oundations

Lecture 8: Performance Evaluation of MPI applications



2020-2021 Stefano Cozzini

"Foundation of HPC" course

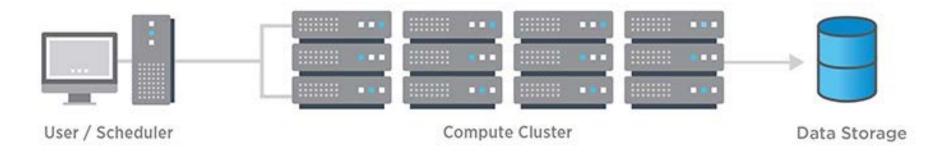
DATA SCIENCE & SCIENTIFIC COMPUTING

Agenda

- Network basic for parallel architecture
- Network basic performance characteristics
- Discussion of the Jacoby 3D solver

Recap on HPC architecture

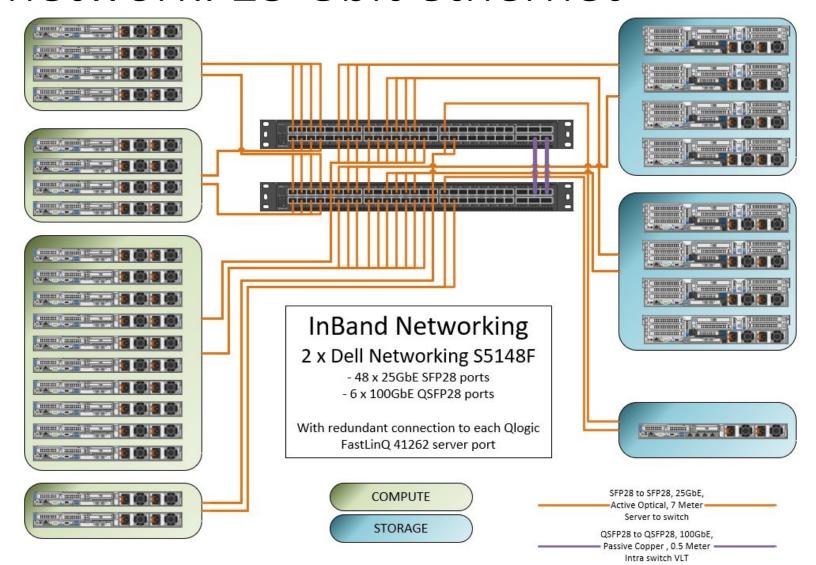
- Several computers (nodes) often in special cases for easy mounting in a rack
- One or more networks (interconnects) to hook the nodes together
- MP application' performance rely on the characteristics of the networks.



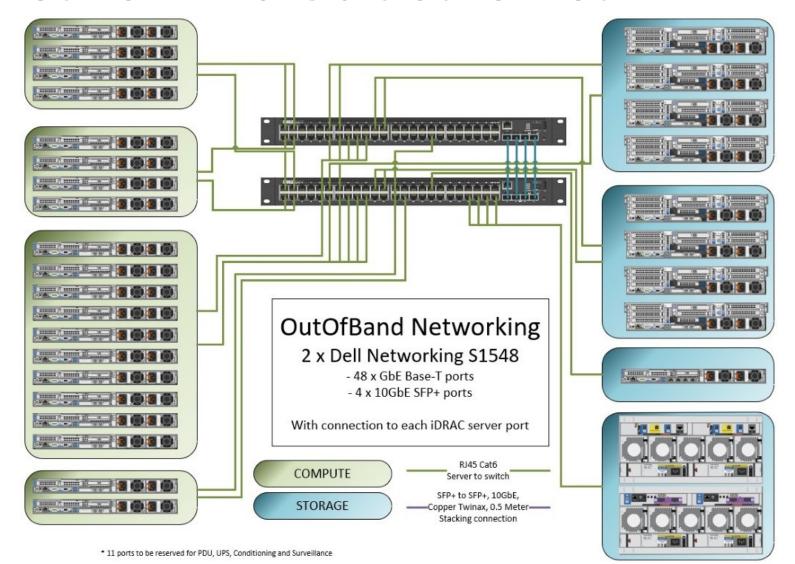
Network cluster classification

- HIGH SPEED NETWORK
 - parallel computation
 - low latency /high bandwidth
 - Usual choices: Infiniband...
- I/O NETWORK
 - I/O requests (NFS and/or parallel FS)
 - latency not fundamental/ good bandwidth
 - GIGABIT could be ok /10Gb and/or Infiniband better
- In band Management network
 - management traffic of all services (LRMS/NFS/software etc..)
- Out of band Management network:
 - Remote control of nodes and any other device

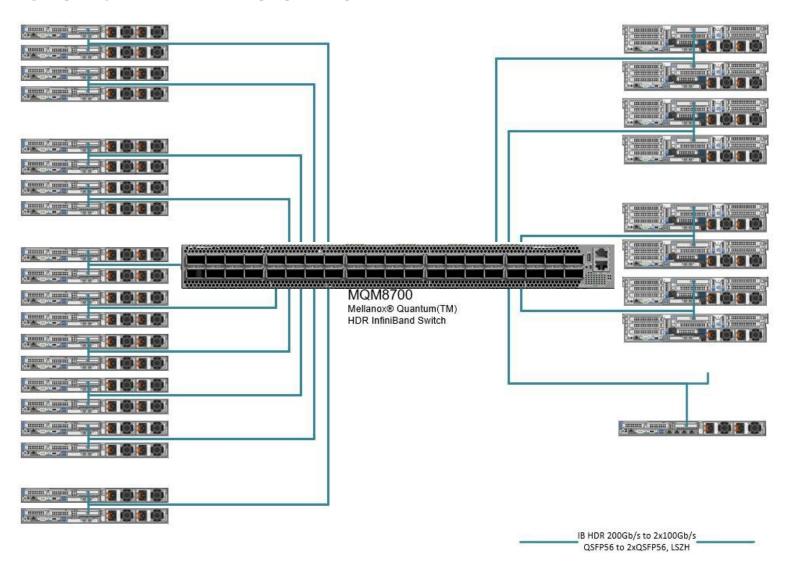
Orfeo in band management network: 25 Gbit ethernet



Orfeo out of band management network: 10 Gbit ethernet



Orfeo High Speed network: 100 Gbit Infiniband



Orfeo network classification

HIGH SPEED NETWORK

100 Gbit HDR Infiniband

• I/O NETWORK

 In band Management network

25Gbit Ethernet

 Out of band Management network:

10Gbit Ethernet

how to model network performance?

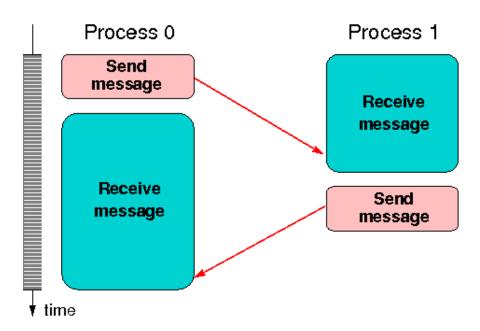
- Network capacity to tranfer data
- Very simple model:
 - Total transfer time of a message

```
T_{comm} = \lambda + (Size \ of \ message) / b_{network}
```

- λ is the latency of the network : i.e. the time to setup the communication channel
- b_{network} is the asymptotic network bandwith measured in Mb/sec.

How can we estimate/measure latency and bandwidth?

- Using a simple "Ping-Pong" program :
 - Two processes on the network exchange point-to-point message.
 - A single message of N Bytes is sent forward and backward: data transfer is 2N



Ping-Pong algorithm

```
1 myID= get process ID()
2 if(myID.eq.0) then
3
    targetID= 1
     S = get walltime()
4
5
     call Send message(buffer,N,targetID)
6
     call Receive message(buffer,N,targetID)
7
      E = get walltime()
8
      MBYTES = 2*N/(E-S)/1.d6 ! MBytes/sec rate
9
      TIME = (E-S)/(2*1.d6) ! transfer time in microsecs
10
                             ! for single message
11 else
12
     targetID= 0
13
      call Receive_message(buffer,N,targetID)
14
      call Send message(buffer,N,targetID)
15 endif
```

Ping Pong implementations

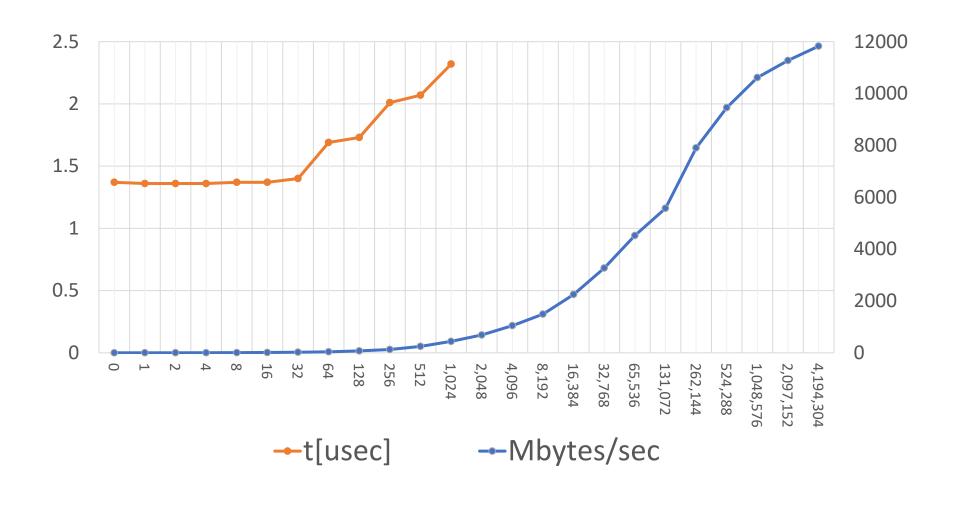
Available on the most common benchmark suite:

- IMB: Intel MPI benchmark
 - intel/mpi-benchmarks (github.com)
- OSU microbenchmarks
 - MVAPICH :: Benchmarks (ohio-state.edu)

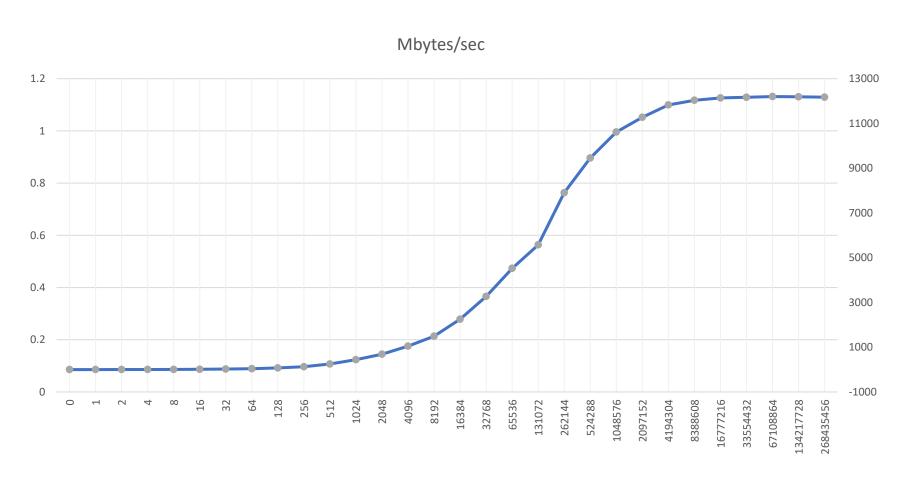
Measuring MPI point-to-point performance on Orfeo

- Download Intel MPI benchmark
- Compile it
- Run it
- Get results and interpret it
- See README file in day16 directory...

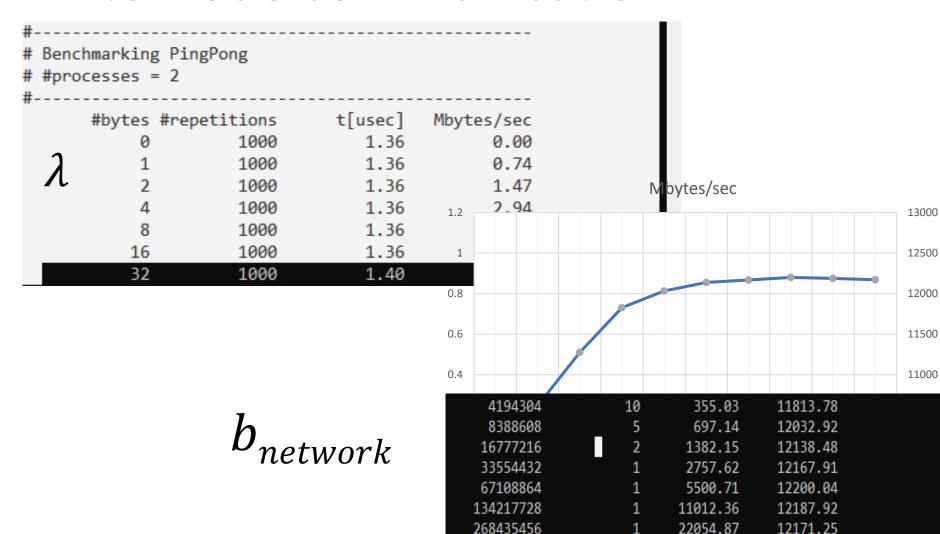
Measuring MPI point-to-point performance on Orfeo



Measuring MPI performance on Orfeo

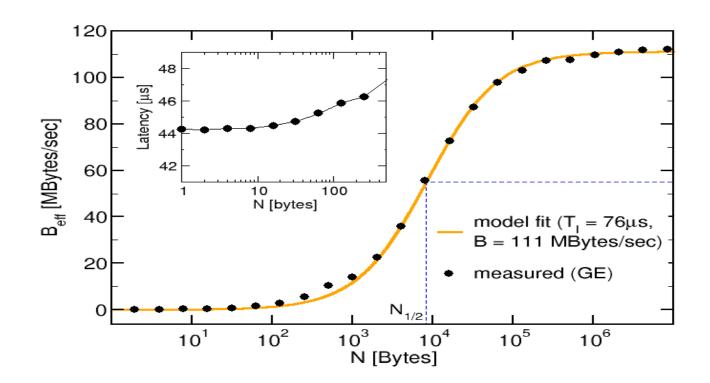


Extrapolating values for internode communication



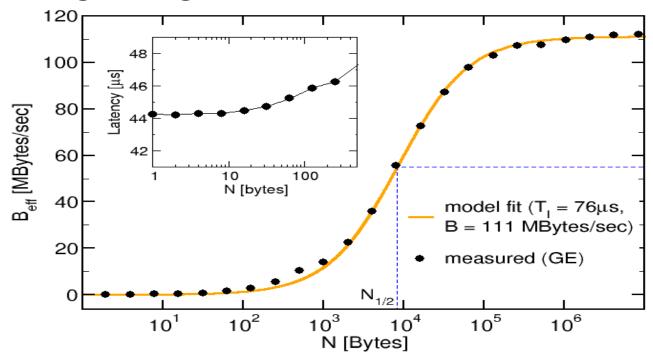
Gbit ethernet performance

- Latency: ~44 microsecond
- BW: ~ 111 Mb/second (theoretical one: 1000/8=125)



Gbit ethernet performance model

- Latency: 76 microsecond >> 44 (qualitative agreement)
- BW: good agreement



Network performance modeling

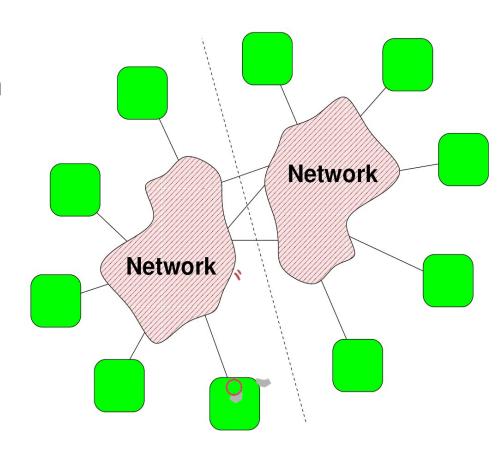
- "First Principles" modeling of Beff(V) provides good qualitative results but quantitative description in particular of latency dominated region (V small) may fail because
 - Overhead for transmission protocols, e.g. message headers
 - Minimum frame size for message transmission, e.g. TCP/IP over Ethernet does always transfer frames with V>1
 - Message setup/initialization involves multiple software layers and protocols; each
 - software layer adds to latency; hardware only latency is often small
 - As the message size increases the software may switch to different protocol, e.g. from "eager" to "rendezvous"

Network topology

- How the components are connected.
- Important properties
 - Diameter: maximum distance between any two nodes in the network (hop count, or # of links).
 - Nodal degree: how many links connect to each node.
 - Bisection bandwidth: The smallest bandwidth between half of the nodes to another half of the nodes.
- A good topology: small diameter, small nodal degree, large bisection bandwidth

Bisection bandwidth: B_b

- Split N nodes into two groups of N/2 nodes such that the bandwidth between these two groups is minimum
- general metric for the data transfer "capability" of a system
- More meaningful metric in terms of system scalability: B_b/Nodes

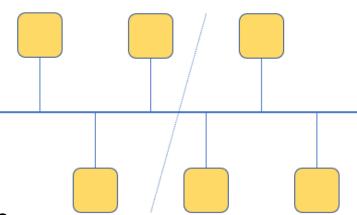


Common Topologies in HPC

- Bus
- Crossbar switches
- Fat tree
- CBB (Constant Bi-sectional Bandwidth)
- Mesh
 - 3D torus

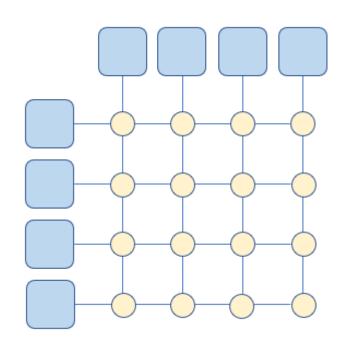
Bus topology

- Bus can be used by one connection at a time
- Bandwidth is shared among all devices
- Bisection BW is constant: Bb/Nnodes ~ 1/Nnodes
- Examples: PCI bus
- Advantages
 - Low latency
 - Easy to implement
- Disadvantages
 - Shared bandwidth, not scalable
 - Problems with failure resiliency (one defective agent may block bus)



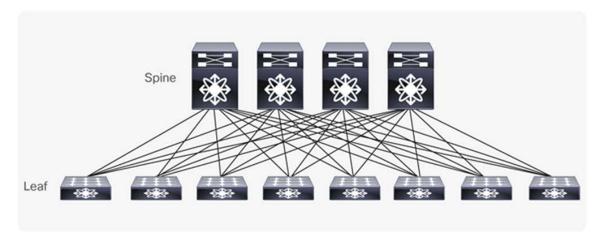
Non blocking crossbar switch

- A non-blocking crossbar can mediate a number of connections between a group of input and a group of output elements
- This can be used as a 4-port nonblocking switch
- Switches can be cascaded to form hierarchies (common case)
- Allows scalable communication at high hardware/energy costs
- Not feasible for large HPC installations



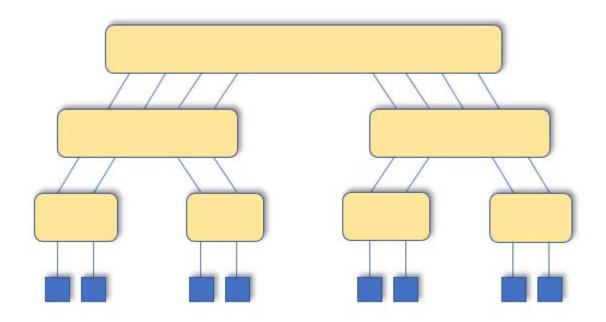
Switches and Fat-Trees

- HPC clusters are built with switched networks
- Compute nodes ("devices") are split up in groups each group is connected to single (non-blocking crossbar-) switch ("leaf/edge switches")
- Leaf switches are connected with each other using an additional switch hierarchy ("spine switches") or directly (for small configs.)
- "Perfect" world: fat- trees



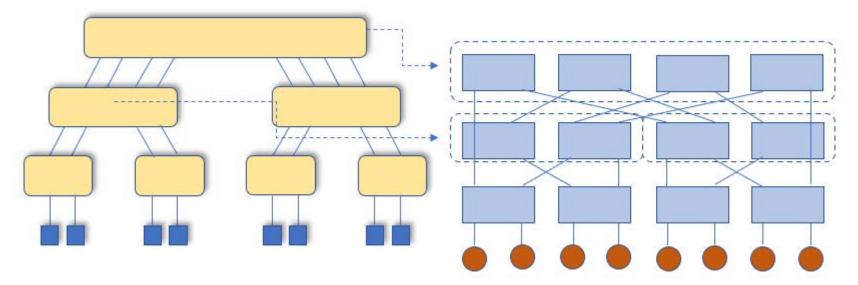
Fat-trees switch hierarchy...

- Fully non-blocking:
 - Each level double the number of link of the switches
 - Not practical. Root is NXN switch



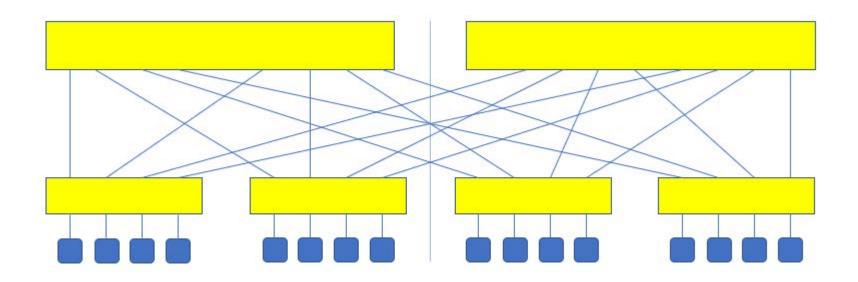
Practical fat-tree implementation

- Use smaller switches to approximate large switches.
- Most commodity large clusters use this topology.
- Also call constant bisection bandwidth network (CBB)
 - N_{nodes}/2 end-to-end connections with full bandwidth
 - $B_b = B * N_{nodes}/2$
 - $B_b / N_{nodes} = const. = B/2$



Two level CBB example

- N_{nodes}/2 end-to-end connections with full bandwidth: 8
- $B_b = B * N_{nodes}/2 = 8B$
- $B_b / N_{nodes} = const. = B/2$

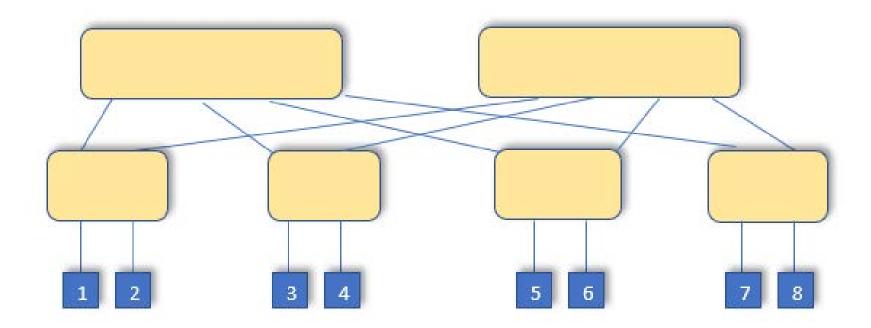


Fat tree and static routing

- Generally, CBB are using static routing algorithm.
- path taken between any two node pairs is statically computed
- Full bandwidth is not always seen in practice.
- The number of potential routes R for a total node count of N: $R=N(N-1)=N^2-N$.
- Number of routes $o(N^2)$
- Number of Intermediate Spine link is o (N)
- → There are scenarios where certain host communications will use the same Intermediate Spine link

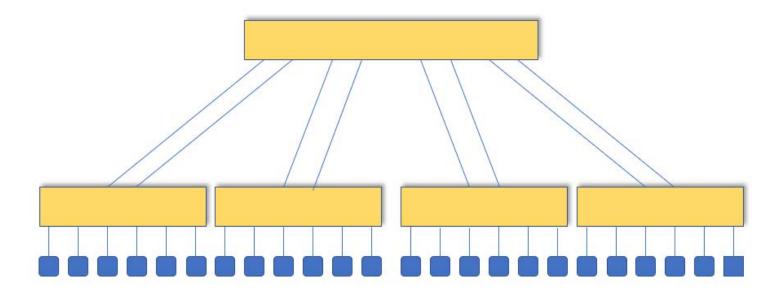
Example

- For 1->5,2->6,3->7,4->8 is ok
- For 1->5,2->7,3->6,4->8 is no longer fine if there is static routing



Oversubscription

- Spine does not support Nnodes/2 full BW end-toend connections
- B_b/Nnodes = const. = B/(2k), with k oversubscription factor (k=3 for the example)
- Resource management (job placement) is crucial



High speed networks

- Infiniband
 - The de-facto standard
 - 27% of ToP500 are based on infiniband
- Omni Path
 - started by Intel in 2015
 - one of the youngest HPC interconnects
 - 8.6% of Top4500 are Omni-Path systems
- Both are used behind a MPI implementation..

Meshes

 Fat trees can become prohibitively expensive in large systems

- Compromise: Meshes
 - n-dimensional Hypercubes
 - Toruses (2D / 3D)
 - Many others (including hybrids)
- Each node is a "router"
- Direct connections only between direct neighbors
- Different from a crossbar!
- Intelligent resource management and routing algorithms are essential

Infiniband speed: physical layer...

- InfiniBand uses serial stream of bits for data transfer
- Linkwidth
 - 1x One differential pair per Tx/Rx
 - 4x Four differential pairs per Tx/Rx
 - 12x Twelve differential pairs per Tx and per Rx

LinkSpeed

- Single Data Rate (SDR) 2.5Gb/s per lane (10Gb/s for 4x)
- Double Data Rate (DDR) 5Gb/s per lane (20Gb/s for 4x)
- Quad Data Rate (QDR) 10Gb/s per lane (40Gb/s for 4x)
- Fourteen Data Rate (FDR) 14Gb/s per lane (56Gb/s for 4x)
- Enhanced Data rate (EDR) 25Gb/s per lane (100Gb/s for 4x)

Linkrate

- Multiplication of the link width and link speed
- Most common shipping today is 4x ports DFR/EDR

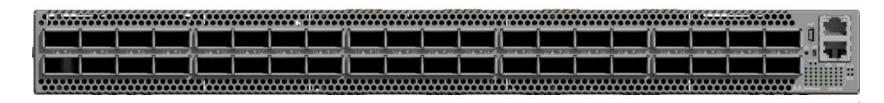
Infiniband speed: data encoding

- For SDR, DDR and QDR, links use 8b/10b encoding:
 - every 10 bits sent carry 8bits of data
- Thus single, double, and quad data rates carry 2, 4, or 8 Gbit/s useful data, respectively.
- For FDR and EDR, links use 64b/66b encoding
 - every 66 bits sent carry 64 bits of data.

InfiniBand performance

	SDR	DDR	QDR	FDR	EDR	HDR
Signaling rate (Gbit/s)	2.5	5	10	14.0625	25.78125	50
Encoding (bits)	8/10	8/10	8/10	64/66	64/66	64/66
Theoretical 2 hroughput 1x Gbit/s) 2		4	8	13.64	25	50
Theoretical throughput 4x (Gbit/s)	8	16	32	54.54	100	200
Theoretical throughput 12x (Gbit/s)	24	48	96	163.64	300	600

ORFEO IB network



Performance

- 40 x HDR 200Gb/s ports in a 1U switch
- 80 x HDR100 100Gb/s ports (using splitter cables)
- 16Tb/s aggregate switch throughput
- Sub-130ns switch latency



Our network: ORFEO ones...

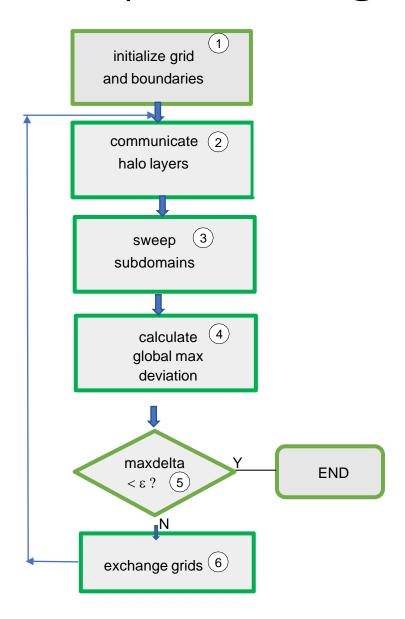
We can assume full non-blocking network:
 P/2 pair of nodes communicate in parallel at full speed

$$T_{comm} = \lambda + \text{message-size}/b_{network}$$

Where

$$\lambda$$
=1.35 microsecond $b_{network}$ =12Gb/second

Jacoby solver parallel algorithm



Analysis of the Jacobi Solver...

- Performance depends on L grid point over a N=N_xN_vN_z processors
- Where:
 - Ts(L) sweep partl: sequential time
 - Tc(L,N) communication time

$$P(L, \vec{N}) = \frac{L^3 N}{T_s(L) + T_c(L, \vec{N})}$$
,

Jacoby: computing time

- Cost of sweep domain:
 - The subdomain size (L³) is the same regardless of the number of processes, so the raw compute time T_s for all cell updates in a Jacobi sweep is also constant

→ Ts= 22.07 seconds (for L=1200) on GPU node on ORFEO

Jacoby: communication time: halo exchange

- Each process sends each of the 6 of point to point communication at the same time.
- we need to consider bandwidth number for fullduplex data transfer over a single link.
- Communication time T_c depends on the number and size of domain cuts that lead to internode communication.
- Assumption:
 - copying to/from intermediate buffers and communication of a process with itself come at no cost.

Communication time:

$$T_{\rm c}(L,\vec{N}) = \frac{c(L,\vec{N})}{B} + kT_{\ell}$$
.

- c(L,N): amount of data volume transferred over a node's network link
- B: bidirectional bandwidth of the network link
- T_1 = latency of the network
- k the largest number (over all domains) of coordinate directions in which the number of processes is greater than one.

$$\rightarrow$$
 c(L,N)=L²*k *2 *8 (Mb)

Our model prediction:

N	Nx		Ny	Nz	k	C(L,N)	Tc(L,N)	P(L,N)	P(1)*N/P(L,N)
	1	1	1	1	0	0	0.00	78.30	1.00
	2	2	1	1	2	46080	1.92	144.06	1.09
	3	3	1	1	2	46080	1.92	216.09	1.09
	4	2	2	1	4	92160	3.84	266.77	1.17
	6	3	2	1	4	92160	3.84	400.15	1.17
	8	2	2	2	6	138240	5.76	496.73	1.26
:	L2	3	3	3	6	138240	5.76	745.10	1.26
:	L 6	4	2	2	6	138240	5.76	993.46	1.26

Exercises

• Verify if the model discussed is working correctly...