Software solutions in High Performance Computing

Matthias Rauter

Universität Innsbruck, fall 2024

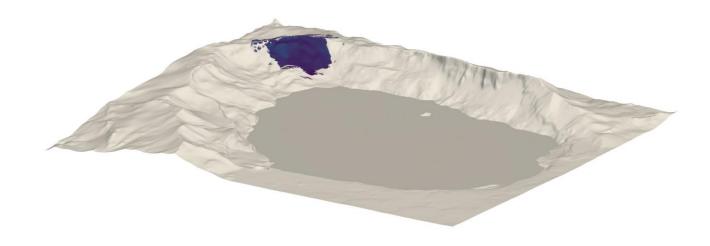
Agenda

- 1. About me, about this.
- 2. Basics of HPC: Hardware, history, architecture: Distributed memory
- 3. Introduction to Message Passing Interface (MPI)
- 4. Coding with MPI
- 5. Exercise: Calculate Pi with MPI
- 6. Building and running on a cluster
- 7. Questions.
- 8. Extra: Sheard memory: Pthread, Mutex, Race conditions

About me

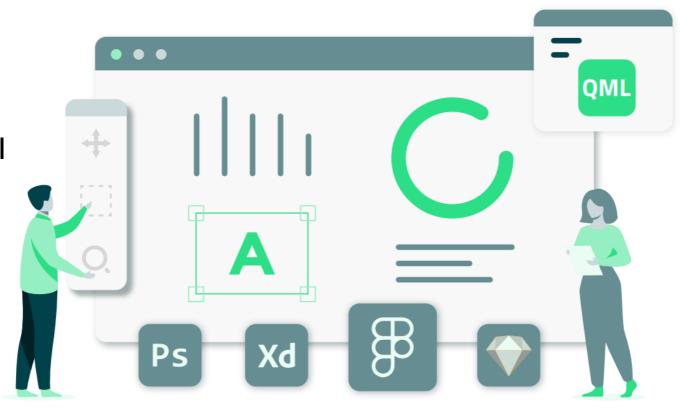
Matthias Rauter: Education

- MSc from UIBK
- Started C++ as hobby (lol)
- 2 PhDs in Engineering / Math
 - Avalanches (UIBK)
 - o Tsunamis (UiO)
 - Both with HPC
 - o Both with CFD



Matthias Rauter: Work

- Worked for Government in Natural Hazard Mgmt
- Short Postdoc at BOKU
- Now: The Qt Company
 - Senior/Staff Dev Graphics & UI
 - Team Lead Core & Network



Matthias Rauter: Contact

- Mail: matthias@rauter.it
- Code: https://github.com/mattisnowman
- Papers: https://www.researchgate.net/profile/Matthias-Rauter
- LinkedIn: https://www.linkedin.com/in/matti-rauter/

About this

https://github.com/mattisnowman/mpiplayground

Sources:

- Standards & library documentation: Hard to read but trustable.
 - Standard: https://www.mpi-forum.org/docs/
 - C docs: https://www.open-mpi.org/doc/
 - Python docs: https://mpi4py.readthedocs.io/en/stable/
 - Extra: Unix threads: https://man7.org/linux/man-pages/man7/pthreads.7.html
 - Extra: QThreads: https://doc.qt.io/qt-6/qthread.html
- Books: Didn't find any outstanding books. Happy for tips.
- Wikipedia: Good for general information/history. Quite reliable but check with standards if important.
- ChatGPT: Well informed about topic, produces correct code for simple stuff, fails for complex stuff.
- Try & Error: Just to make sure...

If no source is given, it is from Wikipedia.

Basics of High Performance Computing

Goals:

- 1. Understand the basics and how we got here.
- 2. Make sense out of HPC error messages & issues.

Methods:

- 1. Quick look at history and architecture
- 2. Write an example from scratch (C/C++ because I was told python-mpi does not work here)

Grading:

- 1. Finish / change the example.
- 2. Answer two questions via mail.

History, Hardware, Architecture

https://en.wikipedia.org/wiki/History_of_supercomputing

1960-1990:

- Learning to walk
- Very specific "CPU" designs: One-offs
- Not much concurrency

1963: Atlas



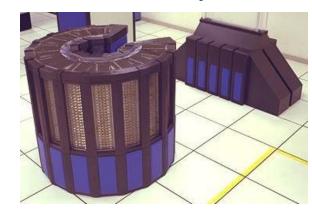
pioneered virtual memory and paging

1964: CDC6000



3 MFLOPS, it was dubbed a supercomputer

1985: Cray 2



Four-processor fluorinert cooled computer.

from 1990:

- Architecture with massive amounts of CPUs
- Parallelization and distributed computing becomes important
- Using mainstream hardware in huge amounts

1994: Fujitsu NWT



166 vector processors
Picture: blog.de.fujitsu.com

1996: Hitachi SR2201



2048 RISC processors
Picture: museum.ipsj.or.jp

1990++: Intel Paragon



1000 to 4000 Intel i860 processors. MPI

Top500.org

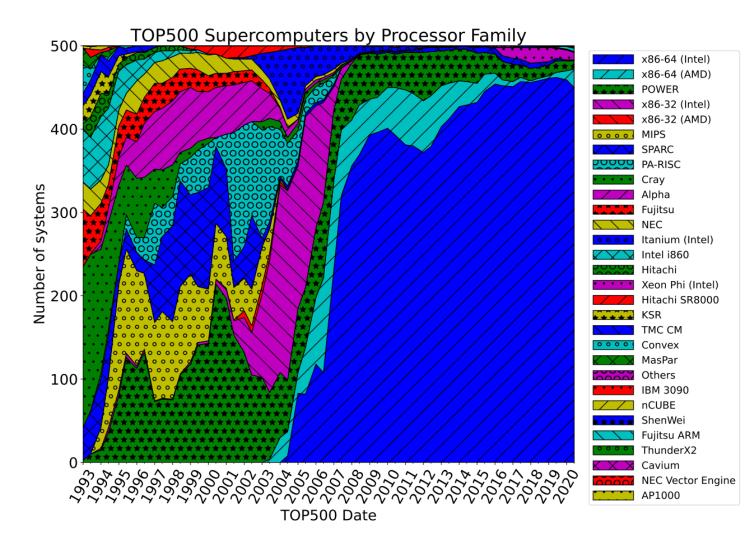
- Est. 1993
- Tracks the top-500 super computers
- LINPACK benchmark
 64-bit floating-point op
- Take a look at <u>www.top500.org/25years/</u>



Top500 Performance in GFLOPS 64-bit floating point (double)

Top500.org

- Est. 1993
- Tracks the top-500 super computers
- LINPACK benchmark
 64-bit floating-point op
- Take a look at <u>www.top500.org/25years/</u>



How to parallelize?

- Each CPU/Core has dedicated memory:
 - Distributed Calculation Power
 - Distributed Data
- Split tasks into independent subtasks:
 - Multiple levels.
 - Multiple solutions.
- Classic HPC: Loop level All data interacts sooner or later.

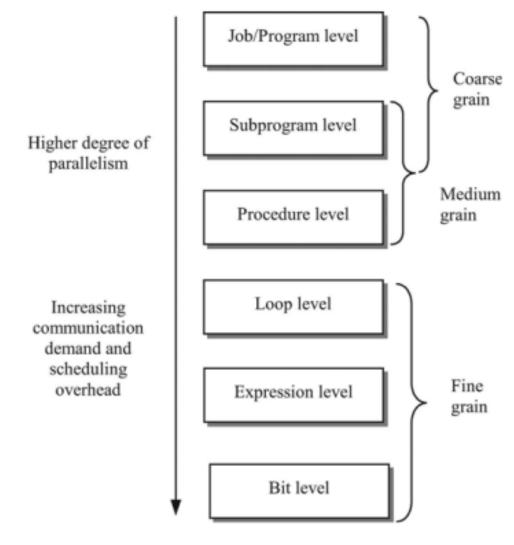


Figure 1.3. Levels of parallelism

How to parallelize?

- Lowest level (on CPU):
 - Shared memory
 - Threads, OpenMP, pthreads
 - o MPI
 - o SIMD
- Mid level (HPC):
 - Distributed memory
- High level:
 - Independent Processes
 - Use the OS/Service to start many processes

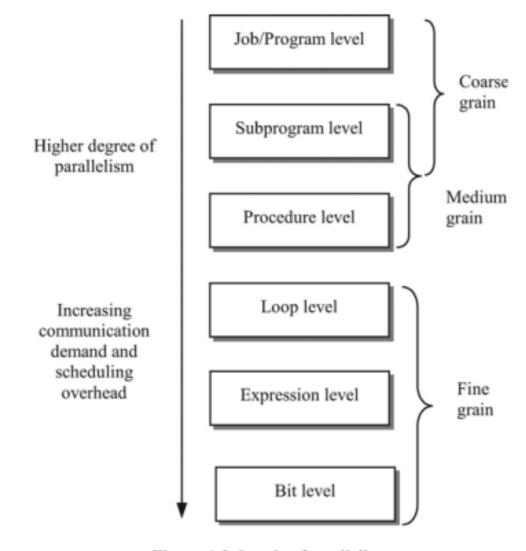
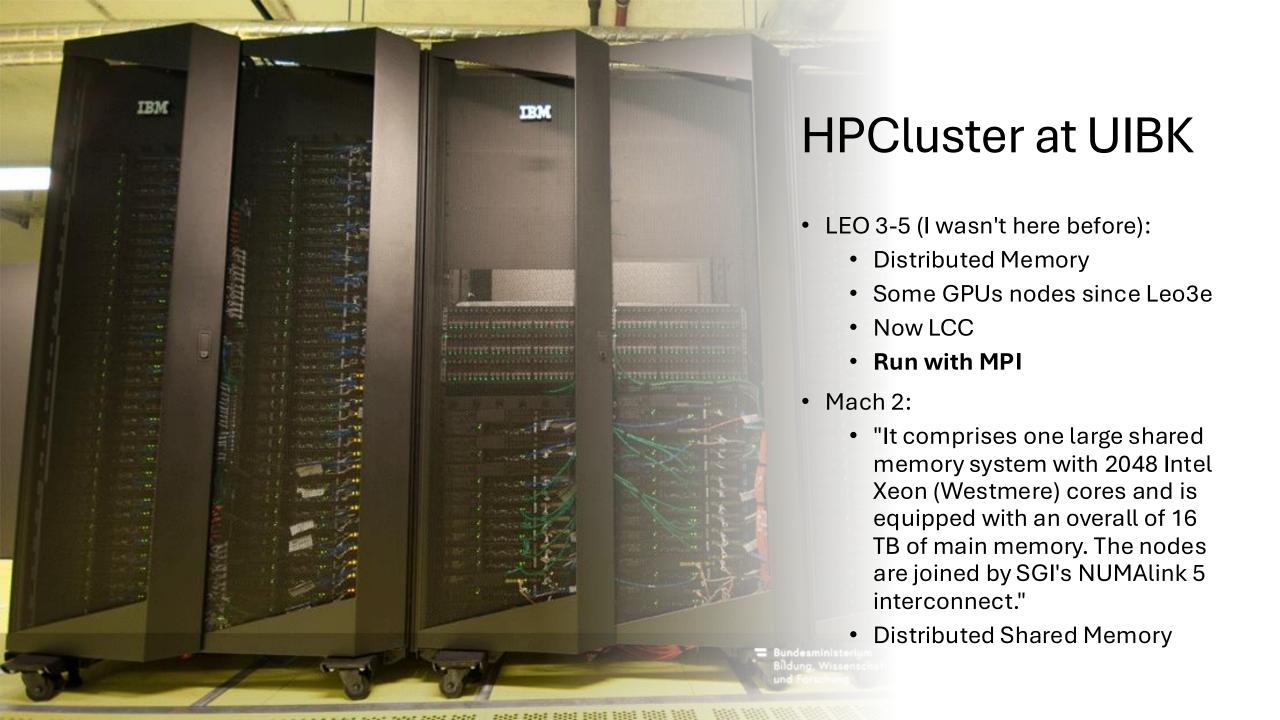


Figure 1.3. Levels of parallelism

M. O. Tokhi, M. A. Hossain, M. H. Shaheed: Parallel Computing for Real-time Signal Processing and Control



Introduction to Message Passing Interface

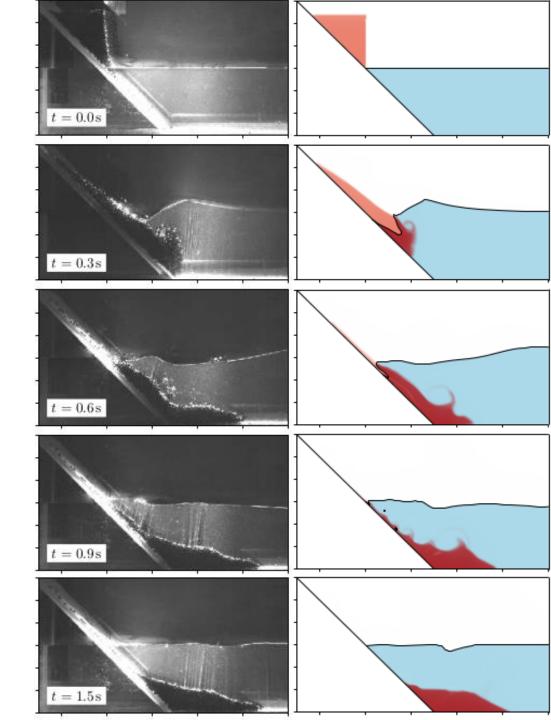
Message Passing Interface

- Challenge: Distribute one job across many nodes/computers/CPUs
- Concept: Start multiple **processes** (simplest case: same executables):
 - Each process has its own memory
 - Each process has its own core (ideally)
 - Can be on the same machine, can be in the same network
- New Problem: How to coordinate and exchange information?
- MPI is a standard (www.mpi-forum.org) and library in form of e.g. openMPI to:
 - Pass memory between processes to
 - If processes are on separate machines: Ethernet or proprietary connections

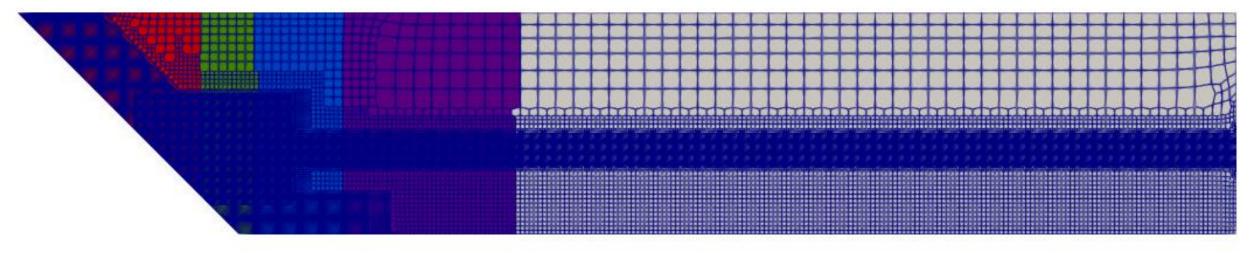
Example: Running distributed OpenFOAM simulation

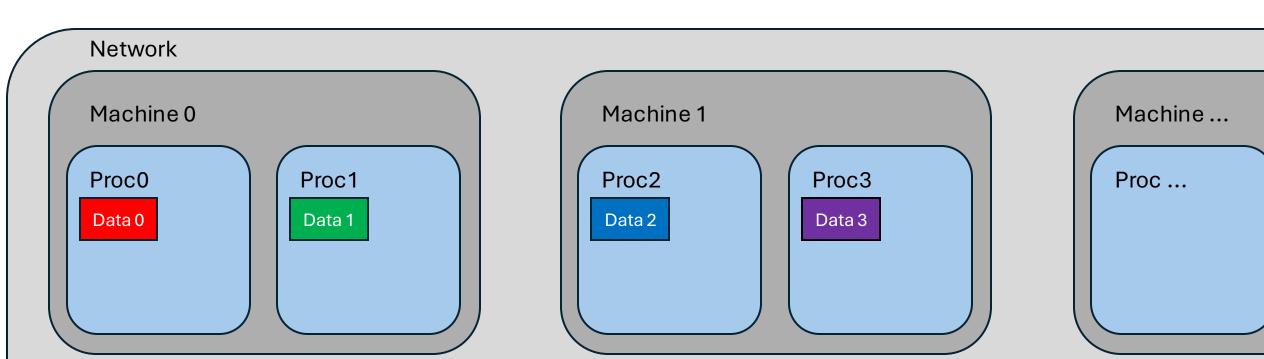
```
# create mesh in 2D
cartesian2DMesh
# copy blank initial fields (mesh independent)
cp -r 0/ 0.orig/
# set initial fields (mesh dependent)
setFields
# split the mesh and the data into (here 8) parts
decomposePar
# run the solver 8 times. npi for communication
mpirun -np 8 multiphaseTsunamiFoam
# stitch the data back together (optional)
reconstructPar
```

If you want to try it use OpenFOAM-v2312/tutorials/incompressible/simpleFoam/airFoil2D



Example: Distributed Data in OpenFOAM:





Prepare dev environment on Windows

In a PowerShell:

```
C:\Users\c00000000> wsl.exe --list --online
C:\Users\c00000000> wsl.exe --install Ubuntu
C:\Users\c00000000> wsl.exe
```

Then in the Linux shell (compiler, development library, mpi executables)

```
User@ZID-T9PCXXXX:~$ sudo apt-get update
User@ZID-T9PCXXXX:~$ sudo apt-get install g++ libopenmpi-dev openmpi-bin
```

Clone the repo and test:

```
User@ZID-T9PCXXXX:~$ git clone
https://github.com/mattisnowman/mpiplayground
User@ZID-T9PCXXXX:~$ ./mpiplayground/cpp/run.sh
```

MPI: Compiling and running on Linux

```
mpicxx -o mpi_pi mpi_pi.c -lm -Wall -std=c++11
# Compile C++. With Math (-lm) and all Warnings (-Wall). C++11 Standard.
# Reads code "mpi_pi.c", writes executable to mpi_pi
# MPI libraries are linked automatically thanks to mpicxx (instead of e.g. g++).
# run "mpicxx -show" to see what mpicxx is doing
```

- mpicxx calls the compiler:
 - -o mpi_pi mpi_pi.c Output and input names.
 - o -lm -Wall Link math library, show all warnings
 - o -std=c++11 C++11 Standard

```
# Run mpi_pi on 4 nodes.
# Oversubscribe: If there are not enough nodes, run multiple instances on a single
node.
mpirun -np 4 --oversubscribe ./mpi_pi
```

- mpirun –np 4 does two things:
 - Set up MPI environment on 4 nodes.
 - Execute the binary mpi_pi on those 4 nodes.
 - o --oversubscribe if there are less than 4 nodes, run more than one binary per node.

And for python, just in case you prefer that...

In a PowerShell:

```
C:\Users\c00000000> wsl.exe --list --online
C:\Users\c00000000> wsl.exe --install Ubuntu
C:\Users\c00000000> wsl.exe
```

Then in the Linux shell (compiler, development library, mpi executables)

```
User@ZID-T9PCXXXX:~$ sudo apt-get update
User@ZID-T9PCXXXX:~$ sudo apt-get install openmpi-bin python3-mpi4py
```

Clone the repo and test:

```
User@ZID-T9PCXXXX:~$ git clone
https://github.com/mattisnowman/mpiplayground
User@ZID-T9PCXXXX:~$ ./mpiplayground/python/run.sh
```

MPI: Running with python on Linux

```
# Run mpi_pi on 4 nodes.
# Oversubscribe: If there are not enough nodes, run multiple instances on a single
node.
mpirun -np 4 --oversubscribe python3 mpi_pi.py
```

Same as with C++, just run python3 executable with mpi script.

MPI: Getting libraries, config on Rocky Linux.

```
#!/bin/sh
sudo dnf install -y openmpi openmpi-devel

# MPI not in the standard paths on rocky linux? Here is how to add them:
export PATH=/usr/lib64/openmpi/bin:$PATH
export LD_LIBRARY_PATH=/usr/lib64/openmpi/lib/:$LD_LIBRARY_PATH
# Some adjustments. Bug workaround??
export PSM3_DEVICES='self,shm'
```

- Installation on Linux about the same everywhere
- Some paths need to be set manually in the terminal (export):
 - PATH contains all places where Linux searches for executables (+local dir)
 - LD_LIBRARY_PATH contains all shared libraries (*.so)
- PSM3_DEVICES='self,shm' a workaround for some intel stuff? (Thanks Eduard Reiterer)

MPI with C/C++: Setup & Boilerplate code

```
#include <mpi.h>
int main (int argc, char* argv[])
    MPI_Init(&argc, &argv);
    int rank, size;
    MPI_Comm_rank(MPI_COMM_WORLD, &rank);
    MPI_Comm_size(MPI_COMM_WORLD, &size);
    // code
    // code
    // code...
    MPI_Finalize();
    return 0;
```

- Size gives the total number of processes
- Rank gives the index of the current processor
- MPI works with Communicators.
 MPI_COMM_WORLD is a communicator that includes all processes.
- Remember to MPI_Init and MPI_Finalize.

MPI with C/C++: Hello World!

```
#include <mpi.h>
int main (int argc, char* argv[])
    MPI_Init(&argc, &argv);
    int rank, size;
    MPI_Comm_rank(MPI_COMM_WORLD, &rank);
    MPI Comm size(MPI COMM WORLD, &size);
    std::cout << "Hello MPI from Process "</pre>
              << rank << "/"
              << size << "!" << std::endl;
    MPI_Finalize();
    return 0;
```

- 1.Compile the code (mpicxx hello.cpp -o hellp)
- 2.Run it normally (./hello)
- 3.Run it with MPI (mpirun np [2,4,8,16] ./hello)

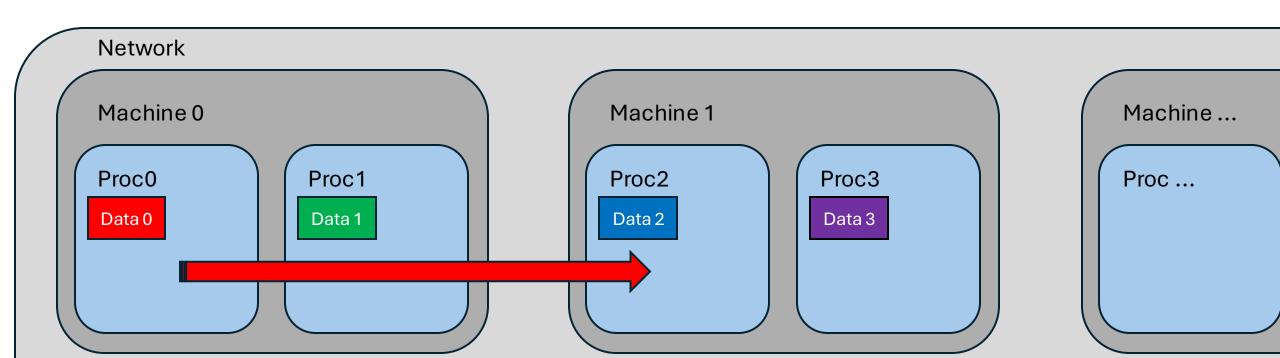
- 1. What happens?
- 2.Can you make sense out of it?

MPI_Send: Send local data to another node

```
int MPI_Send(const void *buf,
    int count,
    MPI_Datatype datatype,
    int dest,
    int tag,
    MPI_Comm comm)
```

www.mpich.org/static/docs/v4.1/www3/MPI Send.html www.mpich.org/static/docs/v4.1/www3/Constants.html

- buf: data to be send
- count: how big buf is
- datatype: e.g. MPI_DOUBLE
- dest: target node

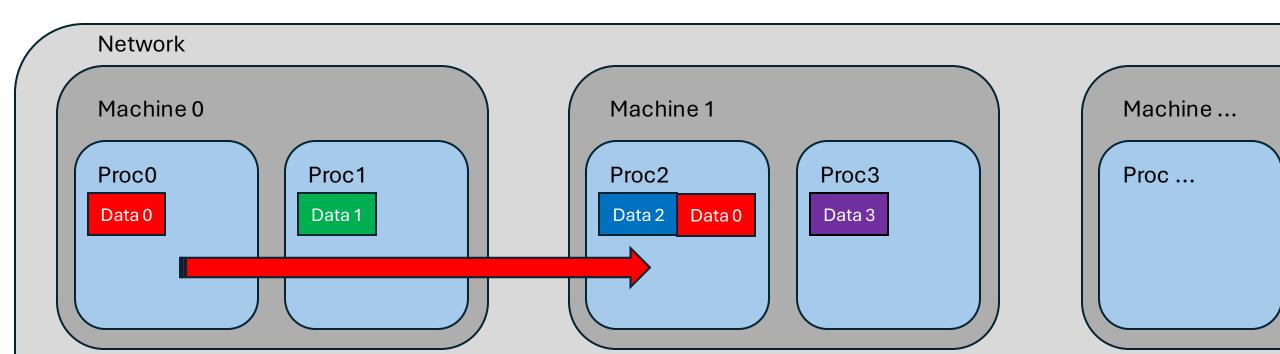


MPI_Recv: Receive data from another node

```
int MPI_Recv(void *buf,
    int count,
    MPI_Datatype datatype,
    int source,
    int tag,
    MPI_Comm comm,
    MPI_Status *status)
```

www.mpich.org/static/docs/v4.1/www3/MPI Recv.html

- buf: here goes the data
- count: how big buf is
- datatype: e.g. MPI_DOUBLE
- source: sender node



MPI_Send and MPI_Recv: Minimal example

Write an example that creates a random number in processor 0 and sends it to processor 2. Print it on processor 2. Start with the boilerplate. Here are some tips:

Check if you are on proc with ID:

```
if (rank == ID) {
   //code
}
```

Get a random integer:

```
value = std::rand();
```

Print stuff:

MPI_SEND for a single int value:

```
MPI_Send(&value, 1, MPI_INT,
dest_ID, 0, MPI_COMM_WORLD);

*buf = &value, count = 1, type = MPI_INT,
dest = dest_ID, tag = 0
```

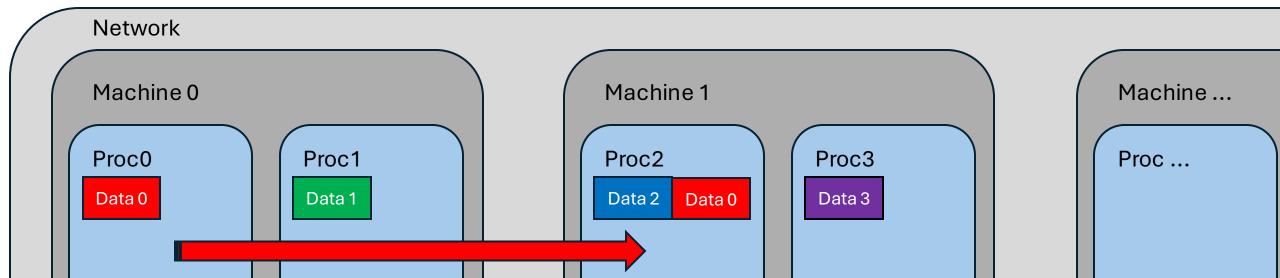
MPI_RECV for a single int value:

```
MPI_Recv(&value, 1, MPI_INT,
MPI_ANY_SOURCE, MPI_ANY_TAG,
MPI_COMM_WORLD, 0);
```

*buf = &value, count = 1, type = MPI_INT, source = whatefver, tag = whatever, STATUS = I don't care.

MPI_Send and MPI_Recv: Minimal example

```
int source_ID = 0;
int dest_ID = 2;
int value;
if (rank == source_ID) {
    value = std::rand();
    std::cout << "proc " << rank << ": sending " << value << " to proc " << dest_ID << std::endl;
    MPI_Send(&value, 1, MPI_INT, dest_ID, 0, MPI_COMM_WORLD);
} else if (rank == dest_ID) {
    MPI_Recv(&value, 1, MPI_INT, MPI_ANY_SOURCE, MPI_ANY_TAG, MPI_COMM_WORLD, 0);
    std::cout << "proc " << rank << ": received " << value << " from proc " << source_ID <<
std::endl;
}</pre>
```

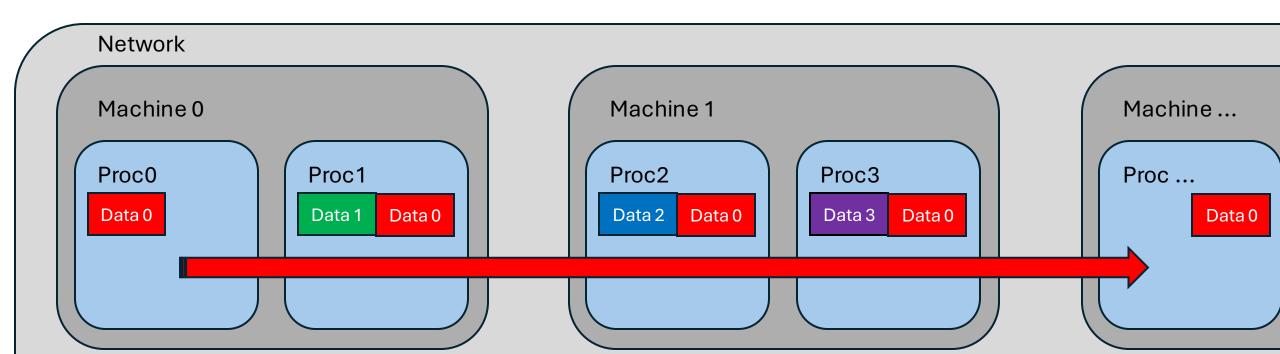


MPI_Bcast: 1 to N communication

```
int MPI_Bcast(void *buffer,
    int count,
    MPI_Datatype datatype,
    int root,
    MPI_Comm comm)
```

- sendbuf: here goes the c
- count: how big *buf is
- datatype: e.g. MPI_DOUBLE
- root: sender node, all others are receiver

www.mpich.org/static/docs/v4.1/www3/MPI_Bcast.html

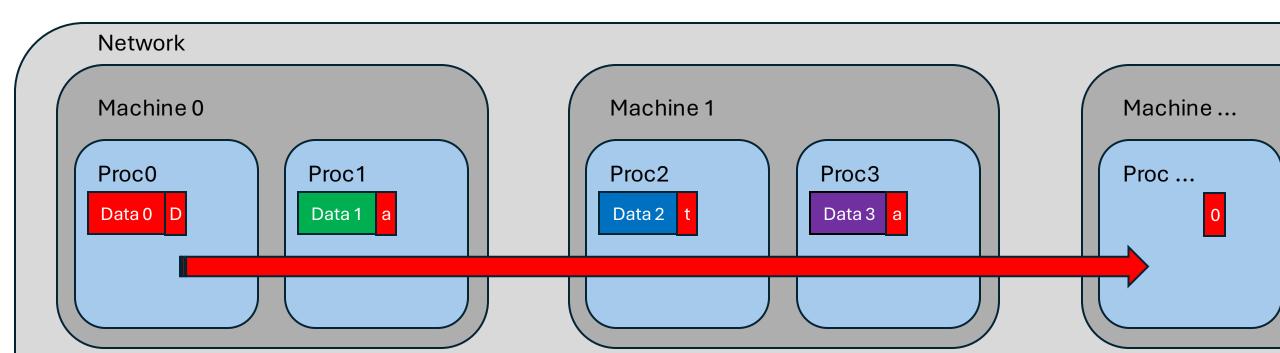


MPI_Scatter: Also 1 to N communication

```
int MPI_Scatter(const void *sendbuf,
   int sendcount,
   MPI_Datatype sendtype,
   void *recvbuf, int recvcount,
   MPI_Datatype recvtype,
   int root, MPI_Comm comm)
```

- sendbuf: sending data
- recvbuf: receiving data
- root: sender node

www.mpich.org/static/docs/v4.1/www3/MPI_Scatter.html

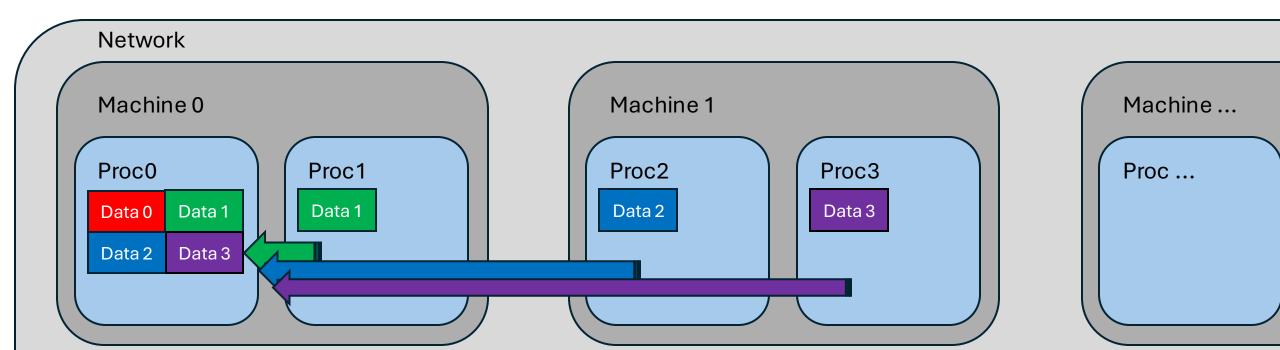


MPI_Gather: N to 1 communication

```
int MPI_Gather(const void *sendbuf,
    int sendcount,
    MPI_Datatype sendtype,
    void *recvbuf, int recvcount,
    MPI_Datatype recvtype,
    int root,
    MPI_Comm comm)
```

- sendbuf: data to be send
- Recvbuf: data to be written
- root: receiver node, all others are sender

www.mpich.org/static/docs/v4.1/www3/MPI Gather.html

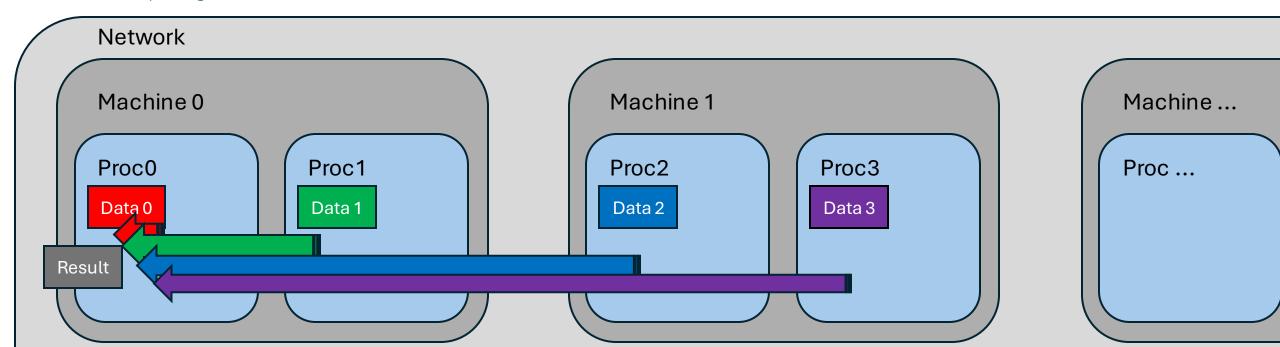


MPI_Reduce: Do an operation while gathering

```
int MPI_Reduce(const void *sendbuf,
    void *recvbuf,
    int count,
    MPI_Datatype datatype,
    MPI_Op op,
    int root,
    MPI_Comm comm)
```

www.mpich.org/static/docs/v4.1/www3/MPI Reduce.html www.mpich.org/static/docs/v4.1/www3/Constants.html

- sendbuf: data to be send
- recvbuf: data to be written
- Op: reduce operation, e.g.
 MPI_MAX
- root: receiver node



What else is there in MPI?

- All to all communication: MPI_Allgather, MPI_Allreduce
- Syncronize: MPI_Barrier (wait in all processes)
- Get time: MPI_Wtime
- Split Communicator: MPI_Comm_split, MPI_Comm_join, ...
- Register your own type: MPI_Type_create_struct, MPI_Type_commit
- Non-blocking functions: MPI_Isend, MPI_Irecv
- File I/O (less common): MPI_File_open, MPI_File_set_view, ...
- Much, much more...

Proof to me that this really is how it is done...

- Foam::Sum(field) is calculating the sum of a field on a single node.
- Foam::gSum(field) is calculating the sum of a field on all nodes.

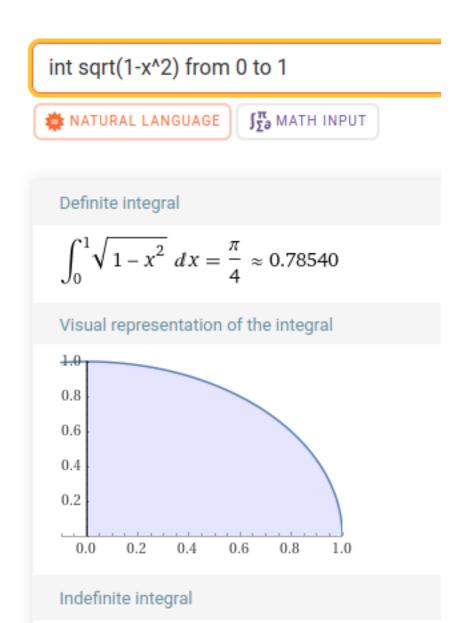
```
matti@tsunami:~/OpenFOAM/OpenFOAM-v2312$ grep -nr "Foam::gSum"
modules/external-solver/src/petsc4Foam/utils/petscUtils.C:64:
                                                                Foam::solveScalar Foam::gSum(Vec input)
Foam::solveScalar Foam::gSu
                            (Vec input)
                                                                    PetscScalar val:
                                                                    AssertPETSc(VecSum(input, &val));
PetscErrorCode VecSum(Vec v, PetscScalar *sum)
    PetscScalar tmp = 0.0;
   [pseudocode: x = v]
    for (PetscInt i = 0; i < n; ++i) tmp += x[i];
    PetscCallMPI(MPIU_Allreduce(MPI_IN_PLACE, &tmp, 1, MPIU_SCALAR, MPIU_SUM,
                 PetscObjectComm((PetscObject)v)));
    *sum = tmp;
    PetscFunctionReturn(PETSC_SUCCESS);
```

Do GPUs (NVLink, Cuda) replace MPI?

"MPI is fully compatible with CUDA, CUDA Fortran, and OpenACC, all of which are designed for parallel computing on a single computer or node. There are a number of reasons for wanting to combine the complementary parallel programming approaches of MPI & CUDA (/CUDA Fortran/OpenACC)."

https://developer.nvidia.com/mpi-solutions-gpus

MPI Exercise: Distributed calculation of PI



- We can calculate PI with numerical integration of a quarter circle $(f(x) = sqrt(1-x^2))$
- Split the interval [0, 1] in N = 1e7 equal parts.
 Calculate their area (1/N * f(x)). Distribute the parts equally to all processes (easy option: for (int i = rank; i < N; i += size)).
- Develop 2 versions:
 - Gather/reduce results in every step of the for loop.
 - Gather/reduce results after the loop. Use a temporary variable within the loop.
- Run your examples with [1,2,4,8,16,32] nodes. How do they scale with number of nodes? Can you make sense of it? How would you describe the difference between the applications?

MPI Exercise: Tips

Add this to the beginning/end to get execution duration:

This does not include e.g. creating of processes. For that you have to use Linux bash commands, but this is good enough.

This is a very easy way to distribute over size processes:

```
for (int i = rank; i <= N; i += size)
{
    double x = from + i * d;
    double fx = f(x);
    part_sum += fx * d;
}</pre>
```

The two versions should have MPI_Reduce in:

```
for (int i = rank; i <= N; i += size){
    // do stuff
    MPI_Reduce(...);
}</pre>
```

And outside the loop (different granularity):

```
for (int i = rank; i <= N; i += size) {
     // do stuff
}
MPI_Reduce(...);</pre>
```