

# FEM for 1D problems

Summary and discussion of results

Real world problem

Actual displacement

Computer model

① Strong form (D)  
Differential equ. + BCs

②

Weak form (V)  
 $a(u, \delta u) = b(\delta u)$

③

Discrete equation  
 $\underline{K} \underline{\hat{u}} = \underline{f}$

⑤

Problem Data

Material, geometry, BCs

Approximation  
 $u_h = \sum_{i=1}^N \varphi_i \cdot \hat{u}_i$

④

⑥ Coefficients of  $u_h$   
 $\hat{u}_1, \hat{u}_2, \dots, \hat{u}_N$

⑦

Predicted displacement

Difference  $\hat{=}$  Error

Applicability

- Specific task
- Problem class
- General

# Errors introduced in each step

## ① Modelling error

- Nonlinear material behaviour of soil
- Material properties vary

## ② None here

## ③ None here

## ④ Discretization error $e = u - u_h$

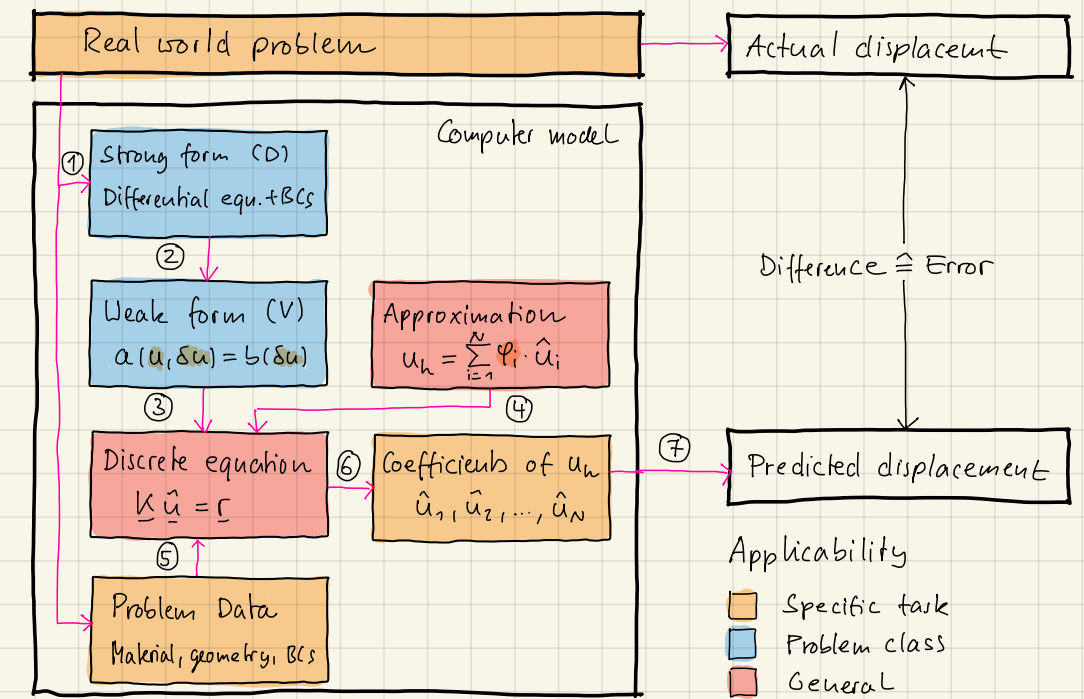
## ⑤ Data error GIGO (Garbage in, garbage out)

## ⑥ Roundoff errors

- Most of the time not a problem

## ⑦ Interpretation error

- Draw the right conclusions!



# Validation and verification

**Validation** – Do the equations in (D) capture all relevant effects?

"Do I solve the right equation?"

**Verification** – Does my numerical solution solve (D)?

"Do I solve the equation right?"

# Discretization error

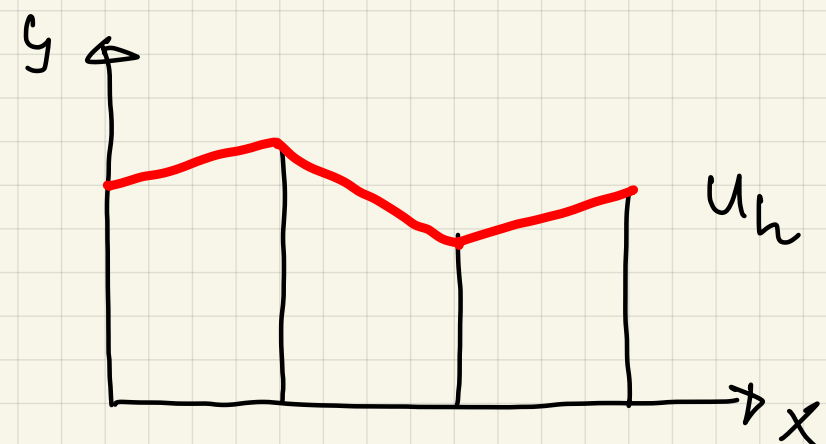
Error function

$$e = u - u_h$$

How to make sure the discretization error is sufficiently small

- Exact solution, but only available in simple cases
- Theory of error estimators (mathematicians)
- Rules of thumb and engineering expertise
  - Inspect stresses and jumps
  - Study results for different meshes

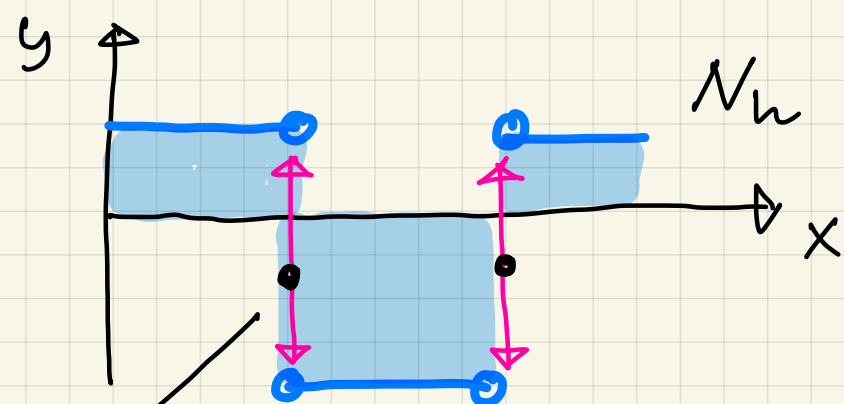
# Axial force



$u_h$  is piecewise linear

$N_h$  is piecewise constant

$$N(x) = EA u'(x)$$

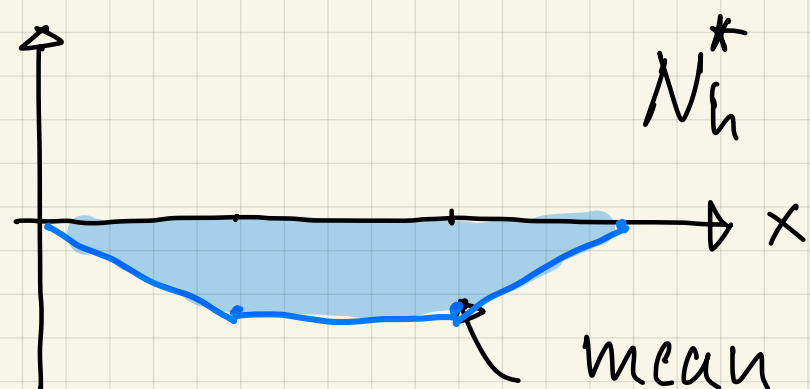


In FE-programs: Element solution

Use that  
to assess  
the quality  
of your  
results

Jumps physically not possible

"Improved" plot

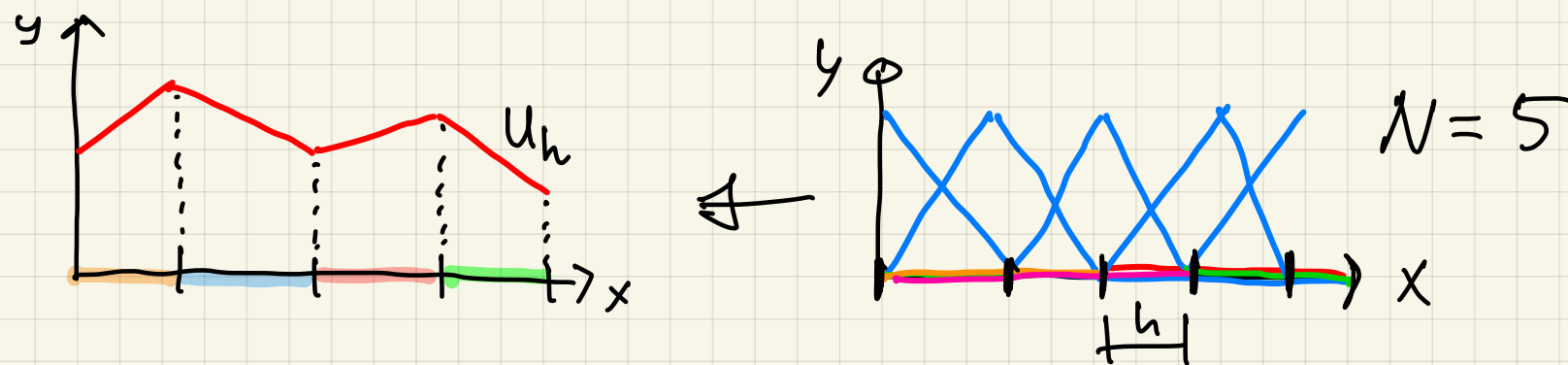


Nodal solution in FE-software

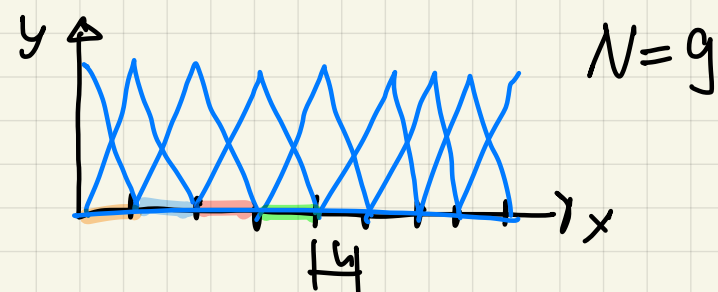
Show this  
to your  
clients

mean value of both elements

# How to improve the approximate solution $u_h$

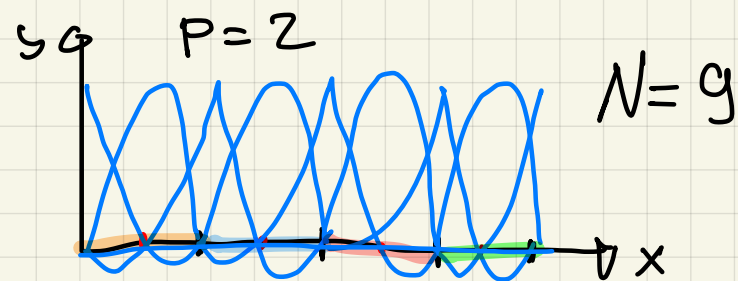


Reduce element size



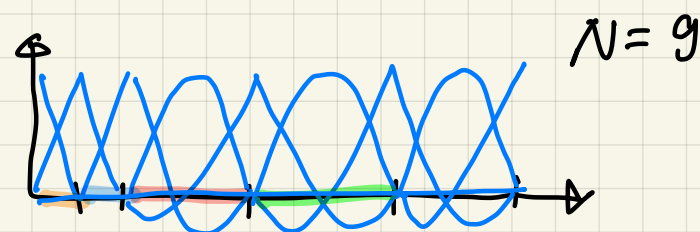
$h$ -version of finite element method

Increase polynomial degree



$p$ -version of FEM  
up to  $p \approx 15$

Combination

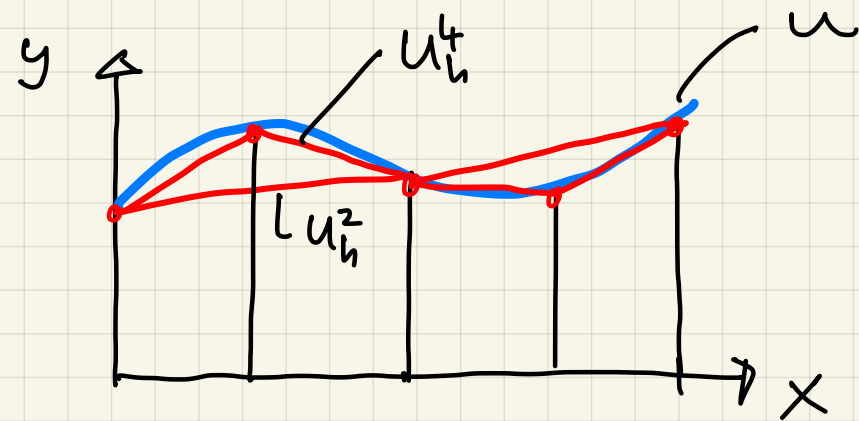


$hp$ -version of FEM

Converges faster to exact solution than  $h$ -version but difficult to program

→ Better solution with same  $N$

# Convergence of solution



Sequence of functions  $u_h^k$  with

$$\lim_{k \rightarrow \infty} (u_h^k - u) = 0$$

Proof is difficult (we leave that to mathematicians)

In our computation, we used the supremum-norm

$$\|f\|_{\infty} = \sup \{ |f(x)| \mid 0 \leq x \leq L \} \quad (\text{gleichmaige Konvergenz})$$

More common: Energy-norm

$$\|f\|_a = \frac{1}{2} a(f, f)$$

$$a(u, \delta u) = EA \int_0^L u' \delta u' dx + C \int_0^L u \delta u dx + S \cdot u(l) \cdot \delta u(l)$$

→ Computes energy associated with the error



# Convergence plots

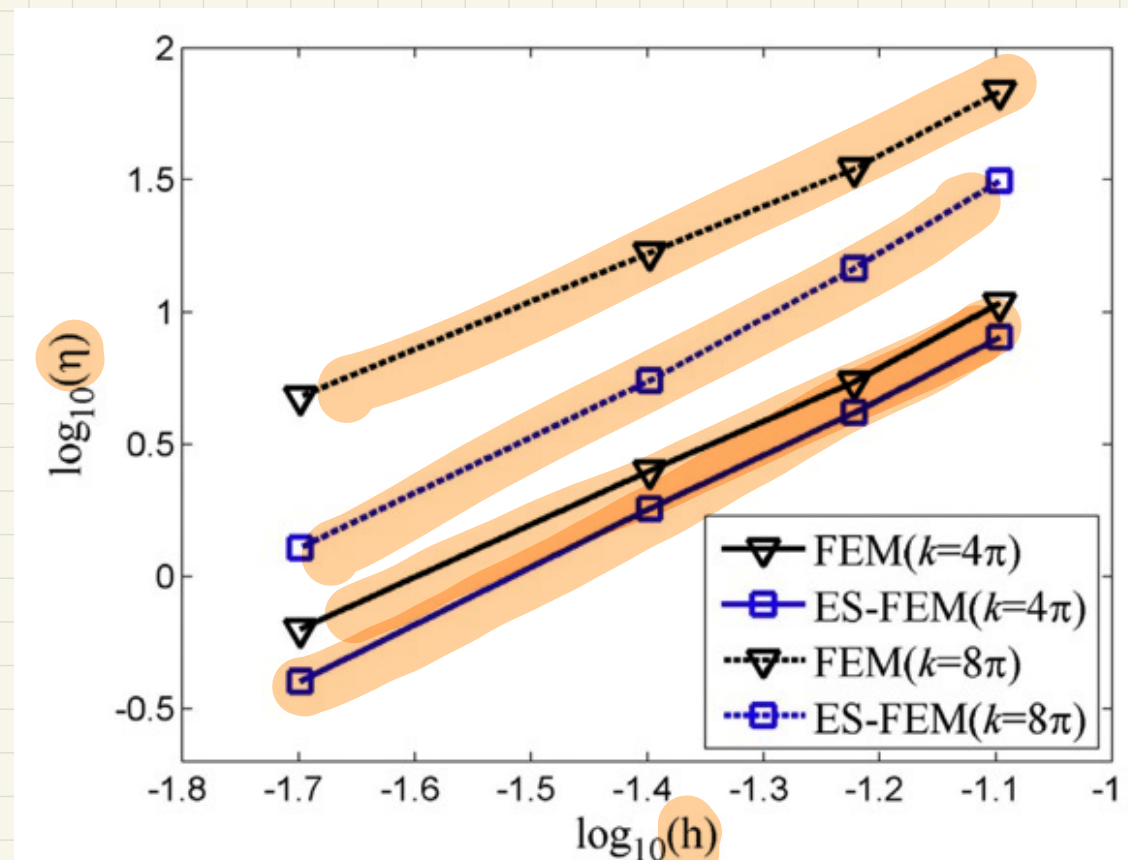
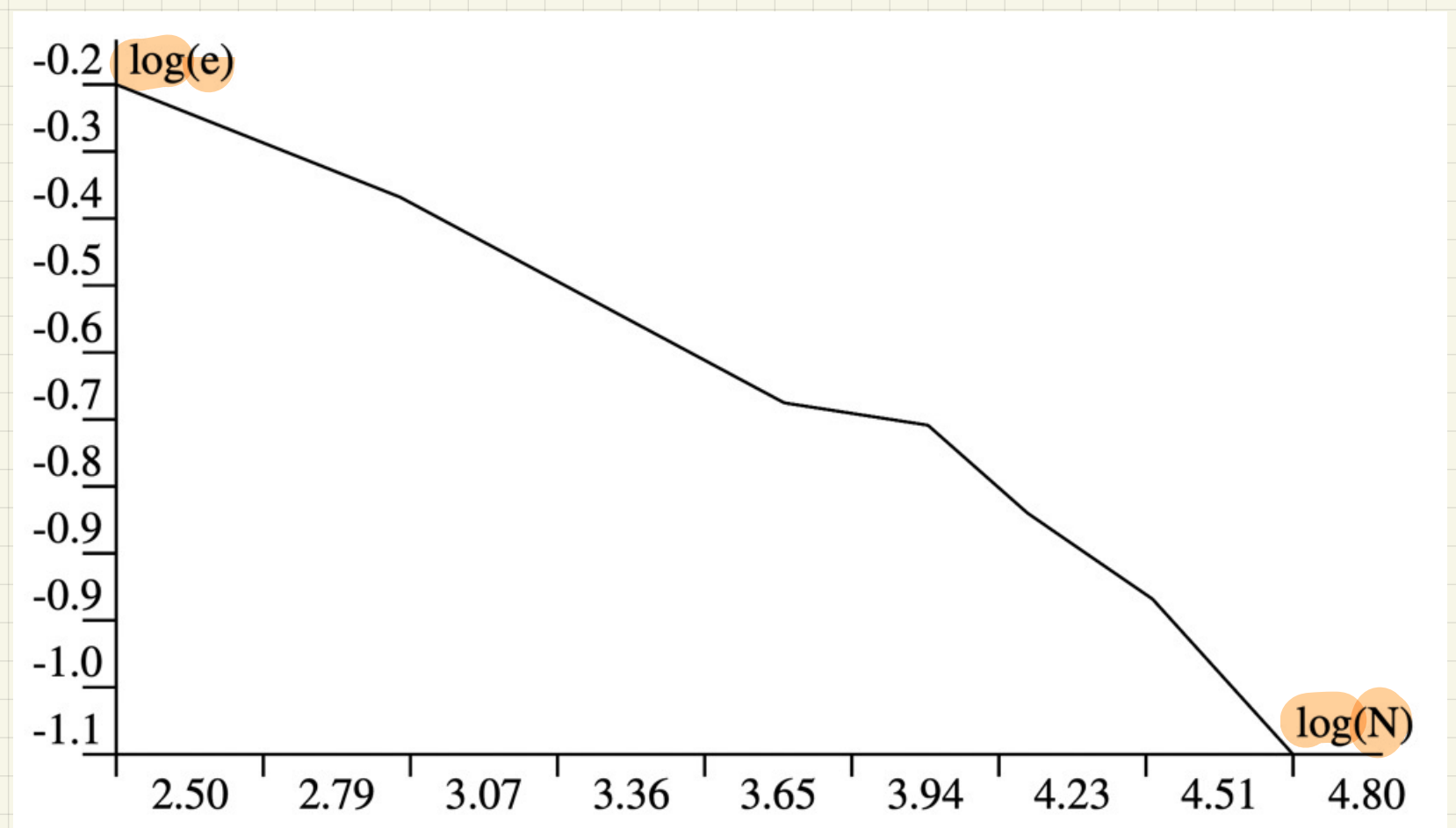


Fig. 9. The convergence rate results for FEM and ES-FEM.

Chai et al. (2018)



Rachowicz et al. (2006)