

# CEAL: A C-based Language for Self-Adjusting Computation

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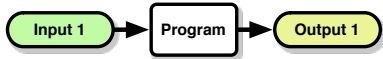
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- ▶ Background (self-adjusting computation)
- ▶ CEAL via example
- ▶ Compilation process: CEAL to C
- ▶ Performance results & comparison to SaSML
- ▶ Conclusion

# Self-Adjusting Computation

## Ordinary Program Runs



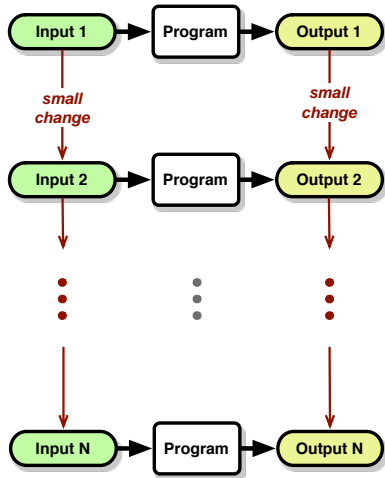
⋮



- ▶ Ordinary programs often run repeatedly on changing input.
- ▶ What if input and output change by only small increments?

# Self-Adjusting Computation

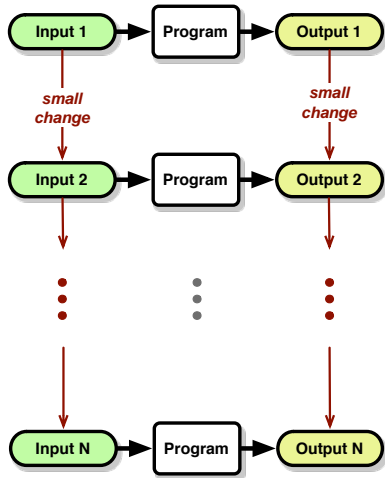
## Ordinary Program Runs



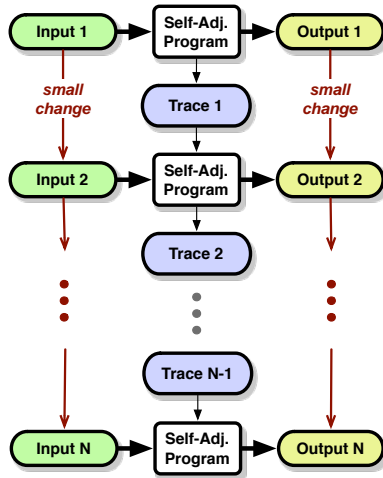
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# Self-Adjusting Computation

## Ordinary Program Runs



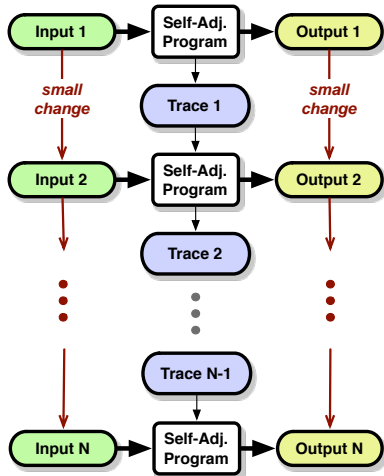
## Self-Adjusting Program Runs



# Self-Adjusting Computation

- ▶ Record execution in a program trace
- ▶ When input changes, a **change propagation** algorithm updates the output and trace as if the program was run “from-scratch”.
- ▶ Tries to reuse past computation when possible

## Self-Adjusting Program Runs



**Motivation** : Incremental change is pervasive.

Many applications encounter data that changes slowly or *incrementally* over time.

- ▶ Applications that interact with a physical environment.  
*E.g., Robots.*
- ▶ Applications that interact with a user.  
*E.g., Games, Editors, Compilers, etc.*
- ▶ Applications that rely on modeling or simulation.  
*E.g., Scientific Computing, Computational Biology, Motion Simulation.*

Previous work has shown effectiveness for many applications:

List primitives (map, reverse, ...)	$O(1)$	
Sorting: mergesort, quicksort	$O(\log n)$	
2D Convex hulls	$O(\log n)$	[ESA '06]
Tree contraction [Miller, Reif '85]	$O(\log n)$	[SODA '04].
3D Convex Hulls	$O(\log n)$	[SCG '07]
Meshing in 2D and 3D	$O(\log n)$	[FWCG '07]
Bayesian Inference on Trees	$O(\log n)$	[NIPS '07]
Bayesian Inference on Graphs	$O(s^d \log n)$	[UAI '08]

All bounds are randomized (expected time) and are within an expected constant factor of optimal or best known-bounds.



## modifiable references (**modref** for short)

- ▶ analogous to ordinary mutable memory
- ▶ each hold one word (e.g., a pointer)
- ▶ primitives to create/read/write them

## mutator & core programs: two stratified levels

1. mutator runs core, whose execution is traced
2. mutator inspects core output
3. mutator typically loops:
  - 3.1 mutator changes core input
  - 3.2 mutator invokes automatic **change propagation** mechanism
  - 3.3 mutator inspects (automatically updated) core output

## Core language

`modref_t* modref()` Create empty modrefs  
`void write(modref_t *m, void *p)` Write to modrefs  
`void* read(modref_t *m)` Read from modrefs  
`void* alloc(int sz, f, ...)` Allocate and initialize

## Meta (aka mutator) language

`void run_core(f, ...)` Run core program  
`void* deref(modref_t* m)` Inspect modrefs  
`void modify(modref_t* m, void *p)` Modify modrefs  
`void propagate()` Propagate modifications

- ▶ INPUT: CEAL program (set of core and mutator functions)
- ▶ CEAL primitives provided by ordinary header file
- ▶ Our run-time library provides tracing, change propagation & memory management.
- ▶ CIL [Necula et al] parses/type-checks CEAL as C code
- ▶ We extend CIL to:
  - ▶ Build our own CFG representation
    - ★ Analyze & transform CFG according to reads (**normalization**)
    - ★ Translate CFG into C with runtime calls
- ▶ last, use GCC to compile and link target program

```
typedef struct {  
    int hd;  
    modref_t *tl;  
} cons_t;  
  
void cons_init(cons_t *c, int h) {  
    c->hd = h;  
    c->tl = modref();  
}
```

$\text{Cons}(h) \equiv \text{alloc}(\text{sizeof}(\text{cons\_t}), \text{cons\_init}, h)$

- ▶ Cells allocated with given head, empty (modifiable) tail
- ▶ Cells are reused based on matching heads  
(and re-evaluation context)

## Example: Merging two sorted lists

```
ceal merge( $L_1, L_2, D$ ) {  
   $c_1 = \text{read}(L_1)$ ;  
   $c_2 = \text{read}(L_2)$ ;  
  while( $c_1 \ \&\& \ c_2$ ) {  
    if( $c_1 \rightarrow \text{hd} < c_2 \rightarrow \text{hd}$ ) {  
       $c' = \text{Cons}(c_1 \rightarrow \text{hd})$ ;  
       $c_1 = \text{read}(c_1 \rightarrow \text{tl})$ ;  
    } else {  
       $c' = \text{Cons}(c_2 \rightarrow \text{hd})$ ;  
       $c_2 = \text{read}(c_2 \rightarrow \text{tl})$ ;  
    }  
    write( $D, c'$ );  
     $D = c' \rightarrow \text{tl}$ ;  
  }  
  if( $c_1$ )  
    write( $D, c_1$ );  
  else  
    write( $D, c_2$ );  
}
```

►  $L_1, L_2, D : \text{modref\_t}^*$

►  $c_1, c_2, c' : \text{cons\_t}^*$

### Example (from-scratch) input/output

**Pre:**

$L_1 = [1, 2, 5], L_2 = [3, 4, 6]$

**Post:**

$D = [1, 2, 3, 4, 5, 6]$

# Tracing, re-evaluation and memo-matching

## Main Ideas

- ▶ Each read has a “*context*” using the read value
- ▶ Contexts correspond to a *closure* (or *thunk* or *continuation*, etc.) of some kind; we include it in trace.
- ▶ When read value changes, re-evaluate context
- ▶ When current read-context matches past one, reuse it

## Questions

- ▶ How much context do we have to capture in the trace?
  - ▶ Do we include the call stack?
  - ▶ No, assume no return values (dest-passing style)
- ▶ How do we represent it for C programs in a C runtime?
  - ▶ Want: a function pointer and args (a closure)
  - ▶ Goal: make read-contexts correspond to invocations

# Example: Merging two sorted lists

```
ceal merge( $L_1$ ,  $L_2$ ,  $D$ ) {  
   $c_1$  = read( $L_1$ );  
   $c_2$  = read( $L_2$ );  
  while( $c_1$  &&  $c_2$ ) {  
    if( $c_1$ ->hd <  $c_2$ ->hd) {  
       $c'$  = Cons( $c_1$ ->hd);  
       $c_1$  = read( $c_1$ ->tl);  
    } else {  
       $c'$  = Cons( $c_2$ ->hd);  
       $c_2$  = read( $c_2$ ->tl);  
    }  
    write( $D$ ,  $c'$ );  
     $D$  =  $c'$ ->tl;  
  }  
  if( $c_1$ )  
    write( $D$ ,  $c_1$ );  
  else  
    write( $D$ ,  $c_2$ );  
}
```

## Example (from-scratch) input/output

**Pre:**

$L_1 = [1, 2, 5]$ ,  $L_2 = [3, 4, 6]$

**Post:**

$D = [1, 2, 3, 4, 5, 6]$

## Change Propagation

- ▶ Assume  $L_1$  and  $L_2$  “alternate” sufficiently (e.g., (2,3), (4,5), (5,6))
- ▶ Update for insertion/deletion in  $O(1)$ :
  - ▶ Wake-up and re-evaluate until we redo previous alternation
  - ▶ Implies  $c_1$ ,  $c_2$ ,  $D$  and  $c'$  match previous a read-state
  - ▶ Memo-match rest of computation

<i>Values</i>	$v ::= \ell \mid n$
<i>Expressions</i>	$e ::= n \mid x \mid \oplus(\bar{x}) \mid x[y]$
<i>Commands</i>	$c ::=$ $x := e$ $ $ $x := \text{modref}()$ $ $ $x := \text{read } y$ $ $ $\text{write } x := y$ $ $ $x := \text{alloc } y \ f \ \bar{z}$ $ $ $\text{call } f(\bar{x})$
<i>Jumps</i>	$j ::=$ $\text{goto } l$ $ $ $\text{tail } f(\bar{x})$
<i>Basic Blocks</i>	$b ::=$ $\{l : \text{done}\}$ $ $ $\{l : \text{cond } x \ j_1 \ j_2\}$ $ $ $\{l : c ; j\}$
<i>Fun. Defs</i>	$F ::= f(\bar{x}) \ \{\bar{y}; \bar{b}\}$
<i>Programs</i>	$P ::= \bar{F}$



## Define: Normal Form

**Read blocks** have the form:  $\{l : x = \text{read } y; j\}$

*Not Normal*:  $\{l : x = \text{read } y; \text{goto } l'\}$

*Normal*:  $\{l : x = \text{read } y; \text{tail } f(x, \dots)\}$

Program is in **Normal Form** iff each read block is in NF.

## Normalization

**Goal**: put all read blocks into normal form.

- ▶ Repartition basic blocks (as coarsely as possible)
- ▶ Turn successors of read-blocks into function entry nodes.
- ▶ Non-local gotos become tail jumps
- ▶ Preserve the program's:
  - ▶ Size (e.g., total basic blocks)
  - ▶ Input/output behavior
  - ▶ Time/space requirements

# Dominators

Assume: CFG has designated **root** node,  
every node is reachable from root.

Def: Dominator relation

$a$  **dominates**  $b$  if every path from root to  $b$  contains  $a$ .  
(note: every node dominates itself).

Def: Immediate dominator relation

$a$  is the (unique) **immediate dominator** of  $b$  if

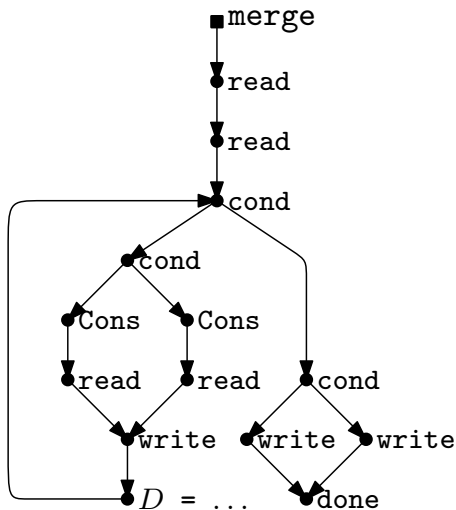
- ▶  $a \neq b$
- ▶  $a$  dominates  $b$
- ▶  $c$  dominates  $b$  implies  $c$  dominates  $a$

Def: Dominator tree

Immediate dominator relation forms a tree, rooted at the CFG root.

## Example: Normalizing merge

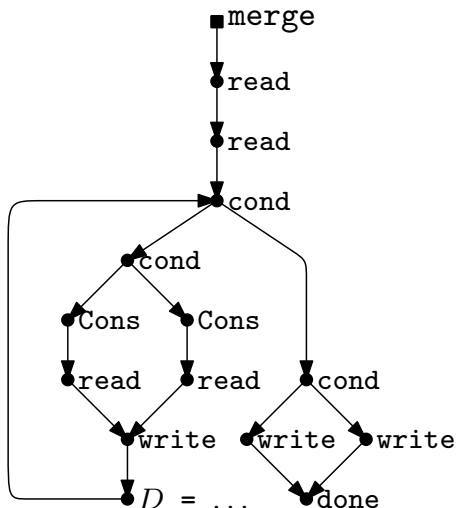
```
ceal merge( $L_1$ ,  $L_2$ ,  $D$ ) {  
   $c_1$  = read( $L_1$ );  
   $c_2$  = read( $L_2$ );  
  while( $c_1 \ \&\& \ c_2$ ) {  
    if( $c_1 \rightarrow \text{hd} < c_2 \rightarrow \text{hd}$ ) {  
       $c' = \text{Cons}(c_1 \rightarrow \text{hd})$ ;  
       $c_1 = \text{read}(c_1 \rightarrow \text{tl})$ ;  
    } else {  
       $c' = \text{Cons}(c_2 \rightarrow \text{hd})$ ;  
       $c_2 = \text{read}(c_2 \rightarrow \text{tl})$ ;  
    }  
    write( $D$ ,  $c'$ );  
     $D = c' \rightarrow \text{tl}$ ;  
  }  
  if( $c_1$ )  
    write( $D$ ,  $c_1$ );  
  else  
    write( $D$ ,  $c_2$ );  
}
```



# Example: Normalizing merge

## Normalization

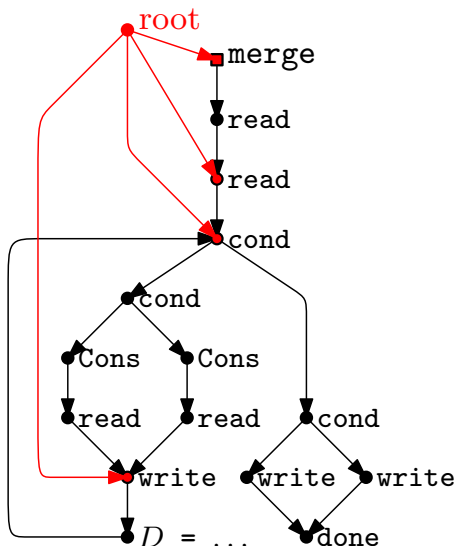
- ▶ Compute CFG
- ▶ Add **root node** & edges to **entry nodes**
- ▶ Compute dominator tree
- ▶ Root subtrees are **units**
- ▶ CFG partitioned by **units**, Each **unit** is a new CFG
- ▶ Cross-unit **gotos** become **tail jumps** to new funs, Live variables become arguments.



# Example: Normalizing merge

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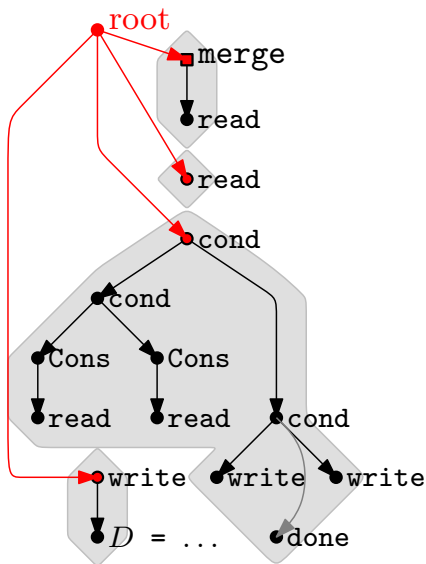




# Example: Normalizing merge

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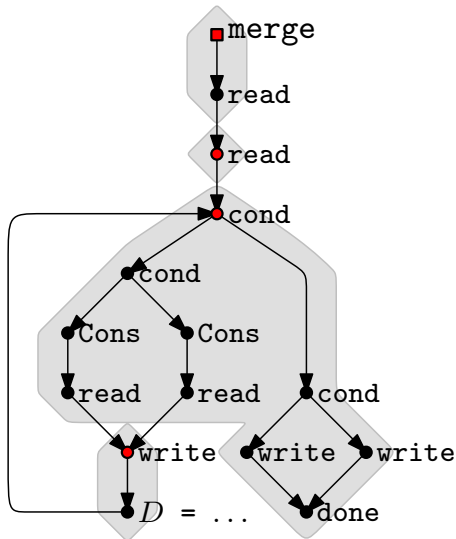
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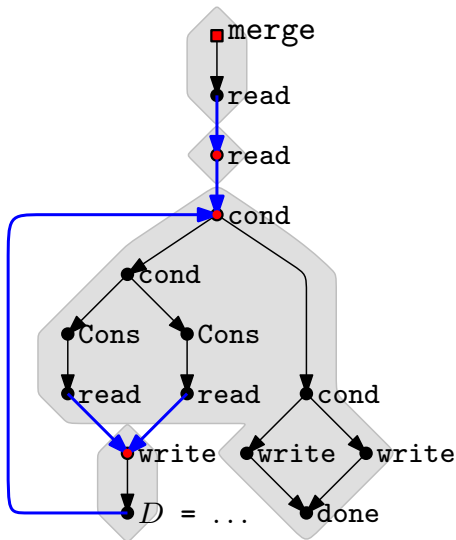




# Example: Normalizing merge

## Normalization

- ▶ Compute CFG
- ▶ Add **root node** & edges to **entry nodes**
- ▶ Compute dominator tree
- ▶ Root subtrees are **units**
- ▶ CFG partitioned by **units**, Each **unit** is a new CFG
- ▶ Cross-unit **gotos** become **tail jumps** to new funs, Live variables become arguments.



## Example: Normalized merge

```
ceal merge( $L_1$ ,  $L_2$ ,  $D$ ) {  
     $c_1$  = read( $L_1$ );  
    tail merge2( $c_1$ ,  $L_2$ ,  $D$ );  
}  
  
ceal merge2( $c_1$ ,  $L_2$ ,  $D$ ) {  
     $c_2$  = read( $L_2$ );  
    tail merge3( $c_1$ ,  $c_2$ ,  $D$ );  
}  
  
ceal merge4( $c_1$ ,  $c_2$ ,  $c'$ ,  $D$ ) {  
    write( $D$ ,  $c'$ );  
     $D$  =  $c'$ ->tl;  
    tail merge3( $c_1$ ,  $c_2$ ,  $D$ );  
}
```

```
ceal merge3( $c_1$ ,  $c_2$ ,  $D$ ) {  
    if( $c_1$  &&  $c_2$ ) {  
        if( $c_1$ ->hd <  $c_2$ ->hd) {  
             $c'$  = Cons( $c_1$ ->hd);  
             $c_1$  = read( $c_1$ ->tl);  
            tail merge4( $c_1$ ,  $c_2$ ,  $c'$ ,  $D$ );  
        } else {  
             $c'$  = Cons( $c_2$ ->hd);  
             $c_2$  = read( $c_2$ ->tl);  
            tail merge4( $c_1$ ,  $c_2$ ,  $c'$ ,  $D$ );  
        }  
    } else {  
        if( $c_1$ )  
            write( $D$ ,  $c_1$ );  
        else  
            write( $D$ ,  $c_2$ );  
    }  
}
```

## Basic Properties

- ▶ Works on arbitrary control-flow (e.g., non-natural loops)
- ▶ Preserves program semantics, space & time
- ▶ Can be implemented to run in linear-time,  
(Assuming we use linear-time dominator tree algo)

## Per-function transformation

Normalization can be performed on per-function basis:

- ▶ Every function is immediately dominated by root
- ▶ So, dominator tree oblivious to inter-procedural edges
- ▶ So, units & normal-form determined by local control-flow

## Short digression: Trampolines

We realize tail-calls with *trampolines* for portable C code.

### Basic trampoline

```
void trampoline(c){  
    while(c  $\neq$  NULL) {  
         $(f, x_1, \dots, x_n) \leftarrow \text{unpack } c$   
         $c \leftarrow f(x_1, \dots, x_n)$   
    }  
}
```

### Using trampolines

Call	$f(\bar{x});$	$\rightsquigarrow$	<code>trampoline(<math>f(\bar{x})</math>);</code>
Tail-call	<code>tail <math>f(\bar{x});</math></code>	$\rightsquigarrow$	<code>return (closure(<math>f, \bar{x}</math>));</code>
Return	<code>return;</code>	$\rightsquigarrow$	<code>return NULL;</code>

```
/* Closures */
typedef struct {...} closure_t;
closure_t* closure_make(closure_t* (*f)( $\overline{\tau X}$ ),  $\overline{\tau X}$ );
void closure_run(closure_t* c);

/* Modifiabiles */
typedef struct {...} modref_t;
void modref_init(modref_t *m);
void modref_write(modref_t *m, void *v);
closure_t* modref_read(modref_t *m, closure_t *c);

/* Allocation */
void* allocate(size_t n, closure_t *c);
```

## Functions:

$$\llbracket f(\overline{\tau_x} \overline{x}) \{ \overline{\tau_y} \overline{y} ; \overline{b} \} \rrbracket = \text{closure\_t} * f(\overline{\tau_x} \overline{x}) \{ \overline{\tau_y} \overline{y} ; \llbracket \overline{b} \rrbracket \}$$

## Jumps:

$$\llbracket \text{goto } l \rrbracket = \text{goto } l;$$

$$\llbracket \text{tail } f(\overline{x}) \rrbracket = \text{return } (\text{closure\_make}(f, \overline{x}));$$

## Basic Blocks:

$$\llbracket \{ l : \text{done} \} \rrbracket = \{ l : \text{return NULL}; \}$$

$$\llbracket \{ l : \text{cond } x \ j_1 \ j_2 \} \rrbracket = \{ l : \text{if } (x) \ \{ \llbracket j_1 \rrbracket \} \text{ else } \{ \llbracket j_2 \rrbracket \} \}$$

$$\llbracket \{ l : c ; j \} \rrbracket = \{ l : \llbracket c \rrbracket ; \llbracket j \rrbracket \}$$

$$\begin{aligned} \llbracket \{ l : x := \text{read } y ; \\ \text{tail } f(x, \overline{z}) \} \rrbracket &= \{ l : \text{closure\_t } * c ; \\ &\quad c = \text{closure\_make}(f, \text{NULL} :: \overline{z}) ; \\ &\quad \text{return } (\text{modref\_read}(y, c)); \} \end{aligned}$$

## Functions:

$$\llbracket f(\overline{\tau_x} \overline{x}) \{ \overline{\tau_y} \overline{y} ; \overline{b} \} \rrbracket = \text{closure\_t} * f(\overline{\tau_x} \overline{x}) \{ \overline{\tau_y} \overline{y} ; \llbracket \overline{b} \rrbracket \}$$

## Jumps:

$$\llbracket \text{goto } l \rrbracket = \text{goto } l;$$
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## Basic Blocks:

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$$\llbracket \{ l : c ; j \} \rrbracket = \{ l : \llbracket c \rrbracket ; \llbracket j \rrbracket \}$$
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## Commands:

```
     $\llbracket \text{nop} \rrbracket$     =    ;  
     $\llbracket x := e \rrbracket$     =     $x = \llbracket e \rrbracket$ ;  
     $\llbracket x[y] := e \rrbracket$  =     $x[y] = \llbracket e \rrbracket$ ;  
     $\llbracket \text{call } f(\bar{x}) \rrbracket$  =     $\text{closure\_run}(f(\bar{x}))$ ;  
     $\llbracket x := \text{alloc } y \text{ } f \text{ } \bar{z} \rrbracket$  =     $\text{closure\_t } *c$ ;  
                                      $c = \text{closure\_make}(f, \text{NULL}::\bar{z})$ ;  
                                      $x = \text{allocate}(y, c)$ ;  
     $\llbracket x := \text{modref}() \rrbracket$  =     $\llbracket x := \text{alloc } (\text{sizeof}(\text{modref\_t}))$   
                                      $\text{modref\_init } \langle \rangle \rrbracket$   
     $\llbracket \text{write } x := y \rrbracket$  =     $\text{modref\_write}(x, y)$ ;
```



# Benchmarks

## List Primitives

**filter**, **map**, **reverse**, **minimum**, and **sum**

## Sorting

**quicksort** and **mergesort**

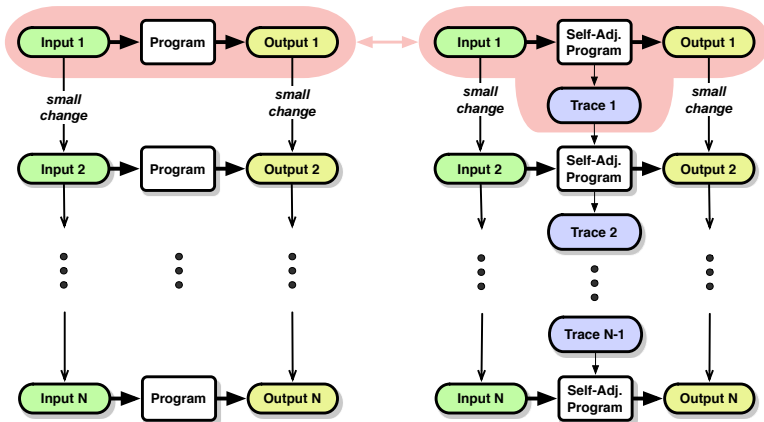
## Computational Geometry

- ▶ **quickhull** finds convex hull
- ▶ **diameter** finds diameter of a set of points
- ▶ **distance** finds distance between two sets of points

## Tree Algorithms

- ▶ **exptree** evaluates an expression tree
- ▶ **tcon** performs **tree contraction**
  - general technique to compute properties of trees

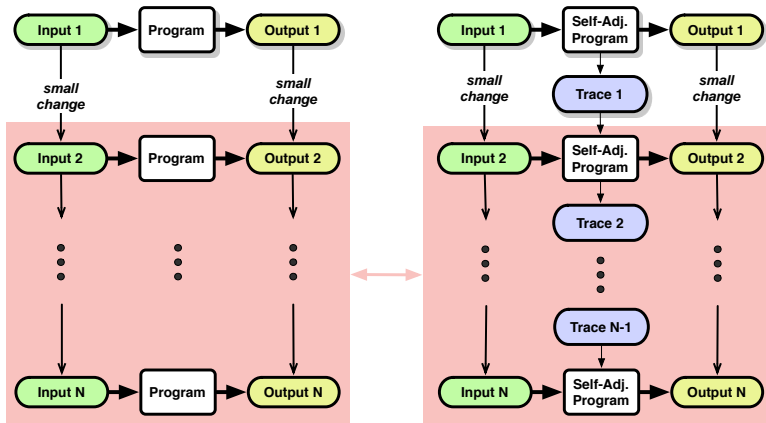
# Overhead



## Overhead

How much **slower** is the self-adjusting program when running "from-scratch"?

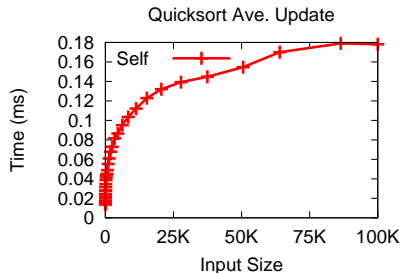
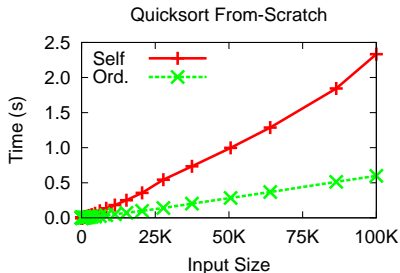
# Speedup



## Speedup

How much **faster** can the self-adjusting program update the output for a small change?

# Evaluation Example: Quicksort



**Overhead:** about 4x

**Speedup:**  $1.8 \times 10^4$

# CEAL: Overhead & Speedup

Application	$n$	From-Scratch			Propagation		
		Cnv.	Self.	O.H.	Ave. Update	Speedup	Max Live
filter	1.0M	0.2	0.9	5.8	$1.7 \times 10^{-6}$	$9.3 \times 10^4$	292.4M
map	1.0M	0.4	1.0	2.5	$1.9 \times 10^{-6}$	$2.0 \times 10^5$	322.9M
reverse	1.0M	0.4	1.0	2.6	$2.0 \times 10^{-6}$	$2.0 \times 10^5$	322.9M
minimum	1.0M	0.2	1.3	7.7	$4.0 \times 10^{-6}$	$4.1 \times 10^4$	379.8M
sum	1.0M	0.2	1.3	7.9	$6.4 \times 10^{-5}$	$2.5 \times 10^3$	379.7M
quicksort	100.0K	0.6	2.3	3.9	$1.8 \times 10^{-4}$	$3.4 \times 10^3$	834.3M
quickhull	100.0K	0.2	1.2	7.0	$1.3 \times 10^{-4}$	$1.3 \times 10^3$	649.4M
diameter	100.0K	0.2	1.1	6.4	$1.2 \times 10^{-4}$	$1.4 \times 10^3$	642.8M
exptrees	1.0M	3.8	4.9	1.3	$2.5 \times 10^{-4}$	$1.5 \times 10^4$	517.9M
mergesort	100.0K	0.9	3.6	3.8	$9.6 \times 10^{-5}$	$9.9 \times 10^3$	1.4G
distance	100.0K	0.2	1.1	6.5	$1.8 \times 10^{-4}$	$9.5 \times 10^2$	501.6M
tcon	100.0K	1.2	4.1	3.5	$3.2 \times 10^{-4}$	$3.7 \times 10^3$	899.6M

- **Average Overhead:** 5x
- **Average Speedup:**  $9.2 \times 10^4$  ( $n = 1\text{M}$ ),  $3.4 \times 10^3$  ( $n = 100\text{k}$ ),

# CEAL vs SaSML: Summary

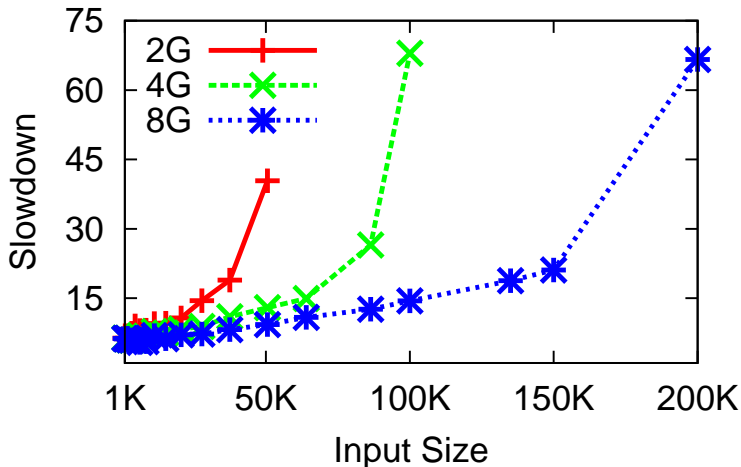
## Measurements with SaSML

App.	From-Scratch			Propagation		
	Cnv.	Self.	S.D.	Ave. Update	S.D.	Max Live
filter	0.1	6.9	7.7	$8.7 \times 10^{-6}$	5.1	1398M
map	0.1	7.8	7.8	$1.1 \times 10^{-5}$	5.8	1593M
reverse	0.1	6.7	6.7	$9.3 \times 10^{-6}$	4.7	1516M
minimum	0.1	5.1	3.9	$3.0 \times 10^{-5}$	7.5	1168M
sum	0.1	5.1	3.9	$1.7 \times 10^{-4}$	2.7	1187M
quicksort	0.2	52	22.6	$1.7 \times 10^{-3}$	9.4	3950M
quickhull	0.7	5.1	4.2	$3.3 \times 10^{-4}$	2.5	774M
diameter	0.9	5.2	4.7	$3.7 \times 10^{-4}$	3.1	943M

## SaSML vs CEAL in summary

- ▶ **From-Scratch** slowdown: 4-23x, (8x on average)
- ▶ **Change propagation** slowdown: 3-9x (5x on average)
- ▶ **Max live**: up to 5x larger (3.5x on average)

# CEAL vs SaSML: Quicksort Slowdown



Change prop. “slowdown”: SaSML time divided by CEAL time.

## In Summary

- ▶ CEAL is a C-based language for self-adjusting computation
- ▶ CEAL can be compiled directly to (portable) C code:
  - ▶ **Normalization** transform for tracing, re-evaluation and reuse.
  - ▶ **Translation** to C uses trampolines to implement tail jumps.
- ▶ Performance results are promising.

## Future work

- ▶ Separate memo primitive
- ▶ Eliminate need for explicit allocation init funs
- ▶ Automatically minimize “read scopes”



Thank You!  
Questions?