

# Section 16 Neural Network (and Deep Learning)

## Basic Structures of Neural Network (NN)

Intuitively, Neural Network is nothing but the construction of one nonlinear (vector-valued) function  $\mathbf{h}(\mathbf{x}; W, b) \in \mathbb{R}^p \rightarrow \mathbb{R}^k$  with a series of composite functions (layers). For the interactive visualization and exploration of NN, you can refer [here](#).

The layers can be further classified into three categories:

- **Input layer:**  $p$  nodes representing the input sample  $x \in \mathbb{R}^p$
- **Hidden layers:** Calculate the values on the nodes of  $(l + 1)$ -th layers based on those on the  $l$ -th layer as

$$\begin{aligned}\mathbf{z}^{(l+1)} &= W^{(l)} \mathbf{a}^{(l)} + \mathbf{b}^{(l)} \\ \mathbf{a}^{(l+1)} &= \sigma(\mathbf{z}^{(l+1)})\end{aligned}$$

where  $\sigma$  is the nonlinear [activation function](#) (common choices include sigmoid, tanh or ReLU), and the second equation is element-wise.

*Note:* Suppose there are  $m$  nodes in layer  $l$  and  $n$  nodes in layer  $(l + 1)$ . Then there are  $(m + 1) \times n$  trainable parameters between the two layers, or sometimes by convention, we just say they are the parameters are on the  $(l + 1)$ -th layer.

- **Output layer:**  $k$  nodes representing the output, and dependent on the problem can be
  - 1) For regression problem, just as another regular hidden layer of  $k$  nodes
  - 2) For classification problem, apply the [softmax function](#) on the vector  $\mathbf{z}$  to ensure that the output is the probability vector for  $k$  classes.

After constructing the mapping, in supervised problem, the loss function  $J(W, b; \mathbf{x}, y)$  can be choosed the same as other machine learning models.

- For regression: MSE (mean squared error)
- For classification: Cross Entropy

**Interesting Facts** (not required in exam):

- Logistic regression can be viewed as "the simplest" NN with only the input layer ( $p$  nodes) and output layer (softmax output). Because it only has "[one layer of parameters](#)", sometimes it is also called [single-layer NN](#).
- NN can also be used in unsupervised tasks, such as [Autoencoder](#) for dimension reduction.

# Training Algorithms: BP (Back Propagation) and SGD (or other optimization method)

As we've known well, training the machine learning model is largely dependent on minimizing the loss function, where its gradient provides the important information.

Intuitively speaking, **back propagation** is just the right algorithm to find such gradient for the training of NN, which is based on the **chain-rule** of derivatives in hierarchical network-structured composite function.

In detail, the backpropagation algorithm for NN training can be described as (not required):

Step 1: Perform a **forward pass**, computing the values for layers  $L_2, L_3$ , and so on up to the output layer  $L_{n_l}$ . We take the loss of MSE in regression as example.

Step 2: For each output unit  $i$  in layer  $n_l$  (the output layer), set

$$\delta_i^{(n_l)} := \frac{\partial}{\partial z_i^{(n_l)}} J(W, b; \mathbf{x}, y) = \frac{\partial}{\partial z_i^{(n_l)}} \frac{1}{2} \|y - h(\mathbf{x}; W, b)\|^2 = -(y - a_i^{(n_l)}) \cdot \sigma'(z_i^{(n_l)})$$

Step 3: For  $l = n_l - 1, n_l - 2, n_l - 3, \dots, 2$  For each node  $i$  in layer  $l$ , set

$$\delta_i^{(l)} := \frac{\partial}{\partial z_i^{(l)}} J(W, b; \mathbf{x}, y) = \frac{\partial}{\partial a_i^{(l)}} J(W, b; \mathbf{x}, y) \frac{\partial a_i^{(l)}}{\partial z_i^{(l)}} = \left( \sum_{j=1}^{s_{l+1}} w_{ji}^{(l)} \delta_j^{(l+1)} \right) \sigma'(z_i^{(l)})$$

Step 4: the desired partial derivatives are computed as:

$$\begin{aligned} \frac{\partial}{\partial w_{ij}^{(l)}} J(W, b; \mathbf{x}, y) &= a_j^{(l)} \delta_i^{(l+1)} \\ \frac{\partial}{\partial b_i^{(l)}} J(W, b; \mathbf{x}, y) &= \delta_i^{(l+1)}. \end{aligned}$$

After obtaining the gradient with BP, we can then use stochastic gradient descent (SGD, or other methods) to minimize the loss function.

## Deep Learning: What packages/platforms to choose?

By making the NN "deeper" (increase the hidden layers and add other complex structures), we have the deep learning models. Of course, deep NN will face the serious problem of overfitting (can be alleviated by regularization or dropout) and huge computation cost (can be solved by using GPU instead of CPU).

The [neural network models](#) in scikit-learn does not provide the flexible support for large-scale deep learning applications.

For beginners, [Keras](#) (high-level API that supports [tensorflow](#), which developed by Google) and [Pytorch](#) (developed by Facebook) are the most accessible and popular deep learning packages in

Python.

To get access to free GPU resources for training deep learning models (see here for [why GPU is widely applied in deep learning](#)), you can use the online notebook provided by Kaggle or [google colab](#). If you are using very basic Keras or Pytorch, there's no need to change the code much to adopt to GPU computation. With GPU, you can even give up sklearn and replace much of your codes using the GPU-version machine learning algorithms with the package [cuml](#).

## Exploring Deep Learning with Keras

Let's build our first "deep learning" model (indeed a simple Neural Network model trained with deep learning package)

```
In [ ]: pip install tensorflow # you can also setup the gpu if it is supported in your local co
```

```
In [1]: import numpy as np
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers

mnist = tf.keras.datasets.mnist
(x_train, y_train), (x_test, y_test) = mnist.load_data()
x_train, x_test = x_train / 255.0, x_test / 255.0
```

```
In [ ]: # sequential model to define a graph of neural network
model = tf.keras.models.Sequential([
    tf.keras.layers.Flatten(input_shape=(28, 28)), # input layer
    tf.keras.layers.Dense(128, activation='relu'), # hidden layer
    tf.keras.layers.Dense(64, activation='relu'), # hidden layer
    tf.keras.layers.Dense(10, activation='softmax') # output layer for classification
])
```

```
In [ ]: model.summary()
```

```
In [ ]: model.compile(optimizer='adam',
                      loss='sparse_categorical_crossentropy',
                      metrics=['accuracy'])
```

```
In [ ]: model.fit(x_train, y_train, epochs=100, batch_size = 2048)
model.evaluate(x_test, y_test)
```

We can also try autoencoder for the dimension reduction

```
In [2]: from keras import layers
# functional API to define a graph of neural network -- more flexible than sequential

input_img = keras.Input(shape=(784,)) # input layer
encoded = layers.Dense(128, activation='relu')(input_img)
encoded = layers.Dense(32, activation='relu')(encoded)
```

```

encoded = layers.Dense(8, activation='relu')(encoded)
encoded = layers.Dense(2, activation='relu')(encoded)

decoded = layers.Dense(8, activation='relu')(encoded)
decoded = layers.Dense(32, activation='relu')(decoded)
decoded = layers.Dense(128, activation='relu')(decoded)
decoded = layers.Dense(784, activation='sigmoid')(decoded)

```

```

In [3]: autoencoder = keras.Model(input_img, decoded) # builds up the model
autoencoder.summary()

```

Model: "functional\_1"

Layer (type)	Output Shape	Param #
=====		
input_1 (InputLayer)	[(None, 784)]	0
dense (Dense)	(None, 128)	100480
dense_1 (Dense)	(None, 32)	4128
dense_2 (Dense)	(None, 8)	264
dense_3 (Dense)	(None, 2)	18
dense_4 (Dense)	(None, 8)	24
dense_5 (Dense)	(None, 32)	288
dense_6 (Dense)	(None, 128)	4224
dense_7 (Dense)	(None, 784)	101136
=====		
Total params: 210,562		
Trainable params: 210,562		
Non-trainable params: 0		

```

In [10]: autoencoder.compile(optimizer='adam', loss= tf.keras.losses.MeanSquaredError())

autoencoder.fit(x_test.reshape((len(x_test), np.prod(x_test.shape[1:])), x_test.reshape
epochs=200,
batch_size=1024)

```

```

Epoch 1/100
10/10 [=====] - 0s 8ms/step - loss: 0.0440
Epoch 2/100
10/10 [=====] - 0s 8ms/step - loss: 0.0431
Epoch 3/100
10/10 [=====] - 0s 8ms/step - loss: 0.0429
Epoch 4/100
10/10 [=====] - 0s 9ms/step - loss: 0.0428
Epoch 5/100
10/10 [=====] - 0s 9ms/step - loss: 0.0428
Epoch 6/100
10/10 [=====] - 0s 8ms/step - loss: 0.0427
Epoch 7/100
10/10 [=====] - 0s 9ms/step - loss: 0.0427
Epoch 8/100
10/10 [=====] - 0s 8ms/step - loss: 0.0427
Epoch 9/100

```

10/10 [=====] - 0s 8ms/step - loss: 0.0427  
Epoch 10/100  
10/10 [=====] - 0s 7ms/step - loss: 0.0427  
Epoch 11/100  
10/10 [=====] - 0s 8ms/step - loss: 0.0426  
Epoch 12/100  
10/10 [=====] - 0s 8ms/step - loss: 0.0426  
Epoch 13/100  
10/10 [=====] - 0s 8ms/step - loss: 0.0426  
Epoch 14/100  
10/10 [=====] - 0s 8ms/step - loss: 0.0426  
Epoch 15/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0426  
Epoch 16/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0426  
Epoch 17/100  
10/10 [=====] - 0s 10ms/step - loss: 0.0425  
Epoch 18/100  
10/10 [=====] - 0s 8ms/step - loss: 0.0425  
Epoch 19/100  
10/10 [=====] - 0s 8ms/step - loss: 0.0425  
Epoch 20/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0425  
Epoch 21/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0425  
Epoch 22/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0425  
Epoch 23/100  
10/10 [=====] - 0s 8ms/step - loss: 0.0424  
Epoch 24/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0424  
Epoch 25/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0424  
Epoch 26/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0424  
Epoch 27/100  
10/10 [=====] - 0s 8ms/step - loss: 0.0424  
Epoch 28/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0423  
Epoch 29/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0423  
Epoch 30/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0423  
Epoch 31/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0423  
Epoch 32/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0423  
Epoch 33/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0423  
Epoch 34/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0423  
Epoch 35/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0423  
Epoch 36/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0422  
Epoch 37/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0422  
Epoch 38/100  
10/10 [=====] - 0s 10ms/step - loss: 0.0422  
Epoch 39/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0422  
Epoch 40/100  
10/10 [=====] - 0s 8ms/step - loss: 0.0421  
Epoch 41/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0421

Epoch 42/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0421  
Epoch 43/100  
10/10 [=====] - 0s 10ms/step - loss: 0.0421  
Epoch 44/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0421  
Epoch 45/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0420  
Epoch 46/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0420  
Epoch 47/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0420  
Epoch 48/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0420  
Epoch 49/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0420  
Epoch 50/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0420  
Epoch 51/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0420  
Epoch 52/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0419  
Epoch 53/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0419  
Epoch 54/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0419  
Epoch 55/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0419  
Epoch 56/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0419  
Epoch 57/100  
10/10 [=====] - 0s 8ms/step - loss: 0.0418  
Epoch 58/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0418  
Epoch 59/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0418  
Epoch 60/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0418  
Epoch 61/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0418  
Epoch 62/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0418  
Epoch 63/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0418  
Epoch 64/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0417  
Epoch 65/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0417  
Epoch 66/100  
10/10 [=====] - 0s 8ms/step - loss: 0.0417  
Epoch 67/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0417  
Epoch 68/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0417  
Epoch 69/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0416  
Epoch 70/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0416  
Epoch 71/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0416  
Epoch 72/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0416  
Epoch 73/100  
10/10 [=====] - 0s 9ms/step - loss: 0.0416  
Epoch 74/100

```

10/10 [=====] - 0s 9ms/step - loss: 0.0416
Epoch 75/100
10/10 [=====] - 0s 9ms/step - loss: 0.0415
Epoch 76/100
10/10 [=====] - 0s 9ms/step - loss: 0.0416
Epoch 77/100
10/10 [=====] - 0s 9ms/step - loss: 0.0415
Epoch 78/100
10/10 [=====] - 0s 9ms/step - loss: 0.0415
Epoch 79/100
10/10 [=====] - 0s 9ms/step - loss: 0.0415
Epoch 80/100
10/10 [=====] - 0s 9ms/step - loss: 0.0415
Epoch 81/100
10/10 [=====] - 0s 9ms/step - loss: 0.0414
Epoch 82/100
10/10 [=====] - 0s 10ms/step - loss: 0.0414
Epoch 83/100
10/10 [=====] - 0s 10ms/step - loss: 0.0414
Epoch 84/100
10/10 [=====] - 0s 10ms/step - loss: 0.0414
Epoch 85/100
10/10 [=====] - 0s 10ms/step - loss: 0.0414
Epoch 86/100
10/10 [=====] - 0s 11ms/step - loss: 0.0414
Epoch 87/100
10/10 [=====] - 0s 10ms/step - loss: 0.0414
Epoch 88/100
10/10 [=====] - 0s 10ms/step - loss: 0.0414
Epoch 89/100
10/10 [=====] - 0s 10ms/step - loss: 0.0413
Epoch 90/100
10/10 [=====] - 0s 10ms/step - loss: 0.0413
Epoch 91/100
10/10 [=====] - 0s 10ms/step - loss: 0.0413
Epoch 92/100
10/10 [=====] - 0s 11ms/step - loss: 0.0413
Epoch 93/100
10/10 [=====] - 0s 10ms/step - loss: 0.0413
Epoch 94/100
10/10 [=====] - 0s 10ms/step - loss: 0.0412
Epoch 95/100
10/10 [=====] - 0s 10ms/step - loss: 0.0412
Epoch 96/100
10/10 [=====] - 0s 10ms/step - loss: 0.0412
Epoch 97/100
10/10 [=====] - 0s 10ms/step - loss: 0.0412
Epoch 98/100
10/10 [=====] - 0s 10ms/step - loss: 0.0412
Epoch 99/100
10/10 [=====] - 0s 11ms/step - loss: 0.0411
Epoch 100/100
10/10 [=====] - 0s 9ms/step - loss: 0.0411

```

Out[10]: <tensorflow.python.keras.callbacks.History at 0x7ffb282a3390>

```

In [11]: encoder = keras.Model(input_img, encoded) # also define the encoder part
encoder.get_weights()

```

Out[11]: [array([[ -0.05947556, 0.02999774, 0.03496894, ..., 0.06997635,  
 -0.02443226, -0.05765174],  
 [ 0.01859826, -0.05337664, 0.01222368, ..., 0.02130038,  
 0.03675849, -0.02764505],  
 [ -0.00772542, 0.01606809, 0.00638994, ..., -0.0793802 ,

```

-0.07776325, -0.03962534],
...,
[-0.00762312, 0.03418265, 0.01706019, ..., 0.04284579,
 0.02790998, 0.01960173],
[ 0.07160843, 0.01389702, 0.04417362, ..., -0.0403284 ,
 0.04575133, 0.07278159],
[-0.06782561, 0.07357565, -0.05206133, ..., 0.07031503,
 0.06448487, 0.06966222]], dtype=float32),
array([ 2.40136936e-01, 2.63595849e-01, 6.58800080e-02, 1.70697942e-01,
 1.90887064e-01, -1.34922396e-02, -1.50258336e-02, -8.04297277e-04,
 2.66798466e-01, 5.87142520e-02, -1.74439456e-02, -1.40925134e-02,
 1.82616100e-01, -2.10637636e-02, 3.52401212e-02, 8.98889229e-02,
-2.07967479e-02, 6.67532953e-03, -1.54011518e-01, 3.65302563e-01,
 7.14327022e-02, 2.77068555e-01, 9.01356488e-02, 2.73365527e-01,
 8.10998529e-02, 3.69344167e-02, -4.15288396e-02, 1.82149887e-01,
 2.59497136e-01, 1.57676488e-01, -1.50681622e-02, -1.59129295e-02,
 1.15949780e-01, -1.66473128e-02, 1.30678877e-01, -1.95026267e-02,
 1.64657667e-01, 1.16247386e-01, 4.94658172e-01, 8.40974331e-01,
 1.04063742e-01, 7.52099603e-02, 7.85653666e-02, -1.55108282e-02,
 9.45800319e-02, 1.40961289e-01, 3.37453216e-01, -1.47448024e-02,
 6.93240538e-02, 8.11441168e-02, -1.66967455e-02, 3.51815403e-01,
 8.29982042e-01, 2.00706646e-01, -1.60036981e-02, -1.79883260e-02,
 3.21504474e-02, 5.07089972e-01, 5.77833988e-02, 2.52949059e-01,
-1.65693108e-02, 8.99084881e-02, 1.23093031e-01, -1.81887858e-02,
 1.08325332e-01, 1.69933036e-01, 8.36526334e-01, -7.26310983e-02,
-1.42500782e-02, -1.86911672e-02, -1.57157816e-02, 1.04814932e-01,
 5.00704125e-02, -7.45654758e-03, -1.91297438e-02, 8.39748859e-01,
 1.95849724e-02, -1.27952054e-01, 3.26722600e-02, -1.07801922e-01,
-1.99855752e-02, 5.35094261e-01, 3.94111693e-01, -1.88885070e-02,
 7.95129463e-02, -1.89713743e-02, 9.54800844e-02, 1.94479153e-01,
 9.27215517e-01, -3.60916206e-03, 1.46221310e-01, -1.46909487e-02,
 2.96686172e-01, 5.00534117e-01, 2.05044940e-01, -1.63684711e-02,
 3.08393478e-01, -2.03671735e-02, 7.88885236e-01, 9.39736590e-02,
 1.35885462e-01, 5.05500972e-01, -1.38311023e-02, 2.68366754e-01,
 1.61574893e-02, 1.81143433e-01, 7.86647275e-02, -2.00592410e-02,
 5.43132126e-01, 7.84727260e-02, -1.54982153e-02, -1.84051245e-02,
 2.19278887e-01, 1.65609524e-01, -1.85344759e-02, 1.77413508e-01,
-1.84267275e-02, 1.44426495e-01, 5.13321877e-01, -1.79356545e-01,
 3.63828361e-01, -1.41581237e-01, 5.81640601e-01, 1.91846266e-01,
 1.11846365e-01, 1.75797582e-01, -1.73756927e-02, -1.31474081e-02],
dtype=float32),
array([[-0.42971066, -0.10588566, 0.4236499 , ..., 0.17884333,
 0.2563132 , 0.39318204],
[ 0.34058133, 0.18111633, 0.6851588 , ..., -0.11377961,
-0.20210741, 0.05846188],
[-0.09290195, -0.05543005, 0.1760109 , ..., 0.3172078 ,
-0.15837938, -0.28363746],
...,
[ 0.19722241, -0.10217646, 0.7285515 , ..., 0.00933621,
-0.16007745, 0.05143999],
[ 0.09728131, 0.1213326 , 0.1580048 , ..., -0.09850125,
0.15406206, -0.03437775],
[ 0.05645077, -0.044066 , -0.10675615, ..., -0.14322896,
0.16919908, 0.00784586]], dtype=float32),
array([ 0.02981751, 0.05343308, 0.8463537 , 0.15047933, 0.11920236,
0.09623373, 0.07064325, 0.16425121, 0.16182274, 0.04715717,
0.6506759 , 0.13108687, 0.4883804 , 0.15848926, 0.00482019,
-0.31285816, 0.37398085, 0.24226628, 0.11423625, 0.33841768,
-0.00471628, 0.11195443, 0.1449951 , 0.26420838, 0.0942094 ,
0.01801389, 0.69322354, -0.00355269, 0.15458152, 0.05959609,
0.05216391, -0.0085267 ], dtype=float32),
array([[-0.6085141 , 0.03899195, 0.11315902, -0.2467418 , 0.48680893,
0.14605574, -0.00474455, -0.11922214],
[ 0.30479074, 0.22602326, 0.20132744, 0.09678176, -0.19986086,
0.10472327, -0.20857438, -0.1898901 ]],

```



```

[ 0.34882623, -0.15259178, 0.10349804, 0.6591769 , 0.37066194,
-0.36874518, -0.0549324 , 0.2957819 ],
[ 0.04735119, -0.29941946, 0.23046184, 0.20572415, 0.3881902 ,
-0.09417078, -0.2757015 , -0.08009816],
[ 0.26537007, -0.33547738, -0.28256068, 0.3246253 , 0.28150526,
0.06180848, -0.14622097, -0.11724952],
[-1.212921 , -0.13626626, 0.3213269 , -0.8549572 , -0.19157548,
0.1196871 , 0.1278217 , -0.20940109],
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dtype=float32),
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[ 0.5957006 , -0.37706986],

```

```

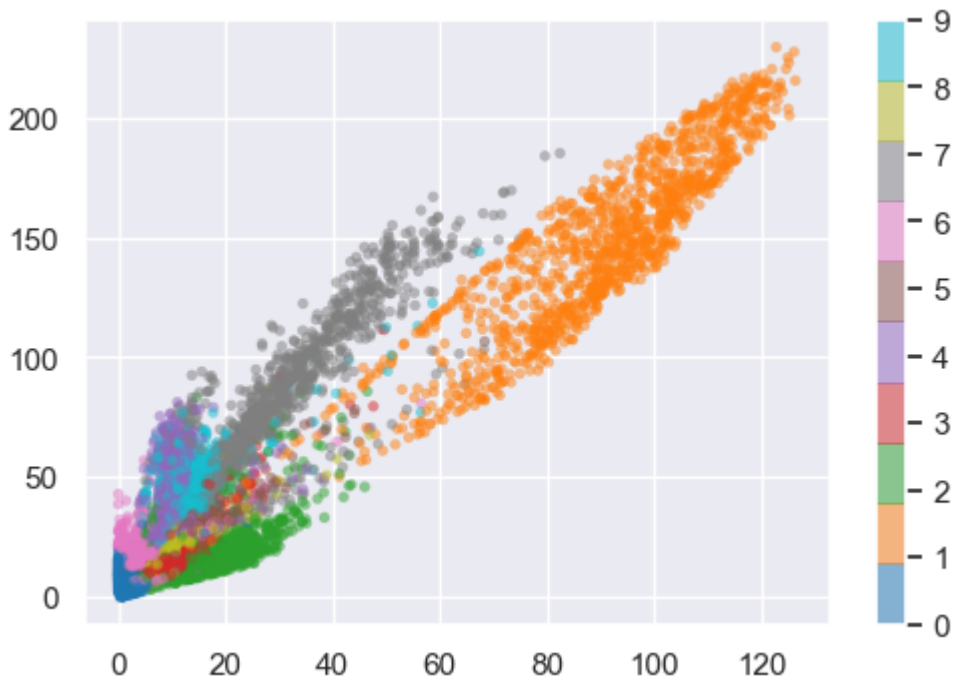
[ 0.34214923, -0.22898577],
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[ 0.42550644, -0.7541872 ],
[ 0.45924413, -0.05488669],
[ 0.5632348 ,  0.23399091]], dtype=float32),
array([0.30013943, 0.01383021], dtype=float32)]

```

```
In [12]: encoded_coord = encoder.predict(x_test.reshape((len(x_test), np.prod(x_test.shape[1:])))
```

```
In [13]: import matplotlib.pyplot as plt
import seaborn as sns; sns.set()
fig = plt.figure(dpi=100)
plt.scatter(encoded_coord[:, 0], encoded_coord[:, 1], c=y_test, s=15, edgecolor='none',
plt.colorbar())
```

```
Out[13]: <matplotlib.colorbar.Colorbar at 0x7ffb2d469610>
```

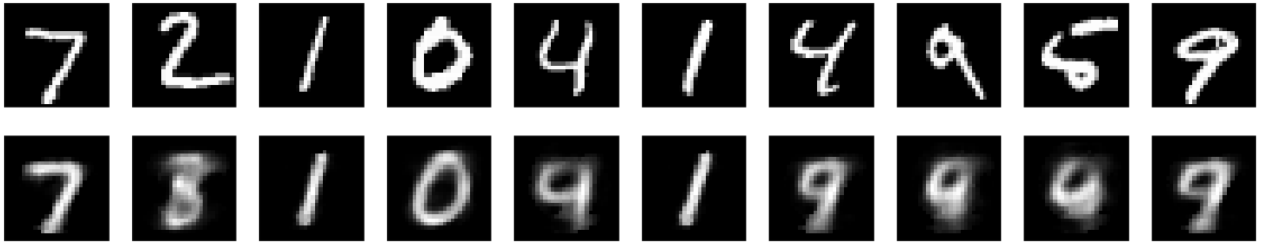


```
In [8]: decoded_imgs = autoencoder.predict(x_test.reshape((len(x_test), np.prod(x_test.shape[1:]
```

```
In [9]: n = 10 # How many digits we will display
plt.figure(figsize=(20, 4))
for i in range(n):
    # Display original
    ax = plt.subplot(2, n, i + 1)
    plt.imshow(x_test[i])
    plt.gray()
    ax.get_xaxis().set_visible(False)
    ax.get_yaxis().set_visible(False)

    # Display reconstruction
    ax = plt.subplot(2, n, i + 1 + n)
    plt.imshow(decoded_imgs[i].reshape(28, 28))
    plt.gray()
```

```
ax.get_xaxis().set_visible(False)
ax.get_yaxis().set_visible(False)
plt.show()
```



Maybe condensing to 2D layer loses too much information. Let's try a more realistic model

```
In [ ]: from keras import layers
input_img = keras.Input(shape=(784,))
encoded = layers.Dense(128, activation='relu')(input_img)
encoded = layers.Dense(64, activation='relu')(encoded)
encoded = layers.Dense(32, activation='relu')(encoded)

decoded = layers.Dense(64, activation='relu')(encoded)
decoded = layers.Dense(128, activation='relu')(decoded)
decoded = layers.Dense(784, activation='sigmoid')(decoded)

autoencoder = keras.Model(input_img, decoded)
autoencoder.summary()
```

```
In [ ]: autoencoder.compile(optimizer='adam', loss= tf.keras.losses.MeanSquaredError())

autoencoder.fit(x_test.reshape((len(x_test), np.prod(x_test.shape[1:]))), x_test.reshape(
    epochs=200,
    batch_size=256)
```

```
In [ ]: encoder = keras.Model(input_img, encoded)
encoded_coord = encoder.predict(x_test.reshape((len(x_test), np.prod(x_test.shape[1:]))
encoded_coord.shape
```

```
In [ ]: from sklearn.manifold import TSNE # for GPU acceleration, use the cuml
tsne = TSNE(n_jobs = -1)
X_tsne = tsne.fit_transform(encoded_coord)
import matplotlib.pyplot as plt
import seaborn as sns; sns.set()
fig = plt.figure(dpi=100)
plt.scatter(X_tsne[:, 0], X_tsne[:, 1], c=y_test, s=15, edgecolor='none', alpha=0.5, cmap
plt.colorbar()
```

```
In [ ]: decoded_imgs = autoencoder.predict(x_test.reshape((len(x_test), np.prod(x_test.shape[1:
n = 10 # How many digits we will display
plt.figure(figsize=(20, 4))
for i in range(n):
    # Display original
    ax = plt.subplot(2, n, i + 1)
    plt.imshow(x_test[i])
    plt.gray()
```

```
ax.get_xaxis().set_visible(False)
ax.get_yaxis().set_visible(False)

# Display reconstruction
ax = plt.subplot(2, n, i + 1 + n)
plt.imshow(decoded_imgs[i].reshape(28, 28))
plt.gray()
ax.get_xaxis().set_visible(False)
ax.get_yaxis().set_visible(False)
plt.show()
```

## Other Useful References and Suggestions for Future Learning in Data Science

### Websites for Everyday Practice

- Python Programming: [Leetcode](#)
- Data Science: [Kaggle](#)

### Courses and Books

- UCI ICS 31-33 (Python Programming), CS 178 (Machine Learning)
- [Berkeley Stat 157](#)
- [Stanford CS 231](#)
- [The Deep Learning Book](#)

In [ ]: