
9	$r_1$			
	$r_2$			
10	$r_1$			
	$r_2$			
11	$r_1$			
	$r_2$			
12	$r_1$			
	$r_2$			
13	$r_1$			
	$r_2$			

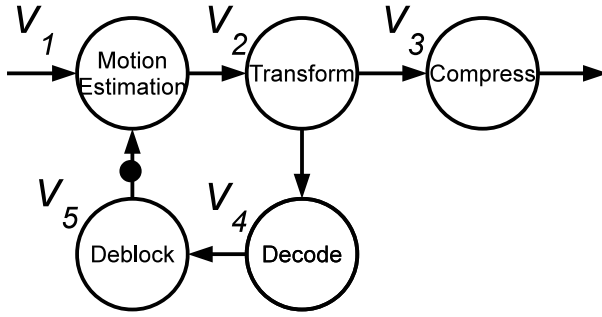
Table 1: Table for Task 1

### Task 3: Iterative Algorithms

Please answer the following questions considering the given video codec application specified as a marked graph in Figure 4.

	$l_i$ (ASAP)	$h_i$ (ALAP)
$v_1$		
$v_2$		
$v_3$		
$v_4$		
$v_5$		
$v_6$		
$v_7$		
$v_8$		
$v_9$		
$v_{10}$		
$v_{11}$		

Table 2: Earliest and latest starting times (Task 2a)



	$\nu_1$	$\nu_2$	$\nu_3$	$\nu_4$	$\nu_5$
$w(\nu_i)$	10	10	10	5	5

Figure 4: Video codec marked graph representation

Table 3: Execution time of each function

- (a) Formulate all existing dependencies in Figure 4 from  $\nu_i$  to  $\nu_j$  in the form of

$$\tau(\nu_j) - \tau(\nu_i) \geq w(\nu_i) - d_{ij} \cdot P,$$

where  $P$  is the minimum iteration interval. The execution time of each function is listed in Table 3.

- (b) Assuming unlimited resources and only one token on the edge between  $\nu_5$  and  $\nu_1$ , determine the minimum iteration interval  $P$  and the latency  $L$ . To justify your answer, draw the scheduling on the timeline given in Figure 5 with the dependency from  $\nu_5$  to  $\nu_1$  highlighted.

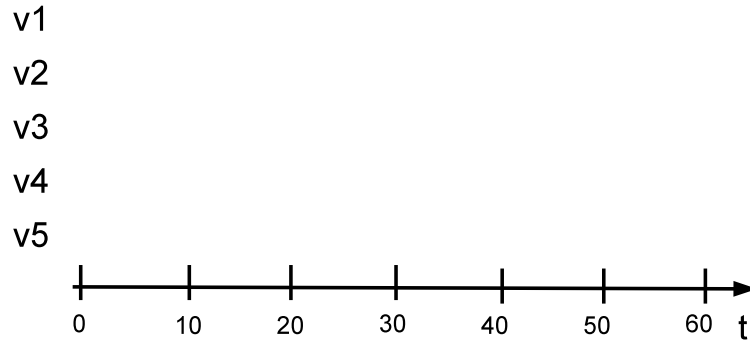


Figure 5: Scheduling result of the video codec

- (c) The motion estimation function ( $\nu_1$ ) uses the result of the previous frame (See the dependency between  $\nu_1$  and  $\nu_5$ ). Let us now suppose that any arbitrary number of tokens can be inserted to reduce  $P$  using functional pipelining. Then, determine the minimum number of tokens that should be added on the

edge  $\nu_5 \rightarrow \nu_1$  to achieve  $P = 10$ ? To justify your answer, draw the pipelined scheduling on the timeline given in Figure 6 with the dependency from  $\nu_5$  to  $\nu_1$  highlighted and calculate the latency  $L$  of the schedule.

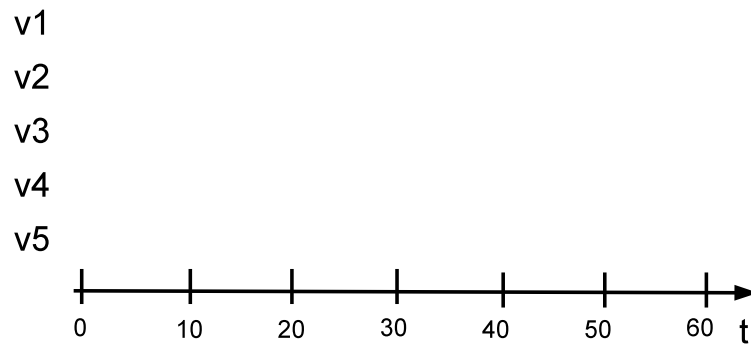


Figure 6: Pipelined scheduling result of the video codec