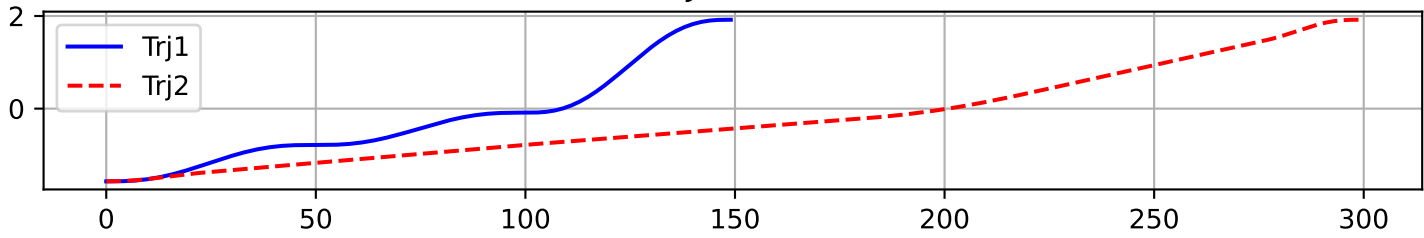
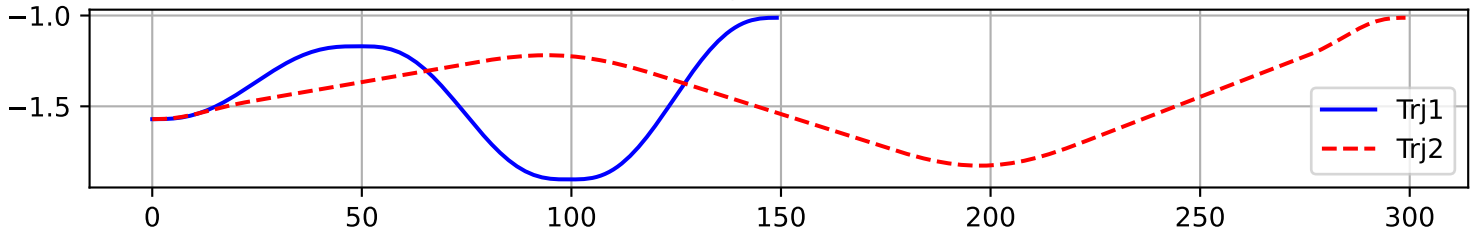


Joint trajectory

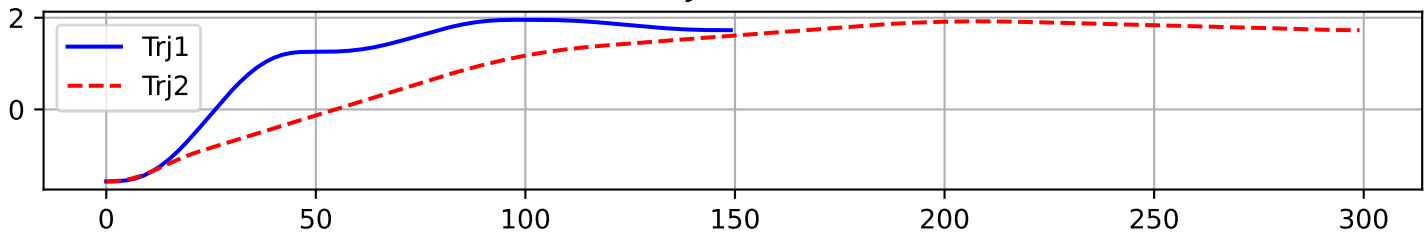
Joint1



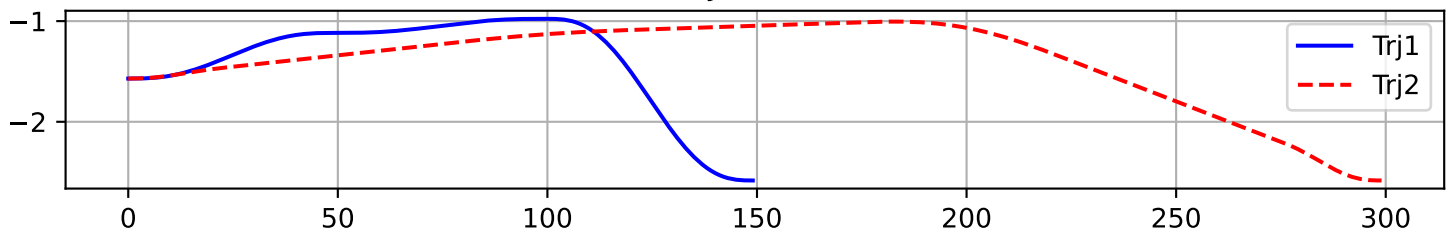
Joint2



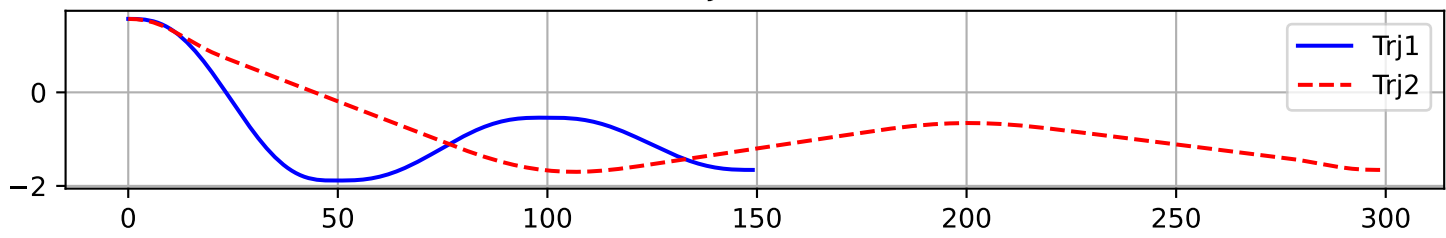
Joint3



Joint4



Joint5



Joint6

