# 50.039 Theory and Practice of Deep Learning

# W5-S3 Introduction to Attacks and Defense on Neural Networks

Matthieu De Mari



### About this week (Week 5)

- 1. What are attacks on Neural Networks (NNs)?
- 2. Why are attacks an **important concept** when studying NNs?
- 3. What are the different **types of attacks** and what is the intuition behind basic attacks?
- 4. How to **defend** against such attacks?

**5. State-of-the-art** of (more advanced) attacks and defense, **open questions** in research.

### About this week (Week 5)

- 1. What are attacks on Neural Networks (NNs)?
- 2. Why are attacks an important concept when studying NNs?
- 3. What are the different **types of attacks** and what is the intuition behind basic attacks?
- 4. How to **defend** against such attacks?

**5. State-of-the-art** of (more advanced) attacks and defense, **open questions** in research.

### In the last episode

Exploiting the intrinsic properties/limits of deep learning models allows for powerful attacks with high efficacy and plausibility.

In some cases, we might be able to attack a model with 100% efficacy and very good plausibility.

- Can we implement more advanced attacks?
- Can we defend against these attacks?
- Can attackers respond to such defenses?

#### About attacks

#### Basic attacks (discussed in previous lecture):

- 0. (Epsilon Noising Attack)
- 1. Untargeted, one-shot, white-box gradient attack
- 2. Untargeted, one-shot, white-box fast gradient sign attack
- 3. Untargeted, iterated, white-box fast gradient sign attack
- 4. Targeted, one-shot, white-box fast gradient sign attack
- 5. Targeted, iterated, white-box fast gradient sign attack

### About attacks (and defense!)

#### Defense strategies against basic attacks:

- 1. Arms-race defense
- 2. Defensive distillation
- 3. Black-boxing your model
- 4. More?

#### About attacks

#### Advanced attacks (only discussing the concepts briefly):

- 1. Carlini-Wagner attack (targeted, iterated, white-box)
- 2. Surrogate attack (targeted/untargeted, one-shot/iterated, black-box)
- 3. Boundary attack (targeted, iterated, black-box)

4. (And, if time allows, a brief state-of-the-art of other remarkable attacks, for curious students!)

### Untargeted Gradient Attack (option #1)

# Definition (untargeted gradient attack):

The untargeted gradient attack takes a single sample x, of original class  $c \in C$  and attempts to produce a sample  $\tilde{x}$  of class  $\tilde{c} \in C$ , with  $\tilde{c} \neq c$ .

• Option #1: look for the most probable class  $c \in C$  and use gradient ascent to move the sample away from its original class, with step  $\epsilon$ .

$$\tilde{x} \leftarrow x + \epsilon \nabla_x L(x, \theta, c)$$

$$c = argmax_{i \in C}(f_i(x))$$

The attack is successful if 
$$\tilde{c} = argmax_{i \in C}(f_i(\tilde{x})) \neq c$$

And then two options...

## Untargeted Gradient Attack (option #2)

# Definition (untargeted gradient attack):

The untargeted gradient attack takes a single sample x, of original class  $c \in C$  and attempts to produce a sample  $\tilde{x}$  of class  $\tilde{c} \in C$ , with  $\tilde{c} \neq c$ .

$$c = argmax_{i \in C}(f_i(x))$$

And then two options...

• Option #2: look for the least probable class  $c^* \in C$  and use gradient descent to move the sample in the direction of the least probable class, with step  $\epsilon$ .

$$c^* = argmin_{i \in C}(f_i(x))$$
  

$$\tilde{x} \leftarrow x - \epsilon \nabla_x L(x, \theta, c^*)$$

The attack is successful if

$$\tilde{c} = argmax_{i \in C}(f_i(\tilde{x})) \neq c$$

## Fast Gradient Sign Method (FGSM)

# Definition (Fast Gradient Sign Method attack):

The Fast Gradient Sign Method attack only uses the sign of the gradient to create an attack sample.

$$\widetilde{x} \leftarrow x + \epsilon \nabla_x L(x, \theta, c)$$
(Gradient attack)
 $\widetilde{x} \leftarrow x + \epsilon \operatorname{sign}(\nabla_x L(x, \theta, c))$ 
(FGSM attack)

- Important property: this also helps to make more plausible samples, as it will, by design, verify  $\|\widetilde{x} x\|_{\infty} \leq \epsilon$ .
- (Plausibility constraint, we did not have in the previous attacks!)

```
def fgsm_attack(image, epsilon, data_grad):
    # Get element-wise signs of each element of the data gradient
    data_grad_sign = data_grad.sign()

# Create the attack image by adjusting each pixel of the input image
    eps_image = image + epsilon*data_grad_sign

# Clipping eps_image to maintain pixel values into the [0, 1] range
    eps_image = torch.clamp(eps_image, 0, 1)

# Return
return eps_image
```

### Iterative and Targeted FGSM attack

#### **Definition (iterated targeted Fast Gradient Sign Method attack):**

The iterated targeted Fast Gradient Sign Method attack will use the FGSM attack but will use the gradients of a targeted class  $\tilde{c}$ .

This follows the same logic as moving towards the least probable class as in Gradient attack option #2, but you can use it with any class of your choice. This attack uses gradient descent to move the sample towards the targeted class  $\tilde{c}$ .

This is repeated until it reaches a maximal number of iterations or makes the model malfunction with targeted class  $\tilde{c}$ .

$$x_0 = x$$

$$x_{n+1} \leftarrow x_n - \epsilon \operatorname{sign}(\nabla_x L(x_n, \theta, \tilde{c}))$$

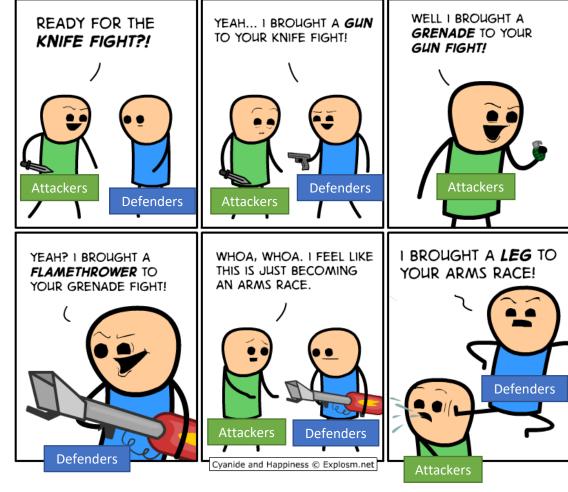
# The Madry's (or arms race) defense

# Definition (the Madry's or arms race defense):

The arms race defense strategy, is the most basic defense strategy.

If we know the type of attack that is coming, we can generate our own attack samples and train our model to correctly classify some of these attack samples.

Doing so, we therefore anticipate for future attacks of this type.



Source: <a href="https://explosm.net/comics/3939/">https://explosm.net/comics/3939/</a>

**Note:** this is also known as the **Madry's defense** [Madry2017].

Let us start with our pre-trained model, and the basic FGSM attack (one-shot, untargeted version).

 Our model is not prepared to face this type of attacks and will suffer badly from it.

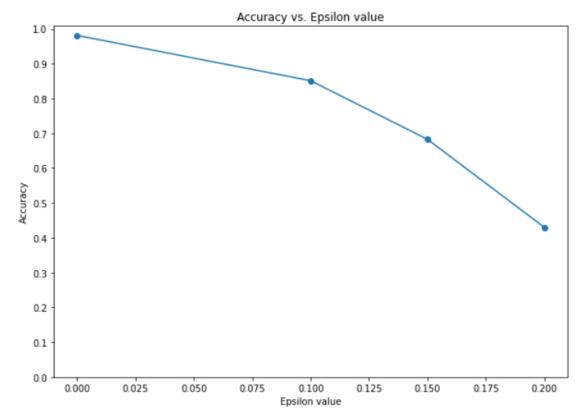
```
1  epsilons = [0, .1, .15, .2]
2  accuracies = []
3  examples = []
4 
5  # Run test() function for each epsilon
6  for eps in epsilons:
7   acc, ex = test(model, device, test_loader, eps)
8   accuracies.append(acc)
9  examples.append(ex)
```

```
Epsilon: 0 - Test Accuracy = 9810/10000 = 0.981

Epsilon: 0.1 - Test Accuracy = 8510/10000 = 0.851

Epsilon: 0.15 - Test Accuracy = 6826/10000 = 0.6826

Epsilon: 0.2 - Test Accuracy = 4301/10000 = 0.4301
```



Our next step would then be to continue the training of our model, integrating samples that have been generated using said FGSM attack.

• Intuition: in a sense, the arms race defense is a sort of data augmentation technique, that helps make the model more robust to attacks of the FGSM type.

- For demonstration, we will create a second model, using the same pre-trained weights.
- We will also retrieve the training dataset and make its dataloader (train\_loader), with minibatches.
- We will then continue the training of this model, using CrossEntropy as our loss and a basic SGD as our optimizer.

```
# Load the pretrained model
model2 = Net().to(device)
pretrained_model = "./mnist_model.data"
model2.load_state_dict(torch.load(pretrained_model, map_location = 'cpu'))

All keys matched successfully>

# MNIST dataset and dataloader
# (For testing only, we will use a pre-trained model)
ds2 = datasets.MNIST('./data', train = True, download = True, transform = tf)
train_loader = torch.utils.data.DataLoader(ds2, batch_size = 64, shuffle = True)

print(len(train_loader))

print(len(train_loader))

# Define a loss function and an optimizer for training
criterion = nn.CrossEntropyLoss()
optimizer = optim.SGD(model2.parameters(), lr = 0.001, momentum = 0.9)
```

#### From Notebook 5.!

```
1 def retrain(model, train loader, optimizer, criterion, n iter = 5):
       # This will make prints happen every 50 mini-batches
       mod val = 50
       # Train over n iter epochs
       for epoch in range (n iter):
            # Keep track of the running losses over batches
9
           running loss normal = 0.0
10
           running loss attack = 0.0
                                                                 32
                                                                 33
13
           for i, data in enumerate(train loader):
                                                                 34
14
                                                                 35
15
               1. Mini-batches on normal samples
                                                                 36
16
                                                                 37
                # Retrieve input images and labels
                                                                 38
               inputs, labels = data
18
                                                                 39
               inputs.requires grad = True
19
20
                                                                 40
                # Zeroing gradients
                                                                 41
               optimizer.zero grad()
                                                                 42
23
24
                # Forward, Loss, Backprop
                                                                 44
               outputs = model(inputs)
                                                                 45
               loss = criterion(outputs, labels)
                                                                 46
27
               loss.backward()
                                                                 47
                # Keep track of running loss (normal samples)
                                                                 48
               running loss normal += loss.item()
                                                                 49
                                                                 50
                                                                 51
                                                                 52
                                                                 53
                                                                 54
```

11

### Retraining our model

```
11 11 11
Mini-batches on generated attack samples
11 11 11
# Collect gradients of image
data grad = inputs.grad.data
# Call FGSM Attack with the 0.15 epsilon value
epsilon = .15
eps image = fgsm attack(inputs, epsilon, data grad)
# Re-classify the epsilon image
output2 = model(eps image)
# Get the index of the max log-probability
eps pred = output2.max(1, keepdim = True)[1]
# Loss, Backprop, Optimize
loss2 = criterion(output2, labels)
loss2.backward()
optimizer.step()
# Keep track of running loss (attack samples)
running loss attack += loss2.item()
```

```
1 def retrain(model, train loader, optimizer, criterion, n iter = 5):
       # This will make prints happen every 50 mini-batches
       mod val = 50
       # Train over n iter epochs
       for epoch in range (n iter):
            # Keep track of the running losses over batches
           running loss normal = 0.0
           running loss attack = 0.0
                                                                 32
11
           for i, data in enumerate(train loader):
13
                                                                 34
14
                                                                 35
15
               1. Mini-batches on normal samples
                                                                 36
16
                # Retrieve input images and labels
                                                                 38
               inputs, labels = data
18
19
               inputs.requires grad = True
                                                                 39
20
                # Zeroing gradients
               optimizer.zero grad()
                                                                 42
23
24
                # Forward, Loss, Backprop
               outputs = model(inputs)
               loss = criterion(outputs, labels)
                                                                 46
27
               loss.backward()
                # Keep track of running loss (normal samples)
                                                                 48
30
               running loss normal += loss.item()
                                                                 49
                                                                 50
                                                                 51
    Just like in "normal" training we are going to train
```

Just like in "normal" training we are going to train on the training samples (this uses our train\_loader, not the test one!)

## Retraining our model

```
11 11 11
Mini-batches on generated attack samples
# Collect gradients of image
data grad = inputs.grad.data
# Call FGSM Attack with the 0.15 epsilon value
epsilon = .15
eps image = fgsm attack(inputs, epsilon, data grad)
# Re-classify the epsilon image
output2 = model(eps image)
# Get the index of the max log-probability
eps pred = output2.max(1, keepdim = True)[1]
# Loss, Backprop, Optimize
loss2 = criterion(output2, labels)
loss2.backward()
optimizer.step()
# Keep track of running loss (attack samples)
running loss attack += loss2.item()
```

53

54

```
1 def retrain(model, train loader, optimizer, criterion, n iter = 5):
       # This will make prints happen every 50 mini-batches
       mod val = 50
       # Train over n iter epochs
       for epoch in range (n iter):
           # Keep track of the running losses over batches
           running loss normal = 0.0
           running loss attack = 0.0
                                                                 32
11
                                                                 33
13
           for i, data in enumerate(train loader):
                                                                 34
14
                                                                 35
15
               1. Mini-batches on normal samples
                                                                 36
16
                                                                 37
                # Retrieve input images and labels
                                                                 38
               inputs, labels = data
18
                                                                 39
19
               inputs.requires grad = True
20
                                                                 40
                # Zeroing gradients
                                                                 41
               optimizer.zero grad()
                                                                 42
23
                                                                 43
24
                # Forward, Loss, Backprop
                                                                 44
               outputs = model(inputs)
                                                                 45
               loss = criterion(outputs, labels)
                                                                 46
               loss.backward()
27
                                                                 47
                # Keep track of running loss (normal samples)
                                                                 48
               running loss normal += loss.item()
                                                                 49
                                                                 50
                                                                 51
    And in the second part, we will do the same, but
                                                                 52
                                                                 53
```

And in the second part, we will do the same, but will transform the samples using our attack function and train on this sample.

## Retraining our model

```
Mini-batches on generated attack samples
# Collect gradients of image
data grad = inputs.grad.data
# Call FGSM Attack with the 0.15 epsilon value
epsilon = .15
eps image = fgsm attack(inputs, epsilon, data grad)
# Re-classify the epsilon image
output2 = model(eps image)
# Get the index of the max log-probability
eps pred = output2.max(1, keepdim = True)[1]
# Loss, Backprop, Optimize
loss2 = criterion(output2, labels)
loss2.backward()
optimizer.step()
# Keep track of running loss (attack samples)
running loss attack += loss2.item()
```

Restricted

54

```
1 def retrain(model, train loader, optimizer, criterion, n iter = 5):
       # This will make prints happen every 50 mini-batches
       mod val = 50
       # Train over n iter epochs
       for epoch in range (n iter):
           # Keep track of the running losses over batches
10
           running loss normal = 0.0
           running loss attack = 0.0
                                                                32
11
                                                                33
13
           for i, data in enumerate(train loader):
                                                                34
14
                                                                35
15
               1. Mini-batches on normal samples
                                                                36
16
                                                                37
               # Retrieve input images and labels
                                                                38
               inputs, labels = data
18
                                                                39
19
               inputs.requires grad = True
20
                                                                40
               # Zeroing gradients
                                                                41
22
               optimizer.zero grad()
                                                                42
23
24
               # Forward, Loss, Backprop
                                                                44
               outputs = model(inputs)
                                                                45
               loss = criterion(outputs, labels)
                                                                46
27
               loss.backward()
                                                                47
               # Keep track of running loss (normal samples)
                                                                48
               running loss normal += loss.item()
                                                                49
                                                                50
                                                                51
    In addition (not shown here), we will display the
                                                                52
                                                                53
    running losses for both the normal and attack
                                                                54
```

# samples.

## Retraining our model

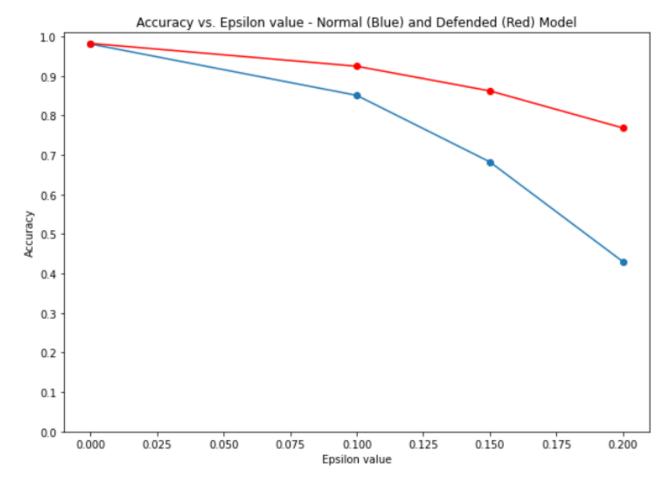
```
11 11 11
Mini-batches on generated attack samples
11 11 11
# Collect gradients of image
data grad = inputs.grad.data
# Call FGSM Attack with the 0.15 epsilon value
epsilon = .15
eps image = fgsm attack(inputs, epsilon, data grad)
# Re-classify the epsilon image
output2 = model(eps image)
# Get the index of the max log-probability
eps pred = output2.max(1, keepdim = True)[1]
# Loss, Backprop, Optimize
loss2 = criterion(output2, labels)
loss2.backward()
optimizer.step()
# Keep track of running loss (attack samples)
running loss attack += loss2.item()
```

Retraining will not necessarily affect the loss on normal samples (it will keep on decreasing, possibly overfitting, but this should not change the accuracy performance of the model on normal samples).

 What is important: We are able to train to recognize attack samples and our model progressively becomes better at classifying those correctly.

```
[Epoch 1, Batch
                   51] Normal Loss: 0.296 - Attack Loss: 0.941
[Epoch 1, Batch
                  101] Normal Loss: 0.257 - Attack Loss: 0.877
[Epoch 1, Batch
                  151] Normal Loss: 0.244 - Attack Loss: 0.857
[Epoch 1, Batch
                  201] Normal Loss: 0.234 - Attack Loss: 0.831
                  251] Normal Loss: 0.226 - Attack Loss: 0.817
[Epoch 1, Batch
[Epoch 1, Batch
                  301] Normal Loss: 0.220 - Attack Loss: 0.798
[Epoch 1, Batch
                  351] Normal Loss: 0.219 - Attack Loss: 0.789
[Epoch 1, Batch
                  401] Normal Loss: 0.216 - Attack Loss: 0.776
                  451] Normal Loss: 0.216 - Attack Loss: 0.769
[Epoch 1, Batch
[Epoch 1, Batch
                  5011 Normal Loss: 0.214 - Attack Loss: 0.761
[Epoch 1, Batch
                  551] Normal Loss: 0.213 - Attack Loss: 0.755
                  601] Normal Loss: 0.212 - Attack Loss: 0.753
[Epoch 1, Batch
[Epoch 1, Batch
                  651] Normal Loss: 0.211 - Attack Loss: 0.749
[Epoch 1, Batch
                  7011 Normal Loss: 0.209 - Attack Loss: 0.744
[Epoch 1, Batch
                  751] Normal Loss: 0.209 - Attack Loss: 0.739
[Epoch 1, Batch
                  801] Normal Loss: 0.209 - Attack Loss: 0.733
[Epoch 1, Batch
                  8511 Normal Loss: 0.208 - Attack Loss: 0.729
[Epoch 1, Batch
                  901] Normal Loss: 0.207 - Attack Loss: 0.725
[Epoch 2, Batch
                   51] Normal Loss: 0.187 - Attack Loss: 0.626
[Epoch 2, Batch
                  101] Normal Loss: 0.184 - Attack Loss: 0.634
[Epoch 2, Batch
                  151] Normal Loss: 0.191 - Attack Loss: 0.625
[Epoch 2, Batch
                  201] Normal Loss: 0.191 - Attack Loss: 0.628
[Epoch 2, Batch
                  251] Normal Loss: 0.189 - Attack Loss: 0.628
[Epoch 2, Batch
                  3011 Normal Loss: 0.188 - Attack Loss: 0.628
[Epoch 2, Batch
                  3511 Normal Loss: 0.189 - Attack Loss: 0.629
[Epoch 2, Batch
                  401] Normal Loss: 0.187 - Attack Loss: 0.629
[Epoch 2, Batch
                  451] Normal Loss: 0.187 - Attack Loss: 0.626
[Epoch 2, Batch
                  5011 Normal Loss: 0.187 - Attack Loss: 0.625
[Epoch 2, Batch
                  551] Normal Loss: 0.187 - Attack Loss: 0.621
[Epoch 2, Batch
                  601] Normal Loss: 0.186 - Attack Loss: 0.618
[Epoch 2, Batch
                  651] Normal Loss: 0.185 - Attack Loss: 0.616
[Epoch 2, Batch
                  701] Normal Loss: 0.186 - Attack Loss: 0.614
[Epoch 2, Batch
                  751] Normal Loss: 0.186 - Attack Loss: 0.614
[Epoch 2, Batch
                  801] Normal Loss: 0.186 - Attack Loss: 0.614
[Epoch 2, Batch
                  851] Normal Loss: 0.186 - Attack Loss: 0.611
                  901] Normal Loss: 0.186 - Attack Loss: 0.610
[Epoch 2, Batch
[Epoch 3, Batch
                   51] Normal Loss: 0.176 - Attack Loss: 0.584
[Epoch 3, Batch
                  101] Normal Loss: 0.178 - Attack Loss: 0.594
[Epoch 3, Batch
                  151] Normal Loss: 0.181 - Attack Loss: 0.591
[Epoch 3, Batch
                  201] Normal Loss: 0.181 - Attack Loss: 0.590
[Epoch 3, Batch
                  251] Normal Loss: 0.180 - Attack Loss: 0.585
[Epoch 3, Batch
                  301] Normal Loss: 0.179 - Attack Loss: 0.582
[Epoch 3, Batch
                  351] Normal Loss: 0.179 - Attack Loss: 0.581
[Epoch 3, Batch
                  401] Normal Loss: 0.179 - Attack Loss: 0.577
```

- Training on the attack samples then makes the model a bit more robust to this type of attacks.
- In blue, you have the original undefended model. In red, the defended model.
- Conclusion: Both of them have the same baseline accuracy, but the second model seems to resist more to the FGSM attacks (Can be improved with more training than just 5 iterations!)



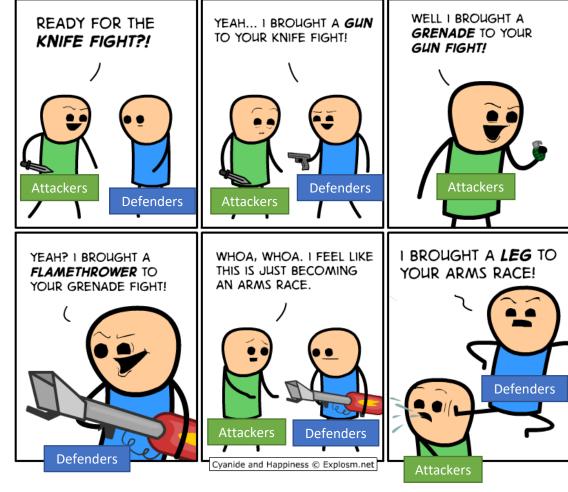
# The Madry's (or arms race) defense

# Definition (the Madry's or arms race defense):

The arms race defense strategy, is the most basic defense strategy.

If we know the type of attack that is coming, we can generate our own attack samples and train our model to correctly classify some of these attack samples.

Doing so, we therefore anticipate for future attacks of this type.



Source: <a href="https://explosm.net/comics/3939/">https://explosm.net/comics/3939/</a>

**Note:** this is also known as the **Madry's defense** [Madry2017].

While this is the most intuitive approach and might work on the type of attacks you train your model for...

- This defense strategy will ultimately be defeated by attackers, who
  just have to implement a new type of attack...
- And your model simply will not know how to handle it.

• For instance, here, we defended against FGSM, but the Gradient attack remains undefended.

While this is the most intuitive approach apting Petty creative attacks you train your model for are general acks.

This defense strategical dathately bore stated by as dels, who just have it is lement a paytype of attachet it.

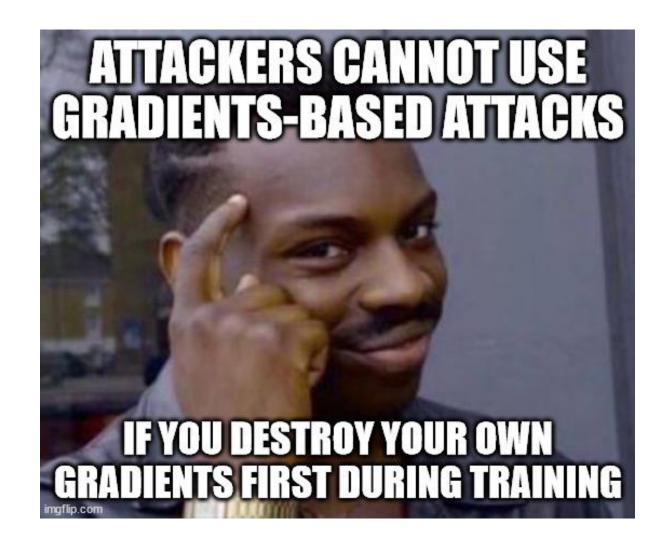
And eyour mode will by will pages who to be a supported by a system.

For iretale, here variately against the Gradient see the control of the control of

#### Defensive distillation

Core idea behind gradient-based defensive distillation.

- Most gradient-based attacks rely on the gradients to compute an attack sample.
- If we were to annihilate these gradients, the attackers would not be able to produce attack samples.



#### Defensive distillation



Core idea behind gradient-based defensive distillation.

- Most gradient-based attacks rely on the gradients to compute an attack sample.
- If we were to annihilate these gradients, the attackers would not be able to produce attack samples.

- Important note: This is a pretty risky strategy, as you need those gradients during the training phase of your model!
- Defensive distillation will however do so, by using some of the softmax function properties.

• Idea comes from [Papernot2015].

#### Reminder: the softmax function

#### **Definition (softmax function):**

The **softmax function** receives a list of values  $x = (x_1, ..., x_N)$  and produces the following outputs  $y = (y_1, ..., y_N)$ .

$$\forall i \in [1, N], \ y_i = \frac{\exp(x_i)}{\sum_{j=1}^{N} \exp(x_j)}$$

#### Reminder: the softmax function

#### **Definition (softmax function):**

The **softmax function** receives a list of values  $x = (x_1, ..., x_N)$  and produces the following outputs  $y = (y_1, ..., y_N)$ .

$$\forall i \in [1, N], \ y_i = \frac{\exp(x_i)}{\sum_{j=1}^{N} \exp(x_j)}$$

# Definition (softmax function with temperature T):

The softmax function with temperature T, receives a list of values  $x = (x_1, ..., x_N)$  and produces the following outputs  $y = (y_1, ..., y_N)$ .

$$\forall i \in [1, N], \quad y_i = \frac{\exp\left(\frac{x_i}{T}\right)}{\sum_{j=1}^{N} \exp\left(\frac{x_j}{T}\right)}$$

# Definition (softmax function with temperature T):

The softmax function with temperature T, receives a list of values  $x = (x_1, ..., x_N)$  and produces the following outputs  $y = (y_1, ..., y_N)$ .

$$\forall i \in [1, N], \quad y_i = \frac{\exp\left(\frac{x_i}{T}\right)}{\sum_{j=1}^{N} \exp\left(\frac{x_j}{T}\right)}$$

# Three interesting properties for the softmax with temperature.

- 1. When  $T \rightarrow 0$ , we have
  - $\forall i \in [1, N], y_i \rightarrow 0$ ,
  - Except for one value k, where  $y_k \to 1$ .
  - The index value k, corresponds to the largest one among the  $(x_i)_{i \in [1,N]}$ , that is  $k = argmax_{i \in [1,N]}(x_i)$ .

# Definition (softmax function with temperature T):

The softmax function with temperature T, receives a list of values  $x = (x_1, ..., x_N)$  and produces the following outputs  $y = (y_1, ..., y_N)$ .

$$\forall i \in [1, N], \quad y_i = \frac{\exp\left(\frac{x_i}{T}\right)}{\sum_{j=1}^{N} \exp\left(\frac{x_j}{T}\right)}$$

2. When  $T \rightarrow \infty$ , we have

• 
$$\forall i \in [1, N], y_i \rightarrow \frac{1}{N}$$
.

# Definition (softmax function with temperature T):

The softmax function with temperature T, receives a list of values  $x = (x_1, ..., x_N)$  and produces the following outputs  $y = (y_1, ..., y_N)$ .

$$\forall i \in [1, N], \quad y_i = \frac{\exp\left(\frac{x_i}{T}\right)}{\sum_{j=1}^{N} \exp\left(\frac{x_j}{T}\right)}$$

3. When  $T \to \infty$ , the gradients will vanish.

# Definition (softmax function with temperature T):

The softmax function with temperature T, receives a list of values  $x = (x_1, ..., x_N)$  and produces the following outputs  $y = (y_1, ..., y_N)$ .

$$\forall i \in [1, N], \quad y_i = \frac{\exp\left(\frac{x_i}{T}\right)}{\sum_{j=1}^{N} \exp\left(\frac{x_j}{T}\right)}$$

- 3. When  $T \rightarrow \infty$ , the gradients will vanish.
  - Indeed, if f is the softmax function, then its derivative f' will produce the following outputs  $z = (z_1, ..., z_N)$ .

$$z_{i} = \frac{1}{T} \cdot \left( \frac{\exp\left(\frac{x_{i}}{T}\right)}{\sum_{j=1}^{N} \exp\left(\frac{x_{j}}{T}\right)} \right) \cdot \left( 1 - \frac{\exp\left(\frac{x_{i}}{T}\right)}{\sum_{j=1}^{N} \exp\left(\frac{x_{j}}{T}\right)} \right)$$

• Using Property 2., this gives

$$\forall i \in [1, N], \lim_{T \to \infty} z_i = \lim_{T \to \infty} \frac{1}{T} \cdot \frac{1}{N} \cdot \left(1 - \frac{1}{N}\right) = 0$$

### The defensive distillation strategy

# Definition (the defensive distillation strategy):

The defensive distillation strategy makes use of the last property of the softmax function and its tendency to vanish gradients.

We can make the gradients of our model vanish by using a softmax with a large temperature T, instead of the standard T = 1 value.

## The defensive distillation strategy



# Definition (the defensive distillation strategy):

The defensive distillation strategy makes use of the last property of the softmax function and its tendency to vanish gradients.

We can make the gradients of our model vanish by using a softmax with a large temperature T, instead of the standard T = 1 value.

This will make the gradients vanish, and they might no longer be usable by the attackers for the gradient and fast gradient sign attacks.

Important: It might however complicate the training of the model! (Remember that we need these gradients to train and backpropagate!)

### Model changes

 We will first change the constructor of our model, and add a temperature T.

```
# Model definition
   class Net(nn.Module):
        This is a basic Neural Net for MNIST
       - Two convolutions, into ReLU activations and dropouts after ReLU,
        - Flattening,
        - Fully connected, into ReLU activation and dropout after ReLU,
        - Fully connected, into Log-Softmax.
10
        def init (self):
            super(Net, self). init ()
13
            # Conv. 1
14
            self.conv1 = nn.Conv2d(1, 10, kernel size = 5)
15
            # Conv. 2
16
            self.conv2 = nn.Conv2d(10, 20, kernel size = 5)
17
            # Dropout for Conv. layers
18
            self.conv2 drop = nn.Dropout2d()
            # FC 1
            self.fc1 = nn.Linear(320, 50)
21
            # FC 2
22
            self.fc2 = nn.Linear(50, 10)
23
            # Temperature (set to 1 by default)
24
25
26
        def forward(self, x):
            # Conv. 1 + ReLU + Dropout
           x = F.relu(F.max pool2d(self.conv1(x), 2))
            # Conv. 2 + ReLU + Dropout
29
30
            x = F.relu(F.max pool2d(self.conv2 drop(self.conv2(x)), 2))
31
            # Flatten
           x = x.view(-1, 320)
33
            # FC 1 + ReLU + Droupout
           x = F.relu(self.fcl(x))
34
35
           x = F.dropout(x, training = self.training)
36
            # FC 2 + Log-Softmax
37
           x = self.fc2(x)
            return F.log softmax(x/self.T, dim = 1)
38
```

Restricted

### Model changes

 We will first change the constructor of our model, and add a temperature T.

• This temperature is then used in the softmax function of the forward() method.

```
# Model definition
     class Net(nn.Module):
         This is a basic Neural Net for MNIST
         - Two convolutions, into ReLU activations and dropouts after ReLU,

    Flattening,

         - Fully connected, into ReLU activation and dropout after ReLU,
         - Fully connected, into Log-Softmax.
         def init (self):
             super(Net, self). init ()
             # Conv. 1
 14
             self.conv1 = nn.Conv2d(1, 10, kernel size = 5)
 15
             # Conv. 2
             self.conv2 = nn.Conv2d(10, 20, kernel size = 5)
 16
 17
             # Dropout for Conv. layers
             self.conv2 drop = nn.Dropout2d()
             # FC 1
             self.fc1 = nn.Linear(320, 50)
 21
             # FC 2
             self.fc2 = nn.Linear(50, 10)
             # Temperature (set to 1 by default)
             self.T = 1
         def forward(self, x):
             # Conv. 1 + ReLU + Dropout
             x = F.relu(F.max pool2d(self.conv1(x), 2))
 29
             # Conv. 2 + ReLU + Dropout
             x = F.relu(F.max pool2d(self.conv2 drop(self.conv2(x)), 2))
 30
 31
             # Flatten
             x = x.view(-1, 320)
 33
             # FC 1 + ReLU + Droupout
             x = F.relu(self.fcl(x))
             x = F.dropout(x, training = self.training)
 36
             # FC 2 + Log-Softmax
 37
            x = self.fc2(x)
             return F.log softmax(x/self.T, dim = 1)
 38
Restricted
```

# Model changes

 We will first change the constructor of our model, and add a temperature T.

 This temperature is then used in the softmax function of the forward() method.

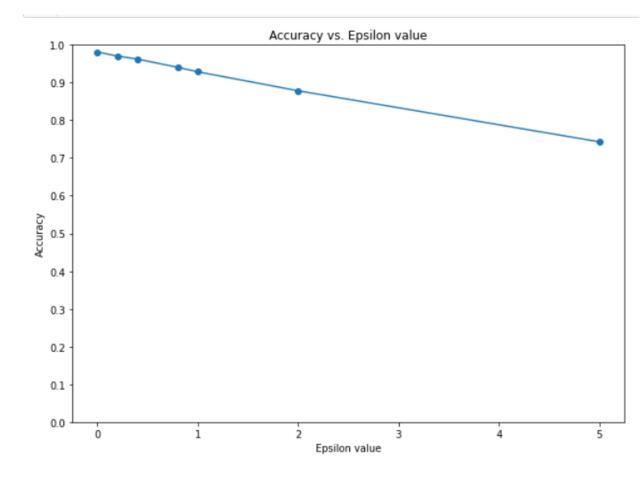
 It can later be changed using model.T = new\_value

```
# Model definition
   class Net(nn.Module):
       This is a basic Neural Net for MNIST
       - Two convolutions, into ReLU activations and dropouts after ReLU,
       - Flattening,
        - Fully connected, into ReLU activation and dropout after ReLU,
       - Fully connected, into Log-Softmax.
10
       def init (self):
            super(Net, self). init ()
            # Conv. 1
14
            self.conv1 = nn.Conv2d(1, 10, kernel size = 5)
15
            # Conv. 2
16
            self.conv2 = nn.Conv2d(10, 20, kernel size = 5)
17
            # Dropout for Conv. layers
            self.conv2 drop = nn.Dropout2d()
            # FC 1
           self.fc1 = nn.Linear(320, 50)
21
            # FC 2
            self.fc2 = nn.Linear(50, 10)
            # Temperature (set to 1 by default)
            self.T = 1
       def forward(self, x):
            # Conv. 1 + ReLU + Dropout
           x = F.relu(F.max pool2d(self.conv1(x), 2))
29
            # Conv. 2 + ReLU + Dropout
30
            x = F.relu(F.max pool2d(self.conv2 drop(self.conv2(x)), 2))
31
            # Flatten
           x = x.view(-1, 320)
33
           # FC 1 + ReLU + Droupout
34
           x = F.relu(self.fcl(x))
           x = F.dropout(x, training = self.training)
36
            # FC 2 + Log-Softmax
37
           x = self.fc2(x)
            return F.log softmax(x/self.T, dim = 1)
38
```

## Original model for baseline

• In Notebook 6., we will be using our original model and the Gradient-based attack for reference.

• This is our efficacy vs. epsilon graph for the undefended model.



• The defended model, used for comparison will be a copy of the undefended model.

```
# Load the pretrained model
   model2 = Net().to(device)
   pretrained model = "./mnist model.data"
   model2.load state dict(torch.load(pretrained model, map location = 'cpu'))
<All keys matched successfully>
 1 # MNIST dataset and dataloader
 2 # (For testing only, we will use a pre-trained model)
 3 ds2 = datasets.MNIST('./data', train = True, download = True, transform = tf)
 4 | train loader = torch.utils.data.DataLoader(ds2, batch size = 64, shuffle = True)
 1 print(len(train loader))
938
 1 # Define a loss function and an optimizer for training
 2 criterion = nn.CrossEntropyLoss()
 3 optimizer = optim.SGD(model2.parameters(), lr = 0.001, momentum = 0.9)
 1 # Setting temperature to 100 for training
 2 \mod 2.T = 100
```

- The defended model, used for comparison will be a copy of the undefended model.
- We will then change the temperature to T = 100 (arbitrarily chosen).

```
1 # Load the pretrained model
 2 model2 = Net().to(device)
   pretrained model = "./mnist model.data"
   model2.load state dict(torch.load(pretrained model, map location = 'cpu'))
<all keys matched successfully>
 1 # MNIST dataset and dataloader
 2 # (For testing only, we will use a pre-trained model)
 3 ds2 = datasets.MNIST('./data', train = True, download = True, transform = tf)
   train loader = torch.utils.data.DataLoader(ds2, batch size = 64, shuffle = True)
1 print(len(train loader))
938
 1 # Define a loss function and an optimizer for training
 2 criterion = nn.CrossEntropyLoss()
   optimizer = optim.SGD(model2.parameters(), lr = 0.001, momentum = 0.9)
   # Setting temperature to 100 for training
```

- The defended model, used for comparison will be a copy of the undefended model.
- We will then change the temperature to T = 100 (arbitrarily chosen).
- And will continue the training of this model on the training set, with this new "high" temperature.

```
1 # Load the pretrained model
   model2 = Net().to(device)
   pretrained model = "./mnist model.data"
   model2.load state dict(torch.load(pretrained model, map location = 'cpu'))
<All keys matched successfully>
      (For testing only, we will use a pre-trained model)
  ds2 = datasets.MNIST('./data', train = True, download = True, transform = tf)
   train loader = torch.utils.data.DataLoader(ds2, batch size = 64, shuffle =
1 print(len(train loader))
1 # Define a loss function and an optimizer for training
2 criterion = nn.CrossEntropyLoss()
   optimizer = optim.SGD(model2.parameters(), lr = 0.001, momentum = 0.9)
 1 # Setting temperature to 100 for training
 2 \mod 2.T = 100
```

- The defended model, used for comparison will be a copy of the undefended model.
- We will then change the temperature to T = 100 (arbitrarily chosen).
- If we want, we can continue the training of this model, with this new "high" temperature, to check it leads to very little changes in model parameters (gradients are close to zero).

```
def retrain(model, train loader, optimizer, criterion, n iter = 10):
       # This will make prints happen every 50 mini-batches
       mod val = 50
       # Train over n iter epochs
       for epoch in range (n iter):
            # Keep track of the running losses over batches
           running loss normal = 0.0
10
           for i, data in enumerate(train loader):
                # Retrieve input images and labels
15
               inputs, labels = data
               inputs.requires grad = True
18
                # Zeroing gradients
19
               optimizer.zero grad()
20
                # Forward, Loss, Backprop, Optimize
               outputs = model(inputs)
               loss = criterion(outputs, labels)
                loss.backward()
               optimizer.step()
```

- The defended model, used for comparison will be a copy of the undefended model.
- We will then change the temperature to T = 100 (arbitrarily chosen).
- If we want, we can continue the training of this model, with this new "high" temperature, to check it leads to very little changes in model parameters (gradients are close to zero).

```
1 retrain (model2, train loader, optimizer, criterion, n iter = 50)
                   511 Loss: 2.258
[Epoch 1, Batch
                  101] Loss: 2.256
[Epoch 1, Batch
[Epoch 1, Batch
                  151] Loss: 2.254
[Epoch 1, Batch
                  201] Loss: 2.252
[Epoch 1, Batch
                  251] Loss: 2.250
[Epoch 1, Batch
                  3011 Loss: 2.248
[Epoch 1, Batch
                  3511 Loss: 2.245
[Epoch 1, Batch
                  4011 Loss: 2.243
[Epoch 1, Batch
                  4511 Loss: 2.241
[Epoch 1, Batch
                  501] Loss: 2.238
[Epoch 1, Batch
                  5511 Loss: 2.236
[Epoch 1, Batch
                  6011 Loss: 2.233
[Epoch 1, Batch
                  6511 Loss: 2.230
[Epoch 1, Batch
                  701] Loss: 2.227
[Epoch 1, Batch
                  751] Loss: 2.223
[Epoch 1, Batch
                  801] Loss: 2.220
[Epoch 1, Batch
                  851] Loss: 2.216
[Epoch 1, Batch
                  9011 Loss: 2.212
[Epoch 2, Batch
                   511 Loss: 2.122
```

```
# After retraining, set the model in evaluation mode
[2 # (Important, because we have dropout layers!)
[3 model2.eval()
```

## Defended model performance

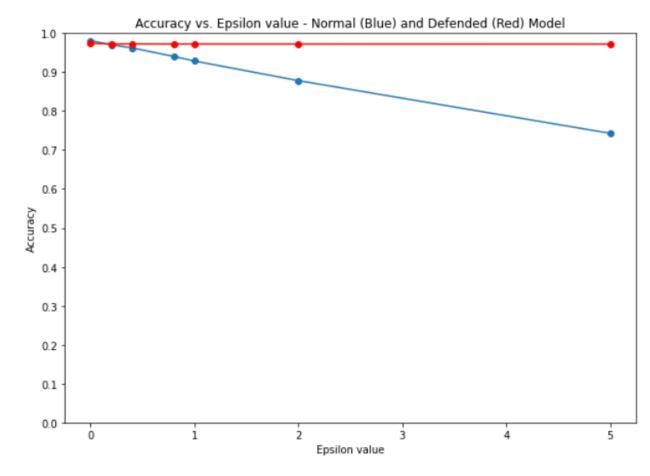
- The high temperature makes the gradients vanish.
- This means that the gradient based attack will now be unable to operate correctly on our defended model!

$$\widetilde{x} = x + \epsilon \nabla_x L(x, \theta, c)$$
But  $\nabla_x L(x, \theta, c) \approx 0$ 
Implies  $\widetilde{x} \approx x$ 

## Defended model performance

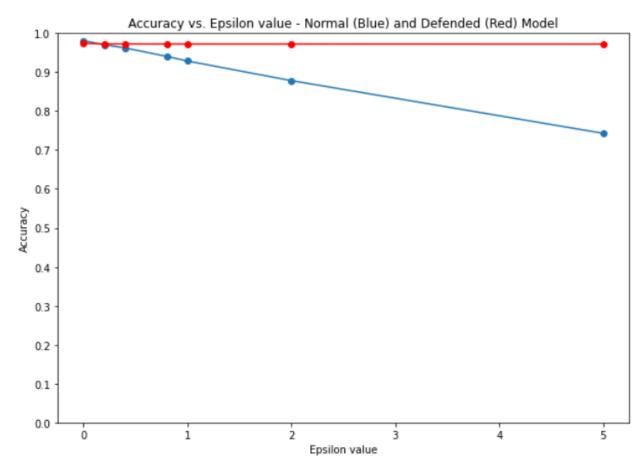
- The high temperature makes the gradients vanish.
- This means that the gradient based attack will now be unable to operate correctly on our defended model!

$$\tilde{x} = x + \epsilon \nabla_x L(x, \theta, c)$$
But  $\nabla_x L(x, \theta, c) \approx 0$ 
Implies  $\tilde{x} \approx x$ 



## Defended model performance

- The high temperature makes the gradients vanishion ••



# The current state of our defenses against white-box models

So far, defenders have only two options to defend against gradientbased attacks.

- 1. Either train specifically in anticipation for these attacks (and we have seen it works quite well on FGSM attacks).
- 2. Or make the gradients vanish to mess with the attackers (and we have seen it works quite well on gradient-based attacks).

# The current state of our defenses against white-box models

So far, defenders have only two options to defend against gradientbased attacks.

- 1. Either train specifically in anticipation for these attacks (and we have seen it works quite well on FGSM attacks).
- 2. Or make the gradients vanish to mess with the attackers (and we have seen it works quite well on gradient-based attacks).

That should be good enough, right?

# The current state of our defenses against white-box models

So far, defenders have only two options to defend against gradientbased attacks.

- 1. Either train specifically in anticipation for these attacks (and we have seen it works quite well on FGSM attacks).
- 2. Or make the gradients vanish to mess with the attackers (and we have seen it works quite well on gradient-based attacks).

That should be good enough, right?

I mean, there is now way for attackers to come up with something else, to attack my model, right?

# Carlini-Wagner attack (targeted, iterated, white-box)

 The Carlini-Wagner attack is a targeted, (one-shot or) iterated, white-box attack [Carlini2017].

# Carlini-Wagner attack (targeted, iterated, white-box)

- The Carlini-Wagner attack is a targeted, (one-shot or) iterated, white-box attack [Carlini2017].
- It uses some of the model properties to perform create adversarial samples.
  - It does not use the gradients...
  - It uses the **logits** of the model instead.
  - This means that the defensive distillation or the arms race defense will not work against this attack.

# Carlini-Wagner attack (targeted, iterated, white-box)

- The Carlini-Wagner attack is a targeted, (one-shot or) iterated, white-box attack [Carlini2017].
- It uses some of the model properties to perform create adversarial samples.
  - It does not use the gradients...
  - It uses the **logits** of the model instead.
  - This means that the defensive distillation or the arms race defense will not work against this attack.

- This attack generates samples by solving a "simple" optimization problem.
- It also ensures **plausibility** by controlling a norm  $\|\tilde{x} x\|$  between the generated sample and the original image.

$$\min_{u} (\|u - x\|_{2} + \alpha \max(d(u), 0))$$

$$with d(u) = \max_{t \neq \tilde{c}} (f_{t}(u) - f_{\tilde{c}}(u))$$

$$\min_{u} (\|u - x\|_{2} + \alpha \max(d(u), 0))$$

$$with d(u) = \max_{t \neq \tilde{c}} (f_{t}(u) - f_{\tilde{c}}(u))$$

- The objective to generate the best image u, which minimizes our objective function.
- The first part penalizes images u, which are far from the original image x.
   (this encourages plausibility).
- The second part is a positive non-zero value if the image u does not have the target label, and zero otherwise.

$$\min_{u} (\|u - x\|_{2} + \alpha \max(d(u), 0))$$

$$with d(u) = \max_{t \neq \tilde{c}} (f_{t}(u) - f_{\tilde{c}}(u))$$

- Indeed, we will have d(u) > 0 if and only if
- there exists a class  $t \neq \tilde{c}$ , such that  $f_t(u) f_{\tilde{c}}(u) > 0$
- Equivalently, this means that image u is not of target class  $\tilde{c}$ .

```
\min_{u} (\|u - x\|_{2} + \alpha \max(d(u), 0))
with d(u) = \max_{t \neq \tilde{c}} (f_{t}(u) - f_{\tilde{c}}(u))
```

- The first part penalizes images u, which are far from the original image x.
   (this encourages plausibility).
- The second part is non-zero if the image u does not have the target label. (this encourages efficacy).
- Both important aspects are covered, and  $\alpha$  can be arbitrarily set to decide on the importance of each aspect.

### Roughly equivalent formulation #1:

generate a sample  $\tilde{x}$  with class  $\tilde{c}$ , from a sample x of class c. Do so by solving the **constrained** optimization problem below.

# Roughly equivalent formulation #2: generate a sample $\tilde{x}$ with class $\tilde{c}$ , fro

$$\min_{u} \left( max(d(u), 0) \right)$$

with 
$$d(u) = \max_{t \neq \tilde{c}} (f_t(u) - f_{\tilde{c}}(u))$$

$$and ||u - x||_2 \le \alpha$$

$$\min_{u} \left( max(d(u), 0) \right)$$

with 
$$d(u) = \max_{t \neq \tilde{c}} (f_t(u) - f_{\tilde{c}}(u))$$

$$and ||u - x||_{\infty} \leq \alpha$$

### Roughly equivalent formulation #1:

generate a sample  $\tilde{x}$  with class  $\tilde{c}$ , from a sample x of class c. Do so by solving the **constrained** optimization problem below.

### Roughly equivalent formulation #2:

generate a sample  $\tilde{x}$  with class  $\tilde{c}$ , from a sample x of class c. Do so by solving the **constrained** optimization problem below.

$$\min_{u} \left( max(d(u), 0) \right)$$

$$\min_{u} \left( max(d(u), 0) \right)$$

wit

**Note:** Solving these optimization problems can prove to be challenging. Implementation is not necessarily difficult, but cumbersome.

We leave the implementation of these methods out of the scope of this class (Have a look at the papers with code website!)

# Interested in implementing advanced algos? Look them up on PapersWithCode first!

#### Towards Evaluating the Robustness of Neural Networks

Edit social preview

16 Aug 2016 • Nicholas Carlini • David Wagner

Neural networks provide state-of-the-art results for most machine learning tasks. Unfortunately, neural networks are vulnerable to adversarial examples: given an input x and any target classification t, it is possible to find a new input x' that is similar to x but classified as t... (read more)





Code		☑ Edit
🗘 carlini/nn_robust_attacks	<b>★</b> 560	1 TensorFlow
• MadryLab/cifar10_challenge	★ 315	1 TensorFlow
♠ LeMinhThong/blackbox-attack	★ 51	O PyTorch
• kkew3/pytorch-cw2	★ 38	O PyTorch
nspire-group/advml-traffic-sign	<b>★</b> 16	

https://paperswithcode.com/paper/ /towards-evaluating-therobustness-of-neural

See all 22 implementations

## Black-boxing your model for defense

### **Definition (Black-boxing defense):**

The **black-boxing defense** refers to the concept of hiding your model parameters to prevent attackers from accessing and using some of these parameters (neither weights, gradients nor logits) in their attacks.

## Black-boxing your model for defense

## **Definition (Black-boxing defense):**

The black-boxing defense refers to the concept of hiding your model parameters to prevent attackers from accessing and using some of these parameters (neither weights, gradients nor logits) in their attacks.

The only thing attackers can do is submit inputs to and get outputs from the model.



## Black-boxing your model for defense

## **Definition (Black-boxing defense):**

The black-boxing defense refers to the concept of hiding your model parameters to prevent attackers from accessing and using some of these parameters (neither weights, gradients nor logits) in their attacks.

The only thing attackers can do is submit inputs to and get outputs from the model.



### **Definition (the surrogate attack):**

The surrogate attack (from [Papernot2017]) is a black-box attack.

Its objective is to recreate a copy g of the model f being attacked.

Then, produce attack samples using your white-box attacks we mentioned earlier on your recreated model g. If they work on g, use them on the model f.

### **Definition (the surrogate attack):**

The surrogate attack (from [Papernot2017]) is a black-box attack.

Its objective is to recreate a copy g of the model f being attacked.

Then, produce attack samples using your white-box attacks we mentioned earlier on your recreated model g. If they work on g, use them on the model f.

### **Step 1:** training a surrogate model *g*

- Use a typical dataset, but do not use the ground truth labels. Instead use the labels produced by the predictions of model f.
- Train the surrogate model g to match the predictions of the original model f.
- A good loss function would be:

$$L(g(x), f) = \sum_{c} -f_{c}(x)\log(g_{c}(x))$$

## **Definition (the surrogate attack):**

The surrogate attack (from [Papernot2017]) is a black-box attack.

Its objective is to recreate a copy g of the model f being attacked.

Then, produce attack samples using your white-box attacks we mentioned earlier on your recreated model g. If they work on g, use them on the model f.

Step 2: use white-box attacks on your surrogate model g.

- For instance, attack your surrogate model g with FGSM.

  If the attack sample  $\tilde{x}$  manages to fool the surrogate model g, then odds are it will probably work on the original model f as well.
- Ultimately, this depends on how close you managed to make your surrogate model g similar to the original model f.

Definition (the surrogate attack):
The surrogate attack (from
[Papernot2017]) is a black-box

Step 2: use white-box attacks on your model g.

• For instance, attack your model gwith EGSM. If the attack sample  $\tilde{x}$ 

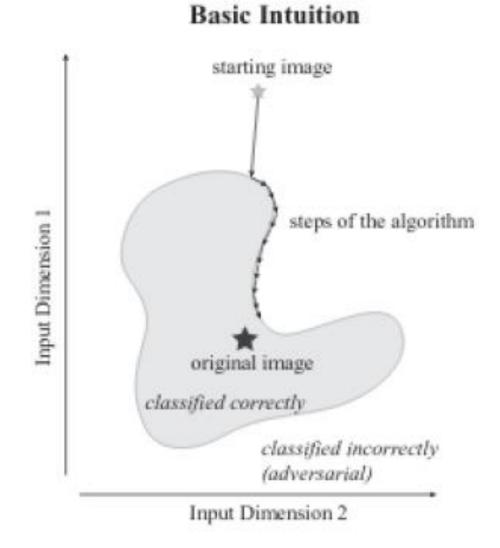
**Note:** Implementation is not necessarily difficult, but has to be done cautiously. Its guided implementation might be part of the next homework! More on this later.

If you are curious, training a surrogate model and attacking it was a Homework in 2023. See attached folder for Homework Notebook (and solutions, maybe)!

## **Definition (the boundary attack):**

The **boundary attack** (from [Brendel2018]) is a **black-box** type of attack, which only requires access to the inputs and outputs of the model under attack f.

It attempts to create an image, which will look plausible, but will be misclassified. It does so by walking on the boundary of the correct prediction region, and attempts to minimize  $\|\tilde{x} - x\|$ .



**Step 1:** Start with a nonadversarial image x (does not have to belong in the original dataset), which is correctly predicted as c.

Make another image  $x_0$ , by (heavily) noising your original image x.

This image  $x_0$  should be misclassified.

**Step 2:** modify your image  $x_n$  for instance by using random noising, with low amplitude.

If the new image  $x_{n+1}$  is incorrectly classified and verifies  $||x_{n+1} - x|| \le ||x_n - x||$ , then keep  $x_{n+1}$ .

**Step 2:** modify your image  $x_n$  for instance by using random noising, with low amplitude.

If the new image  $x_{n+1}$  is incorrectly classified and verifies  $||x_{n+1} - x|| \le ||x_n - x||$ , then keep  $x_{n+1}$ .

Otherwise reuse the previous image, i.e.  $x_{n+1} = x_n$ .

**Step 2:** modify your image  $x_n$  for instance by using random noising, with low amplitude.

If the new image  $x_{n+1}$  is incorrectly classified and verifies  $||x_{n+1} - x|| \le ||x_n - x||$ , then keep  $x_{n+1}$ .

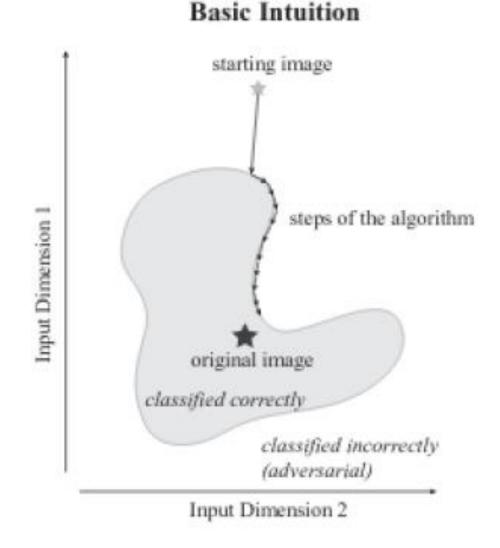
Otherwise reuse the previous image, i.e.  $x_{n+1} = x_n$ .

**Step 3:** repeat step 2, until a maximal number of iterations *N* is reached.

## **Definition (the boundary attack):**

The **boundary attack** (from [Brendel2018]) is a **black-box** type of attack, which only requires access to the inputs and outputs of the model under attack f.

It attempts to create an image, which will look plausible, but will be misclassified. It does so by walking on the boundary of the correct prediction region, and attempts to minimize  $\|\tilde{x} - x\|$ 



## The boundary attack

#### **Definition (the boundary attack):**

The **boundary attack** (from [Brendel2018]) is a **black-box** type of attack, which only requires access to the inputs and outputs of the model under attack f.

It attempts to create an image, which will look plausible, but will be misclassified. It does so by walking on the boundary of the correct prediction region, and attempts to minimize  $\|\tilde{x} - x\|$ 

**Step 3:** repeat step 2, until a maximal number of iterations *N* is reached.

## The boundary attack

#### **Definition (the boundary attack):**

The **boundary attack** (from [Brendel2018]) is a **black-box** type of attack, which only requires access to the inputs and outputs of the model under attack f.

It attempts to create an image, which will look plausible, but will be misclassified. It does so by walking on the boundary of the correct prediction region, and attempts to minimize  $\|\tilde{x} - x\|$ 

#### **Additional notes**

- You can progressively decrease the noise amplitude when generating  $x_{n+1}$  from  $x_n$  (in a similar fashion as with the learning rate scheduling).
- Add an extra condition, being that your  $x_n$  must be of a certain target class  $\tilde{c}$  to make it a targeted attack.

## The boundary attack

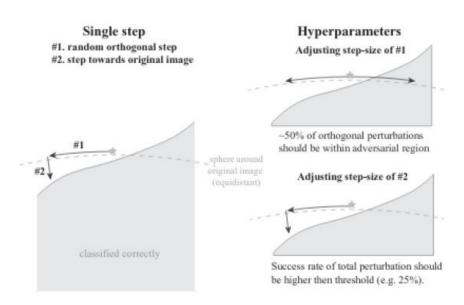
#### **Definition (the boundary attack):**

The **boundary attack** (from [Brendel2018]) is a **black-box** type of attack, which only requires access to the inputs and outputs of the model under attack f.

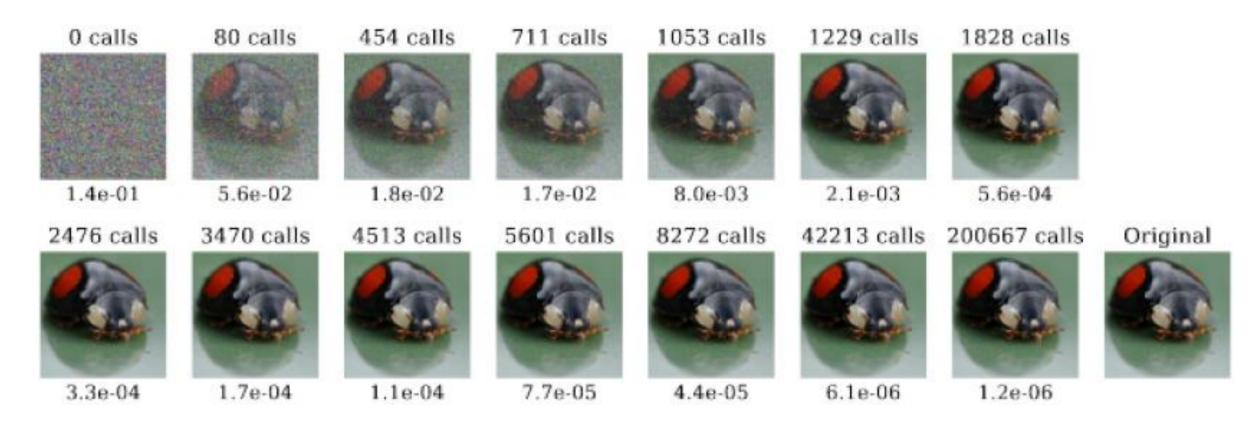
It attempts to create an image, which will look plausible, but will be misclassified. It does so by walking on the boundary of the correct prediction region, and attempts to minimize  $\|\tilde{x} - x\|$ 

#### **Additional notes**

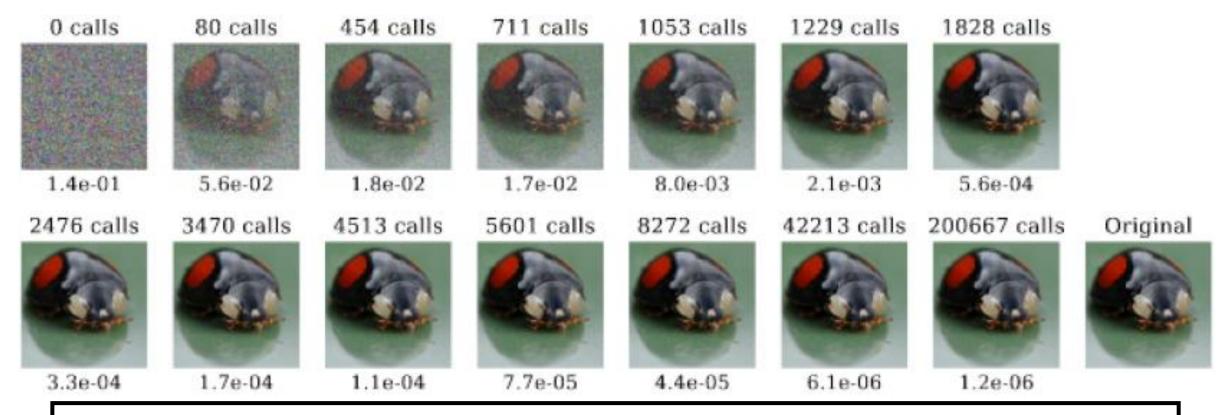
• More advanced methods may even try and guess the local geometry of the boundary to make better iterations on the  $x_n$  images.



## The boundary attack in action



## The boundary attack in action



**Note:** Implementation is not necessarily difficult, but cumbersome. We leave the implementation of these methods out of the scope of this class (Have a look at the papers with code website!)

Restricted

## Black-boxing your model for defense (v2.0!).

## Definition (Black-boxing defense, version 2.0!):

The **black-boxing defense** refers to the concept of hiding your model parameters to prevent attackers from accessing and using some of these parameters (neither weights, gradients nor logits) in their attacks.

The only thing attackers can do is submit inputs and get outputs from the model.

To make the model as black as possible, we can forbid the attacker from even ACCESSING THE MODEL!

## Defending by ensemble-ing your model

#### **Definition (The ensemble defense):**

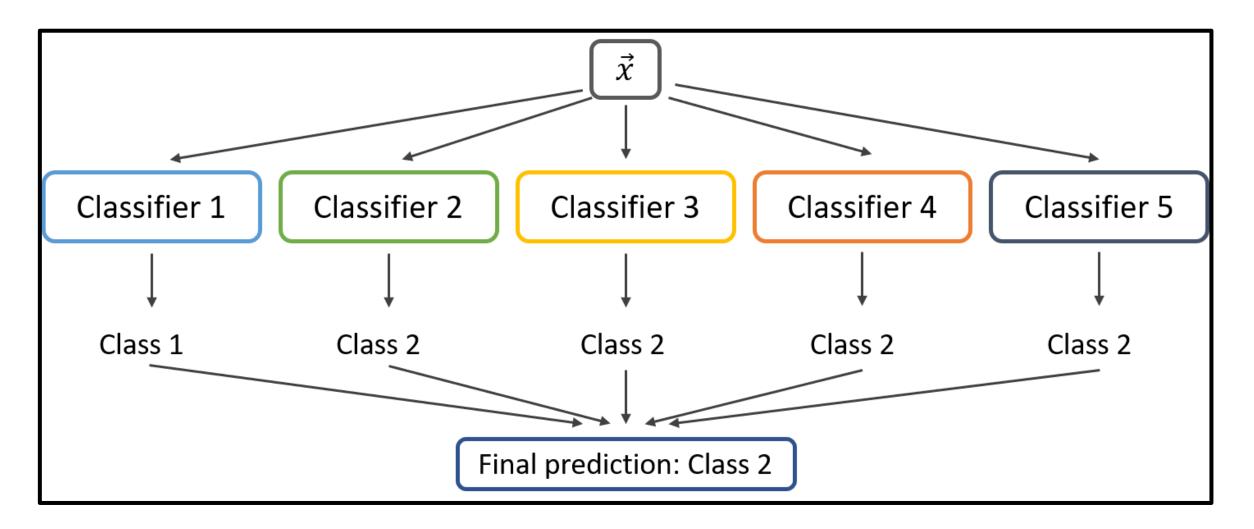
The **ensemble defense** refers to the concept of using multiple models to prevent attackers from making your classifier malfunction.

Each model is trained with a different initialization, hence leading to different weights, gradients, etc.

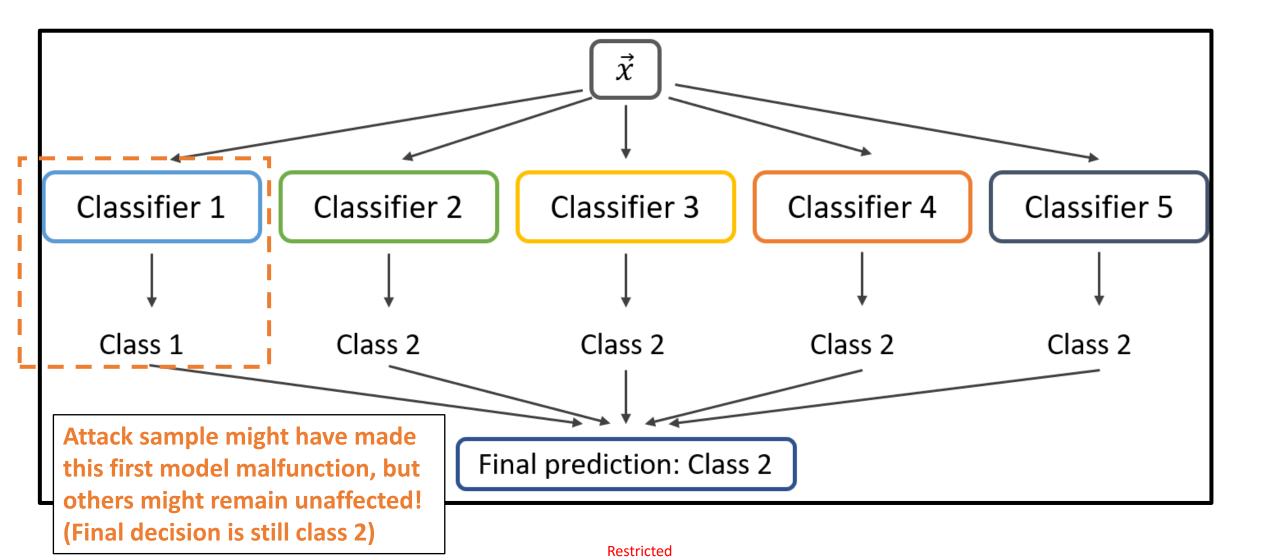
During testing, each image is passed to each different model, and a list of predictions is obtained (one for each model). The label, which appears the most often is the one returned by our ensemble classifier.

This makes the life of attackers extra difficult, as they have to successfully attack multiple models, with the same sample to make the prediction wrong.

## Defending by ensemble-ing your model



## Defending by ensemble-ing your model



#### Maximal defense

- Nothing more defenders can really do at this point. They have kept their model secret and "ensembled" it.
- The attackers only know that the defender has a model, which is trying to accomplish a certain task, but have no access to it.
- Defenders have even used multiple instances of the model to get an ensemble classifier.
- This covers for attacks that would make one model malfunction.

#### Attackers obviously lost, right?

## On the transferability of attacks

# Attackers obviously lost, right? Well... Yes and no.

- While it may seem very difficult to make an **ensemble**, **hidden** model malfunction...
- Recent papers have shown that attacks might be transferable [Liu2017].

- **Note:** this is what we exploited for our **surrogate attack**, in the first place.
- Unfortunately, this means an attack, which makes a certain facial recognition algorithm fail, has great chances to make another mode, even different, fail as well.
- And even more true for models within a same ensemble.

## Conclusion (W5S3)

- Training and attacking a model seem to be the two faces of a same coin.
- Being able to do one, unfortunately exposes you to the second one.
- Both attackers and defenders have many options up their sleeve. But attackers seem to have a clear advantage.

- Attackers are able to exploit
  - Intrinsic information from models.
  - But more importantly, fundamental limits of neural networks.
- It is a very active research field, with many more advanced concepts, for obvious reasons, as any "sensitive" application will require some kind of defense.

- [Madry2017] Madry et al., "Towards Deep Learning Models Resistant to Adversarial Attacks", 2017 <a href="https://arxiv.org/abs/1706.06083">https://arxiv.org/abs/1706.06083</a>
- [Papernot2015] Papernot et al., "Distillation as a Defense to Adversarial Perturbations against Deep Neural Networks", 2015 <a href="https://arxiv.org/abs/1511.04508">https://arxiv.org/abs/1511.04508</a>
- [Dong2017] Dong et al., "Boosting Adversarial Attacks with Momentum", 2017. <a href="https://arxiv.org/abs/1710.06081">https://arxiv.org/abs/1710.06081</a>
- [Carlini2017] Carlini and Wagner, "Towards Evaluating the Robustness of Neural Networks", 2017. https://arxiv.org/abs/1608.04644

- [Papernot2017] Papernot et al., "Practical Black-Box Attacks against Machine Learning", 2017.
  - https://arxiv.org/abs/1602.02697
- [Brendel2018] Brendel et al., "Decision-Based Adversarial Attacks: Reliable Attacks Against Black-Box Machine Learning Models", 2018. https://arxiv.org/abs/1712.04248
- [Liu2017] Liu et al., "Delving into Transferable Adversarial Examples and Blackbox Attacks", 2017.
  - https://arxiv.org/abs/1611.02770

## Interested in implementing advanced algos? Look them up on PapersWithCode first!

#### Towards Evaluating the Robustness of Neural Networks

Edit social preview

16 Aug 2016 • Nicholas Carlini • David Wagner

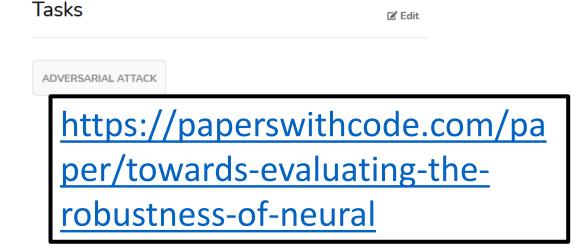
Neural networks provide state-of-the-art results for most machine learning tasks. Unfortunately, neural networks are vulnerable to adversarial examples: given an input x and any target classification t, it is possible to find a new input x' that is similar to x but classified as t... (read more)



 $\sim$  1



Code		☑ Edit
• carlini/nn_robust_attacks	★ 560	TensorFlow
MadryLab/cifar10_challenge	★ 315	1 TensorFlow
♠ LeMinhThong/blackbox-attack	★ 51	O PyTorch
• kkew3/pytorch-cw2	★ 38	O PyTorch
nspire-group/advml-traffic-sign	<b>★</b> 16	
See all 22 implementations		



Out of class, for those of you who are curious

 [Medium1] On the ongoing race of coming up with new attacks. <a href="https://medium.com/mlreview/the-intuition-behind-adversarial-attacks-on-neural-networks-71fdd427a33b">https://medium.com/mlreview/the-intuition-behind-adversarial-attacks-on-neural-networks-71fdd427a33b</a>

- [Medium2]On why security systems using deep learning are potentially under threat.
  - https://medium.com/@chami.soufiane/security-threats-against-machine-learning-based-systems-a-real-concern-2515115c88e4

Out of class, for those of you who are curious

• [YTB1] Generating adversarial patches against YOLOv2, a.k.a. printing patterns to fool Als and become invisible.

https://www.youtube.com/watch?v=MIbFvK2S9g8

 [Stanford] Stanford lecture, by Ian Goodfellow @ Stanford on attacks and defense mechanisms for Neural Networks (long!)

https://www.youtube.com/watch?v=ClfsB EYsVI

#### More fun stuff

- [Eykolt2018] Eykolt et al. "Robust Physical-World Attacks on Deep Learning Models", 2018.
  - Printing stickers to put on your tee-shirts to fool facial recognition systems. <a href="https://arxiv.org/abs/1707.08945">https://arxiv.org/abs/1707.08945</a>
- [Moosavi-Dezfooli2016] Moosavi-Dezfooli et al., "DeepFool: a simple and accurate method to fool deep neural networks", 2016.
   A toolbox with previously mentioned attacks and more advanced attacks. https://arxiv.org/abs/1511.04599
- [Athalye2018] Athalye et al., "Synthesizing Robust Adversarial Examples", 2018.

3D printing misclassified stuff. https://arxiv.org/abs/1707.07397

Tracking important names (Track their works and follow them on Scholar, Twitter, or whatever works for you!)

 Aleksander Madry: Professor at MIT, Director of the MIT Center for Deployable Machine Learning and a Faculty Co-Lead of the MIT AI Policy Forum.

http://madry-lab.ml/

https://people.csail.mit.edu/madry/

https://scholar.google.ch/citations?user=SupjsEUAAAAJ&hl=en

Nicolas Papernot: Assistant Professor at University of Toronto.

https://www.papernot.fr

https://scholar.google.com/citations?user=cGxq0cMAAAAJ&hl=en

Tracking important names (Track their works and follow them on Scholar, Twitter, or whatever works for you!)

Nicholas Carlini: Research Scientist at Google Brain.

<a href="https://nicholas.carlini.com">https://nicholas.carlini.com</a>
<a href="https://scholar.google.com/citations?user=q4qDvAoAAAJ&hl=en">https://scholar.google.com/citations?user=q4qDvAoAAAJ&hl=en</a>

David Wagner: Professor at UC Berkeley.

<a href="https://people.eecs.berkeley.edu/~daw/papers">https://people.eecs.berkeley.edu/~daw/papers</a>
https://scholar.google.com/citations?user=67kghxAAAAAJ&hl=en