Formule RMS

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$$rms \ proportion_e = \frac{rms_e = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (o_{i,e} - d_i)^2}}{max(rms_e), \ \forall e \in epochs}$$
 with
$$\begin{cases} n : number \ of \ neurons \ on \ the \ output \ layer \\ o_{i,e} : value \ obtained \ for \ the \ i^{th} \ neuron \ at \ the \ e^{th} \ epoch \\ d_i : value \ desired \ for \ the \ i^{th} \ neuron \end{cases}$$

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\begin{split} & \textbf{function} \  \, \text{DISCRETIZE}(hiddenNeuron[],piece) \\ & result \leftarrow 0 \\ & \textbf{for} \ i = 0 \rightarrow hiddenNeuron.length \ \textbf{do} \\ & result \leftarrow result + piece^i \times cutting(hiddenNeuron[i],piece) \\ & i \leftarrow i+1 \\ & \textbf{end for} \\ & \textbf{return} \  \, \text{result} \\ & \textbf{end function} \end{split}
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function train(inputs, outputs, add)
   for i = 0 \rightarrow output neurons.length do
       y_{output}[i] \leftarrow g'(output\_neurons[i].a) \times (outputs[i] - output\_neurons.state)
   end for
   for i = 0 \rightarrow hidden neurons.length do
                  output\_neurons.length
                                      output\_neurons[j].weights[i] \times y_{output[j]}
       y_{hidden}[i] \leftarrow g'(hidden\_neurons[i].a) \times w\_sum
   update\_weights\_hidden\_layer(y_{hidden})
   for i = 0 \rightarrow output neurons.length do
       output\_neurons[i].update\_weights\_gradient(y_{output}[i], \ hidden\_neurons, \ add)
       output neurons[i].update weights perceptron(outputs[i], hidden neurons, add)
   end for
end function
function update weights gradient(error, intputs, add)
   calc\_output(inputs + add)
   for j = 0 \rightarrow inputs.length do
       dw \leftarrow weights[j] - last\_weights[j]
       p \leftarrow error \times inputs[j]
       weights[j] \leftarrow weights[j] + learning \quad rate \times p + momentum \times dw
   end for
end function
function update weights perceptron(goal, intputs, add)
   calc\_output(inputs + add)
   for j = inputs.length \rightarrow inputs.length + add.length do
       dw \leftarrow weights[j] - last\_weights[j]
       p \leftarrow (goal - state) \times add[inputs.length - j]
       weights[j] \leftarrow weights[j] + \frac{learning\_rate \times p + momentum \times dw}{rate}
   end for
end function
```