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OpenMP Outline





Parallel Regions





Parallel & Advanced Loops Parallelism

AWARENESS



Parallel Regions



```
#pragma omp parallel some clauses here
single-line-here
#pragma omp parallel _some_clauses_here_
{ ... }
#pragma omp parallel for some clauses here
{ ... }
#pragma omp sections some clauses here
{ ... }
#pragma omp task _some_clauses_here_
{ ... }
```

A parallel region can be as short as a single line

There are no limits on the size of the code included within {..}.

The specific construct about for loops

A more general work-sharing construct

This allows task-based parallelism

The region starts at the opening { brace and ends at the closing } one.

An implicit synchronization barrier is present at the end of the region (*).

However, for efficiency reasons, it may be that the threads do not die at the end of the region but remain alive until the father process dies

(*) we'll see the details about synchronization later on





When you create a parallel region, through an OpenMP directive, a pool of threads is created.

Each one receives an ID, ranging from 0 to n-1, where n is the number of threads.

Their stack and IP are separated from the others' ones and from the father-process' ones.

Can we check that? What is the fate of the creating process (thread)?

```
int
     i;
register unsigned long long base of stack asm("rbp");
register unsigned long long top of stack asm("rsp");
 printf( "\nmain thread (pid: %d, tid: %d) data:\n"
         "base of stack is: %p\n"
         "top of stack is : %p\n"
                          : %td\n"
                          : %td\n"
         getpid(), syscall(SYS gettid),
         (void*) base of stack,
         (void*) top of stack,
         (void*)base of stack - (void*)&i,
         (void*)&i - (void*)top of stack );
#pragma omp parallel private(i)
    int me = omp get thread num();
    unsigned long long my stackbase;
    asm ("mov %%rbp,%0" : "=mr" (my stackbase));
    printf( "\tthread (tid: %ld) nr %d:\n"
                        "\t\tmy base of stack is %p ( %td from main\'s stack )\n",
                        "\t\tmv i address is %p\n"
                        "\t\t\t\td from my stackbase and %td from main\'s\n",
                        syscall(SYS gettid), me,
                        (void*)my stackbase, (void*)base of stack - (void*)my stackbase,
                        &i, (void*)&i - (void*)my stackbase,
                        (void*)&i - (void*)base of stack);
```







```
main thread (pid: 26291, tid: 26291) data: base of stack is: 0x7ffe6f51efc0
                                                                             threads for the OS.
              top of stack is : 0x7ffe6f51ef60
serial
             &i is
                              : 0x7ffe6f51ef7c
section
                 rbp - &i
                              : 68
                 &i - rsp
                               : 28
              thread (tid: 26291) nr 0:
                      my base of stack is 0x7ffe6f51eee0 ( 224 from main's stack )
                      my i address is 0x7ffe6f51eea0
                               -64 from my stackbase and -288 from main's
             thread (tid: 26293) nr 2:
                      my base of stack is 0x7f7342c82ba0 ( 597747680288 from main's stack )
parallel
                      my i address is 0x7f7342c82b60
region
                               -64 from my stackbase and -597747680352 from main's
             thread (tid: 26294) nr 3:
                      my base of stack is 0x7f7342880ba0 ( 597751882784 from main's stack )
                      mv i address is 0x7f7342880b60
                               -64 from my stackbase and -597751882848 from main's
             thread (tid: 26292) nr 1:
                      my base of stack is 0x7f7343084b20 ( 597743477920 from main's stack )
                      mv i address is 0x7f7343084ae0
                               -64 from my stackbase and -597743477984 from main's
```

pid and tid are the IDs of processes and threads for the OS. Here you see that the master thread stops its

Here you see that the master thread stops its activity and join the new pool of threads, while maintaining its own tid.

- Each thread has its own stack; thread 0 inherits its own stack, which has grown to host the data relative to OpenMP parallel region;
- the private is are actually in the threads stacks, and so they are different memory locations than the shared i.





How large is the stack of each thread? The default value is system dependent.

That is the output of the <code>00_stack_and_scope</code> code example: it prints the BP and SP pointers of each thread. Then, we know how large is the threads' stack at a given moment (only an integer is defined, plus the system's thread structure), and how much memory is reserved for the stack to grow:

```
thread 0: bp @ 0x7ffc6edea2f0, tp @ 0x7ffc6edea280: 112 B
thread 1: bp @ 0x7fa371d18b20, tp @ 0x7fa371d18ab0: 112 B
--> -382202615648 B from top of thread 0
thread 2: bp @ 0x7fa371916ba0, tp @ 0x7fa371916b30: 112 B
--> -4202256 B from top of thread 1
thread 3: bp @ 0x7fa371514ba0, tp @ 0x7fa371514b30: 112 B
--> -4202384 B from top of thread 2

you did not define OMP STACKSIZE: try to set it and check what happens to the threads' stack pointers
```

In this case, compiled with gcc, it seems that about 4MB are reserved for each thread. The same value holds with pgi, whereas clang seems to reserve 132MB (i.e., the addresses in the virtual space are spaced by 132MB).

However, you can control the size of the threads' stack using the environmental variable <code>omp_stacksize</code>: <code>export OMP STACKSIZE=N</code>

Where N is a number, followed by a letter: 'β', 'κ', 'M', 'G' mean bytes, kilobytes, megabytes and gigabytes respectively (if no letter is specified, the number is interpreted as kilobytes).





export OMP STACKSIZE=32K

```
thread 0: bp @ 0x7ffd1a2bbc70, tp @ 0x7ffd1a2bbbd0: 160 B
thread 1: bp @ 0x7f18b4be4af0, tp @ 0x7f18b4be4a50: 160 B
--> -980954214624 B from top of thread 0
thread 2: bp @ 0x7f18b4bdab70, tp @ 0x7f18b4bdaad0: 160 B
--> -40672 B from top of thread 1
thread 3: bp @ 0x7f18b4bd0b70, tp @ 0x7f18b4bd0ad0: 160 B
--> -40800 B from top of thread 2

you defined OMP STACKSIZE as 32K: try to change that value and check what happens to the threads' stack pointers
```

export OMP_STACKSIZE=1M

```
thread 0: bp @ 0x7ffc6f8b97f0, tp @ 0x7ffc6f8b9750: 160 B
thread 1: bp @ 0x7fd5bf930af0, tp @ 0x7fd5bf930a50: 160 B
thread 2: bp @ 0x7fd5bec96b70, tp @ 0x7fd5bec96ad0: 160 B
thread 3: bp @ 0x7fd5beb94b70, tp @ 0x7fd5beb94ad0: 160 B
thread 3: bp @ 0x7fd5beb94b70, tp @ 0x7fd5beb94ad0: 160 B
```

you defined OMP_STACKSIZE as 1M: try to change that value and check what happens to the threads' stack pointers





How many threads can be created by a single process?

Also this limit is system-dependent.

On Linux, it depends on the amount of total physical memory: basically, the maximum number of threads is the amount of physical memory divided by the memory amount needed to describe and run a thread, times a factor that accounts for the fact that you don't want all the memory allocated only to make the threads alive.

Within this limit, you can change the behaviour of your OpenMP program by using the env

You can check the OS' limit with

variable OMP THREAD LIMIT.

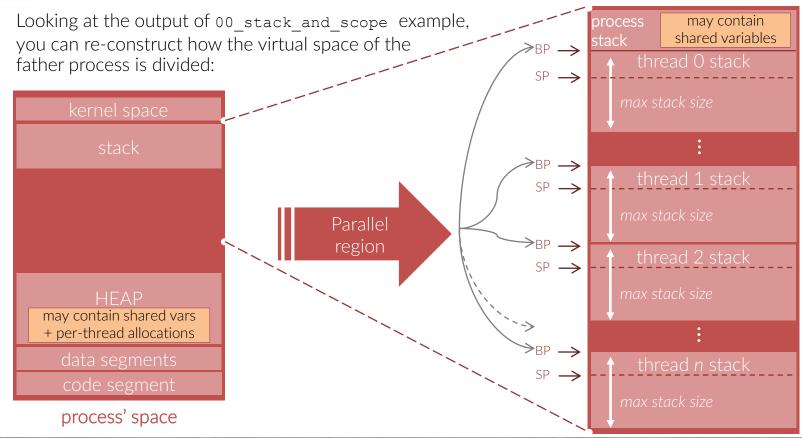
cat /proc/sys/kernel/threads-max

or by calling the omp library function

int omp get max threads()











Looking at the output of <code>00_stack_and_scope</code> example, you can re-construct how the virtual space of the

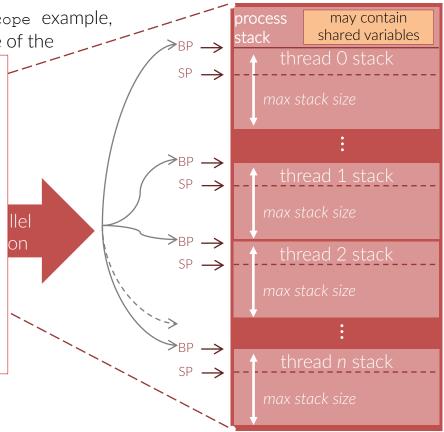
Be aware:

When the threads are created, the space needed for their stack is also allocated. If that space is quite large, you may run out of memory.

Conversely, if the stack is not large enough, you may incur into seg fault error (due to lack of memory in the stack)

code segment

process' space





Parallel Regions



```
returns the ID of the calling thread
int nthreads
int my thread id = 0;
#ifdef OPENMP
#pragma omp parallel
    my thread id = omp get thread num();
    #pragma master
    nthreads
                   = omp_get_num_threads();
#endif
          returns the number of threads active
          in that parallel region
```

By default rules, variables declared outside a parallel region are *shared*, whereas those declared inside a region are *private*.

Then both nthreads and my_thread_id are shared.

As a consequence, in this example:

- all threads are writing in my_thread_id,
 in undefined order
- only the master thread is writing in nthreads

The value of my_thread_id is unpredictable, because it depends on the run-time order by which the threads access it and by each a thread accesses it again to write it.

parallel regions/

01 simple pr wrong.c



Controlling the number of threads



By default the number of threads spawned in a parallel regions is the number of cores available. However, you can vary that number in several way

- OMP_NUM_THREADS environmental variable
- #pragma omp parallel num_threads(n)
- omp_set_num_threads(n);#pragma omp parallel





Controlling the number of threads



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- OMP_NUM_THREADS environmental variable
- #pragma omp parallel num_threads(n)
- omp_set_num_threads(n);#pragma omp parallel

That works if OMP_DYNAMIC variable is set to TRUE, otherwise the number of threads spawned is strictly equal to OMP_NUM_THREADS.

This setting can be changed through omp_set_dynamics(true)





The ordering of the threads



The order by which the greetings appear in the output is not deterministic.

In general, unless either you explicitly requires so – and that is possible only for some constructs, or you directly code it, there is no given order, since the threads are independent entities.

How would you build-up an enforcement of the order in the parallel region here on the left?



The ordering of the threads



```
int order = 0;
#pragma omp parallel
    int myid = omp get thread num();
    #pragma omp critical
    if ( order == myid ) {
       printf( "greetings from thread num %d\n",
               my thread id );
        order++; }
```

The CRITICAL directive defines a region which is executed by all threads but by a single thread at a time. Which starts to sound like an "ordering".

However, although the threads queue at the begin of the region, no particular order is imposed to that queue. As a consequence, the result is unpredictable, aside the fact that thread 0 will print the message and increase order.

For instance, if thread 2 is queued immediately after, it will execute the if evaluation which will fail (order would be equal to 1) and the thread 2 will not print the message.



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The ordering of the threads



```
int order = 0;
#pragma omp parallel
    int myid = omp get thread num();
    int done = 0
    while (!done) {
    #pragma omp critical
    if ( order == myid ) {
       printf( "greetings from thread num %d\n",
               my thread id );
        order++; done=1; } }
```

In this second implementation, the while cycle enforces the threads that fails the if condition to keep trying until the correct order is ensured.

Once a thread has executed the critical region, it then exits the while and join the implicit synchronization barrier at the end of the parallel region.

A note: without the critical directive, this code could work as well on most platform. However, it is still unreliable since it is not guaranteed that each thread complete the region before the successive threads enter in it. For instance, the compiler could have been reshuffled the order++ to be before the print and so the thread *n+1* could enter the region before of the print of the thread n and its message could appear as first.



The ordering of the threads



```
int nthreads = 1;
#pragma omp parallel
    int myid = omp get thread num();
   #pragma omp master
    int nthreads = omp_get_num_threads();
   #pragma omp barrier
   #pragma omp for ordered
    for ( int i = 0; i < nthreads; i++ )</pre>
      #pragma omp ordered
       printf( "greetings from thread num %d\n",
               my_thread_id );
```

In this third implementation, we use the clause ordered which force a work-sharing loop to be executed in the order of the loop iteration. ordered may also be a stand-alone directive that specifies cross-iteration dependences.

A note: without the barrier directive, it may happen that some threads (potentially all of them) arrive at the worksharing contruct for with a wrong value of nthreads







```
#pragma omp parallel
    #pragma omp critical
                                     The critical directive ensures that only a thread at a time executes the
    { code block
                                     block. All the threads will execute it, although in unspecified order.
                                     Like critical but limited to the following single line.
    #pragma omp atomic
                                     The instruction can only be an assignment in the form
    assignment instruction
                                      x \text{ binop} = expr
    #pragma omp single
                                     Only one among the threads will enter the code block
    { code block
    #pragma omp master
                                     Only the master thread will enter the code block
    { code block
```





```
#pragma omp parallel
    #pragma omp critical
    { code block
    #pragma omp atomic
    assignment instruction
    #pragma omp single
    { code block
    #pragma omp master
    { code block
```

A barrier (in the form of queuing) is present at the entry point; no one at the end point, i.e. the threads exiting the region will continue the run.

Synchronization as in critical region.

No explicit synchronization at all (but see relative tips in the following slides).

Only the executing thread is inside the region, the other ones can be everywhere else.







Rationale of

#pragma omp atomic
assignment instruction

When you deal with shared variables, ensuring that the workflow maintains the semantic correctness of your code is fundamental. For instance, the assignment

$$a += b$$

(where either a, b or both are shared) is meaningful only if the value of a (or b, or both) does not change in the middle of the instruction itself.

In fact, while a single assembly instruction is guaranteed not to be ever interrupted on the fly, we have to take into account that even a single C line translates in several asm instructions. So, the value of a shared variable could have been changed in the middle of that groups of asm instructions, breaking the correctness of the code.

To avoid that, it is necessary to "protect" the sensible regions.

An atomic assignment has, obviously, a much lower overhead than a critical region and must be preferred in the appropriate cases.







Special clauses for atomic

read

var = mem

causes an atomic read of the location designated by x regardless of the native machine word size

write

mem = var

causes an atomic write of the location designated by x regardless of the native machine word size

Rationale of

update

mem++, ++mem, mem--, --mem, mem binop= expr

Causes an atomic update of the location designated by x using the designated operator or intrinsic

#pragma omp atomic assignment instruction

val = mem++,val = ++mem.val = mem - -, Causes an atomic update of the location designated by x using the designated operator or intrinsic while also capturing the original or final value of the location designated by x with respect to the atomic update.

Clauses: read, write, update, capture

capture

 $val = --mem_{\bullet}$ val = mem binop= expr {val = mem; mem binop=

expr}

{mem binop= expr; val

= mem

The original or final value of the location designated by x is written in the location designated by v, depending on the form of the atomic construct, structured block, or statements, following the usual language semantics







```
#pragma omp critical
{
     "A" code block
}
#pragma omp critical
{
     "B" code block
}
#pragma omp critical(my_loop)
{
     code block
}
```

Named critical regions

In OpenMP it exists a unique global critical section.

Hence, when you define a critical section, it is logically considered to be part of the global one.

As a consequence only one thread can be inside any of the unnamed <code>critical</code> sections, which of course limits the perfomance whn more than one region is present.

However, that can be cured by the *named regions*, defined as the last one in the code snippet here on the left.

In that example, only one thread can be either in region "A" or in region "B": so, if one thread is executing "A", another one is forced to delay entering "B" even it would have been reading for it.

Instead, the named critical regions can be executed at the same time (by different threads, of course, and only by one thread at a time).







```
#pragma omp critical
{ ...
    some_assignment_to x;
    ...
}

#pragma omp atomic
x op= value
```

critical and atomic

Consider that by design atomic protects memory regions, while critical protects code regions.

Hence they are not mutually exclusive: a thread may be executing the critical region while another may be executing the atomic.







```
#pragma omp single
{ ...code block... }
```

```
#pragma omp master
{ ...code block... }
```

Is there any difference between using single or master?

There obviously is if you're assigning some special workflow to thread 0.

If not, the entity of the difference depends on the implementation details.

In general, using master requires only a simple test on the thread id, while using single requires more synchronization (the openmp infrastructure has to keep track about what thread is in the region and so on).

In general, if you have some insight about the fact that the workload before that point may be systematically unbalanced, so that some thread will likely arrive first, using single is ok.

Otherwise, it may be better to use master.



Work assignment



Inside a parallel region, the work can be assigned to each threads (actually, that's why PR are created..):

```
#pragma omp parallel
                                                                                      dynamic extent
                                               if( mvid \% 3 == 0)
                                                   result = heavy_work_0( );
                                               else if ( myid % 3 == 1 )
                                                                                       parallel_region/
  results[0] = heavy_work_0();
                                                                                       06 assign work.c
                                                   result = heavy work 1();
  results[1] = heavy work 1();
                                               else if ( myid % 3 == 2 )
                                                                                       run with a second
  results[2] = heavy_work_2();
                                                                                       argument >0 to check
                                                   result = heavy work 2( ); V
                                                                                       about it
                                               if ( myid < 3 )
                                                   results[mvid] = result;
parallel region/
```

06 assign work.c



Conditional creation of PR



It is possible to spawn a parallel region only if some conditions are met:

#pragma omp parallel if(any valid C expression)

```
#pragma omp parallel if( amount_of_work > high )
{
   if( myid % 3 == 0)
      result = heavy_work_0( );
   else if ( myid % 3 == 1 )
      result = heavy_work_1( );
   else if ( myid % 3 == 2 )
      result = heavy_work_2( );

   if ( myid < 3 )
      results[myid] = result;
}</pre>
```

If the condition is not fulfilled, the threads are not created and only the master thread will execute the code block.

```
parallel_region/
06_assign_work.c

if the first argument, that determines the amount of work, is ≤10, the parallel region is not created
```



Conditional creation of PR





What is this useful for?

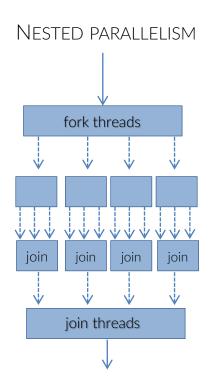
The overhead of the creation of a parallel region is of the order of ~10 μ seconds (that figure is dependent on the system, the compiler, the number of threads,...).

Then, you may want to create a parallel region (i.e. to spawn more threads) only if the serial execution of that code section is at least several times this overhead.



Nested Parallel Regions





Nested parallelism is explicitly_permitted in OpenMP. Whether it is *active* or not, depends on the value of some environmental variables:

Which you can change by calling the appropriate OMP_functions

omp_get_nested(), omp_set_nested(cond)

(*)OMP_NESTED is deprecated in new OpenMP 5.0. You should use only OMP_MAX_ACTIVE_LEVELS and OMP_NUM_THREADS.
OMP_NESTED is in fact redundant. However, at the moment of writing the compilers still support OMP NESTED.





The OpenMP environmental variables



You can configure the OpenMP behaviour through Internal Control Variables (ICV). Those are "conceptual" variables, meaning that you, as a programmer, are not interested in where and how those internal variables are implemented; you are only interested in how to access and use them.

These variables have different scopes:

- Global scope applies to the whole program, it is fixed once at the begin (there's only one, to my knowledge)
- Device scope OpenMP, since v4.0, can deploy threads on heterogeneous platforms (CPUs, GPUs, co-processors, ...); some ICV are naturally different on different devices
- Task scope most ICVs have a local scope, i.e. each OMP task^(*) holds its own values and can change them; when new tasks are created with either a parallel or task directives, they inherit the ICVs. If a task modifies the ICVs, this has effect only during its lifetime and can not be backward-propagated.

^(*) a "task" is in general a target to be executed by a thread: for instance, a section of a for loop scheduled for a thread is, in this sense, a "task.



The OpenMP environmental variables



ICV	Scope	Env. Variable	Accessibility from src
nthreads	TASK	OMP_NUM_THREADS	get / set
nested	Task	OMP_NESTED	get / set
max-active-levels	Task	OMP_MAX_ACTIVE_LEVELS	get / set
active-level	Task	-	get
dynamic	Task	OMP_DYNAMIC	get / set
stacksize	DEVICE	OMP_STACKSIZE	-
threads-limit	TASK	OMP_THREAD_LIMIT	get
waiting-policy	DEVICE	OMP_WAIT_POLICY	-
binding	TASK	OMP_PROC_BIND	set
placement	TASK	OMP_PLACES	-
cancellation	GLOBAL	OMP_CANCELLATION	get
default-device	TASK	OMP_DEFAULT_DEVICE	get / set
run-schedule	DEVICE	OMP_SCHEDULE	get / set
default-schedule	DEVICE	-	-

Affect parallel region

Affect program execution

Affect auto-parallelization of loops

that's all, have fun

