

SUBSTRATE THEORY — SYMBOLIC LOGIC CANONICAL REFERENCE

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TYPES

State := List Bool

Entity : opaque type

Ω : Entity (axiom)

Substrate : Entity (axiom)

Time := \mathbb{R}

Phase := \mathbb{R}

Nbhd := List State

Precision := \mathbb{N}

COMPLEXITY FUNCTIONS

$$K : \text{Entity} \rightarrow \mathbb{R} \quad (\text{noncomputable axiom})$$

$$K_{\text{sum}} : \text{List Entity} \rightarrow \mathbb{R}$$

$$K_{\text{sum}}(es) := \sum_{e \in es} K(e)$$

$$K_{\text{joint}} : \text{List Entity} \rightarrow \mathbb{R} \quad (\text{noncomputable axiom})$$

$$K_{\text{cond}} : \text{Entity} \rightarrow \text{Entity} \rightarrow \mathbb{R}$$

$$K_{\text{cond}}(e_1, e_2) := K_{\text{joint}}([e_1, e_2]) - K(e_1)$$

$$C : \text{Entity} \rightarrow \mathbb{N} \rightarrow \mathbb{R} \quad (\text{noncomputable axiom})$$

$$C_{\text{sum}} : \text{List Entity} \rightarrow \mathbb{N} \rightarrow \mathbb{R}$$

$$C_{\text{sum}}(es, p) := \sum_{e \in es} C(e, p)$$

$$C_{\text{joint}} : \text{List Entity} \rightarrow \mathbb{N} \rightarrow \mathbb{R} \quad (\text{noncomputable axiom})$$

$$C_{\text{cond}} : \text{Entity} \rightarrow \text{Entity} \rightarrow \mathbb{N} \rightarrow \mathbb{R}$$

$$C_{\text{cond}}(e_1, e_2, p) := C_{\text{joint}}([e_1, e_2], p) - C(e_1, p)$$

$$K_{LZ} : \text{State} \rightarrow \mathbb{N} \quad (\text{axiom})$$

$$K_{\text{toy}} : \text{State} \rightarrow \mathbb{N}$$

$$K_{\text{toy}}(s) := |\text{dedup}(s)|$$

RANK FUNCTIONS

$$\text{rank}_K : \text{Entity} \rightarrow \mathbb{N} \quad (\text{noncomputable axiom})$$

$$\text{rank}_C : \text{Entity} \rightarrow \mathbb{N} \rightarrow \mathbb{N} \quad (\text{noncomputable axiom})$$

TEMPORAL FUNCTIONS

$$\text{indexed} : \text{Entity} \rightarrow \text{Time} \rightarrow \text{Entity} \quad (\text{axiom})$$

$$\text{temporal_slice} : \text{List Entity} \rightarrow \text{Time} \rightarrow \text{List Entity}$$

$$\text{slice} : \text{List (Entity} \times \text{Time)} \rightarrow \text{Time} \rightarrow \text{List Entity}$$

$$\text{join} : \text{List State} \rightarrow \text{State} \quad (\text{axiom})$$

$$\text{mode} : \text{State} \rightarrow \text{State} \quad (\text{noncomputable constant})$$

$$\text{traj} : \text{Entity} \rightarrow \text{List (Entity} \times \text{Time)}$$

$$P_{\text{total}} : \text{Entity} \rightarrow \mathbb{R}$$

COHERENCE FUNCTIONS

$$\begin{aligned} \text{Coh} &: \text{List Entity} \rightarrow \text{List Time} \rightarrow \mathbb{R} \\ \text{Coh}(es, \text{times}) &:= 1 - K_{\text{joint}}(\text{slice}(es, \text{times})) / K_{\text{sum}}(\text{slice}(es, \text{times})) \end{aligned}$$

$$\begin{aligned} \text{Coh}_{\text{op}} &: \text{List Entity} \rightarrow \text{List Time} \rightarrow \mathbb{N} \rightarrow \mathbb{R} \\ \text{Coh}_{\text{op}}(es, \text{times}, p) &:= 1 - C_{\text{joint}}(\text{slice}(es, \text{times}), p) / C_{\text{sum}}(\text{slice}(es, \text{times}), p) \end{aligned}$$

$$\begin{aligned} \text{Coh}_{\text{trajectory}} &: \text{Entity} \rightarrow \mathbb{R} \\ \frac{d\text{Coh}}{dt} &: \text{Entity} \rightarrow \text{Time} \rightarrow \mathbb{R} \end{aligned}$$

$$\text{compression_ratio} : \text{List Entity} \rightarrow \text{List Time} \rightarrow \mathbb{R}$$

PARTITION FUNCTIONS

$$\begin{aligned} Z_{\text{ideal}} &: \text{Finset Entity} \rightarrow \mathbb{R} \\ Z_{\text{ideal}}(S) &:= \sum_{e \in S} 2^{-K(e)} \end{aligned}$$

$$\begin{aligned} Z_{\text{op}} &: \text{Finset Entity} \rightarrow \mathbb{N} \rightarrow \mathbb{R} \\ Z_{\text{op}}(S, p) &:= \sum_{e \in S} 2^{-C(e, p)} \end{aligned}$$

GROUNDING FUNCTIONS

$$\begin{aligned} \text{grounds_graph} &: \text{Finset Entity} \rightarrow \mathbb{N} \rightarrow \text{Finset} (\text{Entity} \times \text{Entity}) \\ \text{parents}_C &: \text{Entity} \rightarrow \text{Finset Entity} \rightarrow \mathbb{N} \rightarrow \text{Finset Entity} \\ \text{bfs_depth}_C &: \text{Entity} \rightarrow \mathbb{N} \rightarrow \text{Finset Entity} \rightarrow \mathbb{N} \\ \text{bfs_grounding_path} &: \text{Entity} \rightarrow \text{Finset Entity} \rightarrow \mathbb{N} \rightarrow \text{Option} (\text{List Entity}) \end{aligned}$$

CONSTANTS

$$c_{\text{grounding}} := 50$$

$$c_{\text{margin}} := 5$$

$$c_{\text{sub}} : \mathbb{R} \quad (\text{constant})$$

$$c_{\text{single}} : \mathbb{R} \quad (\text{constant})$$

$$C_{\text{mode}} : \mathbb{R} \quad (\text{constant})$$

$$c \approx 299792458 \text{ m/s}$$

$$\hbar : \mathbb{R} \quad (\text{axiom}, \hbar > 0)$$

$$G : \mathbb{R} \quad (\text{axiom}, G > 0)$$

$$k_B : \mathbb{R} \quad (\text{axiom}, k_B > 0)$$

$$e : \mathbb{R} \quad (\text{axiom}, e > 0)$$

$$\varepsilon_0 : \mathbb{R} \quad (\text{axiom}, \varepsilon_0 > 0)$$

$$\alpha : \mathbb{R} \quad (\text{axiom}, 1/138 < \alpha < 1/137)$$

$$\ell_{\text{Planck}} := \sqrt{\frac{\hbar G}{c^3}}$$

$$t_{\text{Planck}} := \ell_{\text{Planck}}/c$$

$$M_{\text{Planck}} := \sqrt{\frac{\hbar c}{G}}$$

$$E_{\text{Planck}} := M_{\text{Planck}} \cdot c^2$$

$$T_{\text{Planck}} := E_{\text{Planck}}/k_B$$

$$\kappa_{\text{energy}} := E_{\text{Planck}}$$

$$\hbar_{\text{eff}} : \mathbb{R} \quad (\text{axiom}, \hbar_{\text{eff}} > 0)$$

$$\varepsilon_{\text{geom}} : \mathbb{R} \quad (\text{axiom}, \varepsilon_{\text{geom}} > 0)$$

$$H_0 : \mathbb{R} \quad (67 < H_0 < 74)$$

$$\Omega_m : \mathbb{R} \quad (0.3 < \Omega_m < 0.32)$$

$$\Omega_\Lambda : \mathbb{R} \quad (0.68 < \Omega_\Lambda < 0.70)$$

$$\Omega_r : \mathbb{R} \quad (0 < \Omega_r < 0.0001)$$

$$\Omega_k : \mathbb{R} \quad (|\Omega_k| < 0.01)$$

$$\Omega_{DM} : \mathbb{R} \quad (0.25 < \Omega_{DM} < 0.27)$$

$$\Omega_{\text{baryon}} : \mathbb{R} \quad (0.04 < \Omega_{\text{baryon}} < 0.05)$$

$$t_{\text{universe}} : \mathbb{R} \quad (13.7 \times 10^9 < t_{\text{universe}} < 13.9 \times 10^9)$$

CORE AXIOMS

Axiom 1 (K2 (Substrate Minimality)).

$$\begin{aligned} K(\text{Substrate}) &= 0 \\ K(\Omega) &= 0 \end{aligned}$$

Axiom 2 (G1 (Substrate Grounds All)).

$$\forall e. \text{is_presentation}(e) \rightarrow \text{is_grounded}(e, \text{Substrate})$$

where $\text{is_grounded}(e, ctx) := K_{cond}(ctx, e) < K(e) - K(ctx) + c_{grounding}$

Axiom 3 (T7 (Time Arrow)).

$$\begin{aligned} \forall hist, next. hist.length \geq 2 \rightarrow \\ K_{joint}(next :: hist) - K_{joint}(hist) \leq K_{joint}([hist.last, hist.init]) - K(hist.init) \end{aligned}$$

Axiom 4 (T4 (Emergence/Collapse)).

$$\begin{aligned} \forall e_{classical}, e_{quantum}. \\ emergent(e_{classical}, e_{quantum}) \rightarrow \\ is_measurement_device(e_{classical}) \vee is_observable(e_{classical}) \end{aligned}$$

where $emergent(e_{classical}, e_{quantum}) := K_{cond}(\text{Substrate}, e_{classical}) < K(e_{quantum})$

Axiom 5 (C6 (Coherence Preservation)).

$$\forall e. is_quantum_state(e) \rightarrow coherent(e)$$

where $coherent(e) := \forall t_1, t_2. t_1 < t_2 \rightarrow K_{cond}(indexed(e, t_1), indexed(e, t_2)) = K_{cond}(indexed(e, t_2), indexed(e, t_1))$

AXIOM CONSEQUENCES

Theorem 1 (substrate_ultimate_ground).

$$\begin{aligned} \forall e. is_presentation(e) \rightarrow \exists path. \\ path.head = \text{Substrate} \wedge path.last = e \wedge \\ \forall i. i + 1 < path.length \rightarrow is_grounded(path[i + 1], path[i]) \end{aligned}$$

Theorem 2 (decoherence_implies_classical).

$$\begin{aligned} \forall e. is_presentation(e) \wedge \neg coherent(e) \rightarrow \\ \exists t_0. \forall t > t_0. \neg is_quantum_state(indexed(e, t)) \end{aligned}$$

Theorem 3 (measurement_breaks_coherence).

$$\begin{aligned} \forall e_q, e_c. is_quantum_state(e_q) \wedge coherent(e_q) \wedge emergent(e_c, e_q) \rightarrow \\ \neg coherent(e_c) \end{aligned}$$

BRIDGE AXIOMS

Axiom 6 (BRIDGE1 (Pointwise Convergence)).

$$\forall e, \varepsilon > 0. is_presentation(e) \rightarrow \exists p_0. \forall p \geq p_0. |C(e, p) - K(e)| < \varepsilon$$

Axiom 7 (BRIDGE2 (Uniform Convergence)).

$$\forall S, \varepsilon > 0. (\forall e \in S. is_presentation(e)) \rightarrow \exists p_0. \forall p \geq p_0, e \in S. |C(e, p) - K(e)| < \varepsilon$$

Axiom 8 (BRIDGE3 (Probability Convergence)).

$$\begin{aligned} \forall S, \varepsilon > 0. (\forall e \in S. is_presentation(e)) \wedge Z_{ideal}(S) > 0 \rightarrow \\ \exists p_0. \forall p \geq p_0. |Z_{op}(S, p) - Z_{ideal}(S)| / Z_{ideal}(S) < \varepsilon \end{aligned}$$

Axiom 9 (BRIDGE4 (Grounding Convergence)).

$$\begin{aligned} \forall S, \varepsilon > 0, e_1, e_2. e_1, e_2 \in S \wedge is_presentation(e_1) \wedge is_presentation(e_2) \rightarrow \\ \exists p_0. \forall p \geq p_0. grounds_K(e_1, e_2) \leftrightarrow grounds_C(e_1, e_2, p) \end{aligned}$$

where:

$$\begin{aligned} grounds_K(e_1, e_2) &:= K_{cond}(e_1, e_2) < K(e_2) - K(e_1) + c_{grounding} \\ grounds_C(e_1, e_2, p) &:= C_{cond}(e_1, e_2, p) < C(e_2, p) - C(e_1, p) + c_{grounding} \end{aligned}$$

Axiom 10 (BRIDGE5 (Rank Stability)).

$$\begin{aligned} \forall S, e. e \in S \wedge is_presentation(e) \rightarrow \\ \exists p_0. \forall p \geq p_0. rank_C(e, p) = rank_K(e) \end{aligned}$$

Axiom 11 (BRIDGE6 (Temporal Continuity)).

$$\begin{aligned} \forall e, times, \varepsilon > 0. is_temporal_presentation(e) \rightarrow \\ \exists p_0. \forall p \geq p_0, t \in times. |Coh_{op}([e], [t], p) - Coh([e], [t])| < \varepsilon \end{aligned}$$

Axiom 12 (BRIDGE7 (Conditional Convergence)).

$$\begin{aligned} \forall e_1, e_2, \varepsilon > 0. is_presentation(e_1) \wedge is_presentation(e_2) \rightarrow \\ \exists p_0. \forall p \geq p_0. |C_{cond}(e_1, e_2, p) - K_{cond}(e_1, e_2)| < \varepsilon \end{aligned}$$

Axiom 13 (BRIDGE7_joint (Joint Convergence)).

$$\begin{aligned} \forall es, \varepsilon > 0. (\forall e \in es. is_presentation(e)) \rightarrow \\ \exists p_0. \forall p \geq p_0. |C_{joint}(es, p) - K_{joint}(es)| < \varepsilon \end{aligned}$$

Axiom 14 (BRIDGE8 (Continuum Limit)).

$$\begin{aligned} \forall e, times, \varepsilon > 0. is_temporal_presentation(e) \rightarrow \\ \exists p_0, \delta. \delta > 0 \wedge \forall p \geq p_0, t \in times. \\ \left| \frac{Coh_{op}([e], [t + \delta], p) - Coh_{op}([e], [t], p)}{\delta} - \frac{dCoh}{dt}(e, t) \right| < \varepsilon \end{aligned}$$

CA RULES

$$F : \text{State} \rightarrow \text{State} \quad (\text{noncomputable})$$

$$\text{merge} : \text{State} \rightarrow \text{State} \rightarrow \text{State} \quad (\text{noncomputable})$$

$$R_{\text{Cohesion}} : \text{List State} \rightarrow \text{State} \rightarrow \text{State}$$

$$R_{\text{Cohesion}}(n, h) := \text{merge}(F(\text{join}(n)), h)$$

$$R_{\text{Reduction}} : \text{List State} \rightarrow \text{State}$$

$$R_{\text{Reduction}}(n) := \text{mode}(\text{join}(n))$$

$$R_{G1} : \text{List State} \rightarrow \text{State} \rightarrow \text{State}$$

$$R_{G1}(n, h) := \begin{cases} R_{\text{Cohesion}}(n, h) & \text{if } K_{LZ}(\text{join}(n)) \leq c_{\text{grounding}} \\ R_{\text{Reduction}}(n) & \text{otherwise} \end{cases}$$

$$\text{coherent_state} : \text{State} \rightarrow \text{Prop}$$

$$\text{coherent_state}(s) := K_{LZ}(s) \leq c_{\text{grounding}}$$

CA PRESERVATION THEOREMS

Theorem 4 (P3 (C6 Preservation)).

$$\forall n, h. \text{coherent_state}(\text{join}(n)) \rightarrow K_{LZ}(R_{G1}(n, h)) = K_{LZ}(h)$$

Theorem 5 (R_G1_grounding_reduction).

$$\forall n, h. K_{LZ}(\text{join}(n)) > c_{\text{grounding}} \rightarrow K_{LZ}(R_{G1}(n, h)) < K_{LZ}(\text{join}(n)) + c_{\text{grounding}}$$

Theorem 6 (R_G1_preserves_time_arrow).

$$\forall hist, n, h. K_{LZ}(\text{join}(R_{G1}(n, h) :: hist)) \leq K_{LZ}(\text{join}(hist)) + c_{\text{margin}}$$

FUNDAMENTAL THEOREMS

Theorem 7 (E_K (Energy-Complexity Equivalence)).

$$\forall e. \text{is_presentation}(e) \rightarrow$$

$$(\text{has_mass}(e) \rightarrow \exists \Delta > 0. K(e) = K(\Omega) + \Delta) \wedge$$

$$\text{energy_of}(e) = \kappa_{\text{energy}} \cdot K(e)$$

Theorem 8 (G_Ψ (Grounding Stability)).

$$\forall e. \text{stable}(e) \leftrightarrow K_{\text{cond}}(\Omega, e) > c_{\text{grounding}}$$

$$\text{where } \text{stable}(e) := \text{is_presentation}(e) \wedge K_{\text{cond}}(\Omega, e) > c_{\text{grounding}}$$

Theorem 9 (B- Ω (Holographic Bound)).

$$\forall region, Area. is_presentation(region) \wedge Area > 0 \rightarrow$$

$$K(region) \leq \frac{Area}{4\ell_{Planck}^2}$$

Theorem 10 (Ψ -I (Coherence Invariant)).

$$\forall e. is_temporal_presentation(e) \wedge coherent(e) \rightarrow$$

$$Coh_{trajectory}(e) \cdot P_{total}(e) = 1$$

Theorem 11 (U- Ω (Uncertainty Principle)).

$$\forall e, \Delta K, \Delta t. is_temporal_presentation(e) \wedge \Delta K > 0 \wedge \Delta t > 0 \rightarrow$$

$$\Delta K \cdot \Delta t \geq \hbar_{eff}$$

RANK SYSTEM

$$\text{rank}_K(\Omega) = 0$$

$$\text{grounds}(e_1, e_2) \rightarrow \text{rank}_K(e_2) < \text{rank}_K(e_1)$$

$$\forall e. \exists n. \text{rank}_K(e) = n$$

$$\text{rank}_C(e, p) = \text{bfs_depth}_C(e, p, S) \quad \text{for } e \in S$$

UNIVERSAL GROUNDING

Theorem 12.

$$\forall e. is_presentation(e) \rightarrow$$

$$\exists path. path.head = \Omega \wedge path.last = e \wedge$$

$$\forall i. i + 1 < path.length \rightarrow \text{grounds}(path[i], path[i + 1])$$

Theorem 13 (grounding-transitive).

$$\forall e_1, e_2, e_3. \text{grounds}(e_1, e_2) \wedge \text{grounds}(e_2, e_3) \rightarrow \text{grounds}(e_1, e_3)$$

Theorem 14 (grounding-acyclic).

$$\forall e. \neg \text{grounds}(e, e)$$

COMPLEXITY BOUNDS

$$K_joint_nonneg : \forall es. 0 \leq K_{joint}(es)$$

$$K_joint_nil : K_{joint}([]) = 0$$

$$K_joint_singleton : \forall e. K_{joint}([e]) = K(e)$$

Theorem 15 (compression_axiom).

$$\forall es. (\forall e \in es. is_presentation(e)) \wedge es.length \geq 2 \rightarrow$$

$$K_{joint}(es) < K_{sum}(es)$$

Theorem 16 (joint_le_sum).

$$\forall es. (\forall e \in es. is_presentation(e)) \rightarrow K_{joint}(es) \leq K_{sum}(es)$$

Theorem 17 (complexity_positive).

$$\forall e. is_presentation(e) \rightarrow 0 < K(e)$$

Theorem 18 (substrate_minimal).

$$\forall e. is_presentation(e) \rightarrow K(Substrate) \leq K(e)$$

OPERATIONAL BOUNDS

$$C_nonneg : \forall e, p. 0 \leq C(e, p)$$

$$C_monotone : \forall e, p_1, p_2. p_1 \leq p_2 \rightarrow C(e, p_2) \leq C(e, p_1)$$

$$C_upper_bound : \forall e, p. is_presentation(e) \rightarrow K(e) \leq C(e, p)$$

$$C_joint_nonneg : \forall es, p. 0 \leq C_{joint}(es, p)$$

$$K_LZ_nonneg : \forall s. 0 \leq K_{LZ}(s)$$

$$K_LZ_empty : K_{LZ}([]) = 0$$

$$K_LZ_monotone : \forall s_1, s_2. s_1.length \leq s_2.length \rightarrow K_{LZ}(s_1) \leq K_{LZ}(s_2)$$

TOY COMPRESSOR BOUNDS

$$K_toy_lower_bound : \forall s. K_{LZ}(s) \leq K_{toy}(s)$$

$$K_toy_upper_bound : \forall s. K_{toy}(s) \leq K_{LZ}(s) + \log_2(s.length)$$

KLZ AXIOMS

Axiom 15 (K_LZ_subadditive_cons).

$$\forall x, xs. K_{LZ}(join(x :: xs)) \leq K_{LZ}(join(xs)) + K_{LZ}(x) + c_{sub}$$

Axiom 16 (K_LZ_prefix).

$$\forall b, s. K_{LZ}(join([b])) \leq K_{LZ}(join(b :: s))$$

Axiom 17 (K_LZ_singleton_bound).

$$\forall b. K_{LZ}(join([b])) \leq c_{single}$$

Axiom 18 (K_LZ_mode_le).

$$\forall s. K_{LZ}(mode(s)) \leq K_{LZ}(s) + C_{mode}$$

Axiom 19 (C_mode_lt_c_grounding).

$$C_{mode} < c_{grounding}$$

COHERENCE BOUNDS

Theorem 19 (coherence_bounds).

$$\forall es, times. (\forall e \in es. is_presentation(e)) \rightarrow 0 \leq Coh(es, times) \wedge Coh(es, times) \leq 1$$

Theorem 20 (compression_ratio_ge_one).

$$\forall es, times. (\forall e \in es. is_presentation(e)) \rightarrow 1 \leq compression_ratio(es, times)$$

PHYSICS CORRESPONDENCES

$$energy_of(e) = \kappa_{energy} \cdot K(e)$$

$$mass(e) = energy_of(e)/c^2$$

$$entropy(e) = k_B \cdot \log(2) \cdot K(e)$$

$$is_quantum(nbhd) := K_{LZ}(join(nbhd)) \leq c_{grounding}$$

$$is_classical(nbhd) := K_{LZ}(join(nbhd)) > c_{grounding}$$

PREDICATES

$\text{is_substrate} : \text{Entity} \rightarrow \text{Prop} \quad (\text{axiom})$
 $\text{is_presentation} : \text{Entity} \rightarrow \text{Prop} \quad (\text{axiom})$
 $\text{is_emergent} : \text{Entity} \rightarrow \text{Prop} \quad (\text{axiom})$
 $\text{is_temporal_presentation} : \text{Entity} \rightarrow \text{Prop} \quad (\text{axiom})$
 $\text{is_static_presentation} : \text{Entity} \rightarrow \text{Prop} \quad (\text{axiom})$
 $\text{is_quantum_state} : \text{Entity} \rightarrow \text{Prop} \quad (\text{axiom})$
 $\text{is_measurement_device} : \text{Entity} \rightarrow \text{Prop} \quad (\text{axiom})$
 $\text{is_observable} : \text{Entity} \rightarrow \text{Prop} \quad (\text{axiom})$

$\text{phenomenal} : \text{Entity} \rightarrow \text{Prop} \quad (\text{axiom})$
 $\text{has_mass} : \text{Entity} \rightarrow \text{Prop} \quad (\text{axiom})$

$\text{grounds} : \text{Entity} \rightarrow \text{Entity} \rightarrow \text{Prop} \quad (\text{axiom})$
 $\text{temporal_grounds} : \text{Entity} \rightarrow \text{Time} \rightarrow \text{Entity} \rightarrow \text{Time} \rightarrow \text{Prop} \quad (\text{axiom})$
 $\text{interacts} : \text{Entity} \rightarrow \text{Entity} \rightarrow \text{Prop} \quad (\text{axiom})$
 $\text{inseparable} : \text{Entity} \rightarrow \text{Entity} \rightarrow \text{Prop} \quad (\text{axiom})$
 $\text{emerges_from} : \text{Entity} \rightarrow \text{List Entity} \rightarrow \text{Prop} \quad (\text{axiom})$
 $\text{phase_coupled} : \text{Entity} \rightarrow \text{Entity} \rightarrow \text{Phase} \rightarrow \text{Prop} \quad (\text{axiom})$

$\text{coherent} : \text{Entity} \rightarrow \text{Prop}$
 $\text{decoherent} : \text{Entity} \rightarrow \text{Prop}$
 $\text{stable} : \text{Entity} \rightarrow \text{Prop}$

$\text{is_quantum} : \text{List State} \rightarrow \text{Prop}$
 $\text{is_classical} : \text{List State} \rightarrow \text{Prop}$
 $\text{coherent_state} : \text{State} \rightarrow \text{Prop}$

ENTITY CLASSIFICATION

Theorem 21 (*entity_classification*).

$$\forall e. (\text{is_substrate}(e) \wedge e = \text{Substrate}) \vee \text{is_presentation}(e) \vee \text{is_emergent}(e)$$

$$\text{substrate_not_presentation} : \forall e. \neg(\text{is_substrate}(e) \wedge \text{is_presentation}(e))$$

$$\text{substrate_not_emergent} : \forall e. \neg(\text{is_substrate}(e) \wedge \text{is_emergent}(e))$$

$$\text{presentation_not_emergent} : \forall e. \neg(\text{is_presentation}(e) \wedge \text{is_emergent}(e))$$

Theorem 22 (presentation_temporal_or_static).

$$\begin{aligned} \forall e. is_presentation(e) \rightarrow \\ (is_temporal_presentation(e) \vee is_static_presentation(e)) \wedge \\ \neg(is_temporal_presentation(e) \wedge is_static_presentation(e)) \end{aligned}$$

SUBSTRATE PROPERTIES

$$\begin{aligned} substrate_unique &: \forall x, y. is_substrate(x) \wedge is_substrate(y) \rightarrow x = y \\ substrate_is_Substrate &: is_substrate(Substrate) \\ Omega_is_substrate &: is_substrate(\Omega) \\ Omega_eq_Substrate &: \Omega = Substrate \end{aligned}$$

TEMPORAL PRESERVATION

Theorem 23 (indexed_preserves_presentation).

$$\forall e, t. is_presentation(e) \rightarrow is_presentation(indexed(e, t))$$

Theorem 24 (temporal_slice_preserves_presentation).

$$\begin{aligned} \forall es, t. (\forall e \in es. is_presentation(e)) \rightarrow \\ (\forall e \in temporal_slice(es, t). is_presentation(e)) \end{aligned}$$

ASSOCIATIVITY

Theorem 25 (join_associative).

$$\forall s_1, s_2, s_3. join([join([s_1, s_2]), s_3]) = join([s_1, join([s_2, s_3])])$$