

The simplest PF and how bad/good it is.

Setting: Model : $x_n = f(x_{n-1}) + v_n, \quad v_n \sim N(0, Q)$
obs. : $y_n = h(x_n) + \eta_n, \quad \eta_n \sim N(0, R)$

target : $p(x_{0:n} | y_{1:n}) \propto p(x_{0:n-1} | y_{1:n-1}) p(x_n | x_{n-1}) p(y_n | x_n)$

proposal : $q(x_{0:n} | y_{1:n}) \propto q(x_0) \prod_{j=1}^n q(x_j | x_{j-1}, y_j)$

We still need to pick a $q(x_j | x_{j-1}, y_j)$

This is one choice (the original one, by now favoured upon!)

$$q(x_j | x_{j-1}, y_j) = p(x_j | x_{j-1})$$

→ "forecast ensemble"

→ use model, without most recent obs, to propose states.

weights:

$$w_n \propto w_{n-1} \frac{p(x_n | x_{n-1}) p(y_n | x_n)}{p(x_n | x_{n-1})} \propto w_{n-1} p(y_n | x_n)$$

In SIR setting:

$\{x_{n-1}^j\}$ ensemble.

$x_n^j \sim p(x_n | x_{n-1}^j) \rightsquigarrow$ "Run the stochastic model".

$$w^j \propto p(y_n | x_n^j) \propto \exp\left(-\frac{1}{2} (y_n - h(x_n^j))^T R^{-1} (y_n - h(x_n^j))\right)$$

$$\Rightarrow \{x_n^j, w^j\}$$

Resample : $\{x_n^j\} \sim p(x_n | y_{1:n})$ ✓

- Pros:
- Easy to implement
(no optimization, just simulation + computing weights)
 - flexible: not many assumptions about ψ, η, \int, h

Question: How well does this work?

Simplifying assumptions:

(1) Recall: $N_{\text{eff}} = N_e / \rho$, $\rho = \frac{E[\omega^2]}{E[\omega]^2}$

$$= \frac{\text{var}(\omega)}{E[\omega]^2} + 1$$

→ the larger variance of weights, the worse is the algorithm.

→ Leap of faith: if $\text{var}(-\log(\omega))$ is large, then $\text{var}(\omega)$ is even larger!

$$\text{var}(-\log \omega) = c$$

$$\leadsto \text{var}(\omega) \propto \exp(c)$$

(we don't get data this in detail)

(2) Suppose that: $y_u = Hx_u + \eta_u$, $\eta \sim N(0, R)$

$$y_u - Hx_u \sim N(0, R)$$

$$R^{-1/2}(y_u - Hx_u) \sim N(0, I)$$

l-dimensional,
l = # of obs!

$$\text{var}(-\log w) = \text{var}\left(\frac{1}{2} \underbrace{(y_K - Hx_K)^T R^{-1} (y_K - Hx_K)}_{S^T S}\right)$$

$$S^T S, \text{ where } S = R^{-1/2}(y - Hx) \sim N(0, I)$$

$$= \text{var}\left(\frac{1}{2} S^T S\right) = \text{var}\left(\frac{1}{2} \sum_{j=1}^L S_j^2\right)$$

↑ components of S

$$= \frac{1}{4} \sum_{j=1}^L \text{var}(S_j^2)$$

$2 S_j \sim N(0, 1)$

$$\text{var}(S_j^2) = E[S_j^4] - E[S_j^2]^2 = 3 - 1 = 2$$

$$\Rightarrow \text{var}(-\log w) = \frac{1}{4} \sum_{j=1}^L 2 = \underline{\underline{\frac{1}{2} L}}$$

$\Rightarrow \text{var}(-\log w)$ Scales linearly with L , the # of obs.

$\text{var}(w)$ scales exponentially with L , the # of obs.

$\mathcal{G} = \frac{\text{var}(w)}{E[w]^2} + 1$ scales exponentially with L .

$$\Rightarrow \boxed{N_e \propto \exp(L)}$$

"Not surprising, we already know that sampling in high-D is exponentially hard."

↳ Required ensemble size scales exponentially with L .

↳ not a good algo. if # of obs is large.

↳ has been successful in many apps with low-dimension.