

CompactGpu: Massively Parallel Memory Defragmentation on GPUs



東京工業大学
Tokyo Institute of Technology

Matthias Springer (Tokyo Institute of Technology) <https://github.com/prg-titech/dynasoar>

Why Defragment GPU Memory?

- Space efficiency: **Reduce memory usage**
- Improve runtime performance:
Accessing compact data requires fewer vector accesses
→ **Better memory coalescing**

Design Requirements

- Extension to the DynaSOAr dynamic GPU memory allocator
- **Parallel, in-place, stop-the-world** defragmentation approach
- To reduce defragmentation overhead: Uniform control flow, little synchronization, efficient memory access

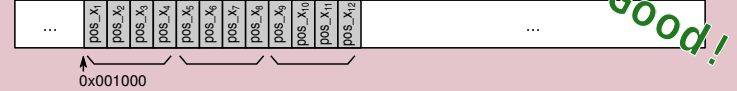
Related Work

- R. Veldema, M. Philippsen. Parallel Memory Defragmentation on GPUs. MSPC '12 Assumes many **different allocation sizes**, not in-place, large runtime overhead
- M. Springer, H. Masuhara. DynaSOAr: A Parallel Memory Allocator for Object-oriented Programming on GPUs with Efficient Memory Access. ECOOP '19
- H. Boehm. Space Efficient Conservative Garbage Collection. PLDI '93 Similar problem: How to **find all pointers to moved objects** that must be rewritten?

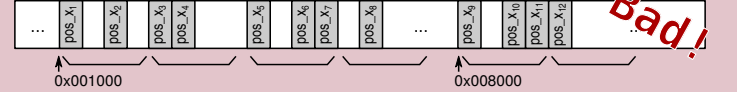
Background: GPU Architecture and Dyn. Memory Allocation

- Pattern: Many small allocations, mostly same size
- For good mem. access performance: **Structure of Arrays (SOA)** data layout
- Recent NVIDIA GPUs have 128-byte vector registers
→ Memory access in aligned, 128-byte transactions

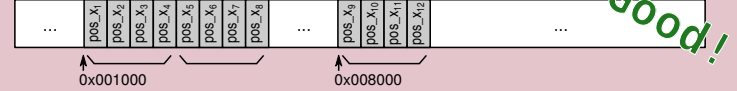
(a) Compact SOA Layout: 3 memory transactions required



(b) Fragmented SOA Layout: 6 memory transactions required

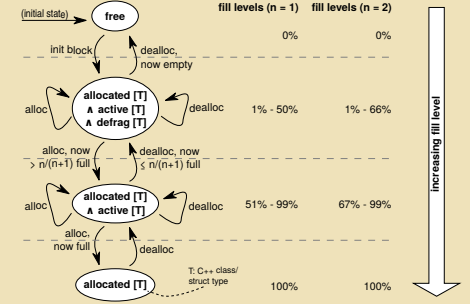
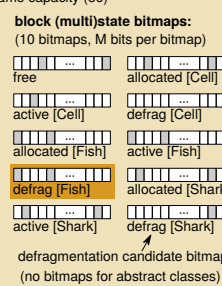
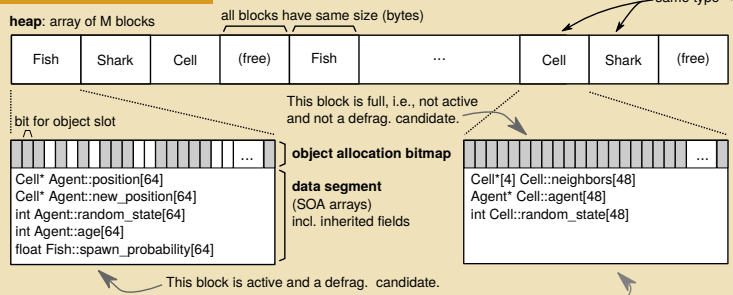


(c) Clustered SOA Layout: 3 memory transactions required



For illustration purposes: Vector length 32 byte (4 scalars) instead of 128 byte (32 scalars). N-body sim.

DynaSOAr Heap Layout



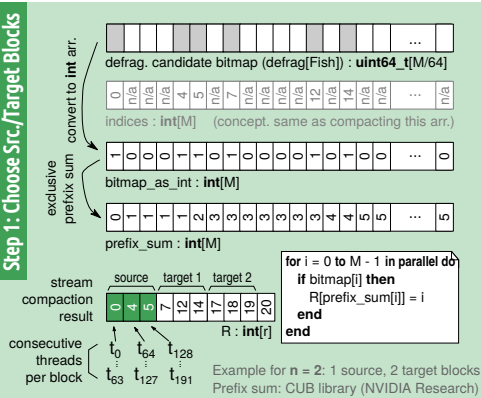
Defragmentation by Block Merging: parallel_defrag<Fish>()

$$F = \frac{1}{\# \text{Blocks}} \sum_{b \in \text{Blocks}} \frac{\# \text{free slots}(b)}{\# \text{slots}(b)}$$

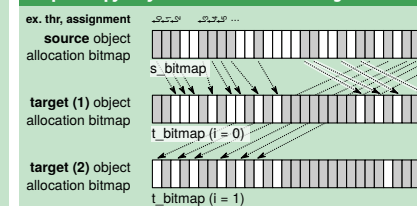
Definition of Defragmentation Candidates:

Depends on defrag. factor n (problem-spec., compile-time parameter)

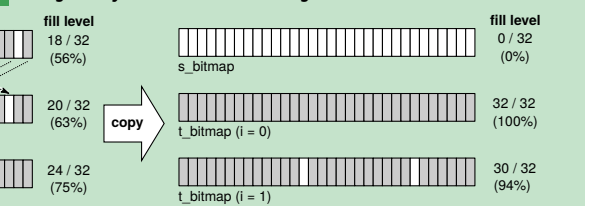
$n = 1$	$n = 2$	Arbitrary n	Guaranteed target
$\leq 50\%$ full	$\leq 66.6\%$ full	$\leq n/(n+1)$ full	frag.: $1/(n+1)$



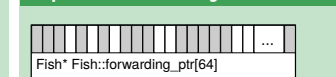
Step 2: Copy Objects from Source to Target Blocks:



Merge every source block into n target blocks.



Step 3: Store Forwarding Ptrs. in Source



Overwrite data segment with pointers.



Step 4: Rewrite Pointers to Relocated Objects with Bitmap

```
for all Fish* & ptr in parallel do
  s_bid = extract_block_id(ptr)
  if defrag[Fish][s_bid] then
    s_oid = extract_object_id(ptr)
    ptr = heap[s_oid].forwarding_ptr[s_oid]
  end
end
```

- How to find all Fish*/Agent* values on the heap?
- Option 1: Scan heap, look for anything that could be a pointer. **Slow!**
- Option 2: Utilize DynaSOAr's data layout DSL. **Scan only mem.** locations of SOA arrays with base type Fish*/Agent* **Fast!**
- Fast: defrag[T] bitmap largely cached in L2

Memory transactions: 2 memory reads + 1 write for relocated objects, 1 memory read for all others

Step 5: Update Block State Bitmaps

Blocks may now be empty, full and/or no longer defrag. candidates.

Step 6: If there are $> n$ defrag. candidates left, go to Step 1.

Generalization: Other Allocators?

Many other GPU allocators (Halloc, ScatterAlloc) use hashing (very high frag.) and do not utilize SOA.

