



ALMA MATER STUDIORUM
UNIVERSITÀ DI BOLOGNA
CAMPUS DI CESENA



One-Shot Near-Field Localization with AI-Optimized Hybrid Beamformer Design

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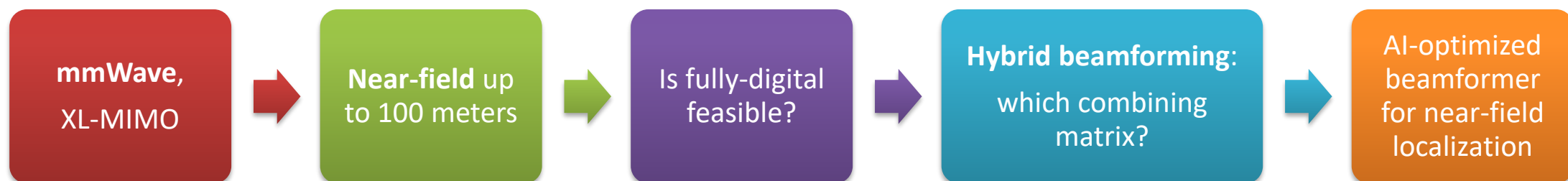
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Introduction

- Is it possible to localize a user in the near-field with a **hybrid beamformer**?
- **How many** RF chains do we need to achieve reasonable localization accuracy?
- What is the **performance gap** compared to the **fully-digital** scheme?



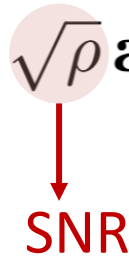
System Model

Received signal: $\mathbf{y} = \sqrt{\rho} \mathbf{a}(\theta, r) + \mathbf{n}$



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A red arrow points from the $\sqrt{\rho}$ term in the equation to the text "SNR" below it.

SNR

System Model

Received signal: $\mathbf{y} = \sqrt{\rho} \mathbf{a}(\theta, r) + \mathbf{n}$

SNR

Near-field array response vector

$$\mathbf{a}(\theta, r) = [e^{-j \frac{2\pi}{\lambda} (r_1 - r)}, \dots, e^{-j \frac{2\pi}{\lambda} (r_N - r)}]^T$$

System Model

Received signal: $\mathbf{y} = \sqrt{\rho} \mathbf{a}(\theta, r) + \mathbf{n}$

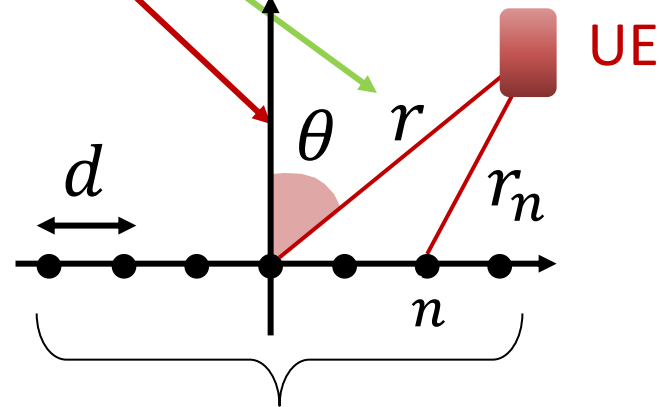
SNR

Array response vector

$$\mathbf{a}(\theta, r) = [e^{-j \frac{2\pi}{\lambda} (r_1 - r)}, \dots, e^{-j \frac{2\pi}{\lambda} (r_N - r)}]^T$$

r Distance from the center of the array

θ Angle from the center of the array



Uniform Linear Array

System Model

Received signal: $\mathbf{y} = \sqrt{\rho} \mathbf{a}(\theta, r) + \mathbf{n}$

SNR

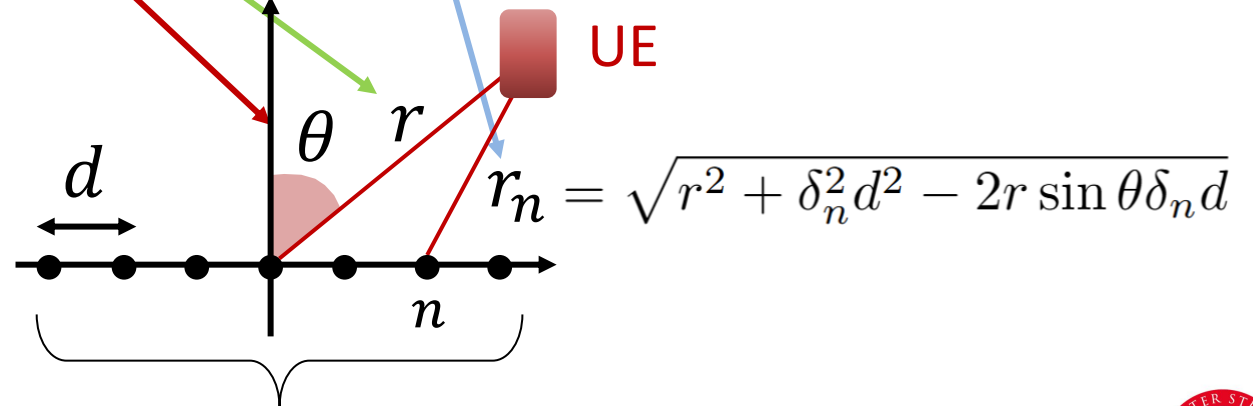
Array response vector

$$\mathbf{a}(\theta, r) = [e^{-j \frac{2\pi}{\lambda} (r_1 - r)}, \dots, e^{-j \frac{2\pi}{\lambda} (r_N - r)}]^T$$

r Distance from the center of the array

θ Angle from the center of the array

r_n Angle from the n -th antenna element

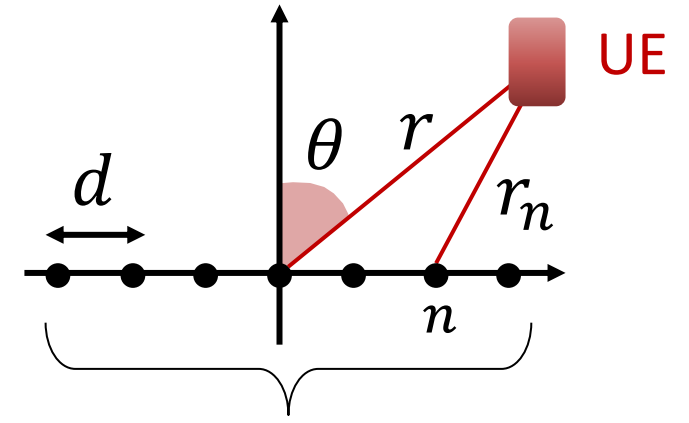


Uniform Linear Array

System Model

Received signal: $\mathbf{y} = \sqrt{\rho} \mathbf{a}(\theta, r) + \mathbf{n}$

Combined signal: $\bar{\mathbf{y}} = \mathbf{V}\mathbf{y} = \sqrt{\rho} \mathbf{V}\mathbf{a}(\theta, r) + \mathbf{V}\mathbf{n}$

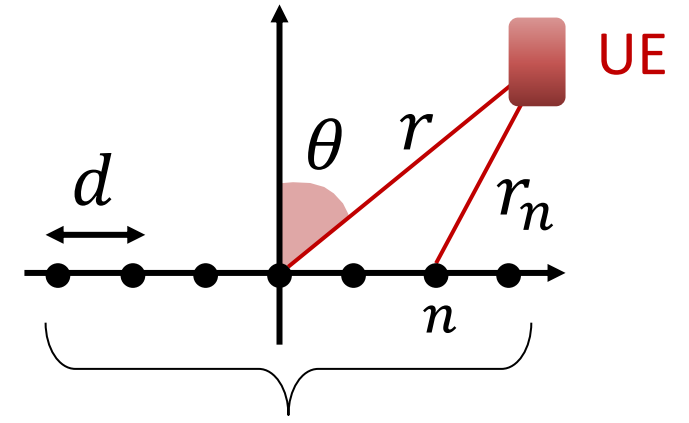


Uniform Linear Array

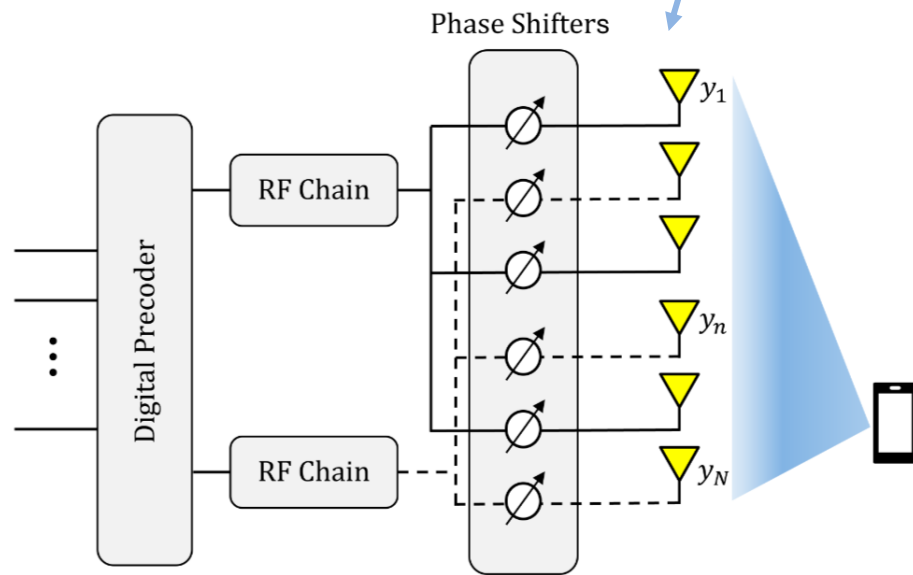
System Model

Received signal: $\mathbf{y} = \sqrt{\rho} \mathbf{a}(\theta, r) + \mathbf{n}$

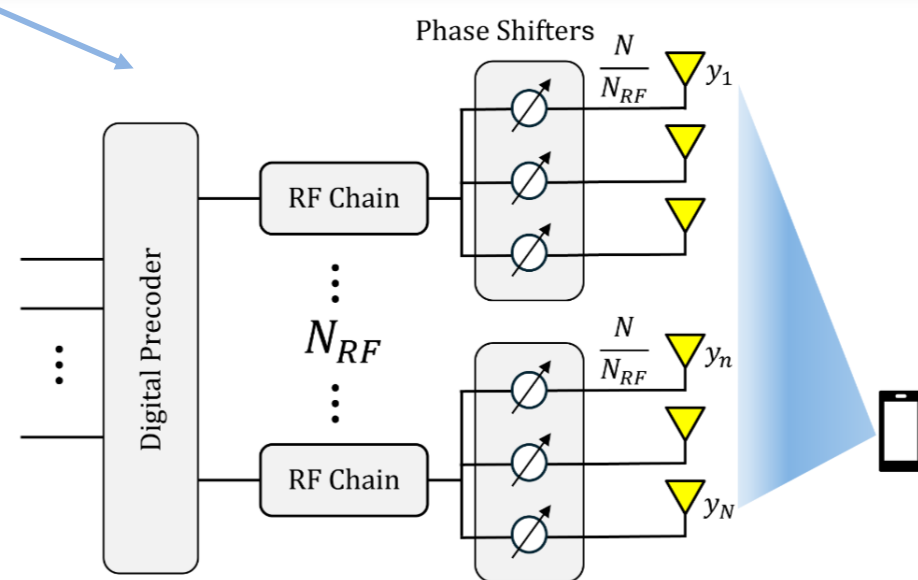
Combined signal: $\bar{\mathbf{y}} = \mathbf{V} \mathbf{y} = \sqrt{\rho} \mathbf{V} \mathbf{a}(\theta, r) + \mathbf{V} \mathbf{n}$



Uniform Linear Array



(b) Inter-connected



(a) Sub-array



Near-Field Localization with Hybrid Beamforming

Methodology

The analog combiner phase shifters are tuned through a set of **constrained** learnable parameters.

Then, a localizing network maps the features into range and angle.

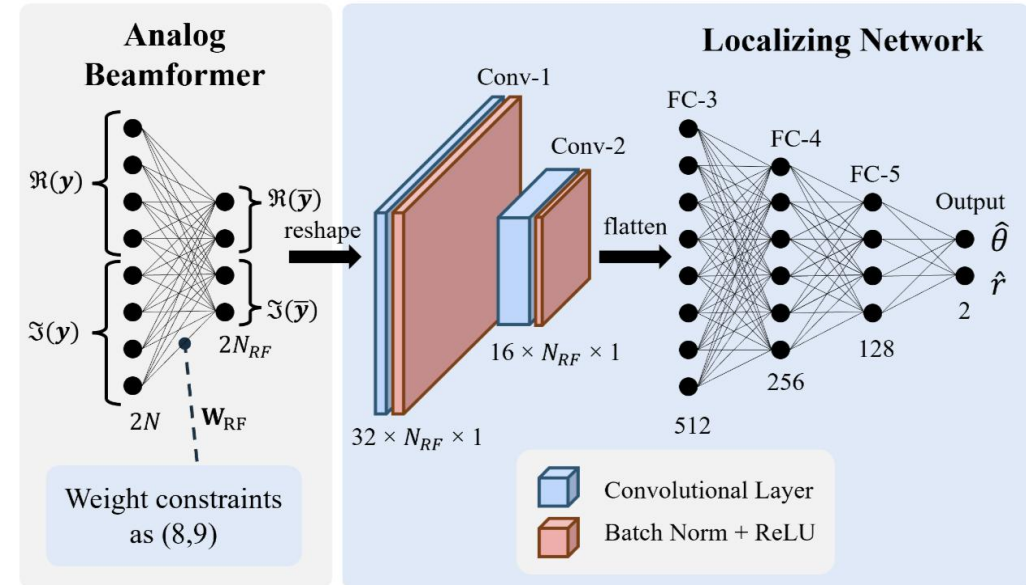


Fig. 2: Structure of the developed DNN, divided into two parts: analog beamformer and localizing function.

Near-Field Localization with Hybrid Beamforming

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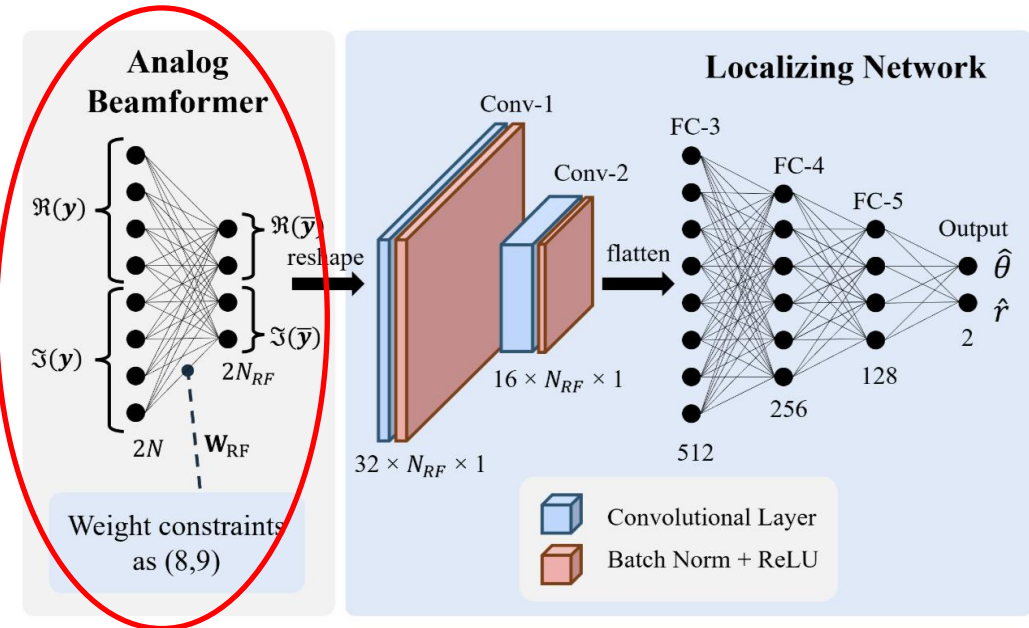
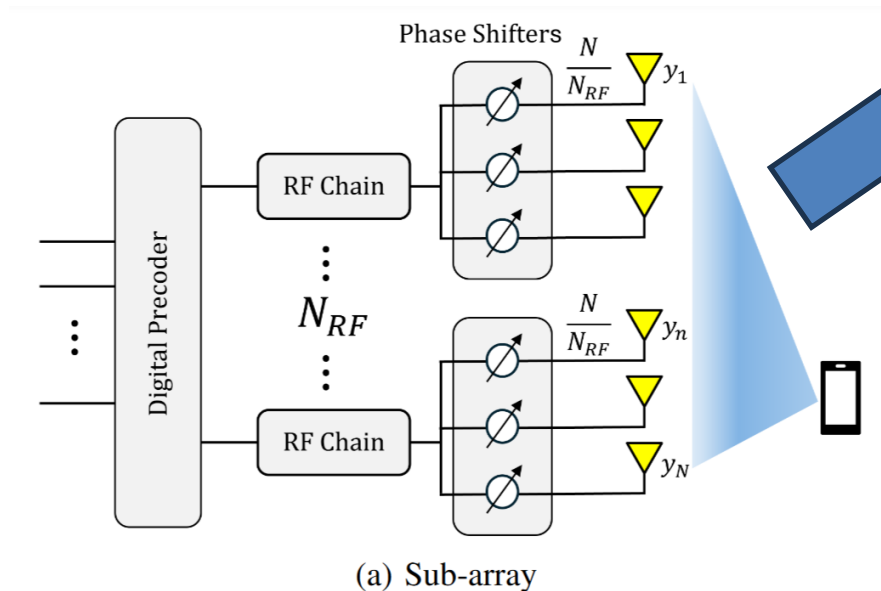


Fig. 2: Structure of the developed DNN, divided into two parts: analog beamformer and localizing function.

Near-Field Localization with Hybrid Beamforming

Objective function: find the optimal weights and biases to minimize the position error.

$$(\widetilde{\mathbf{W}}, \widetilde{\mathbf{b}}) = \arg \min_{\mathbf{W}, \mathbf{b}} \mathbb{E} \left\{ \left\| \gamma^{(i)} - f^{(\text{train})}(\mathbf{y}^{(i)}) \right\|_2^2 \right\}$$

Weight constraints ensure consistency with the hybrid beamforming structure.

$$f^{(\text{train})}(\mathbf{y}^{(i)}) = f^{(\text{out})}(\dots(f^{(1)}(\mathbf{b}^{(\text{in})} + \mathbf{W}^{(\text{in})} \mathcal{F}(\mathbf{y}^{(i)}))))),$$

$$\mathbf{W}^{(\text{in})} = \begin{bmatrix} \mathbf{W}_1^{(\text{in})} - \mathbf{W}_2^{(\text{in})} \\ \mathbf{W}_2^{(\text{in})} \mathbf{W}_1^{(\text{in})} \end{bmatrix} \quad (8)$$

$$\left(\left[\mathbf{W}_1^{(\text{in})} \right]_{m,n} \right)^2 + \left(\left[\mathbf{W}_2^{(\text{in})} \right]_{m,n} \right)^2 = \frac{1}{N}, \quad (9)$$

$$\forall n \in \{1, \dots, N\}, \forall m \in \{1, \dots, M\}$$

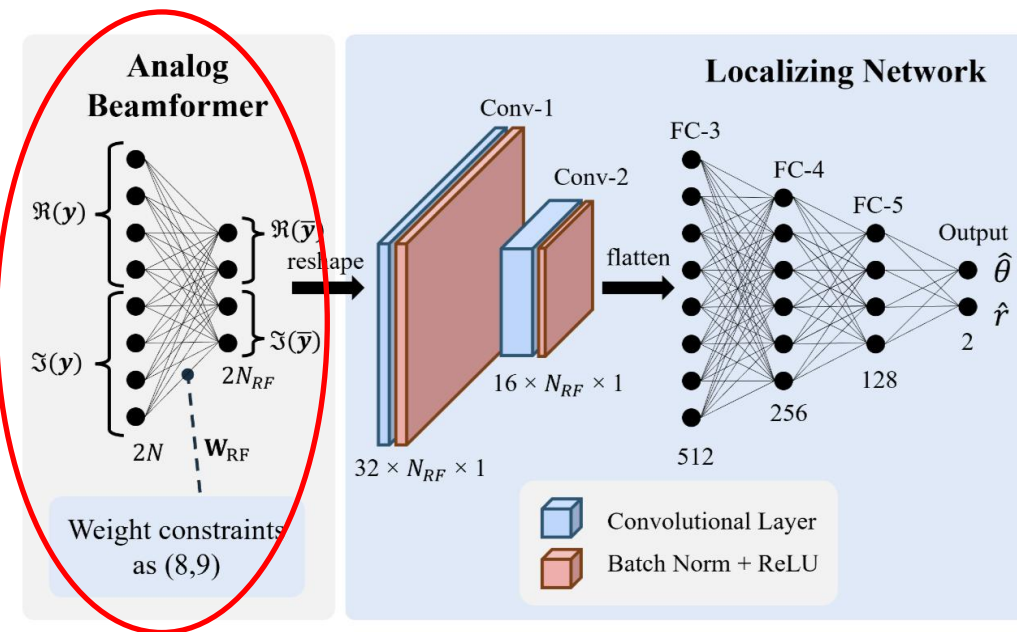


Fig. 2: Structure of the developed DNN, divided into two parts: analog beamformer and localizing function.

Numerical Results

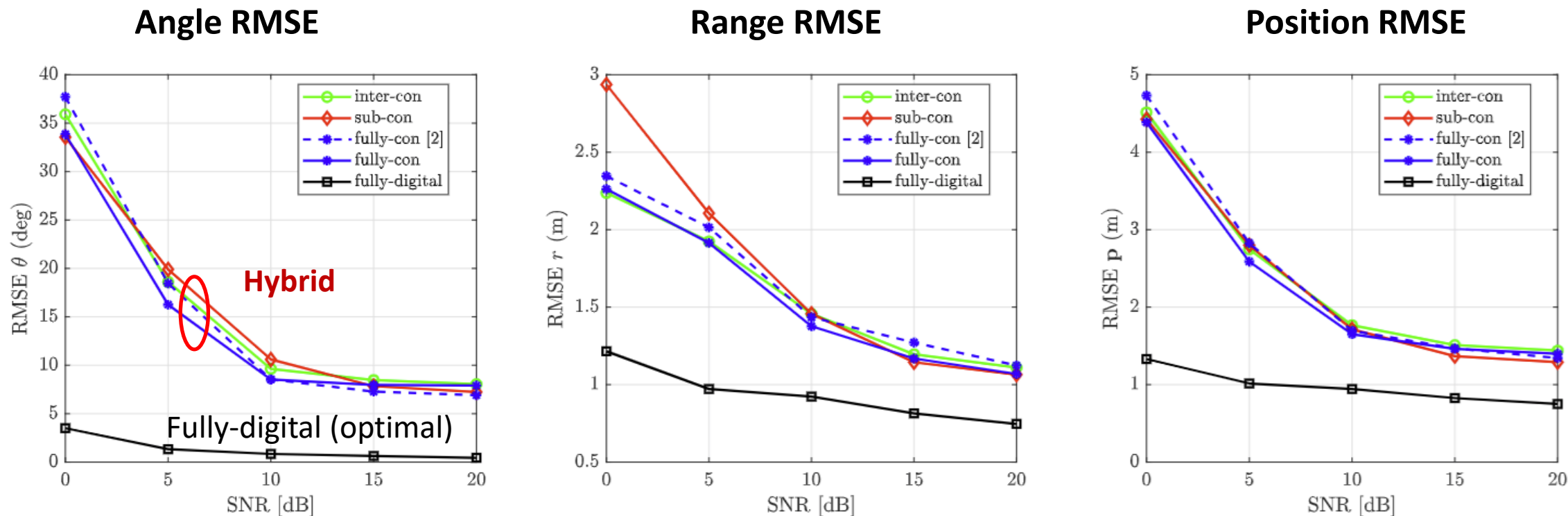
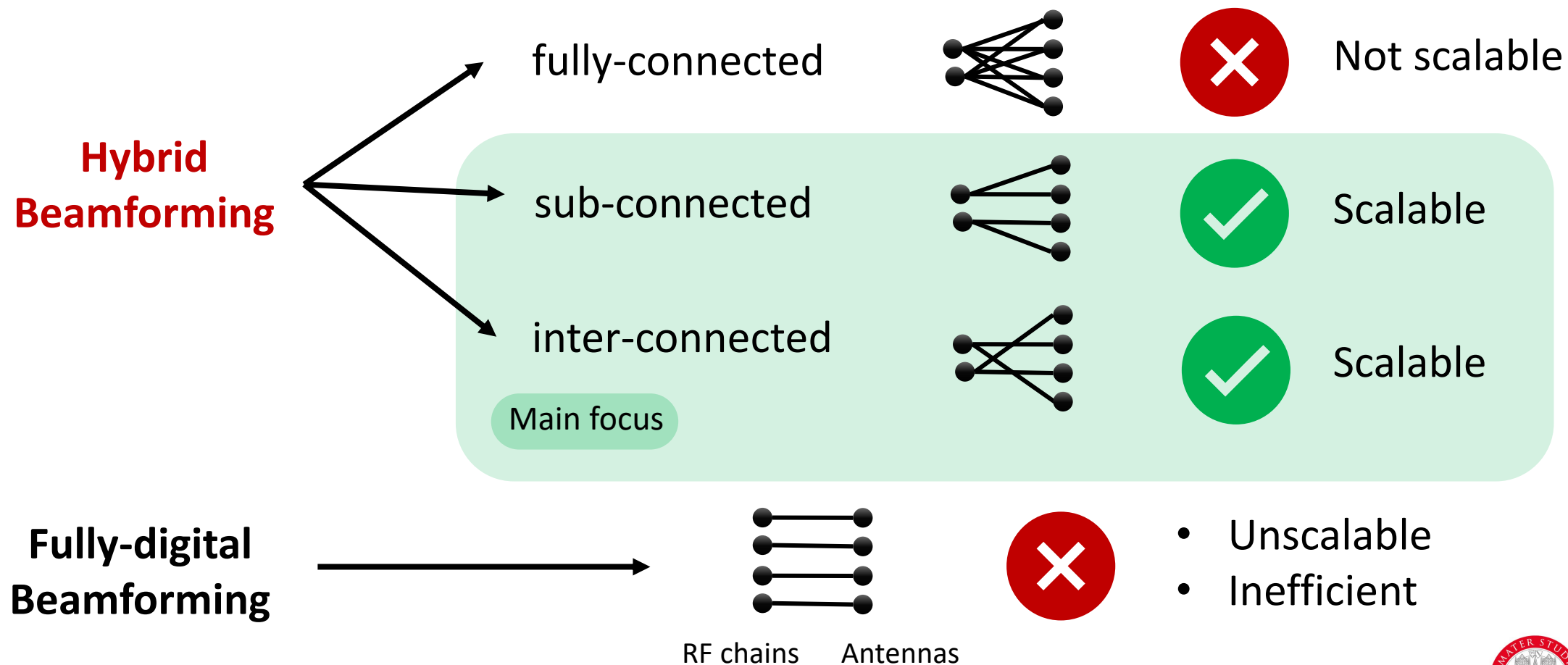


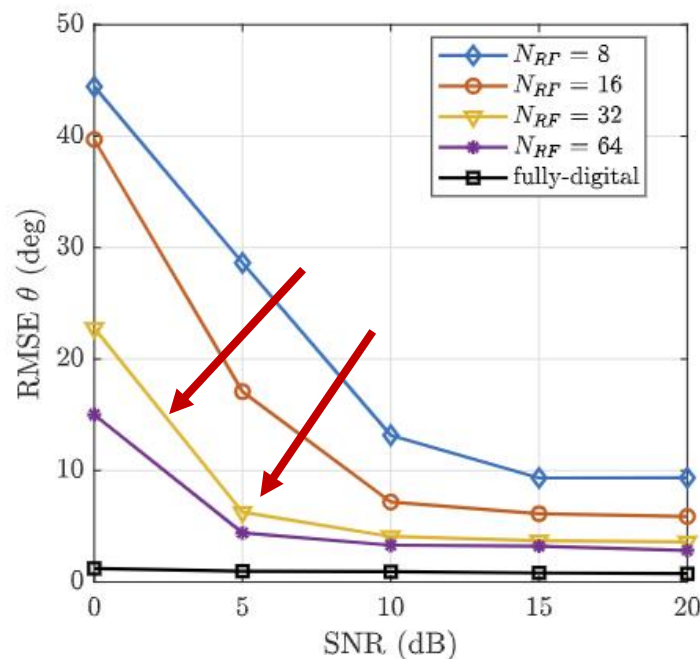
Fig. 3: RMSE of angle, range, and position versus SNR with different hybrid beamforming configurations, when $M = 16$ and $N = 128$.

Numerical Results

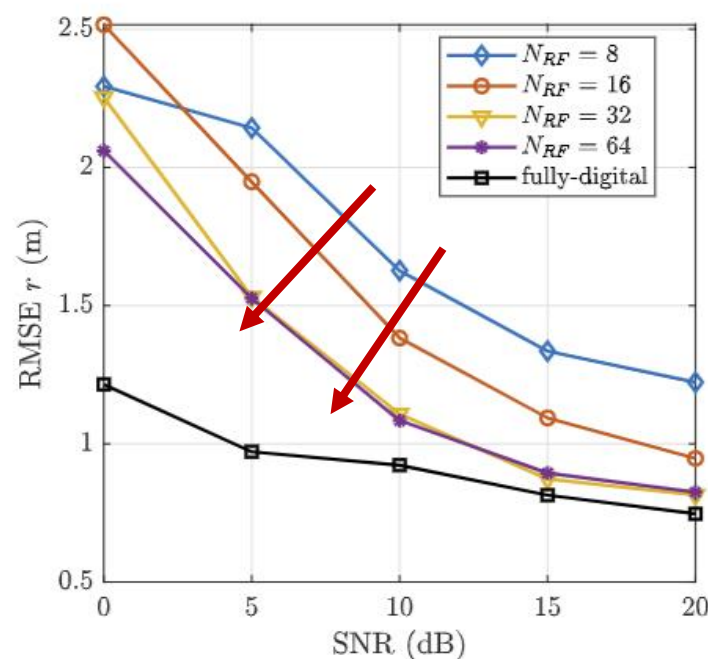


Numerical Results

Angle RMSE



Range RMSE



Position RMSE

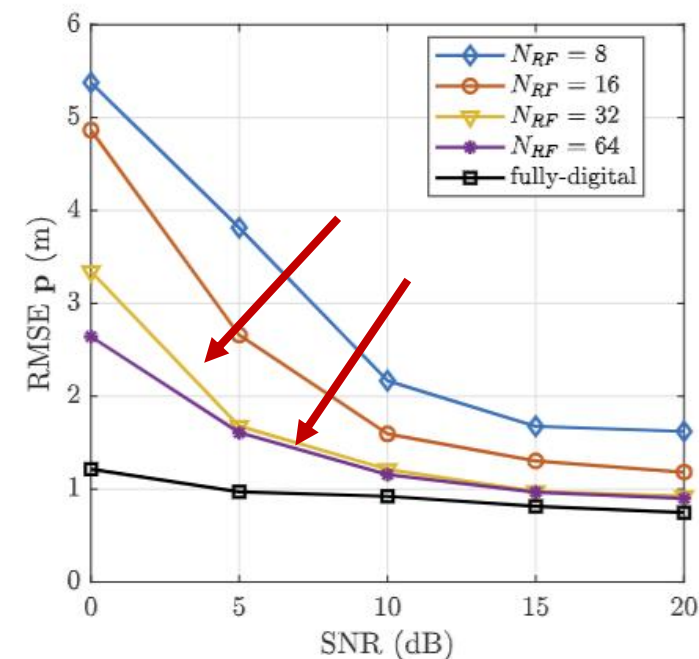


Fig. 4: RMSE of angle, range, and position versus SNR when the number of RF chains varies in a sub-array beamformer configuration with $M = 16$ and $N = 128$.

Numerical Results

Is the proposed scheme robust to **multipath effects**?

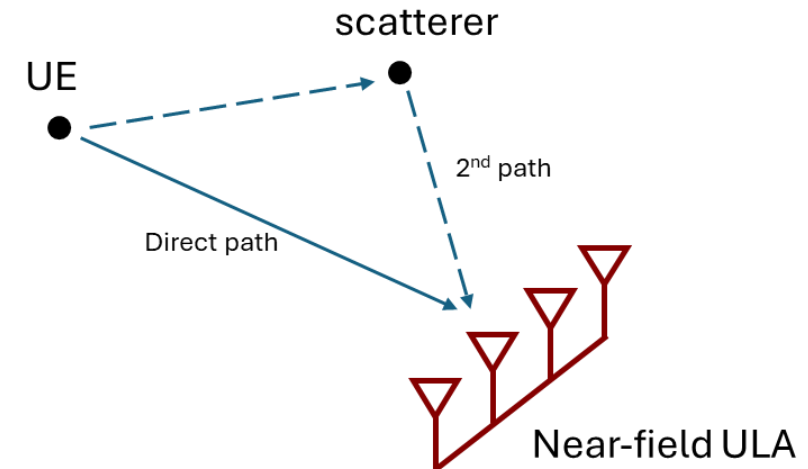
Hypothesis:

- A **point-like scatterer** is randomly placed in the strong near-field region of the ULA

Objective:

- **Localize** both the **user** and a **scatterer** in a single snapshot

$$\begin{cases} \mathbf{h}_{\text{LoS}} = \sqrt{\rho} \mathbf{a}(\theta, r) \\ \mathbf{h}_{\text{NLoS}} = \sum_{i=1}^P \sqrt{\rho_i} e^{j\phi_i} \mathbf{a}(\theta_i, r_i) \end{cases}$$



Numerical Results

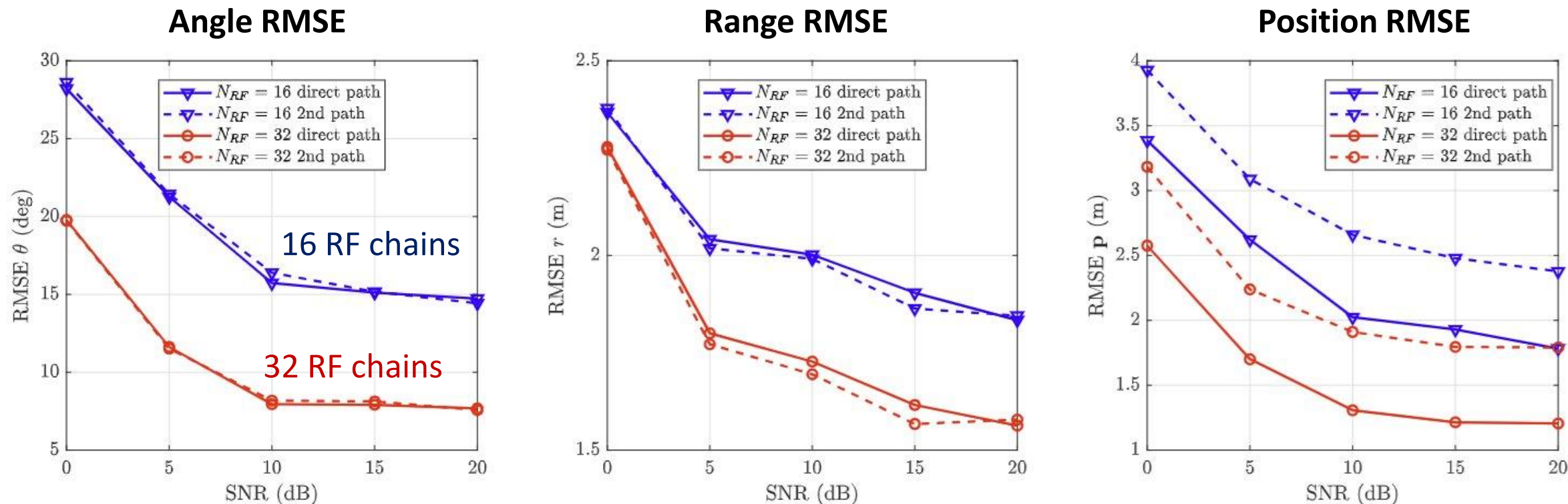


Fig. 5: RMSE of angle, range, and position versus SNR when the number of RF chains varies in a sub-array configuration with multipath.

Conclusions

- The proposed CNN-based framework achieves sub-meter localization accuracy from a single snapshot.
- It reduces phase shifter requirements by a factor of M compared to fully-connected architectures, improving scalability.
- Robustness against multipath effects.



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Thanks for your attention!

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